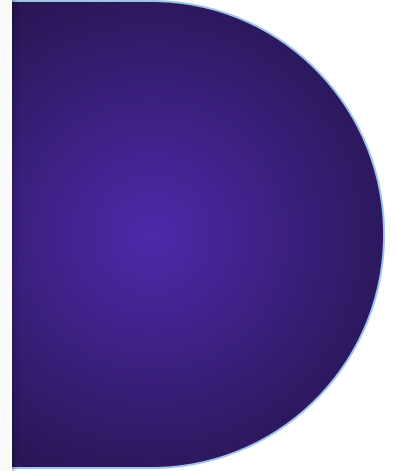
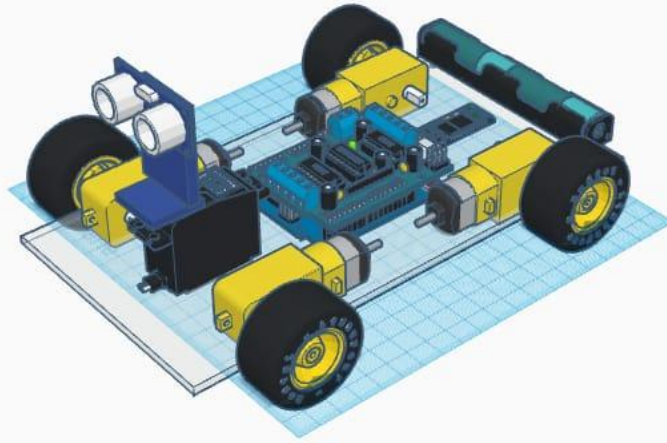
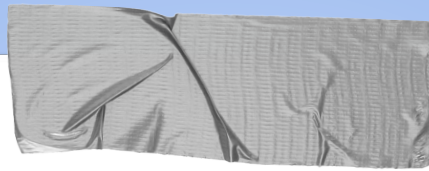


# Bluetooth controlled smart car





## Why did we choose this project?

→ **The most beneficial**

Among all the other projects  
this one was more appealing

→ **Coping with technology and  
the world of robotics**

→ **Easily modified to be  
applicable in several fields**

# About the car..

As technology progresses, so too does the scope of what is considered robotics...our car is a semi-autonomous bot that uses a wireless network to enable human control from a safe distance

A combination of data science and robotics, self-driving vehicles are taking the world by storm. Automakers, like **Tesla, Ford, Waymo, Volkswagen and BMW** are all working on the next wave of travel that will let us sit back, relax and enjoy the ride. Rideshare companies Uber and Lyft are also developing autonomous rideshare vehicles that don't require humans to operate the vehicle

# Advantages

The power efficiency

The device consumes less power

Ease of use

Operated easily by your phone by using Bluetooth connection of android system

## Protection of human beings

It protects nature from devastating effects on plants as it doesn't emit gases as NO<sub>x</sub> which causes falling of their leaves

Protection of human beings or living organisms from respiratory track or inflammation of eye for human beings as a result doesn't produce CO

## Effects on nature

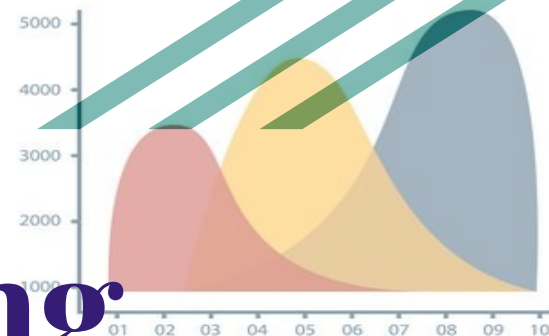
# Environmental sustainability

## Air pollution

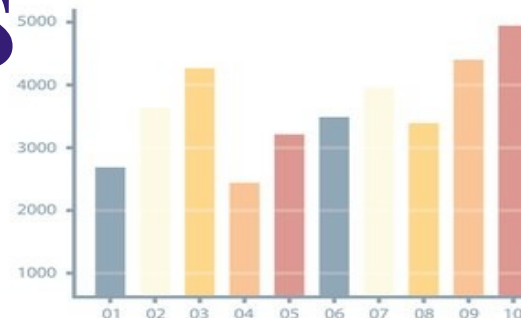
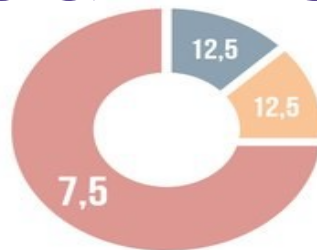
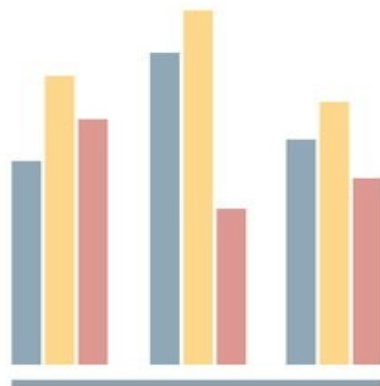
it doesn't support the emission of harmful gases that can cause air and water pollution, for it doesn't produce CO or NOx or Sox...etc

## Source of energy

Our prototype works by electric energy which is eco friendly, however it can be replaced by solar energy generated through solar panels allowing us to use renewable energy.



# Marketing surveys





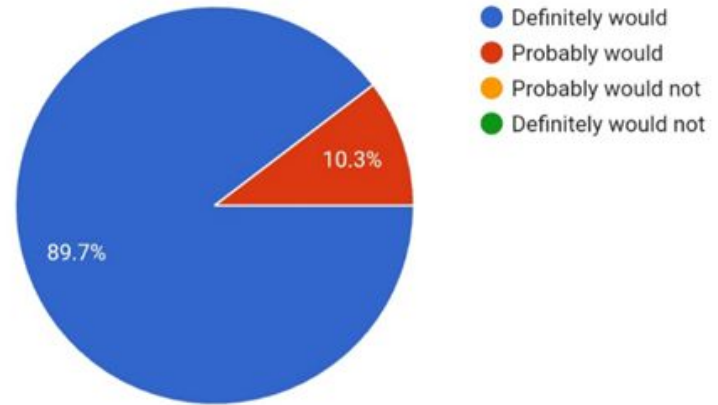
**“The first step in  
exceeding your customer  
expectations is to know  
these expectations “**



**Roy H. Williams**

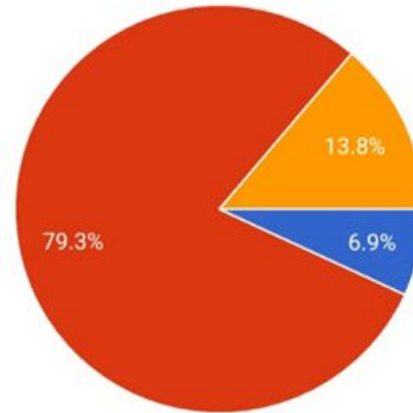
## Some Market Survey Questions and Results:

As technology evolves, robotics is used in our lives more often now. Do you think that will affect our daily lives in the future?



## Some Market Survey Questions and Results:

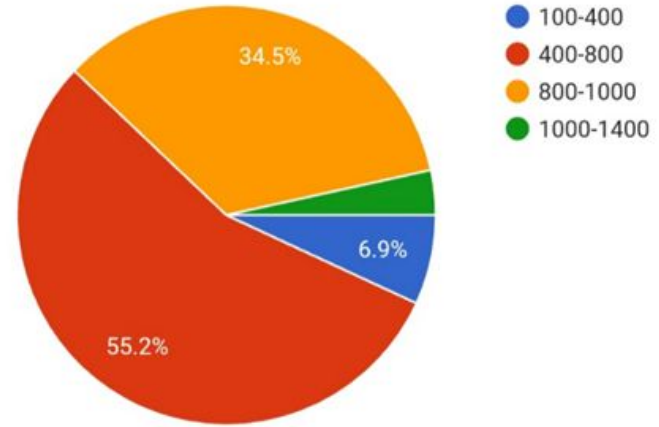
What do you think about using smart cars in our daily lives?

