

# Operating Systems

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## Lecture 15: File Systems Part III: Log-structured File System

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<https://github.com/henryhxu/CSCI3150>

# Outline

- ▣ Key Idea: Writing Sequentially
- ▣ Indirect Mapping and Checkpoint Region
- ▣ Directories
- ▣ Garbage Collection
- ▣ Crash Recovery

# Overview

- In the early 90's, a new file system, the log-structured file system (LFS) was developed
- Motivation
  - ◆ Memory sizes were growing.
  - ◆ Large gap between random IO and sequential IO performance.
  - ◆ Existing File System perform poorly on common workloads.
- In this chapter, we study Log-Structured Filesystem (LFS).
  - ◆ How can a file system **transform all writes into sequential writes**?

John Ousterhout



Mendel Rosenblum

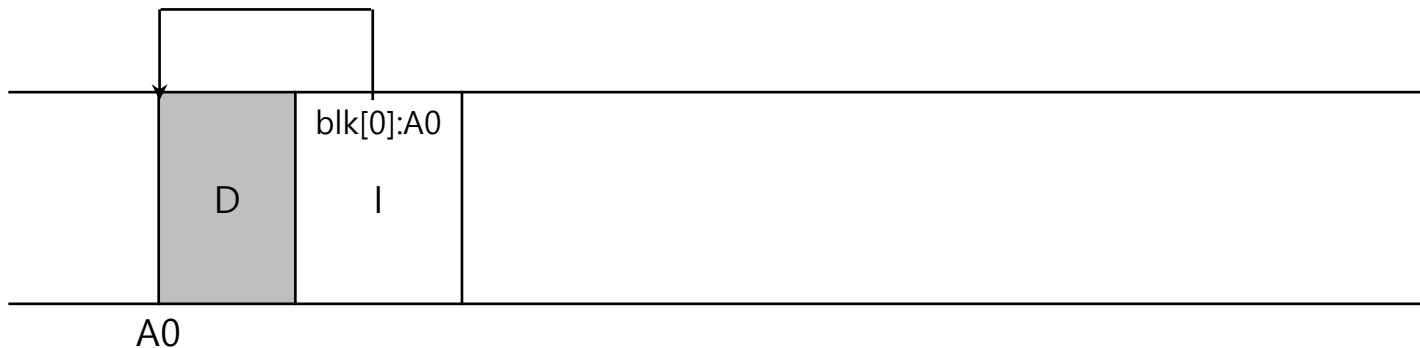
# Writing to Disk Sequentially

- How do we transform all updates to file-system state into a series of sequential writes to disk?

