# Introduction to Artificial Intelligence


**COMP307/AIML420**

**Neural Networks 1: The Perceptron**

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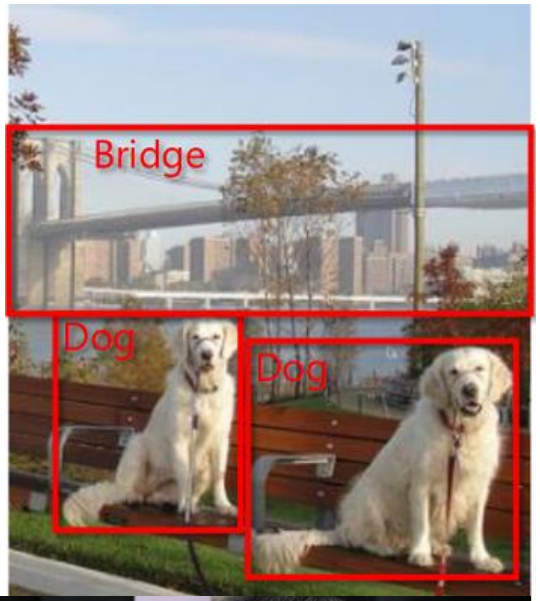
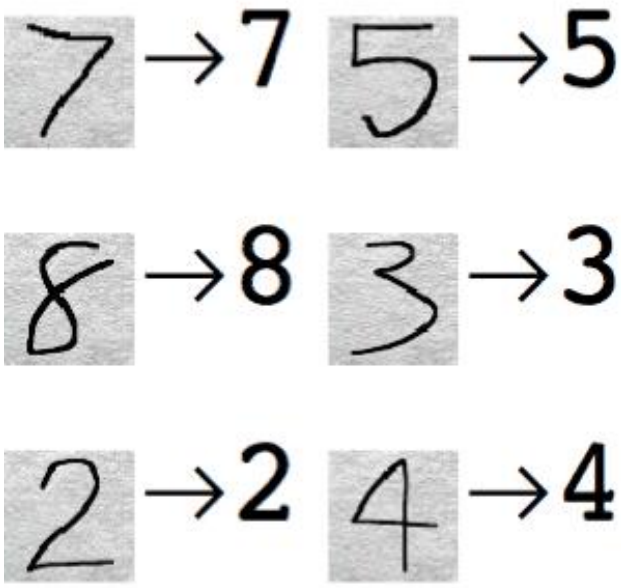
# Outline

- Why ANN?
- Origin
- The perceptron
- Perceptron learning
- What can (not) perceptron learn
- Extending perceptron

# Why Artificial Neural Networks (ANNs)?

- "Killer" applications in a lot of areas
  - Computer vision/image processing
  - Playing games (AlphaGo, Watson, …)
  - Big data
  - …



