# Elevator

## Table of contents

[Elevator 1](#_Toc1)

[1. Table of contents 2](#_Toc2)

[2. Description 3](#_Toc3)

[3. Use cases 3](#_Toc4)

## 2. Description

* System controls 8 elevators
* Each elevator has 20 ‘request floor’ buttons and a current floor indicator
* Each floor has 2 ‘request elevator’ buttons (up, down) and a floor indicator (on the highest and lowest floor there is only one ‘request elevator’ button)
* Both the elevator and the floor has a sliding door that open at the same time
* The floor dock has both pressure and optical sensors to detect obstructions (doors are opened if obstructed and closed again after 5 seconds)
* Speaker on each floor dock that announces requested elevator
* The system only send an idle elevator or an elevator going in the direction of the request (if none are available the request stays pending)
* When any request button is pressed a back-light is turned on until request is satisfied

## 3. Use cases

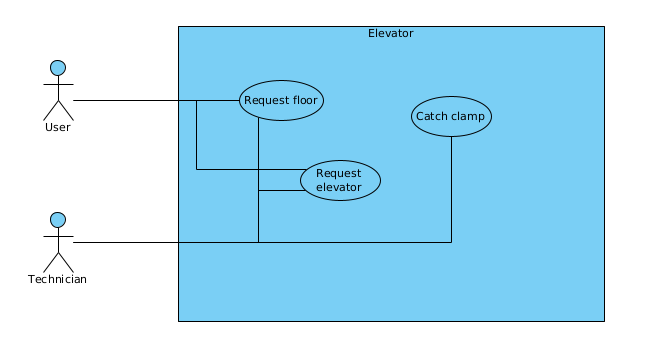
* Control 8 elevators to be able to move to each floor
* Make sure that you can safely load and unload the elevator
* The system makes moving between floors more efficient and easier compared to stairs
* User, Technician

|  |  |
| --- | --- |
| Name | Request Floor |
| Description | Elevator is requested to move to a floor |
| Actor | User, Technician |
| Flow | 1. Actor presses the button for the floor the want to request  2. Doors are closed (if not already)  3. The system moves the elevator to the requested floor  4. Sound is played on the destination floor announcing elevator  5. Doors are opened |
| Exception | 1. Door is obstructed when closing, in this case the door is opened again and waits 5 seconds to retry.  2. Elevator is requested between the current floor and the requested floor, in this case the elevator makes a stop at the floor that requested the elevator. |
| Result | The elevator moves from floor A to floor B |

|  |  |
| --- | --- |
| Name | Request Elevator |
| Description | Elevator is requested to move to a floor |
| Actor | User, Technician |
| Flow | 1. Actor presses the ‘Request Elevator’ button for the direction they want to go in  2. The system checks if there are any elevators that are idle or moving in the direction of the floor that is requesting an elevator  3. If the system finds a elevator with these criteria the system tells that elevator to go to / stop at the requesting floor  4. Sound is played on the requesting floor announcing elevator  5. Doors are opened |
| Exception | 1. If the system finds no elevator with the criteria from step 3 the system will wait until the criteria is met and continue the steps. |
| Result | The elevator moves to the requesting floor |

|  |  |
| --- | --- |
| Name | Catch Clamp |
| Description | Clamps that catch the elevator when falling |
| Actor | Technician |
| Flow | 1. A fall is detected  2. Clamps are initiated |
| Exception | 1. When the technician is testing the system it will activate regardless of fall detection. |
| Result | Catch clamps initiated |

# 4. Use case diagram



# 5. Class diagram

##### 5.1 Class list:

– Controller

– Elevator

– Door (elevator / floor)

– Button?

– Floor Indicator

– Pressure Sensor

– Optical Sensor

– IObstruction Sensor

– Catch Clamp

– Tension sensor

##### 5.2 Object diagram: