

maze

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Contents

1	README	1
2	Data Structure Index	3
2.1	Data Structures	3
3	File Index	5
3.1	File List	5
4	Data Structure Documentation	7
4.1	_item Struct Reference	7
4.1.1	Field Documentation	7
4.1.1.1	data	7
4.1.1.2	priority	7
4.2	_map Struct Reference	7
4.2.1	Field Documentation	8
4.2.1.1	capacity	8
4.2.1.2	data	8
4.2.1.3	size	8
4.3	_pqueue Struct Reference	8
4.3.1	Field Documentation	8
4.3.1.1	capacity	8
4.3.1.2	cmp	8
4.3.1.3	data	8
4.3.1.4	size	8
4.4	_vmap Struct Reference	8

4.4.1	Field Documentation	9
4.4.1.1	capacity	9
4.4.1.2	data	9
4.4.1.3	size	9
4.5	edge_ Struct Reference	9
4.5.1	Field Documentation	9
4.5.1.1	next	9
4.5.1.2	to	9
4.5.1.3	weight	9
4.6	entry Struct Reference	9
4.6.1	Field Documentation	10
4.6.1.1	key	10
4.6.1.2	next	10
4.6.1.3	value	10
4.6.1.4	value	10
4.7	graph Struct Reference	10
4.7.1	Field Documentation	10
4.7.1.1	root	10
4.8	node_ Struct Reference	10
4.8.1	Field Documentation	11
4.8.1.1	edges	11
4.8.1.2	name	11
4.8.1.3	next	11

5 File Documentation	13
5.1 Dijkstra.c File Reference	13
5.2 Dijkstra.h File Reference	13
5.2.1 Function Documentation	13
5.2.1.1 Dijkstra_path(const Graph *g, const char *start, const char *end, char ***path)	13
5.2.1.2 Dijkstra_solveMaze(char **mazeFromFile, char **route, size_t hops)	14
5.3 dpqueue/driver.c File Reference	14
5.3.1 Function Documentation	14
5.3.1.1 heap_print(const pqueue *pq)	14
5.3.1.2 main(void)	14
5.4 graph/driver.c File Reference	14
5.4.1 Function Documentation	15
5.4.1.1 main(void)	15
5.5 map/driver.c File Reference	15
5.5.1 Function Documentation	15
5.5.1.1 hashtable_print(map *m)	15
5.5.1.2 main(void)	15
5.6 dpqueue/heap.c File Reference	15
5.6.1 Function Documentation	16
5.6.1.1 heap_print(const pqueue *pq)	16
5.6.1.2 pqueue_create(int(*cmp)(void *, void *))	16
5.6.1.3 pqueue_dequeue(pqueue *pq, void **item)	16
5.6.1.4 pqueue_destroy(pqueue *pq)	16
5.6.1.5 pqueue_enqueue(pqueue *pq, void *item, double priority)	16
5.6.1.6 pqueue_reprioritize(pqueue *pq, void *item, double priority)	16
5.6.1.7 pqueue_search(const pqueue *pq, void *item)	16
5.6.1.8 pqueue_size(const pqueue *pq)	16
5.7 dpqueue/pqueue.c File Reference	16
5.7.1 Function Documentation	17
5.7.1.1 heap_print(const pqueue *pq)	17

5.7.1.2	pqueue_create(int(*cmp)(void *, void *))	17
5.7.1.3	pqueue_dequeue(pqueue *pq, void **item)	17
5.7.1.4	pqueue_destroy(pqueue *pq)	17
5.7.1.5	pqueue_enqueue(pqueue *pq, void *item, double priority)	17
5.7.1.6	pqueue_reprioritize(pqueue *pq, void *item, double priority)	17
5.7.1.7	pqueue_search(const pqueue *pq, void *item)	17
5.7.1.8	pqueue_size(const pqueue *pq)	17
5.8	dpqueue/pqueue.h File Reference	17
5.8.1	Typedef Documentation	18
5.8.1.1	pqueue	18
5.8.2	Function Documentation	18
5.8.2.1	pqueue_create(int(*cmp)(void *, void *))	18
5.8.2.2	pqueue_dequeue(pqueue *pq, void **item)	18
5.8.2.3	pqueue_destroy(pqueue *pq)	18
5.8.2.4	pqueue_enqueue(pqueue *pq, void *item, double priority)	18
5.8.2.5	pqueue_reprioritize(pqueue *pq, void *item, double priority)	18
5.8.2.6	pqueue_search(const pqueue *pq, void *item)	18
5.8.2.7	pqueue_size(const pqueue *pq)	18
5.9	graph/adjlist.c File Reference	18
5.9.1	Macro Definition Documentation	19
5.9.1.1	_XOPEN_SOURCE	19
5.9.2	Typedef Documentation	19
5.9.2.1	edge_	19
5.9.2.2	node_	19
5.9.3	Function Documentation	19
5.9.3.1	Graph_addEdge(Graph *g, const char *from, const char *to, double weight)	19
5.9.3.2	Graph_addNode(Graph *g, const char *name)	20
5.9.3.3	Graph_create(void)	20
5.9.3.4	Graph_deleteEdge(Graph *g, const char *from, const char *to)	20
5.9.3.5	Graph_deleteNode(Graph *g, const char *name)	20