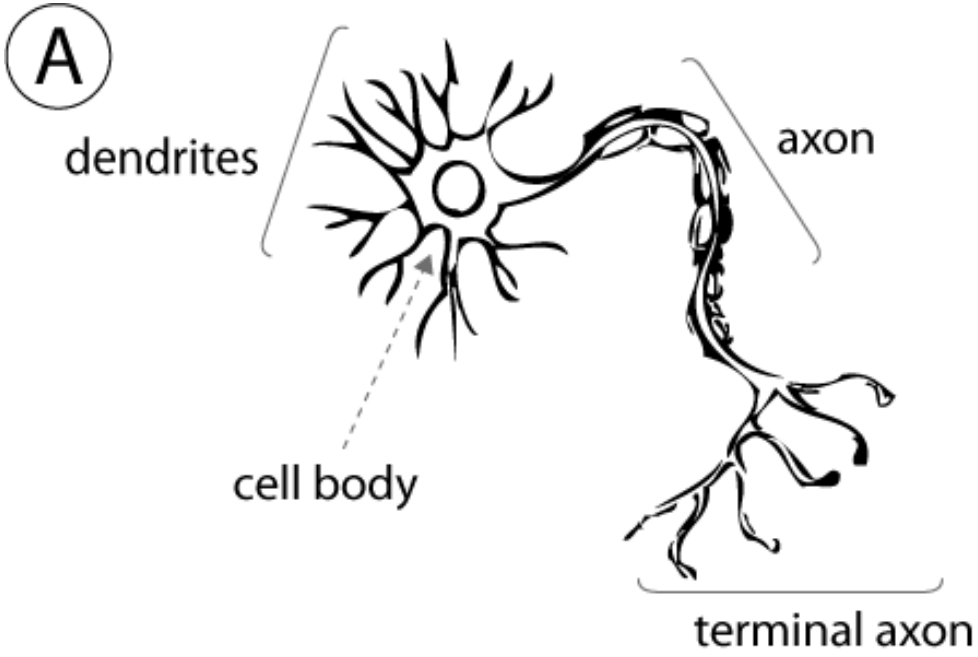

# Origin

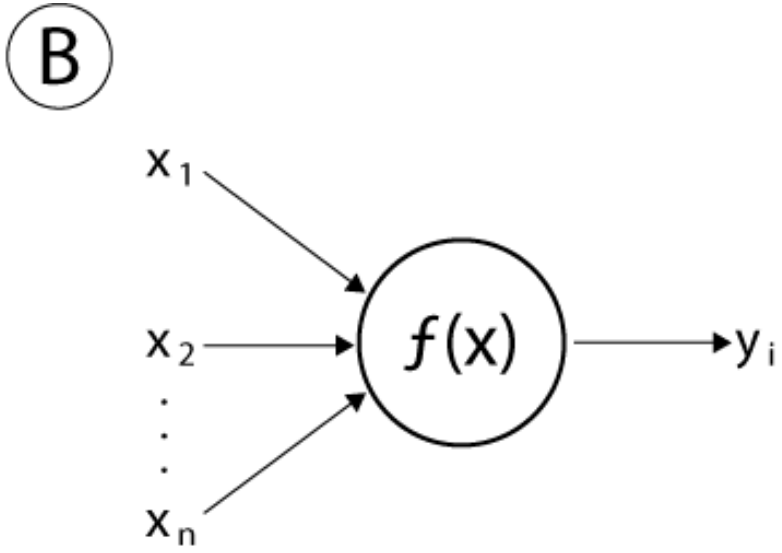
- Human brain shows amazing capability in:
  - Learning
  - Perception
  - Adaptability
  - …

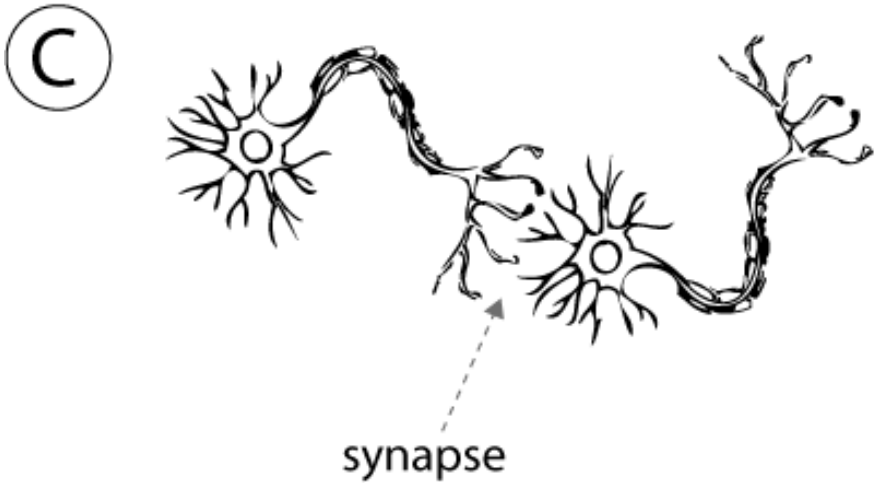
- Can we *simulate the* human brain to achieve the above functionalities?

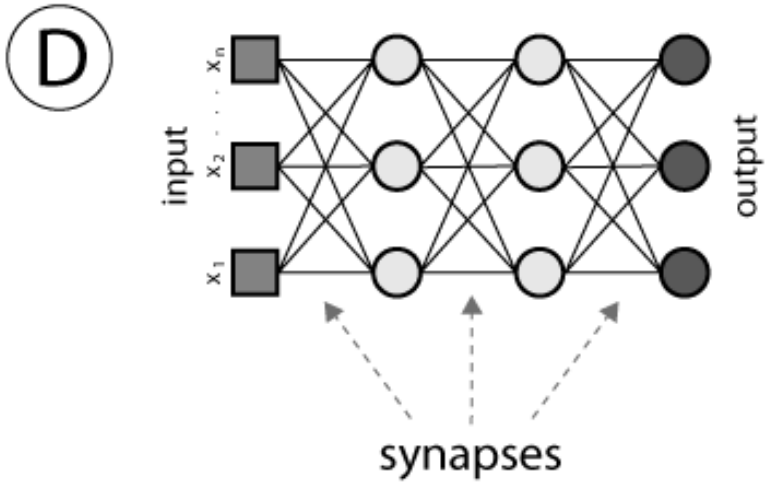
- **Artificial** neural networks use this as inspiration/motivation