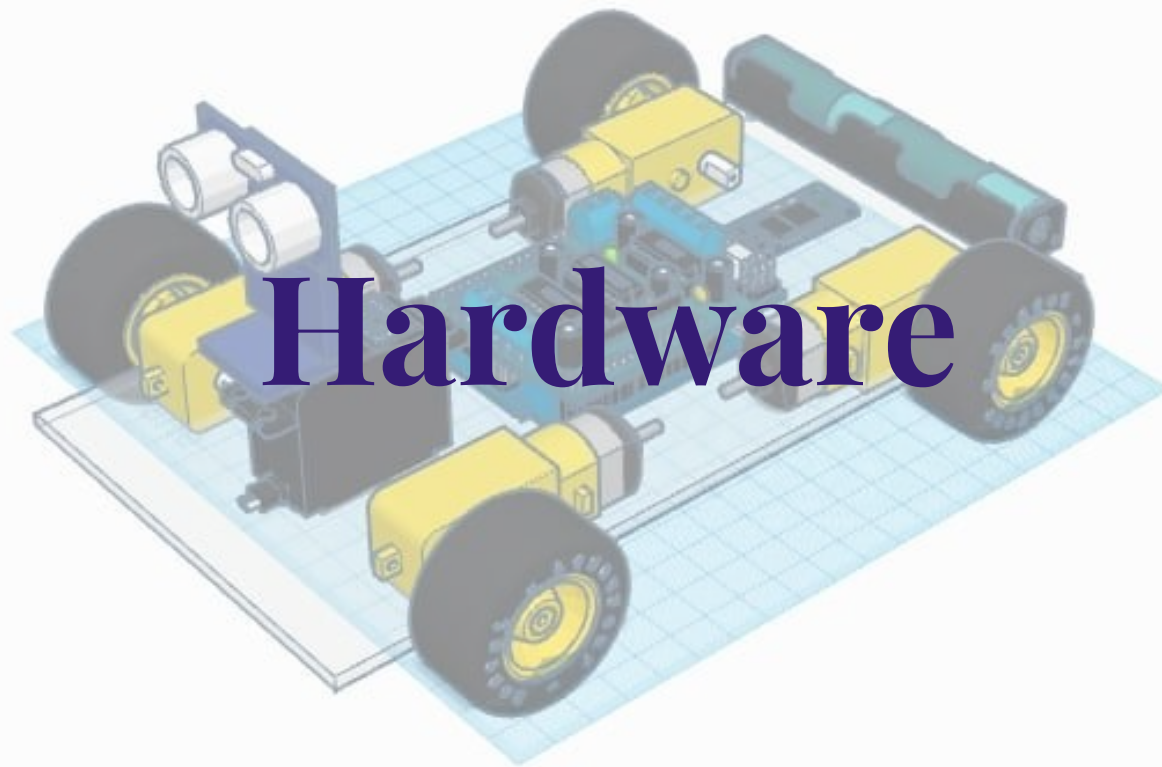


- I think it is inconvenient and unnecessary
- Somehow it will make our daily lives easier as we live in a world that is progressing in a rapid way
- Somehow it will make our daily lives easier as we live in a world that is progressing in a fast way

## Some Market Survey Questions and Results:

If you want to buy such a product that theoretically last and is convenient as most of us like quality over price, then how much are you willing to pay for it?





# Hardware

## Components

1-4x wheels.

2-4xDC Gearbox motors “TTMotor”

3-Car kit

4-Arduino uno board R3

5-Bluetooth module “HC-05”

