

### Geocomputation with R

Spatial cross-validation with **mlr** 

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GeoStats 2018

### Find the slides and code



https://github.com/geocompr/geostats\_18

#### Please install following packages:

1. Study area, data and aim



- 1. Study area, data and aim
- 2. Introduction to (spatial) cross-validation



- 1. Study area, data and aim
- 2. Introduction to **(spatial) cross-validation**
- 3. **mlr** building blocks



- 1. Study area, data and aim
- 2. Introduction to (spatial) cross-validation
- 3. **mlr** building blocks
- 4. Random forest modeling with **mlr**



- 1. Study area, data and aim
- 2. Introduction to (spatial) cross-validation
- 3. **mlr** building blocks
- 4. Random forest modeling with **mlr**



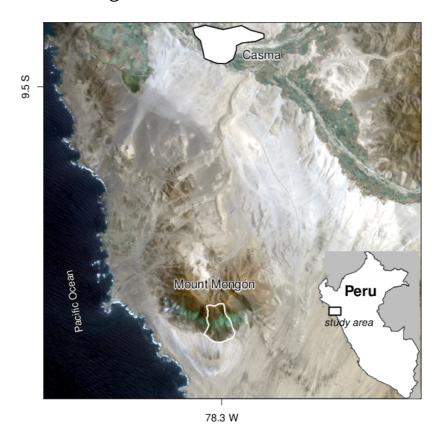


## Study area, data and aim

## Study area



Where are we? Mount Mongón near Casma in northern Peru.



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## Austral summer





## Mount Mongón in summer





## Mount Mongón in austral winter

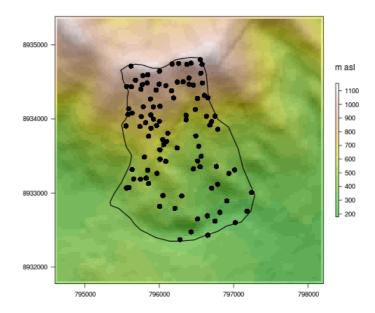




### Data



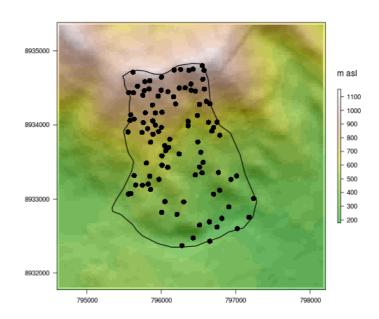
- 100 randomly distributed plots
- coverage of all vascular plants in each plot
- First NMDS axis represents the main gradient (our response, see Chapter 14 of Geocomputation with R (Lovelace, Nowosad, and Muenchow, 2018)



#### Aim



- model the floristic gradient as a function of environmental predictors using a random forest model
- spatial cross-validation to retrieve a bias-reduced estimate of the model's performance
- tune hyperparameters for the predictive mapping of the floristic gradient
- but before we do that, we will introduce the mlr building blocks to easily do spatial crossvalidation with a simple lm (though this definitely is not be the most appropriate model for our data...)





# Introduction to (spatial) cross-validation

### **Cross-validation**



Aim of spatial cross-validation is to find out how generalizable a model is. Fitting to closely the input data, including its noise, leads to a bad predictive performance on unseen data (overfitting).

## Random partitioning





### Random partitioning





Problems with conventional random partitioning when using spatial data:

- violation of the fundamental independence assumption in crossvalidation
- which subsequently leads to overoptimistic, i.e. biased results
- Solution: use spatial partitioning for a bias-reduced assessment of a **model's performance**