5.9.3.6	Graph_disassemble(Graph *g)	21
5.9.3.7	Graph_getEdgeWeight(const Graph *g, const char *from, const char *to)	21
5.9.3.8	Graph_getNeighbors(const Graph *g, const char *name, char ***neighbors)	21
5.9.3.9	Graph_getNodes(const Graph *g, char ***nodes)	21
5.9.3.10	Graph_isAdjacent(const Graph *g, const char *from, const char *to)	22
5.9.3.11	Graph_print(const Graph *g)	22
5.10	graph/Graph.c File Reference	22
5.10.1	Macro Definition Documentation	23
5.10.1.1	_XOPEN_SOURCE	23
5.10.2	Typedef Documentation	23
5.10.2.1	edge_	23
5.10.2.2	node_	23
5.10.3	Function Documentation	23
5.10.3.1	Graph_addEdge(Graph *g, const char *from, const char *to, double weight)	23
5.10.3.2	Graph_addNode(Graph *g, const char *name)	24
5.10.3.3	Graph_create(void)	24
5.10.3.4	Graph_deleteEdge(Graph *g, const char *from, const char *to)	24
5.10.3.5	Graph_deleteNode(Graph *g, const char *name)	25
5.10.3.6	Graph_disassemble(Graph *g)	25
5.10.3.7	Graph_getEdgeWeight(const Graph *g, const char *from, const char *to)	25
5.10.3.8	Graph_getNeighbors(const Graph *g, const char *name, char ***neighbors)	25
5.10.3.9	Graph_getNodes(const Graph *g, char ***nodes)	26
5.10.3.10	Graph_isAdjacent(const Graph *g, const char *from, const char *to)	26
5.10.3.11	Graph_print(const Graph *g)	26
5.11	graph/Graph.h File Reference	26
5.11.1	Typedef Documentation	27
5.11.1.1	Graph	27
5.11.2	Function Documentation	27
5.11.2.1	Graph_addEdge(Graph *g, const char *from, const char *to, double weight)	27
5.11.2.2	Graph_addNode(Graph *g, const char *name)	27

5.11.2.3	<code>Graph_create(void)</code>	28
5.11.2.4	<code>Graph_deleteEdge(Graph *g, const char *from, const char *to)</code>	28
5.11.2.5	<code>Graph_deleteNode(Graph *g, const char *name)</code>	28
5.11.2.6	<code>Graph_disassemble(Graph *g)</code>	28
5.11.2.7	<code>Graph_getEdgeWeight(const Graph *g, const char *from, const char *to)</code>	29
5.11.2.8	<code>Graph_getNeighbors(const Graph *g, const char *name, char ***neighbors)</code>	29
5.11.2.9	<code>Graph_getNodes(const Graph *g, char ***nodes)</code>	29
5.11.2.10	<code>Graph_isAdjacent(const Graph *g, const char *from, const char *to)</code>	29
5.11.2.11	<code>Graph_print(const Graph *g)</code>	30
5.12	<code>graph/GraphSerializer.c</code> File Reference	30
5.12.1	Macro Definition Documentation	31
5.12.1.1	<code>_GNU_SOURCE</code>	31
5.12.2	Function Documentation	31
5.12.2.1	<code>GraphSerializer_fromFile(FILE *fp, char ***mazeFromFile, size_t *maxLength, size_t *lineCount, char flags)</code>	31
5.12.2.2	<code>GraphSerializer_fromMaze(Graph **g, char **maze, size_t *maxLength, size_t *lineCount, char flags)</code>	31
5.12.2.3	<code>GraphSerializer_toStdout(const Graph *g)</code>	31
5.13	<code>graph/GraphSerializer.h</code> File Reference	32
5.13.1	Function Documentation	32
5.13.1.1	<code>GraphSerializer_fromFile(FILE *fp, char ***mazeFromFile, size_t *maxLength, size_t *lineCount, char flags)</code>	32
5.13.1.2	<code>GraphSerializer_fromMaze(Graph **g, char **maze, size_t *maxLength, size_t *lineCount, char flags)</code>	32
5.13.1.3	<code>GraphSerializer_toStdout(const Graph *g)</code>	33
5.14	<code>graph/test/test01.c</code> File Reference	33
5.14.1	Function Documentation	33
5.14.1.1	<code>main(void)</code>	33
5.15	<code>graph/test/test02.c</code> File Reference	33
5.15.1	Function Documentation	33
5.15.1.1	<code>main(void)</code>	33
5.16	<code>graph/test/test03.c</code> File Reference	33