6-Motor driver

7-Jumper wires

8-3x Battery

9-Battery holder

10-USB



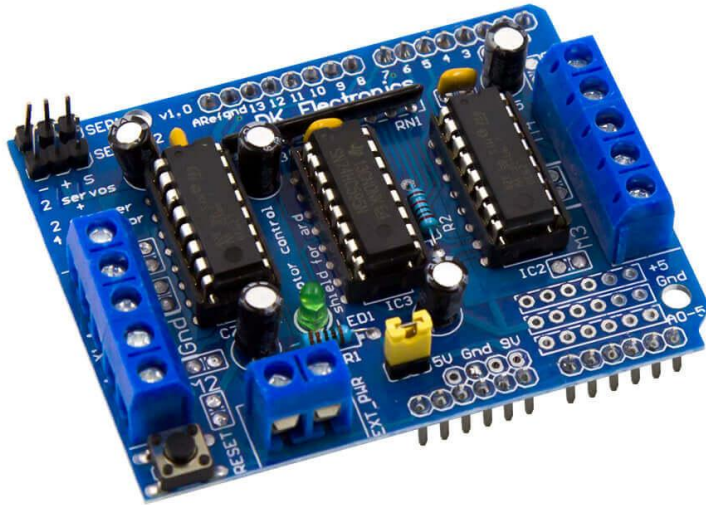
# Arduino uno

- 1) the core component
- 2) method of working

**Note :** we must remove or detach the Bluetooth connected to it while uploading the code

# Motor driver shield

“H-bridgeL293D”.



- 1) Method of working
- 2) It controls 4 gearboxes maximum



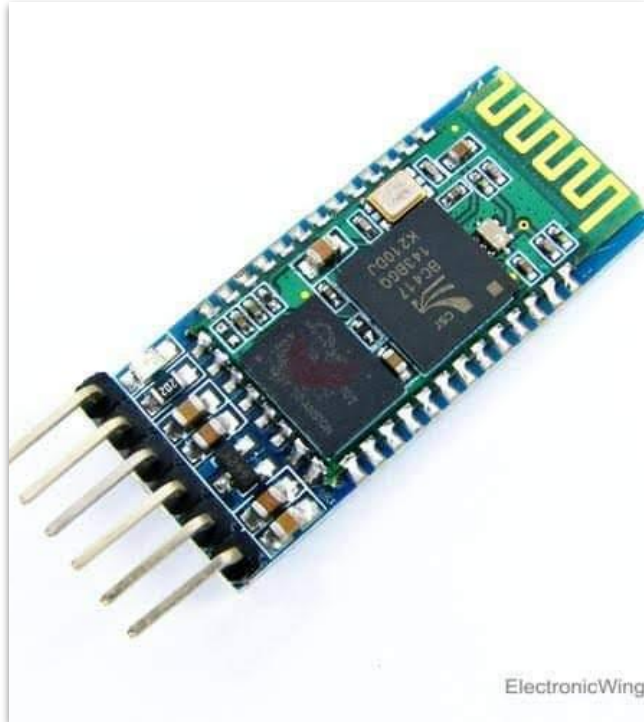
**4x wheels**

**4x DC Gearbox motor**

**“TTMotor”**



- 1)linking the gearbox with wheels and motor driver
- 2)method of working
- 3)how to determine using gearbox



# Bluetooth module

## “HC-05”

- 1) It has 6 terminals four of them are connected to motor driver
- 2) It can easily operate and simple to use and configured with arduino
- 3) Method of working

