Orientation-oop-basics: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/lib/compile/src/hash.hpp>

Orientation-on-class-diagrams: (TODO)

Orientation-unit-testing: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/auto_test.py>

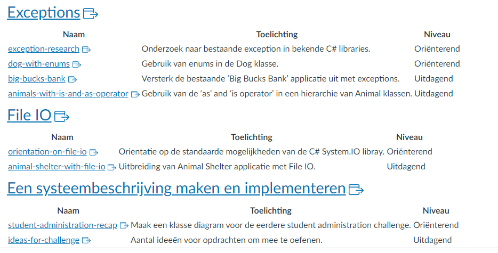
Orientation-inheritance: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/lib/compile/src/hash.hpp>

Orientation-abstract-classes-and-interfaces: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/lib/compile/src/hash.hpp>

Exceptions: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/core.py>

File-io: <https://github.com/MarijnVerschuren/Password_Manager/blob/main/app/core.py>

Student-administration-recap: (TODO)



Bike-computer: <https://github.com/MarijnVerschuren/STM32F4_AS5600_library/blob/main/AS5600>

FIFO-buffers: <https://github.com/MarijnVerschuren/Robotic_Arm/blob/main/ARM_COMPUTER/Core/Inc/uart_buffer.h>

*the uart is configured with a dma which has FIFO enabled*

Array-basics:

Dispatcher:

String-behaviour:

String-calculator:

Structs:

Connectfour:

Ringbuffer:

Studentadmin:

Buffer-unit-tests:

Memory:

Pointers-intro:

Bit-manipulations:

Watch:

Adidas:

Elektrische-basis:

Serialization: <https://github.com/MarijnVerschuren/Info_Generator/blob/main/info_gen/gen.py>

I2C: <https://github.com/MarijnVerschuren/STM32F4_AS5600_library/blob/main/AS5600/src/AS5600.c>

Alarm-states:

Light-controller:

Trafic-light:

*../SEM1/TraficControl*

Analog: <https://github.com/MarijnVerschuren/Robotic_Arm/blob/main/STM32_MCU/stepper/Core/Src/main.c>

Hysteresis: <https://github.com/MarijnVerschuren/Robotic_Arm/blob/main/STM32_MCU/stepper/Core/Src/main.c>

Register-IO:

*../SEM1/ArduinoTester*