

# Downscaling coarse observations to predict continuous species spatio-temporal distribution

Going from coarse landings data to fine scale fish distribution

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# Spatial data in ecology



## Examples



EVHOE data, Bay of Biscay  
(marine ecology)

## Citizen science data

Access to more data  
Exact locations  
available

Opportunistic (or  
even preferential)  
sampling



Ebird application  
(ornithology)

## Declaration data

Mandatory  
declaration  
Massive data

Aggregated at the  
scale of  
administrative units



Harvest data, Wisconsin  
(hunting)

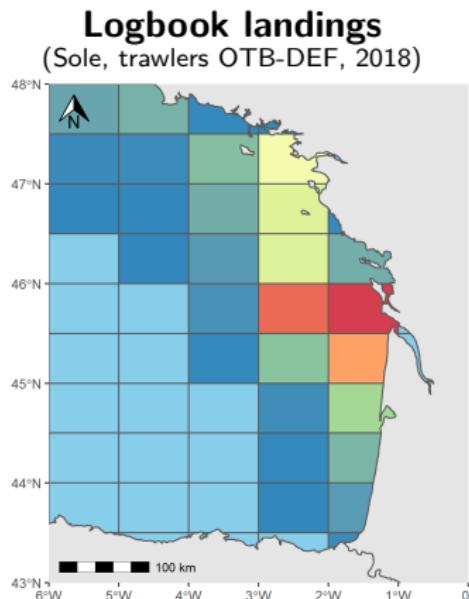
## How to integrate all these datasources? (especially when they do not have the same spatial resolution)

- ➡ Some specific application in the context of fishery science:  
*Alglave Baptiste, Rivot Etienne, Etienne Marie-Pierre, Woillez Mathieu, Thorson James T, Vermard Youen (2022). Combining scientific survey and commercial catch data to map fish distribution. ICES Journal of Marine Science IN PRESS.*  
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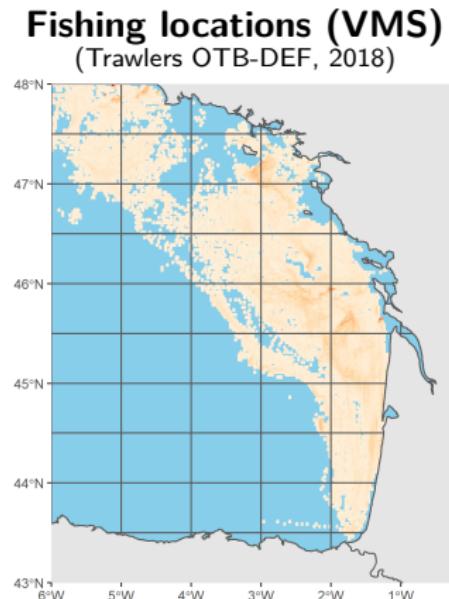
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# Commercial catch declarations data in fishery science



Spatial resolution

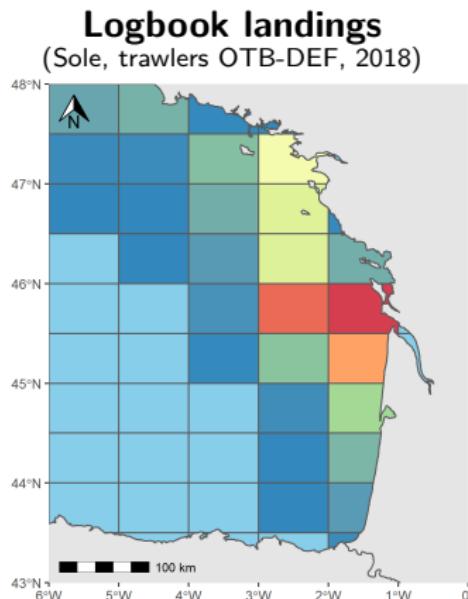
Catch are daily declared at the resolution of ICES rectangles



