# Distributed Systems – Fault Tolerance

### Lab 2

## 2022/2023

# **Quorum replication**

Use quorums for consistent replication with the lin-kv service. Store data as  $key \rightarrow (value, timestamp, writer)$  and implement the following operations:

- Write In two steps:
  - Step 1: Collect timestamp from at least a quorum of servers for the desired key.
  - Step 2: Select the highest timestamp and send (value, timestamp + 1, writer) to the write quorum.
  - In each server, update key if stored (timestamp, writer) is lower and return an acknowledgment.
  - Wait for sufficient acknowledgments and reply to client.
- **Read** Collect (*value*, *timestamp*, *writer*) from a read quorum and return the *value* with the highest *timestamp* (and *writer*).
- CAS Return unsupported.

### **Steps**

- 1. Implement the quorum protocol.
- 2. Test with different quorum combinations (ROWA, majority, ...).
- 3. Retest with increasing request rate (--rate) and network latency (--latency).
- 4. Discussion topics: What happens with concurrent writes? Does the protocol tolerate crashes? Can the CAS operation be supported (and tolerate crashes)?

**Learning Outcomes** Apply quorum replication to build a concurrent linearizable register. Recognize the relevance of quorums for fault tolerance.