- ◆ data update

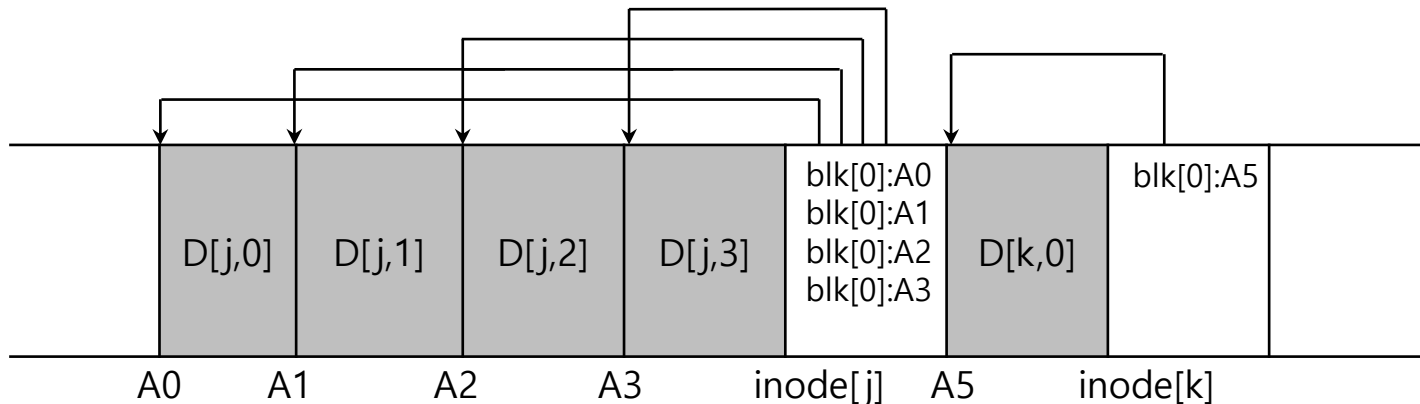


- ◆ metadata needs to be updated too. (Ex. inode)



# Writing Sequentially, and Efficiently!

- ▣ Writing to the disk sequentially is not enough to guarantee the efficient writes.
  - ◆ Disk may rotate between the writes. → lose a single revolution between the writes.
- ▣ Write buffering.
  - ◆ Segment: a set of sequential writes that are written to the disk with a single unit.
  - ◆ Keep track of updates in **memory buffer**. ( a few Mbyte)
  - ◆ Write them to disk all at once, when it has sufficient number of updates.



# Issue #1: How Much to Buffer

- Time to write D MB

$$T_{write} = T_{position} + \frac{D}{R_{peak}}$$

- Effective write bandwidth

$$R_{effective} = \frac{D}{T_{write}} = \frac{D}{T_{position} + \frac{D}{R_{peak}}}$$

- We'd like to make the effective write bandwidth close to peak bandwidth with some fraction F ( $0 < F < 1$ )

$$R_{effective} = \frac{D}{T_{position} + \frac{D}{R_{peak}}} = F \times R_{peak}$$

# Issue #1: How Much to Buffer

- Then, D can be computed as follows

$$D = F \times R_{peak} \times (T_{position} + \frac{D}{R_{peak}})$$

$$D = (F \times R_{peak} \times T_{position}) + \left( F \times R_{peak} \times \frac{D}{R_{peak}} \right)$$

$$D = \frac{F}{1-F} \times R_{peak} \times T_{position}$$

- Example: Positioning time 10ms, peak transfer rate 100MByte/sec, we like to achieve 90% of the peak rate

$$D = 0.9 \times 0.1 \times 100 \text{ Mbyte/sec} \times 0.01 \text{ secs} = 9 \text{ Mbyte}$$

- What is D if F = 0.95?

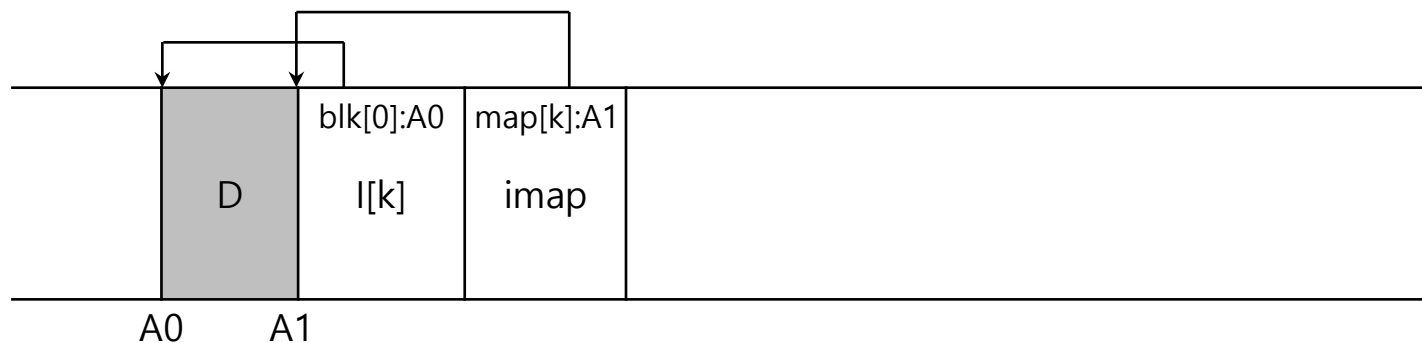
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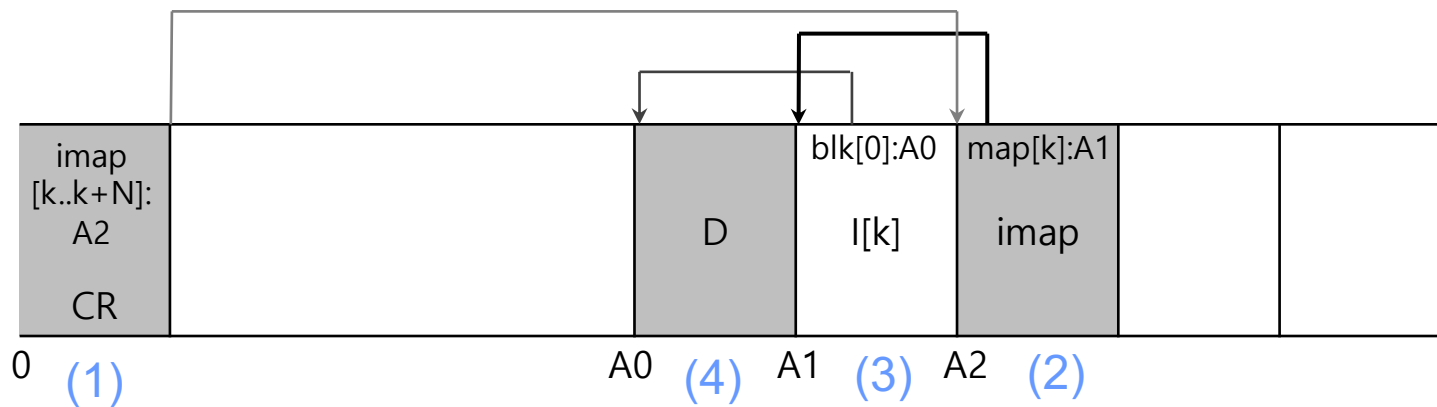
## Issue #2: How to Find Inodes?

- ▣ The position of the inodes keep **changing**.
- ▣ The Inode Map
  - ◆ A data structure that contains the location of the most recent inode for a given inode number.
  - ◆ Places the chunk of updated inode map right next to the updated inode (**why?**)
  - ◆ Where to find the inode map?



## Issue #2: How to Find Inodes?

- How to find the inode map spread across the disk?
  - The LFS must have a fixed location on disk to begin a file lookup.
- Checkpoint Region**
  - A fixed location in the LFS partition.
  - Contain the pointers to the latest of the inode map.
- Wait, then every update still needs to seek to this CR!
  - Inode map also helps to solve the recursive update problem (coming up soon)



# Reading a file from the disk

- ▣ Reading a file block
  - ◆ Read a checkpoint region
  - ◆ Read inode map
  - ◆ Read inode
  - ◆ Read data block
- ▣ What about sequential read?
  - ◆ It may become random read.

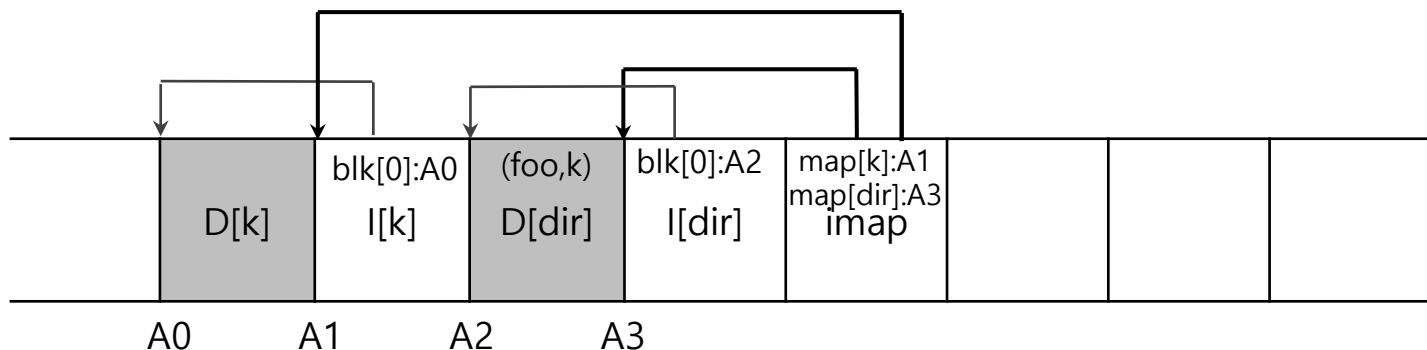
LFS is optimized for writes.

# Outline

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## Issue #3: What About Directories?

- ▣ Directory: a set of <inode, filename>
- ▣ How does LFS store directory data?
- ▣ Creating a file: `foo`
  - ◆ Update the directory inode. (inode #: `dir`)
  - ◆ Update the directory entry. (`foo`, `k`)
  - ◆ Update inode for the created file. (inode #: `k`)
  - ◆ Update the data block for the created file.



## Issue #3: What About Directories?

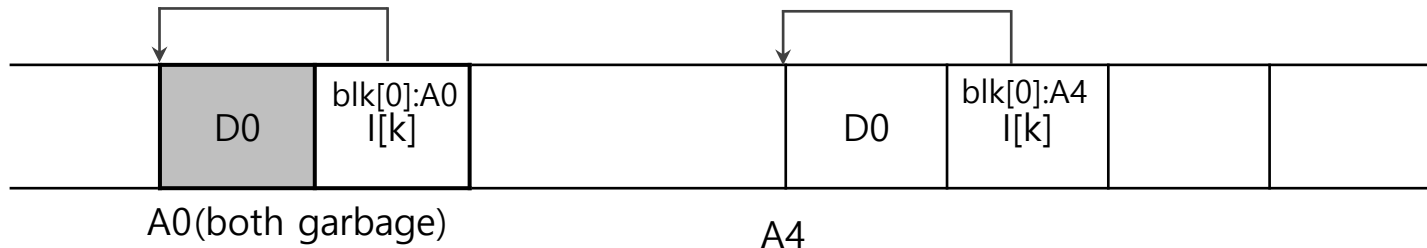
- Recursive update: A serious problem in any FS that never updates in place
  - ◆ Whenever an inode is updated, its **location** on disk changes
    - To keep track of inodes, a directory may have to record a collection of (name, inode-**location**) pairs instead
  - ◆ This would have also entailed **recursive updates** to the directory that points to the file, the parent of that directory, ..., all the way up the file system tree
- LFS cleverly avoids this problem with imap
  - ◆ The directory is still (name, inode-**num**) pairs.
  - ◆ The imap keeps the inode-**num** to inode-**location** mappings
    - The change in inode location is never reflected in the directory itself

# Outline

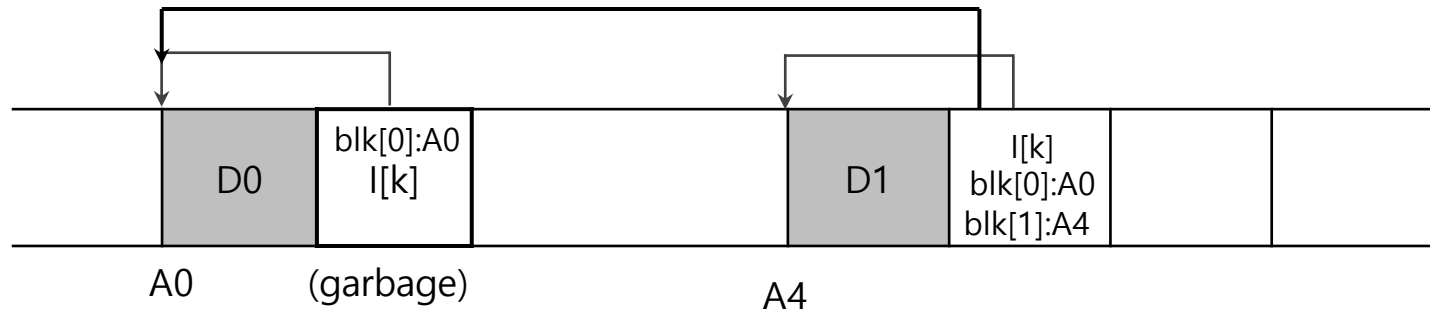
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## Issue #4: Garbage Collection