VMS pings are vessels GPS locations emitted each hour

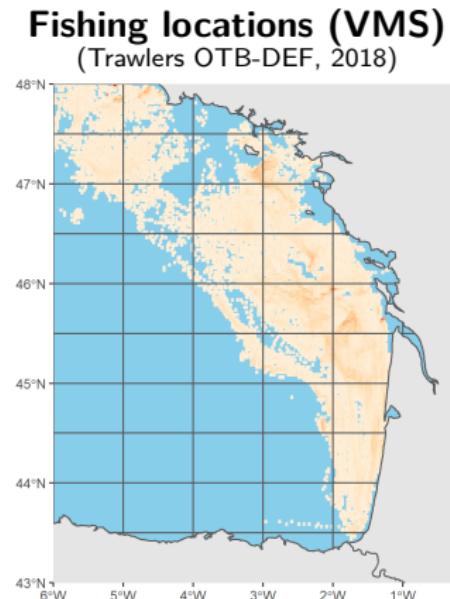
→ Refine landings spatial resolution

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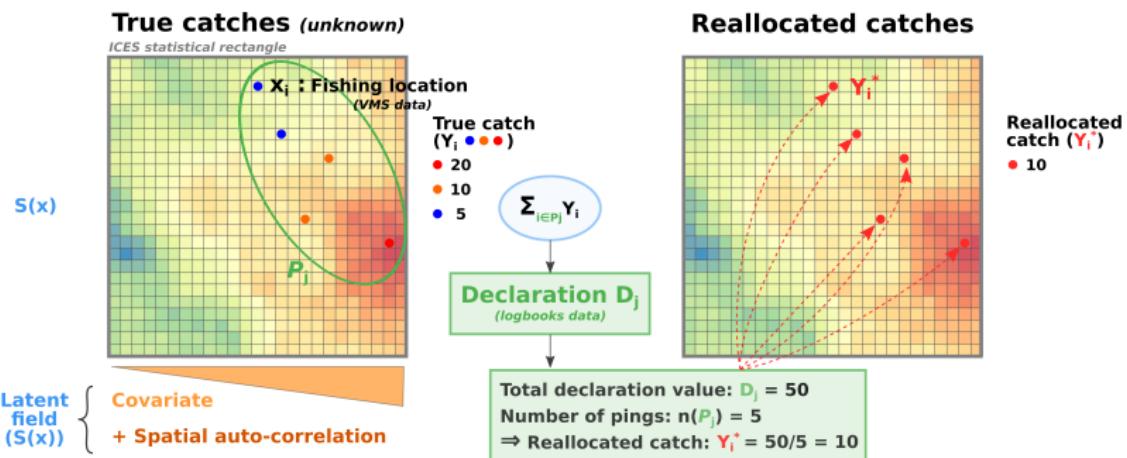
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# Two alternative procedures to reallocate catches



Current situation

$$Y_i | S(x_i), x_i \sim \mathcal{L}_Y(S(x_i), \xi, \sigma^2)$$

$$Y_i = \frac{D_j}{n(P_j)} = Y_i^*$$

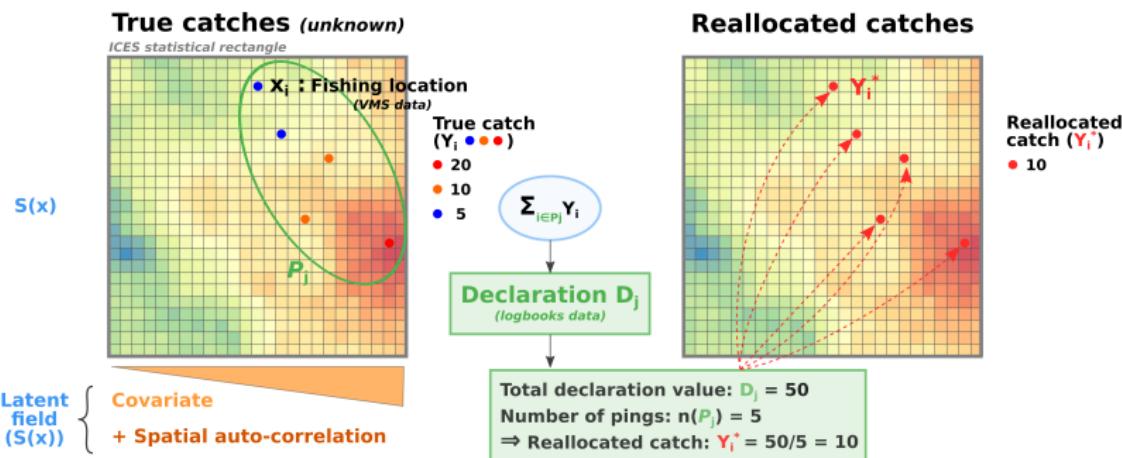
Alternative solution

$$D_j = \sum_{i \in P_j} Y_i$$

$$D_j | S_{P_j}, P_j \sim \mathcal{L}_D(S_{P_j}, \xi, \sigma^2)$$

Match  $\mathcal{L}_D$  and  $\mathcal{L}_Y$  moments (appendix)

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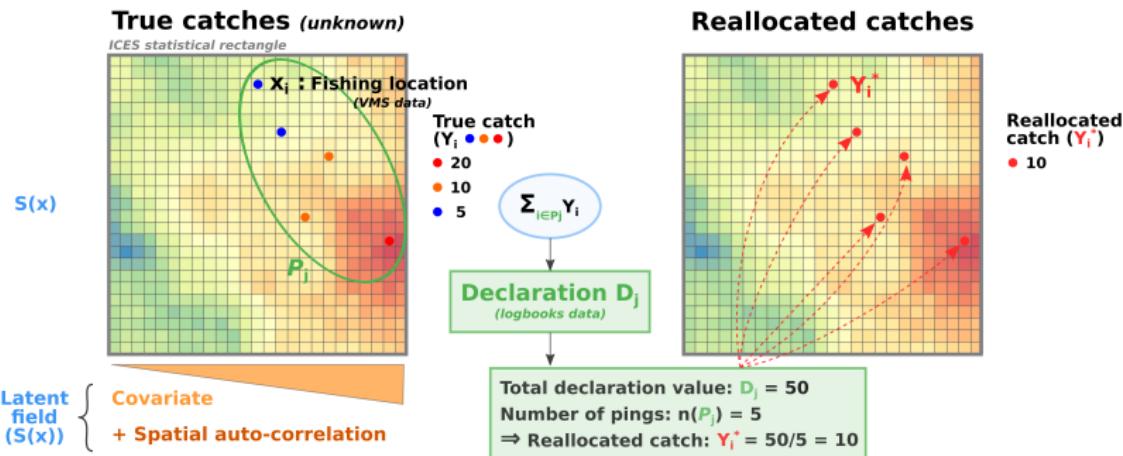
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# Two alternative procedures to reallocate catches

## Punctual observation model ( $Y_i$ )

$L(y, \mu, \sigma^2)$  is the lognormal likelihood for observation  $y$ , mean  $\mu$  and variance  $\sigma^2$

$Y$  and  $D$  are supposed conditional on  $S$  and  $x$

$$P(Y_i = y_i) = \begin{cases} p_i & \text{if } y_i = 0 \\ (1 - p_i) \cdot L\left(y_i, \mu_i = \frac{S(x_i)}{(1-p_i)}, \sigma^2\right) & \text{if } y_i > 0 \end{cases}$$
$$p_i = \exp(-e^\xi \cdot S(x_i))$$

## Declaration model ( $D_j = \sum_{i \in \mathcal{P}_j} Y_i$ )

$$P(D_j = 0) = \prod_{i \in \mathcal{P}_j} P(Y_i = 0) = \exp \left\{ - \sum_{i \in \mathcal{P}_j} e^\xi \cdot S(x_i) \right\} = \pi_j$$

$$P(D_j = d_j | d_j > 0) = ?$$

# Specifying $P(D_j = d_j | d_j > 0)$

## Compute the moments

$$E(D_j | d_j > 0) = \frac{\sum_{i \in \mathcal{P}_j} S(x_i)}{1 - \pi_j}$$

$$Var(D_j | d_j > 0) = \frac{\sum_{i \in \mathcal{P}_j} Var(Y_i)}{1 - \pi_j} - \frac{\pi_j}{(1 - \pi_j)^2} E(D_j)^2$$

$$Var(Y_i) = \frac{S(x_i)^2}{1 - p_i} (e^{\sigma^2} - (1 - p_i))$$

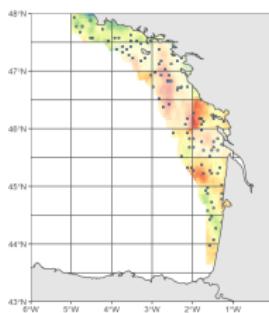
## Consider $D_j$ is Lognormal too

$$P(D_j = d_j | d_j > 0) =$$

$$\mathcal{L} \left( d_j, \mu_j = E(D_j | d_j > 0), \sigma_j^2 = \ln \left( \frac{Var(D_j | d_j > 0)}{E(D_j | d_j > 0)^2} + 1 \right) \right)$$

# Simulation-estimation and case study

## Simulation-estimation



### Simulation

- **Latent field** (covariate + spatial random effect)
- **Commercial data** (3000 samples over 2/3 of the area)
- **Reallocation process** (10 locations per declaration)
- **Scientific data** (100 samples over the whole the area)

## Estimation

Comparison of 3 model configurations:

- 1/ Model fitted to scientific data only
- 2/ Integrated model (= scientific + commercial data) with commercial likelihood built on  $\mathbf{Y}_i^*$
- 3/ Integrated model with commercial likelihood built on  $\mathbf{D}_j$

Estimation realized through TMB (Template Model Builder)  
100 runs of simulation-estimation

### Model evaluation

1/ Mean square prediction error

$$MSPE = \frac{\sum_{x=1}^n (S(x) - \hat{S}(x))^2}{n}$$

2/ Covariate effect (or species-habitat relationship):

$$\beta_S = 2 \text{ versus } \hat{\beta}_S$$

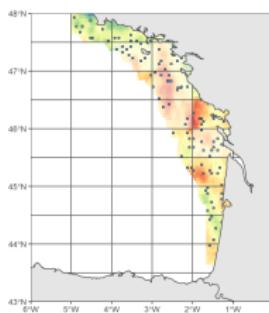
## Case study: Sole in the Bay of Biscay



**Survey data:** Orhago  
**Commercial data:** OTB-DEF trawlers (to ease convergence onboard observer data were integrated in the fit)  
**Fitted models:** same as simulations  
**Covariate:** substrate

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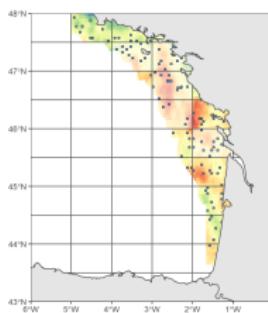
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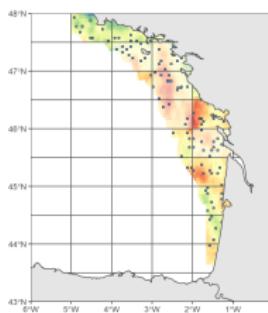
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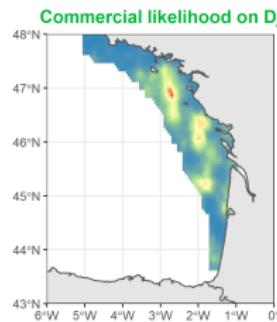
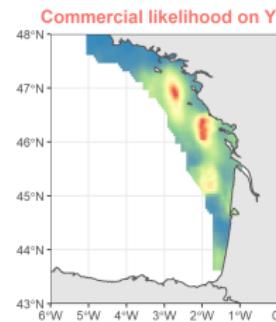
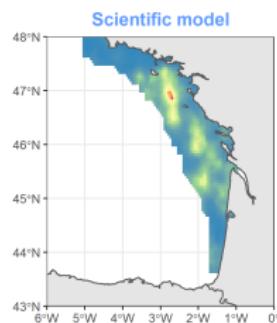
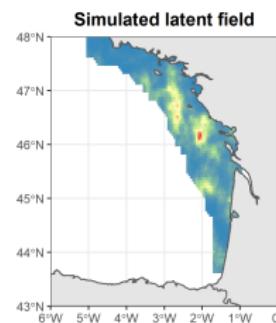
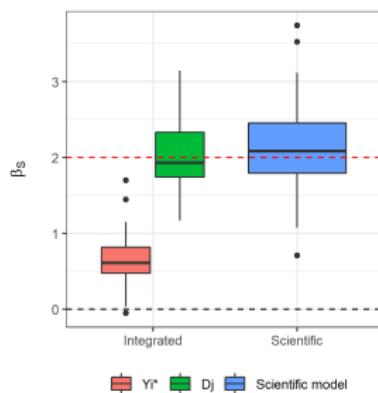
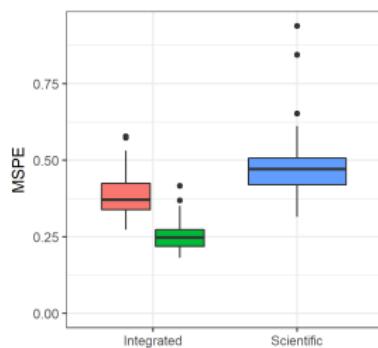
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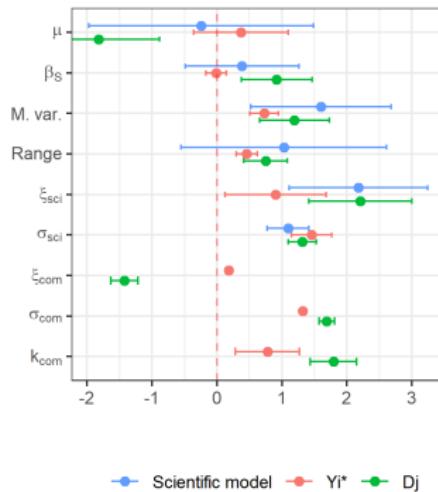
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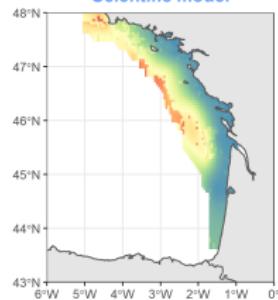