5.16.1	Function Documentation	34
5.16.1.1	main(void)	34
5.17	map/hashtable.c File Reference	34
5.17.1	Macro Definition Documentation	35
5.17.1.1	_XOPEN_SOURCE	35
5.17.2	Function Documentation	35
5.17.2.1	hashtable_print(map *m)	35
5.17.2.2	map_create(void)	35
5.17.2.3	map_destroy(map *m)	35
5.17.2.4	map_exists(map *m, const char *key)	35
5.17.2.5	map_insert(map *m, const char *key, double value)	35
5.17.2.6	map_lookup(map *m, const char *key)	36
5.18	map/map.c File Reference	36
5.18.1	Macro Definition Documentation	37
5.18.1.1	_XOPEN_SOURCE	37
5.18.2	Function Documentation	37
5.18.2.1	hashtable_print(map *m)	37
5.18.2.2	map_create(void)	37
5.18.2.3	map_destroy(map *m)	37
5.18.2.4	map_exists(map *m, const char *key)	37
5.18.2.5	map_insert(map *m, const char *key, double value)	37
5.18.2.6	map_lookup(map *m, const char *key)	38
5.19	map/map.h File Reference	38
5.19.1	Typedef Documentation	38
5.19.1.1	map	38
5.19.2	Function Documentation	38
5.19.2.1	map_create(void)	38
5.19.2.2	map_destroy(map *m)	39
5.19.2.3	map_exists(map *m, const char *key)	39
5.19.2.4	map_insert(map *m, const char *key, double value)	39

5.19.2.5	<code>map_lookup(map *m, const char *key)</code>	39
5.20	<code>map/vmap.c</code> File Reference	40
5.20.1	Macro Definition Documentation	40
5.20.1.1	<code>_XOPEN_SOURCE</code>	40
5.20.2	Function Documentation	40
5.20.2.1	<code>vmap_create(void)</code>	40
5.20.2.2	<code>vmap_destroy(vmap *m)</code>	40
5.20.2.3	<code>vmap_exists(vmap *m, const char *key)</code>	41
5.20.2.4	<code>vmap_insert(vmap *m, const char *key, void *value)</code>	41
5.20.2.5	<code>vmap_lookup(vmap *m, const char *key)</code>	41
5.21	<code>map/vmap.h</code> File Reference	42
5.21.1	Typedef Documentation	42
5.21.1.1	<code>vmap</code>	42
5.21.2	Function Documentation	42
5.21.2.1	<code>vmap_create(void)</code>	42
5.21.2.2	<code>vmap_destroy(vmap *m)</code>	42
5.21.2.3	<code>vmap_exists(vmap *m, const char *key)</code>	43
5.21.2.4	<code>vmap_insert(vmap *m, const char *key, void *value)</code>	43
5.21.2.5	<code>vmap_lookup(vmap *m, const char *key)</code>	43
5.22	<code>maze.c</code> File Reference	43
5.22.1	Function Documentation	44
5.22.1.1	<code>main(int argc, char *argv[])</code>	44
5.22.1.2	<code>Maze_generate(char ***customMaze, size_t maxLineLength, size_t lineCount)</code>	44
5.23	<code>README.md</code> File Reference	44
5.24	<code>tests/door-water.txt</code> File Reference	44
5.25	<code>tests/door.txt</code> File Reference	44
5.26	<code>tests/map01.txt</code> File Reference	44
5.27	<code>tests/map02.txt</code> File Reference	44
5.28	<code>tests/map03.txt</code> File Reference	44
5.29	<code>tests/map04.txt</code> File Reference	45
5.30	<code>tests/map05.txt</code> File Reference	45
5.31	<code>tests/water.txt</code> File Reference	45