- ❑ LFS keeps writing newer versions of a file.
- ❑ Garbage: LFS leaves the older versions of file structures all over the disk.
- ❑ An example of garbage
  - ◆ Overwrite the data block:



- ◆ Append a block to that original file k:

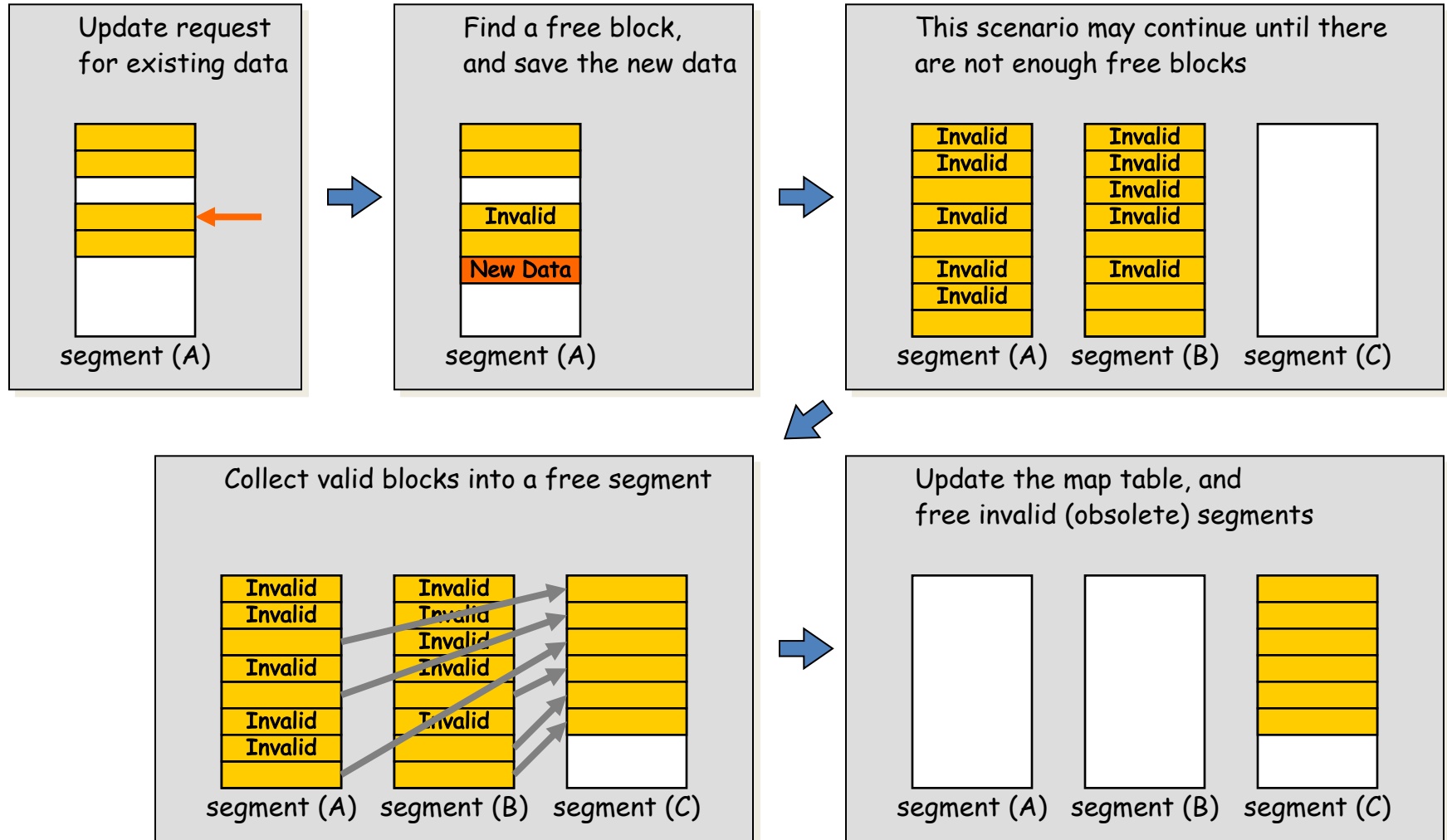




## Issue #4: Garbage Collection

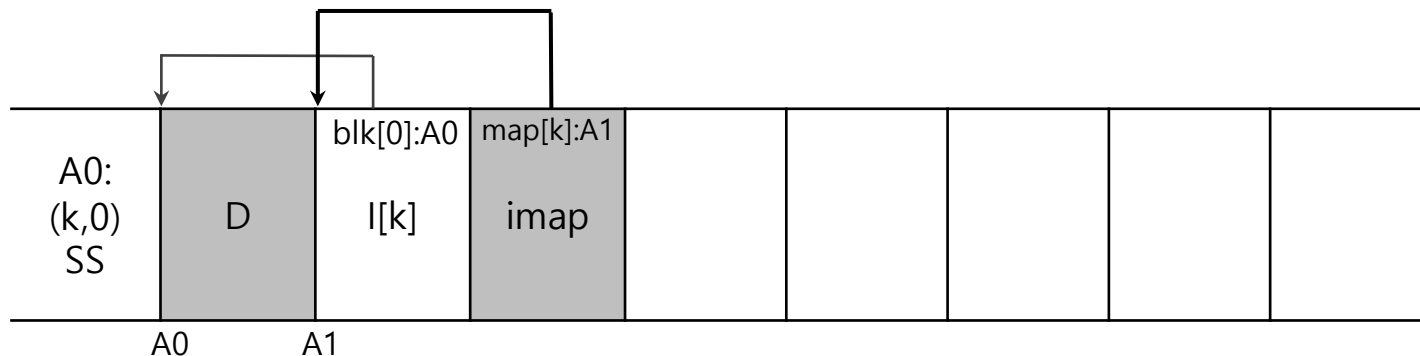
- ▣ What to do with the older versions of the block
  - ◆ Versioning filesystem: keep the old blocks and allow the users to restore to the older version of the filesystem status.
  - ◆ LFS: periodically clean the older versions of the file data, inodes and other structures.
- ▣ Unit of garbage collection: Segment
  - ◆ Read a number of old segments,  $M$  segments.
  - ◆ Identify the valid blocks.
  - ◆ Write them to a number of new segments (in memory),  $N$  segments.
  - ◆ Write  $N$  segments to the disk.
  - ◆ Then,  $N < M$ .

# Issue #4: Garbage Collection



# Mechanism: Segment Summary Block

- Store the **inode number** and the **offset for each data block** in it.
- In garbage collection, we need to identify the obsolete blocks.
- Compare the block address of file k, block offset 0, based upon the Segment Summary and based upon the in-memory imap. If they coincide, the block is alive



# Policy of Garbage Collection

- ▣ When to clean
  - ◆ Periodically
  - ◆ When a system is idle
  - ◆ When the disk is full
- ▣ Which block to consolidate? (heuristic from the original LFS paper)
  - ◆ Hot segment: the blocks are updated periodically
  - ◆ Cold segment: the blocks are not updated.
  - ◆ Hot segment: clean later.
  - ◆ Cold segment: clean sooner.
- ▣ Other policies are possible