Battery holders



Lithium battery

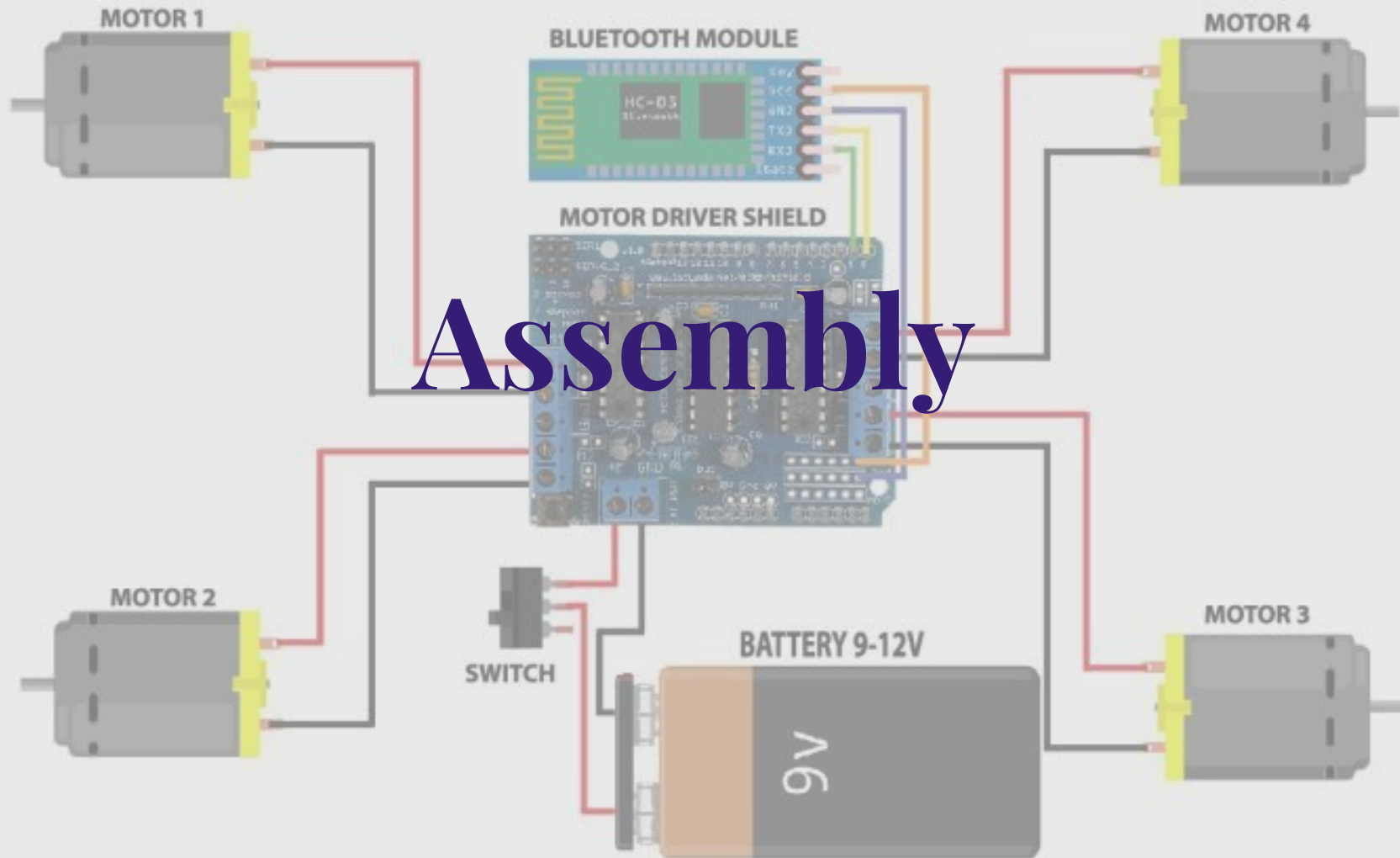


Jumper wires



USB cable







# Software

```
#include <AFMotor.h>
AF_DCMotor motor1(1);
AF_DCMotor motor2(2);
AF_DCMotor motor3(3);
AF_DCMotor motor4(4);
char command;
void setup()
{
  Serial.begin(9600);
}
void loop(){
  if(Serial.available() > 0){
    command = Serial.read();
    Stop();
```

```
Serial.println(command);
switch(command){
  case 'F':
    forward();
    break;
  case 'B':
    back();
    break;
  case 'L':
    left();
    break;
  case 'R':
    right();
    break;
}
}
```

```
void forward()
{
    motor1.setSpeed(255); //Define
    maximum velocity
    motor1.run(FORWARD); //rotate
    the motor clockwise
    motor2.setSpeed(255); //Define
    maximum velocity
    motor2.run(FORWARD); //rotate
    the motor clockwise
    motor3.setSpeed(255); //Define
```

```
maximum velocity
    motor3.run(FORWARD); //rotate the
    motor clockwise
    motor4.setSpeed(255); //Define
    maximum velocity
    motor4.run(FORWARD); //rotate the
    motor clockwise
}
```



```
void back()
{
    motor1.setSpeed(255);
    //Define maximum velocity
    motor1.run(BACKWARD);
    //rotate the motor
    anti-clockwise
    motor2.setSpeed(255);
    //Define maximum velocity
    motor2.run(BACKWARD);
    //rotate the motor
    anti-clockwise
```

```
    motor3.setSpeed(255); //Define
    maximum velocity
    motor3.run(BACKWARD); //rotate
    the motor anti-clockwise
    motor4.setSpeed(255); //Define
    maximum velocity
    motor4.run(BACKWARD); //rotate
    the motor anti-clockwise
}
void left()
{
    motor1.setSpeed(255); //Define
    maximum velocity
    motor1.run(BACKWARD); //rotate
    the motor anti-clockwise
```

```
motor2.setSpeed(255); //Define
maximum velocity
motor2.run(BACKWARD);
//rotate the motor anti-clockwise
motor3.setSpeed(255); //Define
maximum velocity
motor3.run(FORWARD); //rotate
the motor clockwise
motor4.setSpeed(255); //Define
maximum velocity
motor4.run(FORWARD); //rotate
the motor clockwise
}
```

```
void right()
{
  motor1.setSpeed(255); //Define
  maximum velocity
  motor1.run(FORWARD); //rotate
  the motor clockwise
  motor2.setSpeed(255); //Define
  maximum velocity
  motor2.run(FORWARD); //rotate
  the motor clockwise
  motor3.setSpeed(255); //Define
  maximum velocity
  motor3.run(BACKWARD); //rotate
  the motor anti-clockwise
}
```

```
motor4.setSpeed(255); //Define
maximum velocity
motor4.run(BACKWARD); //rotate
the motor anti-clockwise
}
void Stop()
{
  motor1.setSpeed(0); //Define
  minimum velocity
  motor1.run(RELEASE); //stop the
  motor when release the button
  motor2.setSpeed(0); //Define
  minimum velocity
```

```
  motor2.run(RELEASE); //rotate
  the motor clockwise
  motor3.setSpeed(0); //Define
  minimum velocity
  motor3.run(RELEASE); //stop the
  motor when release the button
  motor4.setSpeed(0); //Define
  minimum velocity
  motor4.run(RELEASE); //stop the
  motor when release the button
}
```