# Origin


A
dendrites
axon
cell body
terminal axon

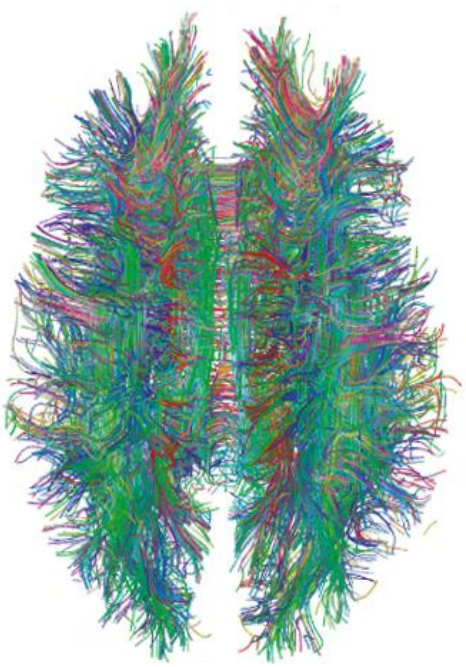

B
x 1
x 2
x n
f(x)
y i


C
synapse

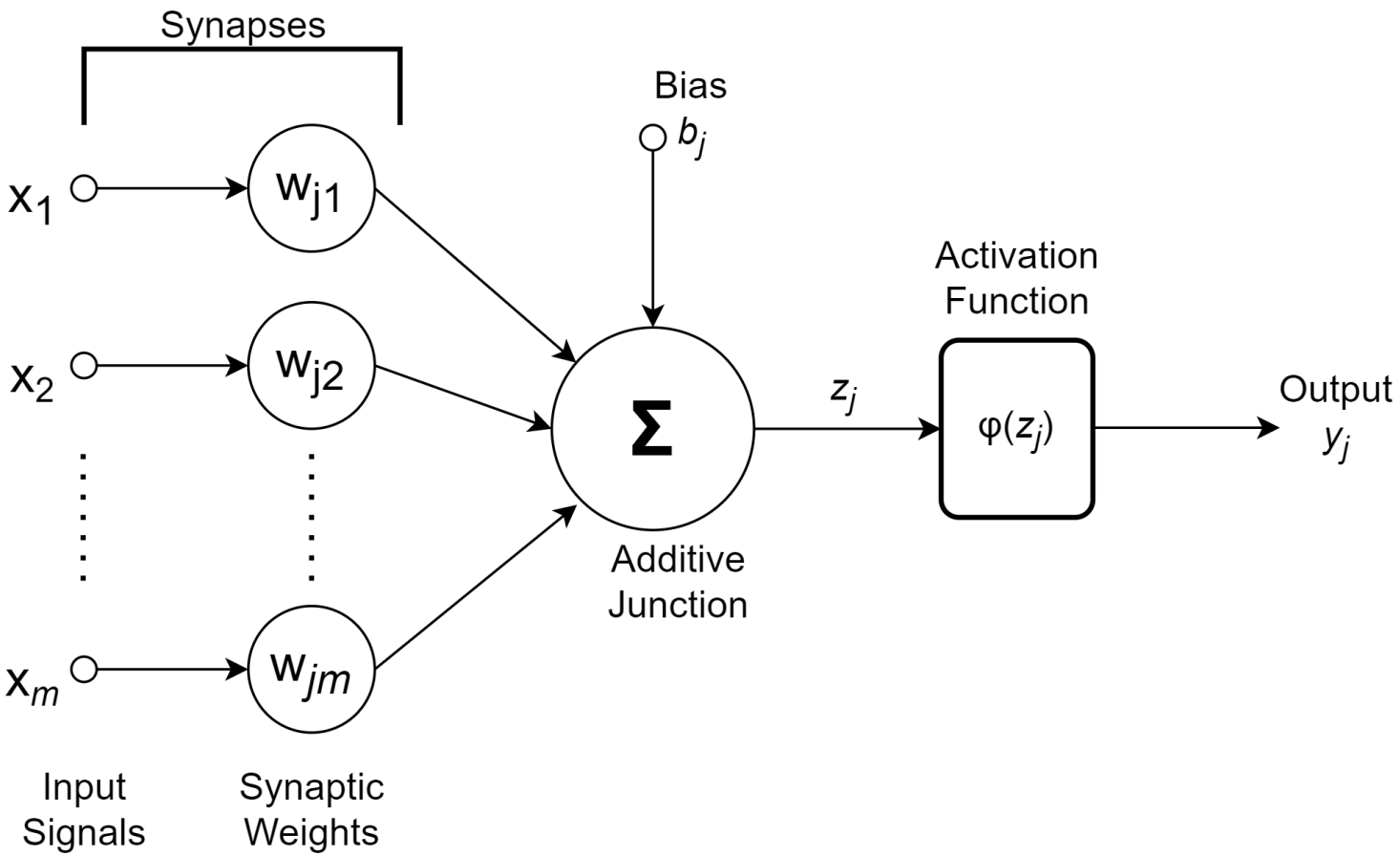

D
input
output
synapses

# Origin

- Facts about human brain:
  - $10^{11}$ neurons, massively connected
  - Each neuron is connected to 1000–10,000 other neurons
  - $10^{14}$ to $10^{15}$ connections in total!
  - Brain message passing is 1 million times **slower** than modern electronic circuits
  - But very *efficient* for complex decision making
  - Usually fewer than 100 serial stages
  - 100 step rule (500ms response time)