## Spatial partitioning







## mlr building blocks

## Input data

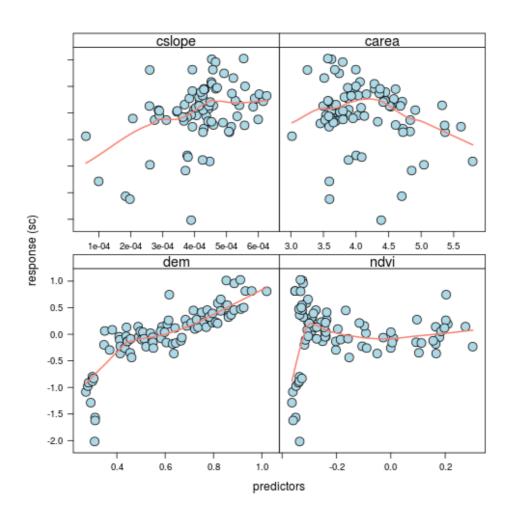


We are already in possession of the following data

```
library(mlr)
library(dplyr)
library(sf)
# response-predictor dataframe
head(rp, 2)
      dem
                ndvi
                            cslope
##
                                      carea
                                                    SC
## 1 0.272 -0.3603059 0.0003712326 4.854817 -1.0843143
## 2 0.280 -0.3487794 0.0002598672 5.043667 -0.9752411
# coordinates
head(coords, 2)
##
            Χ
## 1 797178.6 8932755
## 2 796749.3 8932621
```

## Little data exploration

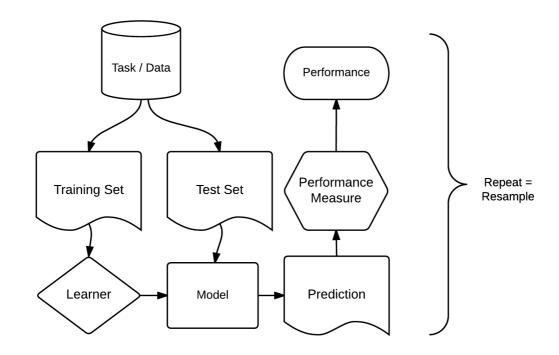




### **Building blocks**



**mlr** is a metapackage that lets you combine hundreds of modeling algorithms of many different package within a single framework (Bischl, Lang, Kotthoff, Schiffner, Richter, Studerus, Casalicchio, and Jones, 2016)



Source: openml.github.io

### Create a task



#### Learner



To find out which learners are available for a specific task run:

```
lrns = listLearners(task, warn.missing.packages = FALSE)
dplyr::select(lrns, class, name, short.name, package)
```

#### Learner



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```
lrns = listLearners(task, warn.missing.packages = FALSE)
dplyr::select(lrns, class, name, short.name, package)
```

We already know that there is a learner named regr.lm for running a simple linear model.

### Define the learner



```
lrn = makeLearner(cl = "regr.lm", predict.type = "response")
```

#### Define the learner



```
lrn = makeLearner(cl = "regr.lm", predict.type = "response")
```

To find out more about the learner, run:

```
# simple lm of the stats package
getLearnerPackages(lrn)
helpLearner(lrn)
```

#### Define the learner



```
lrn = makeLearner(cl = "regr.lm", predict.type = "response")
```

To find out more about the learner, run:

```
# simple lm of the stats package
getLearnerPackages(lrn)
helpLearner(lrn)
```

Just to convince you that we are really using a simple lm, let us retrieve the learner model:

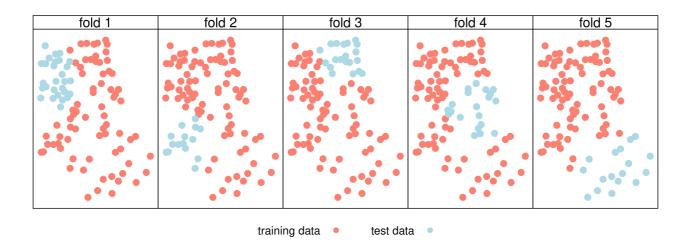
```
##
## Call:
## stats::lm(formula = f, data = d)
##
## Coefficients:
## (Intercept) dem ndvi cslope carea
## -0.8854 2.1124 0.2853 526.8357 -0.1389
```

### Define spatial partitioning



## Define spatial partitioning





### Execute the resampling

```
cv_sp_lm = mlr::resample(
  task = task,
  learner = lrn,
  resampling = perf level,
  # specify the performance measure
  measures = mlr::rmse)
## Resampling: repeated spatial cross-validation
## Measures:
                        rmse
## [Resample] iter 1: 0.3320561
## [Resample] iter 2:
                        0.3523074
## [Resample] iter 3:
                        0.3655570
## [Resample] iter 4:
                        0.8188942
## [Resample] iter 5:
                       0.1668623
## [Resample] iter 6:
                       0.1640437
## [Dacama]a] :+ax 7.
```

### Have a look at the result



```
cv_sp_lm
```

```
## Resample Result
## Task: rp
## Learner: regr.lm
## Aggr perf: rmse.test.rmse=0.4280988
## Runtime: 2.51188
```

Ok, is this good or not?

### Have a look at the result