The background of the slide features a collection of approximately 12-14 small, three-dimensional cubes or blocks scattered across a light blue surface. Each block is a different color and displays a white icon of a popular social media platform. Recognizable icons include the Instagram camera, Facebook 'f', Twitter bird, YouTube play button, Snapchat ghost, and TikTok logo. The blocks are arranged in a casual, overlapping manner, creating a sense of digital connectivity and modern communication.

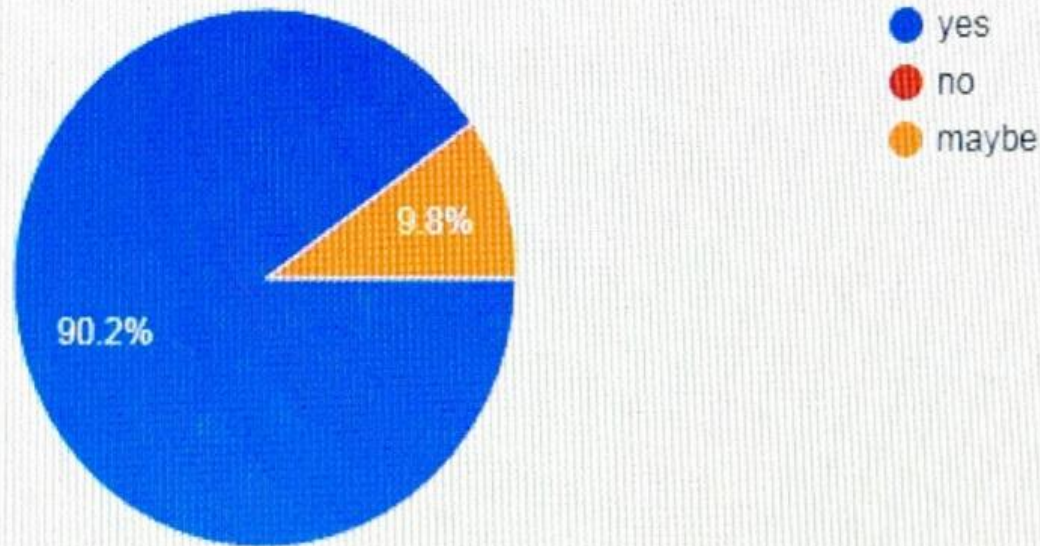
# Social media

## The power of social media

1. The first place consumers go to find review
2. Plays a huge role in the success any product
3. Help in increasing the sales
4. Help in launching any product
5. We can know from it the opinions of our consumers