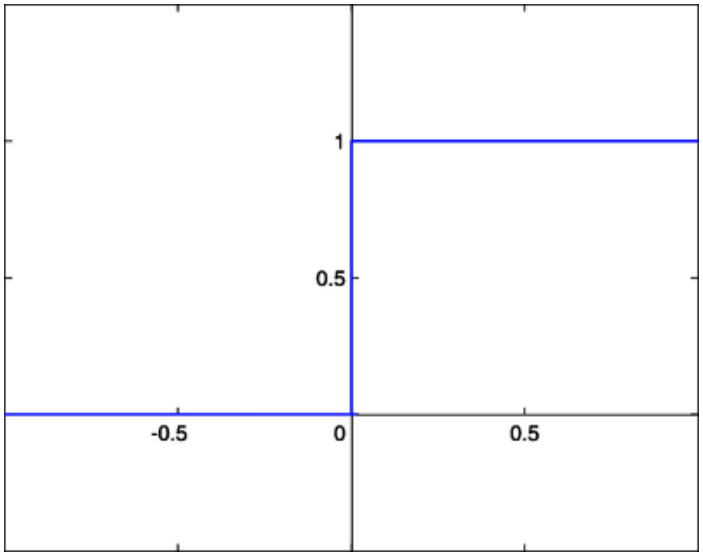


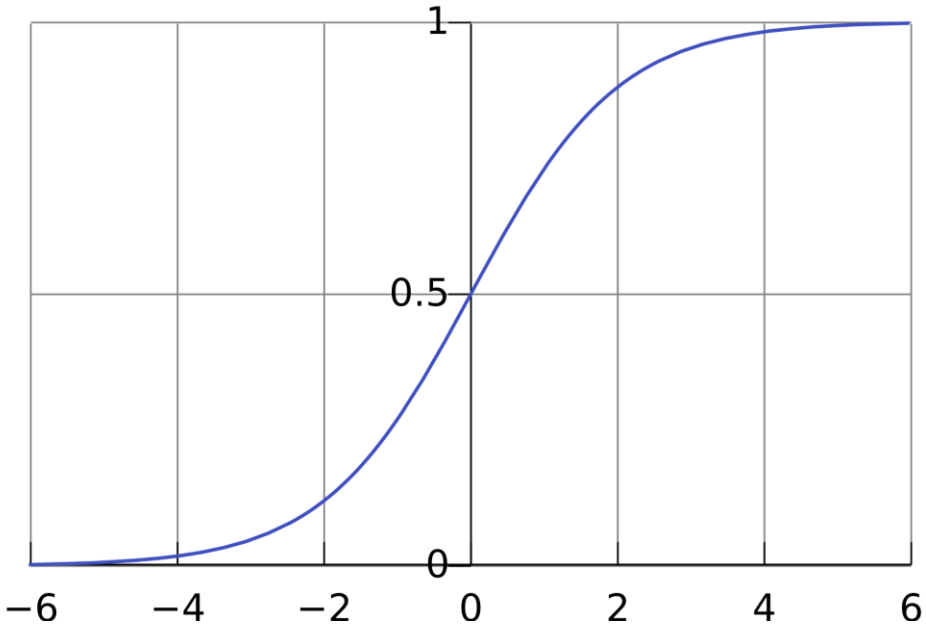
# A Single Artificial Neuron




$$z_j = \sum_{i=1}^{m} w_{ji} x_i + b_j \qquad y_j = \varphi(z_j)$$

# Activation Functions




Threshold

Sigmoid

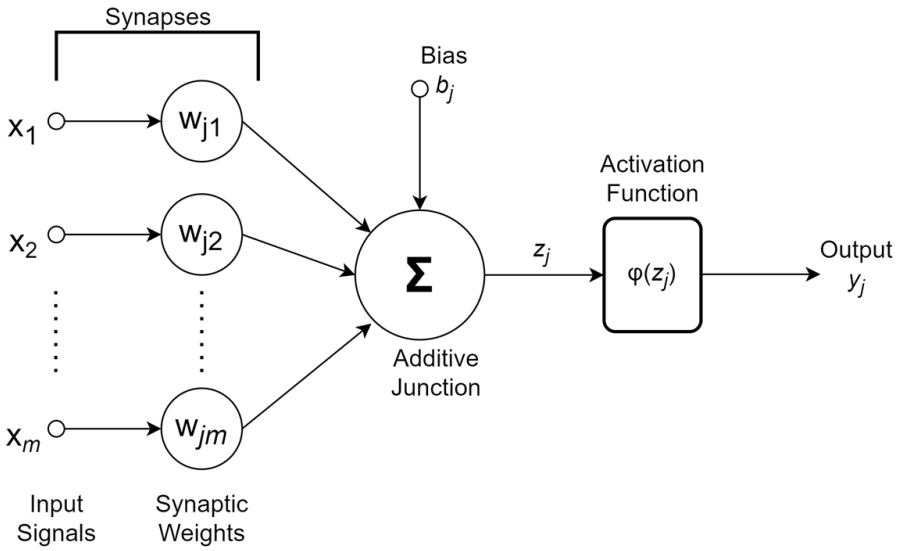
$$y_j = \begin{cases} 1, & \text{if } z_j > 0, \\ 0, & \text{otherwise} \end{cases}$$

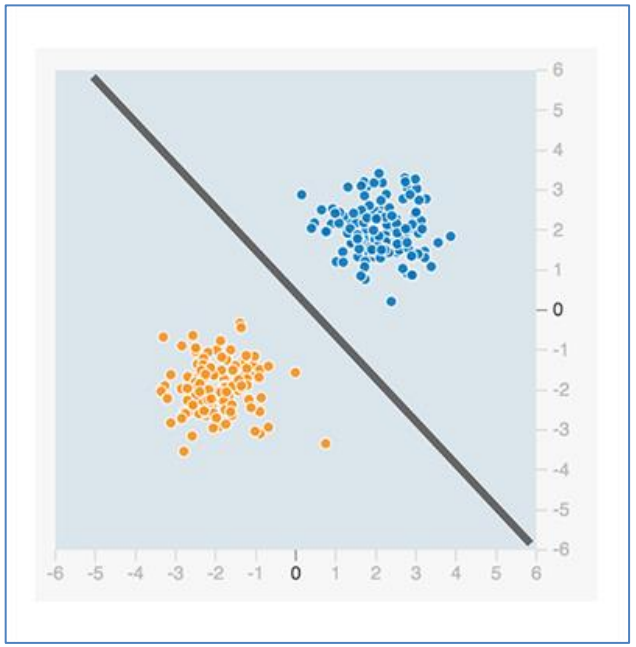
$$y_j = \frac{1}{1 + e^{-z_j}}$$

*Why do we need this?*

# Perceptron

- A *special* type of artificial neuron
  - Real-valued inputs
  - Binary output
  - Threshold activation function