# Outline

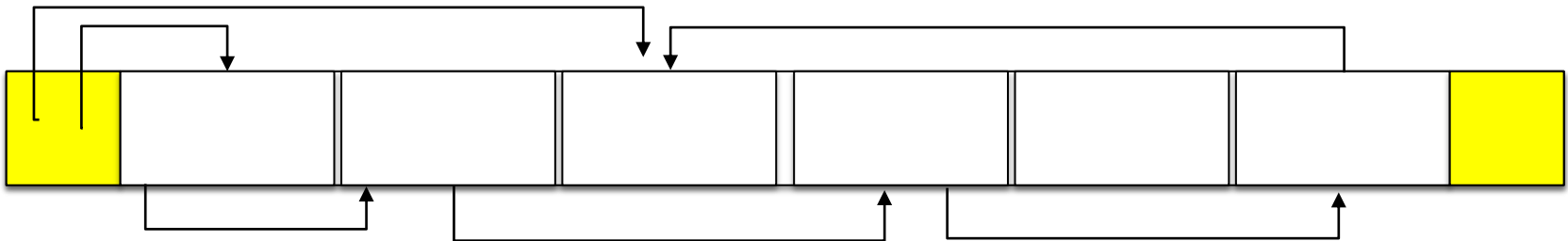
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# Crash recovery

- What if the crash happens when the LFS is in the middle of writing the segment to the disk?
- LFS maintains a set of segments as a linked list in memory



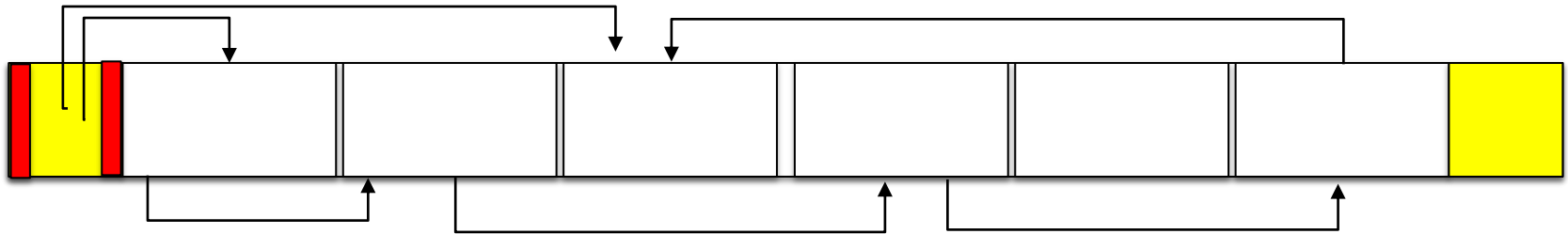
- LFS organizes the filesystem partition as a log (a linked list of the segments).
  - Two checkpoint regions: one at the beginning and the one at the end.



# Crash recovery

## □ Consistent Update on CR

- ◆ Write timestamp at the beginning of CR.
- ◆ Write CR body.
- ◆ Write time stamp at the end of the CR.
- ◆ When crash occurs, chooses the most recent CR with valid consistent time stamps.



## □ Crash recovery

- ◆ Read the CR and rebuild imap.
- ◆ Perform roll-forward.
  - Start from the first segment in CR.
  - Scan the valid segment following the "next segment" pointer and update the imap.

# Summary

- ▣ Introduce a new approach to updating the disk.
  - ◆ **Shadow paging** in database system, **Copy-on-Write** in file system.
- ▣ Gather all updates into an in-memory segment.
  - ◆ Write them out together sequentially.
- ▣ LFS-style is excellent for performance on many different devices.
  - ◆ Hard drives, parity-based RAIDs, even Flash-based SSDs.
- ▣ Some modern commercial filesystems adopt a similar copy-on-write approach even though it generates garbage.
  - ◆ NetApp's **WAFL**, Sun's **ZFS** and Linux **btrfs**
  - ◆ In particular, WAFL turns cleaning problem into a feature, by providing old versions of the file system via **snapshots**.