We tried to use cheap yet effective materials while working on the project to produce the same results but with lower price, would you think of this as a pro? حاولنا؟  
نستخدم ادوات بسعر ارخص يس ف نفس الوقت تقدم نفس المطلوب بجودة كويسة، سايف أن دي حاجة أصح؟

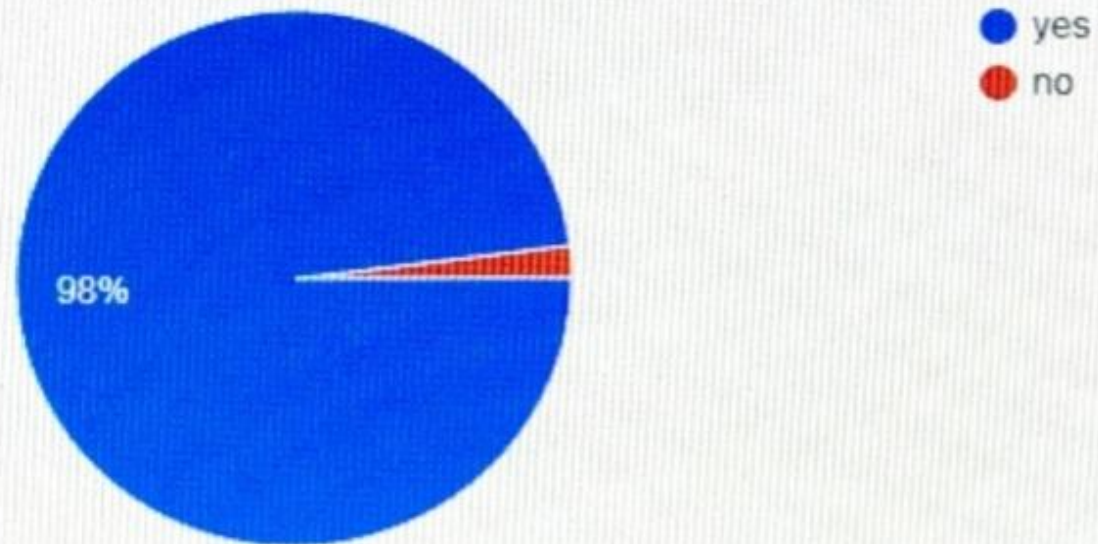
51 responses





Do you think our project fulfilled the desired requirements regarding the specifications?  
تفكر اننا قدرنا تحقق الشروط المطلوبة من حيث المواصفات؟

51 responses



## **Some suggestion and uses offered by the consumers to us :**

1. Add a mic for spying
2. Install a camera to the vehicle
3. Add a sensor to avoid obstacles
4. Add a GPS
5. Add more security precautions for example a warning system



**Where could our smart car be used?**

**There are alot of things that could be added to our car  
depending on where it is used, for example:**

The image shows three autonomous mobile robots (AMRs) in a factory or industrial environment. The robots are primarily orange with white accents and have four large, treaded tires. Each robot has a tall, white, cylindrical mast with an orange top section. The robot in the foreground is the most prominent, showing its side profile. Two other similar robots are visible in the background, one to the left and one to the right. The background is filled with industrial equipment, including pipes, structural beams, and various mechanical components, creating a complex and busy scene. The lighting is somewhat dim, with some bright spots from industrial lights.

In security field and safety field



Our car may be used in industrial plants, oil, gas and chemical production facility.

Things like gas detectors, PIR, metal detection sensor, temperature sensor are added to provide more security.



Our car can be used for border security it can detect gases which can lead to explosion and it is also able to detect bombs .



They are provided with video surveillance and different sensors .They are used as cops to detect undesirable social behaviors like smoking in prohibited areas, improperly parked bicycles and congregation of more than five people in singapore.





