

# Undergraduate Complexity Theory

## Lecture 23: The Polynomial Hierarchy

Marcyhm

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### 1 Lecture Notes

motivation:

recall: NP and coNP

**Observation 1.1.**  $P = NP \implies NP = \text{coNP}$  (contra:  $NP \neq \text{coNP} \implies P \neq NP$ )

$\text{ECLIQUE} = \{\langle G, k \rangle : G \text{ is a graph with a largest clique of exactly size } k\}$

$\text{SMALLEST-CIRCUIT} = \{\langle C \rangle : C \text{ is the smallest circuit computing the function } C_f \text{ that } C \text{ computes}\}$

**Notation 1.2.**  $Q^nu$  means  $Qu, |u| \leq m$  where  $Q \in \{\exists, \forall\}$ .

**Definition 1.3.**  $L \in \Sigma_2$  if  $\exists$  poly-time TM  $V$ ,  $\exists$  polynomial  $p$  s.t.

$$x \in L \iff \exists^{p(x)} u_1 \forall^{p(x)} u_2 : V(x, u_1, u_2) = 1$$

**Definition 1.4.**  $L \in \Pi_2$  if  $\exists$  poly-time TM  $V$ ,  $\exists$  polynomial  $p$  s.t.

$$x \in L \iff \forall^{p(x)} u_1 \exists^{p(x)} u_2 : V(x, u_1, u_2) = 1$$

**Observation 1.5.**  $\Pi_2 = \text{co-}\Sigma_2$ .

**Claim 1.6.**  $\text{ECLIQUE} \in \Sigma_2$ .

**Exercise 1.7.**  $\text{SMALLEST-CIRCUIT} \in \Pi_2$ .

**Notation 1.8.**  $\Sigma_0 = \Pi_0 = P, \Sigma_1 = NP = \exists P, \Pi_1 = \text{coNP} = \forall P, \dots, \Sigma_i = \exists \Pi_{i-1}, \Pi_i = \forall \Sigma_{i-1}$ .

**Observation 1.9.**  $\Sigma_i \subseteq \Sigma_{i+1} \cap \Pi_{i+1}, \Pi_i \subseteq \Pi_{i+1} \cap \Sigma_{i+1}$ .

**Definition 1.10** (Polynomial Hierarchy).  $\text{PH} = \bigcup_{k \in \mathbb{N}} \Sigma_k = \bigcup_{k \in \mathbb{N}} \Pi_k$  contains those languages can be described by constant number of quantifiers.

**Claim 1.11.**  $\text{PH} \subseteq \text{PSPACE}$ .

**Theorem 1.12.**  $P = NP \implies P = \text{PH}$ .

**Theorem 1.13.**  $\Sigma_i = \Pi_i \implies \Sigma_i = \Pi_i = \text{PH}$ . (*hierarchy “collapses” to the  $i$ th level*)

Complete problems for  $\Sigma_i, \Pi_i, \text{PH}$ : Let  $\varphi(y_1, y_2, \dots, y_i)$  be a boolean formula where each  $y_j$  is a vector (or sequence) of boolean variables.

**Definition 1.14.**  $\Sigma_i\text{-SAT} = \{\langle \varphi(y_1, y_2, \dots, y_i) \rangle : \exists z_1 \forall z_2 \dots \varphi(z_1, z_2, \dots, z_i) = 1\}$

**Exercise 1.15.**  $\Sigma_i\text{-SAT}$  is  $\Sigma_i$ -complete.

the same for  $\Pi_i$ .

**Claim 1.16.** If  $\exists L$  s.t.  $L$  is PH-complete, then  $\exists i$  s.t.  $\text{PH} = \Sigma_i$ .

## 2 Reading

### 2.1 sipser 10.3 (Alternation)

definition of Alternating Turing Machine, ATIME, ASpace, AP, APSPACE, AL

**Theorem 2.1.** *For  $f(n) \geq n$ , we have  $\text{ATIME}(f(n)) \subseteq \text{SPACE}(f(n)) \subseteq \text{ATIME}(f^2(n))$ .  
For  $f(n) \geq \log n$ , we have  $\text{ASpace}(f(n)) = \text{TIME}(2^{O(f(n))})$ .*

**Corollary 2.2.**  $\text{AL} = \text{P}$ ,  $\text{AP} = \text{PSPACE}$ ,  $\text{APSPACE} = \text{EXP}$ .

definition of PH.