Chapter 1

README

Maze Solver

Chapter 2

Data Structure Index

2.1 Data Structures

Here are the data structures with brief descriptions:

_item	7
_map	7
_pqueue	8
_vmap	8
edge_	9
entry	9
graph	10
node_	10

Chapter 3

File Index

3.1 File List

Here is a list of all files with brief descriptions:

Dijkstra.c	13
Dijkstra.h	13
maze.c	43
dpqueue/driver.c	14
dpqueue/heap.c	15
dpqueue/pqueue.c	16
dpqueue/pqueue.h	17
graph/adjlist.c	18
graph/driver.c	14
graph/Graph.c	22
graph/Graph.h	26
graph/GraphSerializer.c	30
graph/GraphSerializer.h	32
graph/test/test01.c	33
graph/test/test02.c	33
graph/test/test03.c	33
map/driver.c	15
map/hashtable.c	34
map/map.c	36
map/map.h	38
map/vmap.c	40
map/vmap.h	42

Chapter 4

Data Structure Documentation

4.1 `_item` Struct Reference

Data Fields

- void * [data](#)
- double [priority](#)

4.1.1 Field Documentation

4.1.1.1 void * `_item::data`

4.1.1.2 double `_item::priority`

The documentation for this struct was generated from the following files:

- [dpqueue/heap.c](#)
- [dpqueue/pqueue.c](#)

4.2 `_map` Struct Reference

Collaboration diagram for `_map`:

Data Fields

- struct [entry](#) * [data](#)
- size_t [size](#)
- size_t [capacity](#)

4.2.1 Field Documentation

4.2.1.1 `size_t _map::capacity`

4.2.1.2 `struct entry * _map::data`

4.2.1.3 `size_t _map::size`

The documentation for this struct was generated from the following files:

- [map/hashtable.c](#)
- [map/map.c](#)

4.3 _pqueue Struct Reference

Collaboration diagram for _pqueue:

Data Fields

- `struct _item * data`
- `int(* cmp)(void *, void *)`
- `size_t size`
- `size_t capacity`

4.3.1 Field Documentation

4.3.1.1 `size_t _pqueue::capacity`

4.3.1.2 `int(* _pqueue::cmp)(void *, void *)`

4.3.1.3 `struct _item * _pqueue::data`

4.3.1.4 `size_t _pqueue::size`

The documentation for this struct was generated from the following files:

- [dpqueue/heap.c](#)
- [dpqueue/pqueue.c](#)

4.4 _vmap Struct Reference

Collaboration diagram for _vmap:

Data Fields

- struct [entry](#) * [data](#)
- size_t [size](#)
- size_t [capacity](#)

4.4.1 Field Documentation

4.4.1.1 [size_t _vmap::capacity](#)

4.4.1.2 [struct entry* _vmap::data](#)

4.4.1.3 [size_t _vmap::size](#)

The documentation for this struct was generated from the following file:

- [map/vmap.c](#)

4.5 edge_ Struct Reference

Collaboration diagram for [edge_](#):

Data Fields

- double [weight](#)
- struct [node_](#) * [to](#)
- struct [edge_](#) * [next](#)

4.5.1 Field Documentation

4.5.1.1 [struct edge_ * edge_::next](#)

4.5.1.2 [struct node_ * edge_::to](#)

4.5.1.3 [double edge_::weight](#)

The documentation for this struct was generated from the following files:

- [graph/adjlist.c](#)
- [graph/Graph.c](#)

4.6 entry Struct Reference

Collaboration diagram for [entry](#):

Data Fields

- char * [key](#)
- double [value](#)
- struct [entry](#) * [next](#)
- void * [value](#)

4.6.1 Field Documentation

4.6.1.1 char * entry::key

4.6.1.2 struct entry * entry::next

4.6.1.3 void* entry::value

4.6.1.4 double entry::value

The documentation for this struct was generated from the following files:

- map/[hashtable.c](#)
- map/[map.c](#)
- map/[vmap.c](#)

4.7 graph Struct Reference

Collaboration diagram for graph:

Data Fields

- struct [node_](#) * [root](#)

4.7.1 Field Documentation

4.7.1.1 struct node_ * graph::root

The documentation for this struct was generated from the following files:

- graph/[adjlist.c](#)
- graph/[Graph.c](#)

4.8 node_ Struct Reference

Collaboration diagram for node_:

Data Fields

- char * [name](#)
- struct [node_](#) * [next](#)
- struct [edge_](#) * [edges](#)

4.8.1 Field Documentation

4.8.1.1 struct [edge_](#) * [node_::edges](#)

4.8.1.2 char * [node_::name](#)

4.8.1.3 struct [node_](#) * [node_::next](#)

The documentation for this struct was generated from the following files:

- graph/[adjlist.c](#)
- graph/[Graph.c](#)

Chapter 5

File Documentation

5.1 Dijkstra.c File Reference

```
#include "Dijkstra.h"
#include <errno.h>
#include <math.h>
#include <stdio.h>
#include <string.h>
#include "map/map.h"
#include "map/vmap.h"
#include "dpqueue/pqueue.h"
Include dependency graph for Dijkstra.c:
```

5.2 Dijkstra.h File Reference

```
#include <unistd.h>
#include "graph/Graph.h"
Include dependency graph for Dijkstra.h: This graph shows which files directly or indirectly include this file:
```

Functions

- `ssize_t Dijkstra_path` (const `Graph` *g, const char *start, const char *end, char ***path)
Find path between start and end.
- `void Dijkstra_solveMaze` (char **mazeFromFile, char **route, size_t hops)
Changes 2d array of the maze and changes the route to show the solved maze.

5.2.1 Function Documentation

5.2.1.1 `ssize_t Dijkstra_path (const Graph * g, const char * start, const char * end, char *** path)`

Find path between start and end.

Parameters

<i>g</i>	Graph to traverse
<i>start</i>	starting node in graph
<i>end</i>	ending node in graph
<i>path</i>	output parameter which is filled with shortest start-to-end path

Returns

number of nodes in path (negative if error or disconnected)

5.2.1.2 void Dijkstra_solveMaze (char ** *mazeFromFile*, char ** *route*, size_t *hops*)

Changes 2d array of the maze and changes the route to show the solved maze.

Parameters

<i>mazeFromFile</i>	2d array of maze
<i>route</i>	Nodes in graph that lead to end
<i>hops</i>	Number of hops for tracking in loop

5.3 dpqueue/driver.c File Reference

```
#include <stdio.h>
#include <string.h>
#include "pqueue.h"
Include dependency graph for driver.c:
```

Functions

- void [heap_print](#) (const [pqueue](#) *pq)
- int [main](#) (void)

5.3.1 Function Documentation

5.3.1.1 void [heap_print](#) (const [pqueue](#) * *pq*)

5.3.1.2 int [main](#) (void)

5.4 graph/driver.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "Graph.h"
#include "GraphSerializer.h"
Include dependency graph for driver.c:
```


Functions

- int [main](#) (void)

5.4.1 Function Documentation

5.4.1.1 int main (void)

5.5 map/driver.c File Reference

```
#include <stdio.h>
#include "map.h"
Include dependency graph for driver.c:
```

Functions

- void [hashtable_print](#) (map *m)
- int [main](#) (void)

5.5.1 Function Documentation

5.5.1.1 void hashtable_print (map * m)

5.5.1.2 int main (void)

5.6 dpqueue/heap.c File Reference

```
#include "pqueue.h"
#include <math.h>
#include <stdio.h>
#include <string.h>
Include dependency graph for heap.c:
```

Data Structures

- struct [_item](#)
- struct [_pqueue](#)

Functions

- [pqueue * pqueue_create](#) (int(*cmp)(void *, void *))
- [size_t pqueue_size](#) (const [pqueue](#) *pq)
- [bool pqueue_enqueue](#) ([pqueue](#) *pq, void *item, double priority)
- [bool pqueue_reprioritize](#) ([pqueue](#) *pq, void *item, double priority)
- [double pqueue_dequeue](#) ([pqueue](#) *pq, void **item)
- [void * pqueue_search](#) (const [pqueue](#) *pq, void *item)
- [void pqueue_destroy](#) ([pqueue](#) *pq)
- [void heap_print](#) (const [pqueue](#) *pq)

5.6.1 Function Documentation

5.6.1.1 void heap_print (const pqueue * pq)

5.6.1.2 pqueue* pqueue_create (int(*)(void *, void *) cmp)

5.6.1.3 double pqueue_dequeue (pqueue * pq, void ** item)

5.6.1.4 void pqueue_destroy (pqueue * pq)

5.6.1.5 bool pqueue_enqueue (pqueue * pq, void * item, double priority)

5.6.1.6 bool pqueue_reprioritize (pqueue * pq, void * item, double priority)

5.6.1.7 void* pqueue_search (const pqueue * pq, void * item)

5.6.1.8 size_t pqueue_size (const pqueue * pq)

5.7 dpqueue/pqueue.c File Reference

```
#include "pqueue.h"
#include <math.h>
#include <stdio.h>
#include <string.h>
Include dependency graph for pqueue.c:
```

Data Structures

- struct [_item](#)
- struct [_pqueue](#)

Functions

- [pqueue * pqueue_create](#) (int(*cmp)(void *, void *))
- [size_t pqueue_size](#) (const [pqueue](#) *pq)
- [bool pqueue_enqueue](#) ([pqueue](#) *pq, void *item, double priority)
- [bool pqueue_reprioritize](#) ([pqueue](#) *pq, void *item, double priority)
- [double pqueue_dequeue](#) ([pqueue](#) *pq, void **item)
- [void * pqueue_search](#) (const [pqueue](#) *pq, void *item)
- [void pqueue_destroy](#) ([pqueue](#) *pq)
- [void heap_print](#) (const [pqueue](#) *pq)

5.7.1 Function Documentation

5.7.1.1 void heap_print (const pqueue * *pq*)

5.7.1.2 pqueue* pqueue_create (int(*)(void *, void *) *cmp*)

5.7.1.3 double pqueue_dequeue (pqueue * *pq*, void ** *item*)

5.7.1.4 void pqueue_destroy (pqueue * *pq*)

5.7.1.5 bool pqueue_enqueue (pqueue * *pq*, void * *item*, double *priority*)

5.7.1.6 bool pqueue_reprioritize (pqueue * *pq*, void * *item*, double *priority*)

5.7.1.7 void* pqueue_search (const pqueue * *pq*, void * *item*)

5.7.1.8 size_t pqueue_size (const pqueue * *pq*)

5.8 dpqueue/pqueue.h File Reference

```
#include <stdbool.h>
```

```
#include <stdlib.h>
```

Include dependency graph for pqueue.h: This graph shows which files directly or indirectly include this file:

Typedefs

- typedef struct [_pqueue](#) [pqueue](#)

Functions

- [pqueue](#) * [pqueue_create](#) (int(**cmp*)(void *, void *))
- size_t [pqueue_size](#) (const [pqueue](#) **pq*)
- bool [pqueue_enqueue](#) ([pqueue](#) **pq*, void **item*, double *priority*)
- bool [pqueue_reprioritize](#) ([pqueue](#) **pq*, void **item*, double *priority*)
- double [pqueue_dequeue](#) ([pqueue](#) **pq*, void ***item*)
- void * [pqueue_search](#) (const [pqueue](#) **pq*, void **item*)
- void [pqueue_destroy](#) ([pqueue](#) **pq*)

5.8.1 Typedef Documentation

5.8.1.1 typedef struct _pqueue pqueue

5.8.2 Function Documentation

5.8.2.1 pqueue* pqueue_create (int(*) (void *, void *) *cmp*)

5.8.2.2 double pqueue_dequeue (pqueue * *pq*, void ** *item*)

5.8.2.3 void pqueue_destroy (pqueue * *pq*)

5.8.2.4 bool pqueue_enqueue (pqueue * *pq*, void * *item*, double *priority*)

5.8.2.5 bool pqueue_reprioritize (pqueue * *pq*, void * *item*, double *priority*)

5.8.2.6 void* pqueue_search (const pqueue * *pq*, void * *item*)

5.8.2.7 size_t pqueue_size (const pqueue * *pq*)

5.9 graph/adjlist.c File Reference