```
## Resample Result
## Task: rp
## Learner: regr.lm
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Ok, is this good or not?

range(rp$sc)
## [1] -2.017518 1.023526
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cv_sp_lm
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## Task: rp
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## Aggr perf: rmse.test.rmse=0.4280988
## Runtime: 2.51188
Ok, is this good or not?
range(rp$sc)
## [1] -2.017518 1.023526
Hence, this corresponds to a mean deviation from the true value of (%):
cv_sp_lm$aggr / diff(range(rp$sc)) * 100
## rmse.test.rmse
##
   14.07737
```



### **Random forests**

### Random forests



Like many other machine learning algorithms, random forests have hyperparameters (James, Witten, Hastie, and Tibshirani, 2013). These hyperparameters are not estimated from the data like the coefficients of (semi-)parametric models (lm, glm, gam) but need to be specified before the learning begins. To find the optimal hyperparameters, one needs to run many models using random hyperparameter values. There are several approaches how to do this, here, we will use a random search with 50 iterations while we limit the tuning space to a specific range in accordance with the literature (Probst, Wright, and Boulesteix, 2018; Schratz, Muenchow, Iturritxa, Richter, and Brenning, 2018).

# Again: Define a learner



We can use the already specified regression task... just in case let us repeat it here again

## Again: Define a learner



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But we need to change our learner in order to use a random forest model. Here, we will use a random forest implementation of the **ranger** package, i.e. we replace regr.lm by reg.ranger (again see listLearners (task)).

## Again: Define a learner



We can use the already specified regression task... just in case let us repeat it here again

But we need to change our learner in order to use a random forest model. Here, we will use a random forest implementation of the **ranger** package, i.e. we replace regr.lm by reg.ranger (again see listLearners (task)).

```
lrn = makeLearner(cl = "regr.ranger", predict.type = "response")
```

# Spatial cross-validation



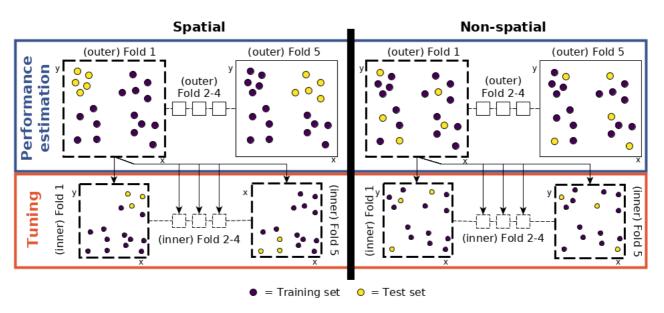
We are already familiar with the spatial cross-validation of the performance level (outer level).

# Hyperparameter tuning

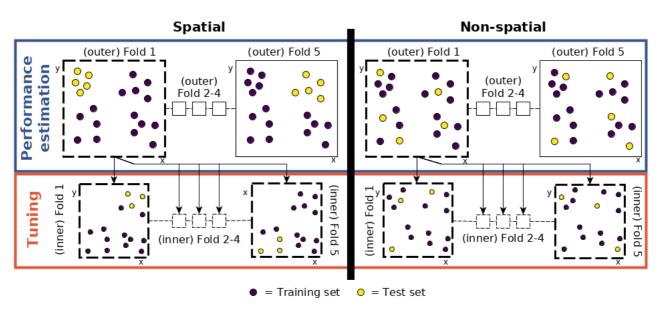


However, now that we use a random forest model, we need to tune its hyperparameters. And we have to do it in an inner loop using again spatial cross-validation. The inner loop is necessary because tuning the hyperparameters in the performance loop would be like cheating a bit since we then would use the same data for the performance estimation and the hyperparameter tuning. This is called nested spatial cross-validation. A visualization might help (taken from Schratz, Muenchow, Iturritxa, et al. (2018)):









I know this might seem a bit overwhelming in the beginning but it is an easy concept once you get your head around it. You can reread nested spatial cross-validation including hyperparamter tuning in Chapter 11 of *Geocomputation* with R (Lovelace, Nowosad, and Muenchow, 2018)

# Hyperparameter tuning



Let us define five spatially disjoint partitions in the tune level (one repetition).