**In hotels and restaurants**

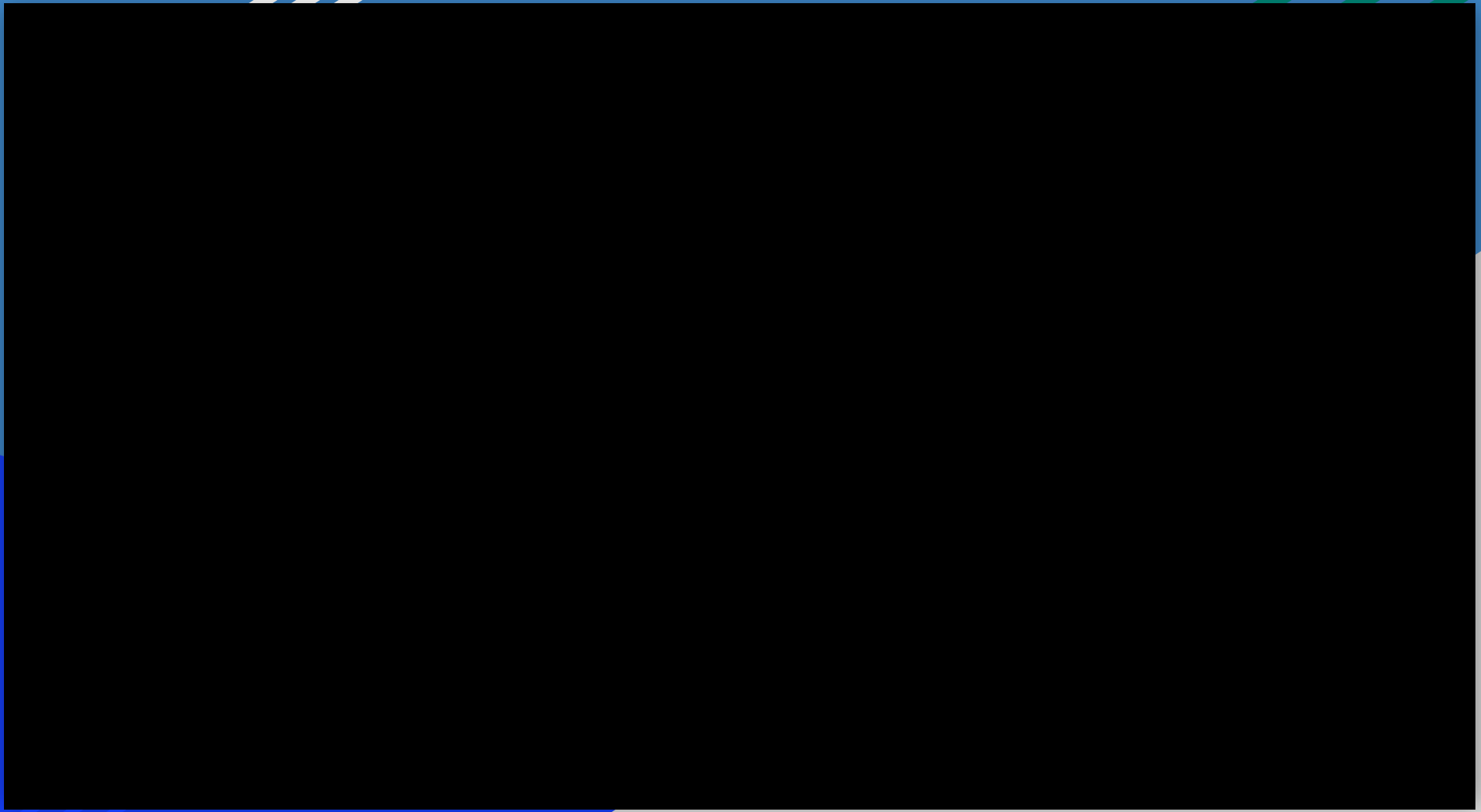


They are used nowadays to deliver food which is cost-effective and help reduce human contact





They are also used as waiters in hotels and restaurants.



In medical field





In china they were used in hospitals and public places to clean , take temperatures, deliver medicine to patients , deliver food, to minimize contact between people.



Also in china they were used as disinfecting car that can disinfect over 10,000 square meters in an hour.



**Presented to you by:**

Mariam Ahmed Hassan

Mariam Galal Anwar

Mariam Abulradi Shaker

Mariam Amin Amin

Mariam Mohamed Saeed

Mariam Emad Abdelsalam

Mariam Tarik Ramadan

Mariam Osama Abdelfatah

**Thank you!**