```
#include "Graph.h"
#include <errno.h>
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
Include dependency graph for adjlist.c:
```

Data Structures

- struct [edge_](#)
- struct [node_](#)
- struct [graph](#)

Macros

- #define [_XOPEN_SOURCE](#) 500

Typedefs

- typedef struct [edge_](#) [edge_](#)
- typedef struct [node_](#) [node_](#)

Functions

- `Graph * Graph_create` (void)
Create an empty graph structure.
- `bool Graph_addNode` (Graph *g, const char *name)
Adds a node to the graph (does not add duplicates)
- `bool Graph_addEdge` (Graph *g, const char *from, const char *to, double weight)
Adds an edge to the graph (does not add duplicates)
- `bool Graph_isAdjacent` (const Graph *g, const char *from, const char *to)
Checks if two nodes are adjacent.
- `ssize_t Graph_getNodes` (const Graph *g, char ***nodes)
provide list of nodes of a graph
- `ssize_t Graph_getNeighbors` (const Graph *g, const char *name, char ***neighbors)
provide list of neighbor's names for a given node
- `double Graph_getEdgeWeight` (const Graph *g, const char *from, const char *to)
Provide edge weight between two nodes.
- `void Graph_deleteNode` (Graph *g, const char *name)
Remove a node from the graph.
- `void Graph_deleteEdge` (Graph *g, const char *from, const char *to)
Remove an edge from the graph.
- `void Graph_print` (const Graph *g)
Prints graph to stdout.
- `void Graph_disassemble` (Graph *g)
Destroy the graph scaffolding without affecting the underlying data.

5.9.1 Macro Definition Documentation

5.9.1.1 `#define _XOPEN_SOURCE 500`

5.9.2 Typedef Documentation

5.9.2.1 `typedef struct edge_ edge_`

5.9.2.2 `typedef struct node_ node_`

5.9.3 Function Documentation

5.9.3.1 `bool Graph_addEdge (Graph * g, const char * from, const char * to, double weight)`

Adds an edge to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>from</i>	Name of source node
<i>to</i>	Name of destination node
<i>weight</i>	Cost of the edge

Returns

true for successful add

5.9.3.2 bool Graph_addNode (Graph * *g*, const char * *name*)

Adds a node to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>name</i>	Name of new node

Returns

true for successful add

5.9.3.3 Graph* Graph_create (void)

Create an empty graph structure.

Returns

the graph structure, or NULL on error

5.9.3.4 void Graph_deleteEdge (Graph * *g*, const char * *from*, const char * *to*)

Remove an edge from the graph.

Parameters

<i>g</i>	Graph to alter
<i>from</i>	Starting node of edge
<i>to</i>	Ending node of edge

5.9.3.5 void Graph_deleteNode (Graph * *g*, const char * *name*)

Remove a node from the graph.

Parameters

<i>g</i>	Graph to alter
<i>name</i>	Name of node to remove

5.9.3.6 void Graph_disassemble (Graph * *g*)

Destroy the graph scaffolding without affecting the underlying data.

Parameters

<i>g</i>	Graph to disassemble
----------	----------------------

5.9.3.7 double Graph_getEdgeWeight (const Graph * *g*, const char * *from*, const char * *to*)

Provide edge weight between two nodes.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Starting node
<i>to</i>	neighbor node

Returns

weight of edge (NAN if edge does not exist)

5.9.3.8 ssize_t Graph_getNeighbors (const Graph * *g*, const char * *name*, char *** *neighbors*)

provide list of neighbor's names for a given node

Parameters

<i>g</i>	Graph to inspect
<i>name</i>	node's name to find neighbors for
<i>neighbors</i>	input parameter to store array of neighbors' names

Returns

number of neighbors found (-1 for error)

5.9.3.9 ssize_t Graph_getNodes (const Graph * *g*, char *** *nodes*)

provide list of nodes of a graph

Parameters

<i>g</i>	Graph to inspect
<i>nodes</i>	input parameter to store array of nodes' names

Returns

number of nodes found (-1 for error)

5.9.3.10 bool Graph_isAdjacent (const Graph * *g*, const char * *from*, const char * *to*)

Checks if two nodes are adjacent.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Name of source node
<i>to</i>	Name of destination node

Returns

True if nodes are adjacent, false otherwise

5.9.3.11 void Graph_print (const Graph * *g*)

Prints graph to stdout.

Parameters

<i>g</i>	Graph to print
----------	----------------

5.10 graph/Graph.c File Reference