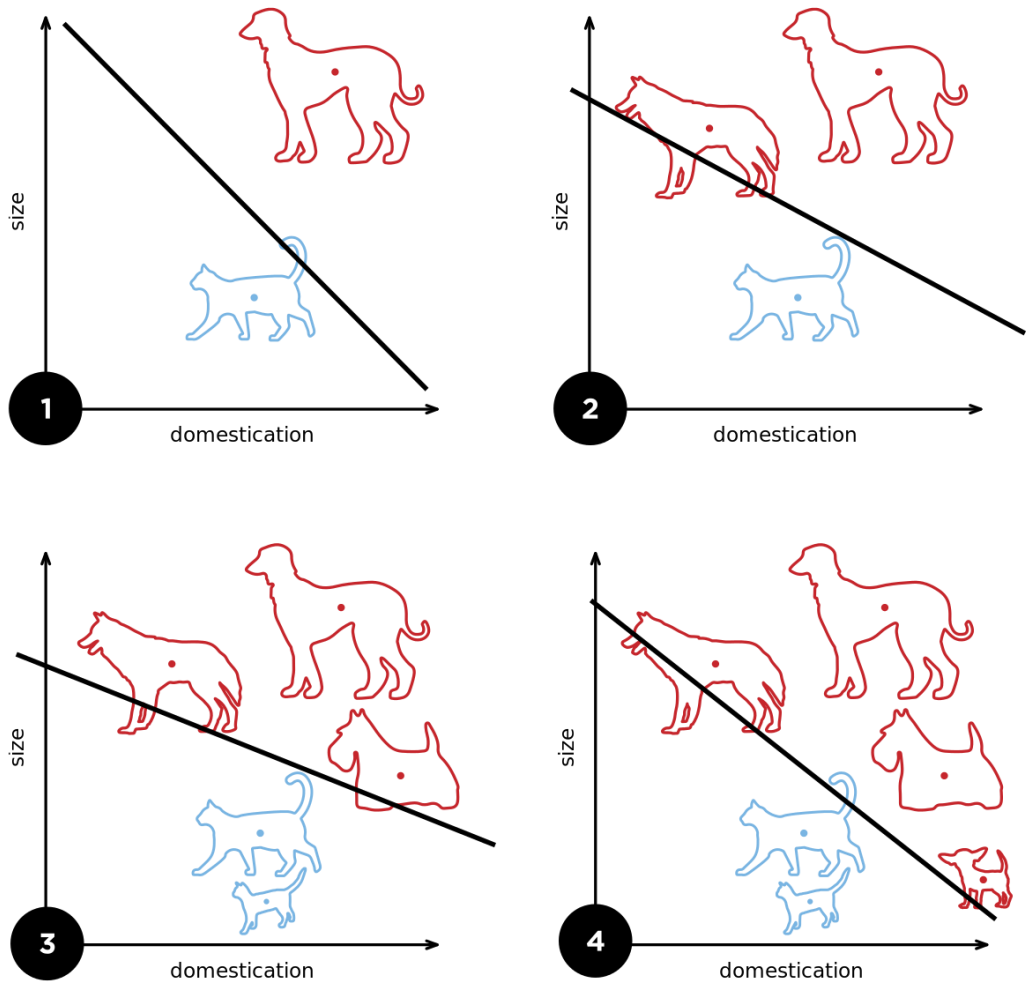



$$y_j = \begin{cases} 1, & \text{if } \sum_{i=1}^{m} w_{ji} x_i + b_j > 0, \\ 0, & \text{otherwise} \end{cases}$$

$$y = \begin{cases} 1, \text{if } x_1 + x_2 > 0, \\ 0, \text{otherwise.} \end{cases}$$

# Perceptron

- To perform linear classification
  - 2 inputs: a line; 3 inputs: a plane
- Can do online learning
  - Update $w_{ji}$ and $b_j$ based on new examples



# Learning A Perceptron

- How to get the **optimal** weights and bias?
- Let us only consider accuracy:
  - *Optimal* if 100% accuracy on training set
  - Can have many optimal solutions…
- To simplify notation, we can transform the bias to a weight $w_{j0} = b_j$, where $x_0 = 1$ always holds

$$y_j = \begin{cases} 1, & \text{if } \sum_{i=1}^{m} w_{ji} x_i + b_j > 0, \\ 0, & \text{otherwise} \end{cases}$$

$$b_j = w_{j0} \cdot 1 = w_{j0} x_0$$

$$y_j = \begin{cases} 1, & \text{if } \sum_{i=0}^{m} w_{ji} x_i > 0, \\ 0, & \text{otherwise} \end{cases}$$

# Learning A Perceptron

- Initialise weights and threshold randomly (or set all to zero)
- Given a new example/instance $(x_1, x_2, \ldots, x_m, d)$:
  - Input feature vector: $(x_1, x_2, \ldots, x_m)$
  - Output (**d**esired class label): $d$
  - Predicted output: $y$

$$y = \begin{cases} 1, & \text{if } \sum_{i=0}^{m} w_i x_i > 0, \\ 0, & \text{otherwise} \end{cases}$$

- If $y = 0$ and $d = 1$,
  - increase $b = w_0$, increase $w_i$ for each positive $x_i$,
    decrease $w_i$ for each negative $x_i$
- If $y = 1$ and $d = 0$,
  - decrease $b = w_0$, decrease $w_i$ for each positive $x_i$,
    increase $w_i$ for each negative $x_i$
- Repeat for each new example until desired result achieved

# Learning A Perceptron

- Initialise weights and threshold randomly (or set all to zero)
- Given a new example/instance $(x_1, x_2, \ldots, x_m, d)$:
  - Input feature vector: $(x_1, x_2, \ldots, x_m)$
  - Output (**d**esired class label): $d$
  - Predicted output: $y$

$$y = \begin{cases} 1, & \text{if } \sum_{i=0}^{m} w_i x_i > 0, \\ 0, & \text{otherwise} \end{cases}$$

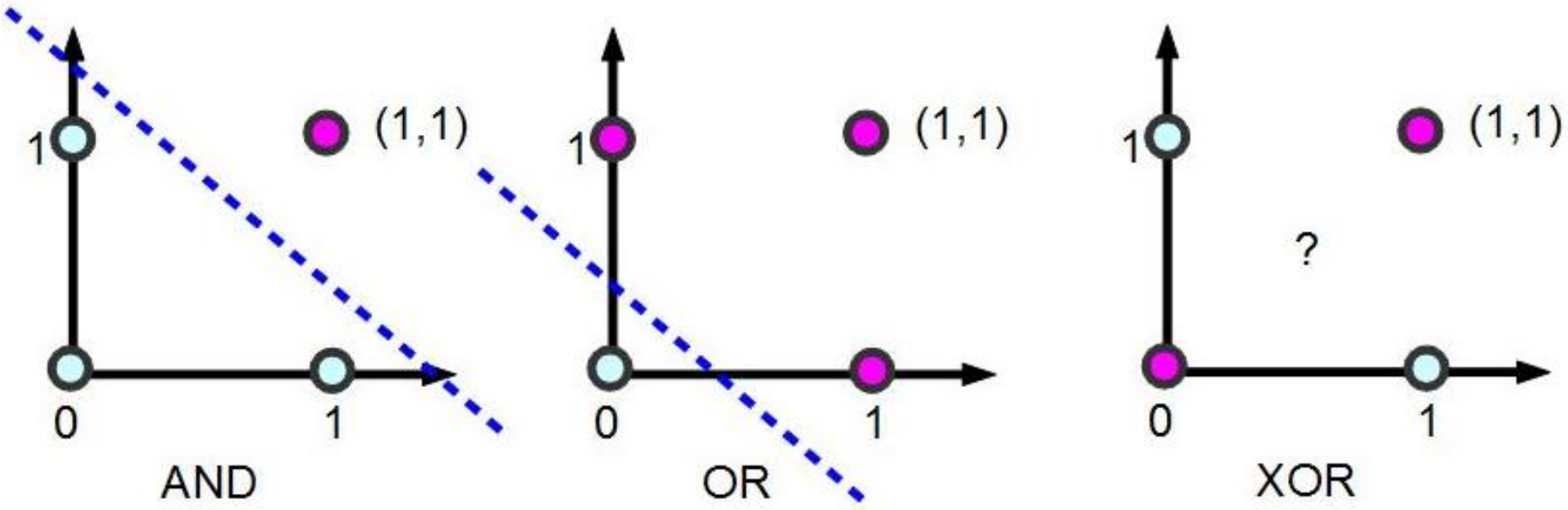
- We can use the equation:

$$w_i \leftarrow w_i + \eta(d - y)x_i, i = 0, 1, 2, \ldots, m$$

- Where $\eta \in [0,1]$ is called the learning rate
- Repeat for each new example until desired result achieved

# Problem with the Perceptron

- What can the perceptron learn?

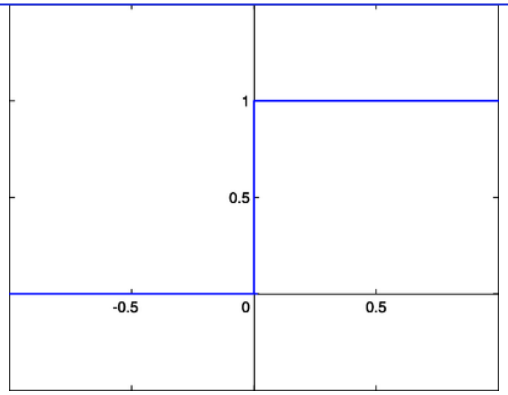



- *Perceptron convergence theorem*: The perceptron learning algorithm will converge **if and only if** the training set is linearly separable.
- Cannot learn for XOR (Minsky and Papert, 1969)

# Multi-Layer Perceptron (MLP)

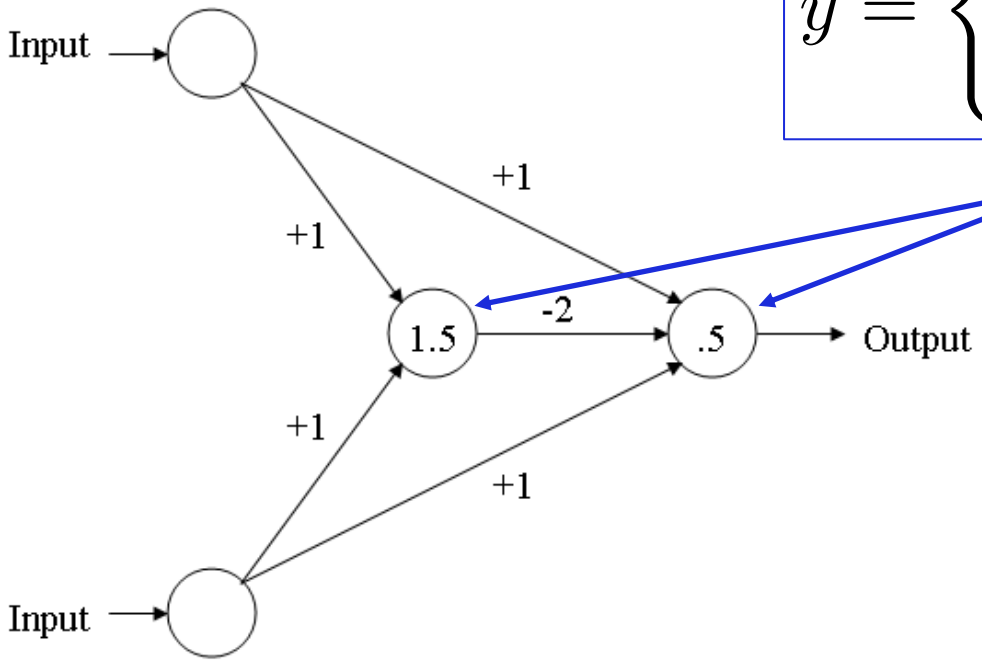
- Add one ***hidden*** node between the inputs and output

| x1 | x2 | y (class) |
|---|---|---|
| 0 | 0 | 0 |
| 1 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 1 | 0 |




$$y = \begin{cases} 1, & \text{if } \sum_i w_i x_i - T > 0, \\ 0, & \text{otherwise} \end{cases}$$

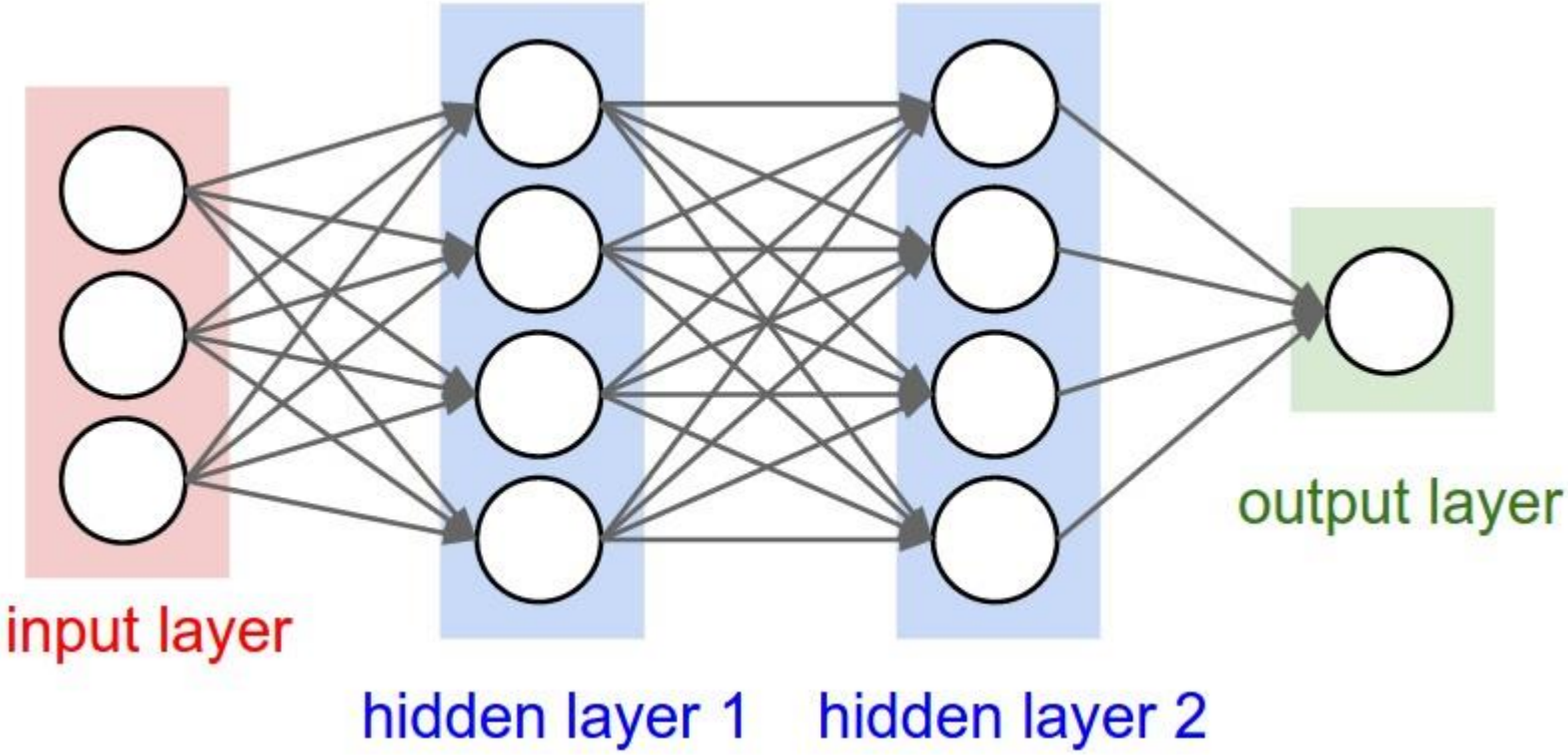
Threshold



# Neural Network

- Add more hidden layers

- Add more nodes for hidden layers



# Summary

- ANN has many “killer” applications
  - Image analysis, playing games, …
- Perceptron – the simplest neural network
- How to learn a perceptron
- Limitations of perceptron, multi-layer perceptron, general neural network

- Reading: Textbook section 20.5 (2nd edition) or section 18.7 ($3^{rd}$/$4^{th}$ edition)