```
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                                         awps.cc
                                                                            Page 1/2
#include <wiringPi.h>
#include <iostream>
#include <unistd.h>
#include <sys/select.h>
#include <sys/time.h>
#include <string>
#include <cstdlib>
#include "mcp3008Reading.h"
//#include "archives.h"
using namespace std;
int main(int argc, char* argv[]){
int cycle = 3600;
if(argc == 2){
        cycle = atoi(argv[1]);
//string filename("/home/pi/Documents/moisture_sensor_TML/mcp.dat");
int tab[3];
//Setup WiringPi in order to use the library wiringPi
wiringPiSetup();
//pinMode(0,OUTPUT);
pinMode(2,OUTPUT);
                         //Relay control
const int moistureChannel = 5;
const int moistureLimit = 500;
//Initialisation of the Virtual Pins
initMCP3008();
while (1) {
        int x = readMCP3008(moistureChannel);
        //double temper = analogRead(BASE+6);
        //cout << "temper = " << temper << endl;
        //temper = temper / 1024 * 3.3 * 10;
        struct timeval tod;
        gettimeofday(&tod, NULL);
        tab[0] = tod.tv_sec;
        if (x < moistureLimit) { // The soil is moist enough</pre>
        digitalWrite (2,LOW);
        else{
        digitalWrite (2, HIGH); //We activate the pump
        tab[1] = x;
        tab[2] = 0;
        tab[2] = (int)temper;
        cout << "time: " << tab[0] << ", Value is: " << tab[1] << ", and T\hat{A}^{\circ} is: " << tab[2]
] \ll "\hat{A}^{\circ}C"\ll endl;
//
        saveInFile(filename, tab, (unsigned int) ( sizeof(tab)/sizeof(*tab) ));
        struct timeval t;
        t.tv_sec = cycle;
```

```
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                                            awps.cc
                                                                                 Page 2/2
         t.tv_usec=0;
         select (0, NULL, NULL, NULL, &t);
cout << "returning 0 " << endl;
return 0;
```

```
mcp3008Reading.cc
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                                                                                             Page 1/1
#include <wiringPi.h>
#include <mcp3004.h>
#include "mcp3008Reading.h"
using namespace std;
#define BASE 100
#define SPI_CHAN 1
int initMCP3008(){
          return mcp3004Setup(BASE, SPI_CHAN);
int readMCP3008(int channel){
// wiringPiSetup();
// mcp3004Setup(BASE, SP1
          mcp3004Setup(BASE, SPI_CHAN);
          int value = analogRead(BASE+channel);
          return value;
```

```
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                                     mcp3008Reading.h
                                                                                  Page 1/1
#ifndef MCP3008READING_H
#define MCP3008READING_H
#define BASE 100
#define SPI_CHAN 1
int initMCP3008();
int readMCP3008(int channel);
#endif
```

```
Makefile
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                                                                        Page 1/1
CXXFLAGS = - Wall #Define CXXFLAGS to automatically add them in the command
SRC=$(wildcard *.cc)
DEPS=$(wildcard *.h)
LDFLAGS=-lwiringPi
OBJ=$(SRC:.cc=.o)
# Redefine the default command to create executable without suffix (use g++ inst
ead of gcc)
awps: $(OBJ)
        g++ $(LDFLAGS) -o $@ $^
all: awps awps.pdf
awps.pdf: $(SRC) $(DEPS) Makefile
        a2ps -o - $^ | ps2pdf - docs/$@
clean:
        rm -f *~ *.o *.bak
mrproper: clean
        rm -f awps
depend:
        makedepend $(sources)
```