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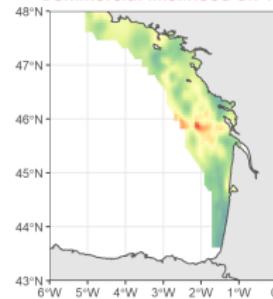
## Parameters estimates



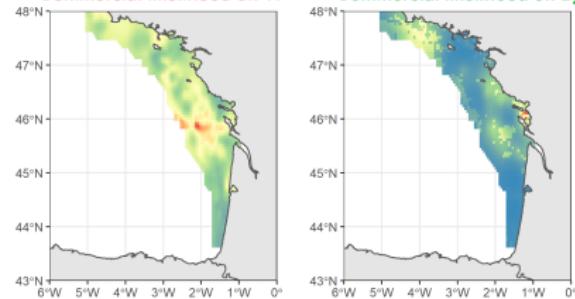
Scientific model



Commercial likelihood on  $\text{Yi}^*$



Commercial likelihood on Dj

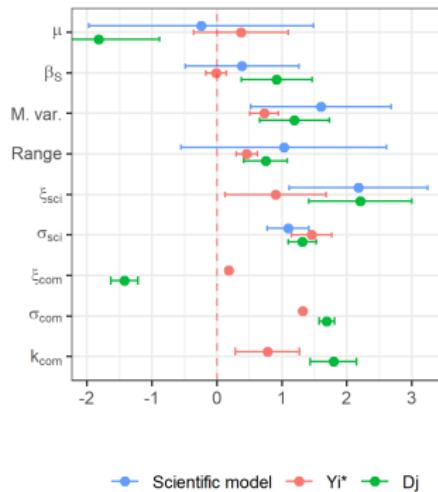


The integrated model fitted to Dj:

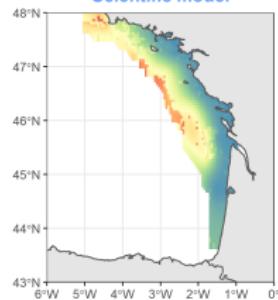
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- Modifies the contrasts of the map (shape and intensity of the hotspots/coldspots)

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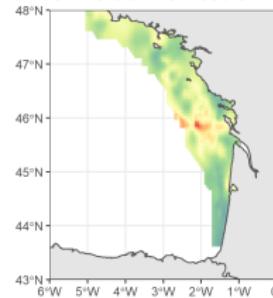
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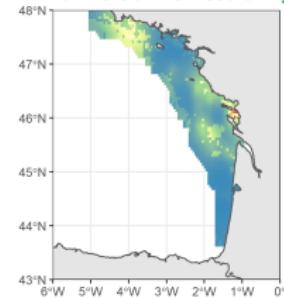
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Commercial likelihood on  $D_j$



The integrated model fitted to  $D_j$ :

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# Discussion

- Integrated framework that combines **catch declarations data** (rough resolution) and **scientific data** (exact locations)
  - ➡ Allows to estimate the **habitat effect** through commercial data
  - ➡ Modifies the **contrasts of the map** (hotspots vs. coldspots)
- Some limits:
  - ➡ How to ease convergence ?
  - ➡ Need to make the hypothesis that fishing locations ( $P_j$ ) are known
- Is it a generic framework ?
  - ➡ The overall approach is,  
*(i.e. modelling observed aggregated observations as a sum of latent punctual observations)*
  - ➡ But need to adapt the observation model to the data  
*(here zeroinflated positive continuous data)*
- Change of support applications
  - ➡ Increasing amount of available data that may face such issues
  - ➡ Here is one proposition to integrate aggregated data in SDM

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