```
tune_level = makeResampleDesc(method = "SpCV", iters = 5)
```

### Random search



Next, we need to tell **mlr** to find the optimal hyperparameters via a random search with 50 iterations:

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ctrl = makeTuneControlRandom(maxit = 50)
```

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```
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```

Let us limit the tuning space in accordance with the literature (Probst, Wright, and Boulesteix, 2018)

```
ps = makeParamSet(
   makeIntegerParam("mtry", lower = 1, upper = ncol(rp) - 1),
   makeNumericParam("sample.fraction", lower = 0.2, upper = 0.9),
   makeIntegerParam("min.node.size", lower = 1, upper = 10)
)
```

### Random search



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)
```

#### Recommended literature:

- James, Witten, Hastie, et al. (2013)
- Probst, Wright, and Boulesteix (2018).
- Chapter 14 of *Geocomputation with R* (Lovelace, Nowosad, and Muenchow, 2018)

## Wrap it all up



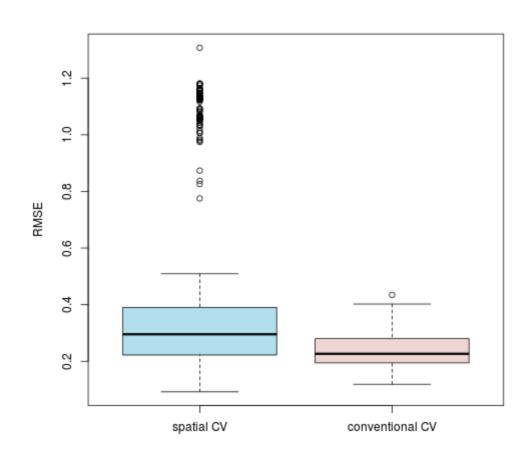
# Resampling



Be careful, running the next code chunk takes a while since we are asking R to run 125,500 models. Parallelization might be a good idea. See code/spatial\_cv/01-mlr.R of the geocompr/geostats\_18 repository how to set it up.

## Have a look at the result





# Interesting...



```
cv_sp_lm$aggr

## rmse.test.rmse
## 0.4280988

cv_sp_rf$aggr

## rmse.test.rmse
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## Interesting...



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The linear model is better than the random forest model...

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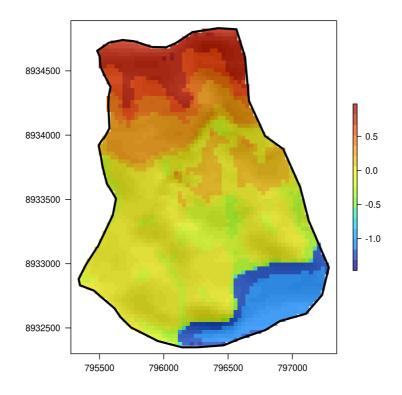
The linear model is better than the random forest model...

- Relationship between response and predictors linear enough
- just four predictors, adding further environmental predictors and xycoordinates might change the result

# Predictive mapping



Find the code again in code/spatial\_cv/01-mlr.R of the geocompr/geostats\_18 respository.



### References



Bischl, Bernd, Michel Lang, Lars Kotthoff, et al. (2016). "Mlr: Machine Learning in R". In: *Journal of Machine Learning Research* 17.170, pp. 1-5. URL: http://imlr.org/papers/v17/15-066.html.

James, Gareth, Daniela Witten, Trevor Hastie, et al, ed. (2013). *An Introduction to Statistical Learning: With Applications in R.* Springer texts in statistics 103. OCLC: ocn828488009. New York: Springer. 426 pp. ISBN: 978-1-4614-7137-0.

Lovelace, Robin, Jakub Nowosad and Jannes Muenchow (2018). Geocomputation with R. The R Series. CRC Press.

Probst, Philipp, Marvin Wright and Anne-Laure Boulesteix (2018). "Hyperparameters and Tuning Strategies for Random Forest".

arXiv: 1804.03515 [cs, stat]. URL: http://arxiv.org/abs/1804.03515 (visited on Aug. 02, 2018).

Schratz, Patrick, Jannes Muenchow, Eugenia Iturritxa, et al. (2018). "Performance Evaluation and Hyperparameter Tuning of Statistical and Machine-Learning Models Using Spatial Data".

arXiv: 1803.11266 [cs, stat]. URL: http://arxiv.org/abs/1803.11266 (visited on Jun. 18, 2018).

