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In [ ]: import numpy as np
        import math
        import numpy.random as rnd
        def metropolis_hastings(g,N,m, burn_in = None):
             burn_in = burn_in if burn_in is not None else N // 10
             #X and Y are random integers from 0 to m
            U = np.random.uniform(0,1,N + burn_in)
            X = np.zeros(N + burn_in,dtype = int)
            X[0] = 3
             \#prob\_of\_sampling = np.minimum(g(X)/g(Y),np.ones(N))
             #sample X with probability prob_of_sampling
             for i in range(1,N+burn_in):
                 x = X[i-1]
                 y = np.random.randint(0,m+1)
                 if U[i] \leftarrow min(g(y) / g(x),1):
                     X[i] = y
                 else:
                     X[i] = x
             # X = np.where(U<prob_of_sampling,X,Y)</pre>
            X = X[burn in:]
             return X
        def truncated_poisson_samples(lam, low, high, size=1, numvars = 1):
             samples = []
            while len(samples) < size:</pre>
                 x = np.random.poisson(lam, numvars)
                 if low <= x <= high:</pre>
                     samples.append(x)
             return np.array(samples)
        def y_sampling_function(m):
                 def y sampling():
                     y1 = np.random.randint(0,m+1)
                     y2 = np.random.randint(0,m+1-y1)
                     #create y as (y1,y2) or (y2,y1) with equal probability
                     return (y1,y2) if np.random.uniform(0,1) < 0.5 else (y2,y1)
                 return y_sampling
        def metropolis_hastings_joint(g_joint,N, burn_in = None, y_sampling_func = y_sam
            burn_in = burn_in if burn_in is not None else N
            #X and Y are random integers from 0 to m
            U = np.random.uniform(0,1,N + burn_in)
            X = np.zeros((N + burn_in,2),dtype = float)
            X[0] = (1.0, 1.0)
             \#prob\_of\_sampling = np.minimum(g(X)/g(Y),np.ones(N))
             #sample X with probability prob_of_sampling
             for i in range(1,N+burn_in):
                 x = X[i-1]
                 y = y_sampling_func()
                 if U[i] \leftarrow \min(g_{joint}(y[0],y[1]) / g_{joint}(x[0],x[1]),1):
                     X[i] = y
                 else:
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X[i] = x
    # X = np.where(U<prob_of_sampling,X,Y)</pre>
   X = X[burn_in:]
    return X
def Gibbs(As, n, x0, m):
   xs = [x0[0]]
   ys = [x0[1]]
   A1 = As[0]
   A2 = As[1]
   for k in range(1,n):
        # Generate i and sample from j
        i = xs[k-1]
        num_{classes_j} = int(m - i + 1)
        ps = np.zeros(num_classes_j)
        k = 0
        for j in range(num_classes_j):
            ps[j] = A2**j / math.factorial(j)
            k += A2**j / math.factorial(j)
        ps /= k
        j = rnd.choice(a=np.arange(num_classes_j), size= 1, p = ps)[0]
        ys.append(j)
        # Newest j has already been found
        num_{classes_i} = int(m-j + 1)
        ps = np.zeros(num_classes_i )
        k = 0
        for i in range(num_classes_i):
            ps[i] = A2**i / math.factorial(i)
            k += A2**i / math.factorial(i)
        ps /= k
        i = rnd.choice(a=np.arange(num_classes_i), size=1, p = ps)[0]
        xs.append(i)
    return np.array(xs), np.array(ys)
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