```
#include "Graph.h"
#include <errno.h>
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
Include dependency graph for Graph.c:
```

Data Structures

- struct [edge_](#)
- struct [node_](#)
- struct [graph](#)

Macros

- `#define _XOPEN_SOURCE 500`

Typedefs

- typedef struct [edge_](#) [edge_](#)
- typedef struct [node_](#) [node_](#)

Functions

- [Graph](#) * [Graph_create](#) (void)
Create an empty graph structure.
- bool [Graph_addNode](#) ([Graph](#) *g, const char *name)
Adds a node to the graph (does not add duplicates)
- bool [Graph_addEdge](#) ([Graph](#) *g, const char *from, const char *to, double weight)
Adds an edge to the graph (does not add duplicates)
- bool [Graph_isAdjacent](#) (const [Graph](#) *g, const char *from, const char *to)
Checks if two nodes are adjacent.
- ssize_t [Graph_getNodes](#) (const [Graph](#) *g, char ***nodes)
provide list of nodes of a graph
- ssize_t [Graph_getNeighbors](#) (const [Graph](#) *g, const char *name, char ***neighbors)
provide list of neighbor's names for a given node
- double [Graph_getEdgeWeight](#) (const [Graph](#) *g, const char *from, const char *to)
Provide edge weight between two nodes.
- void [Graph_deleteNode](#) ([Graph](#) *g, const char *name)
Remove a node from the graph.
- void [Graph_deleteEdge](#) ([Graph](#) *g, const char *from, const char *to)
Remove an edge from the graph.
- void [Graph_print](#) (const [Graph](#) *g)
Prints graph to stdout.
- void [Graph_disassemble](#) ([Graph](#) *g)
Destroy the graph scaffolding without affecting the underlying data.

5.10.1 Macro Definition Documentation

5.10.1.1 #define _XOPEN_SOURCE 500

5.10.2 Typedef Documentation

5.10.2.1 typedef struct [edge_](#) [edge_](#)

5.10.2.2 typedef struct [node_](#) [node_](#)

5.10.3 Function Documentation

5.10.3.1 bool [Graph_addEdge](#) ([Graph](#) * g, const char * from, const char * to, double weight)

Adds an edge to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>from</i>	Name of source node
<i>to</i>	Name of destination node
<i>weight</i>	Cost of the edge

Returns

true for successful add

5.10.3.2 bool Graph_addNode (Graph * *g*, const char * *name*)

Adds a node to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>name</i>	Name of new node

Returns

true for successful add

5.10.3.3 Graph* Graph_create (void)

Create an empty graph structure.

Returns

the graph structure, or NULL on error

5.10.3.4 void Graph_deleteEdge (Graph * *g*, const char * *from*, const char * *to*)

Remove an edge from the graph.

Parameters

<i>g</i>	Graph to alter
<i>from</i>	Starting node of edge
<i>to</i>	Ending node of edge

5.10.3.5 void Graph_deleteNode (Graph * *g*, const char * *name*)

Remove a node from the graph.

Parameters

<i>g</i>	Graph to alter
<i>name</i>	Name of node to remove

5.10.3.6 void Graph_disassemble (Graph * *g*)

Destroy the graph scaffolding without affecting the underlying data.

Parameters

<i>g</i>	Graph to disassemble
----------	----------------------

5.10.3.7 double Graph_getEdgeWeight (const Graph * *g*, const char * *from*, const char * *to*)

Provide edge weight between two nodes.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Starting node
<i>to</i>	neighbor node

Returns

weight of edge (NAN if edge does not exist)

5.10.3.8 ssize_t Graph_getNeighbors (const Graph * *g*, const char * *name*, char * *neighbors*)**

provide list of neighbor's names for a given node

Parameters

<i>g</i>	Graph to inspect
<i>name</i>	node's name to find neighbors for
<i>neighbors</i>	input parameter to store array of neighbors' names

Returns

number of neighbors found (-1 for error)

5.10.3.9 `ssize_t Graph_getNodes (const Graph * g, char *** nodes)`

provide list of nodes of a graph

Parameters

<i>g</i>	Graph to inspect
<i>nodes</i>	input parameter to store array of nodes' names

Returns

number of nodes found (-1 for error)

5.10.3.10 `bool Graph_isAdjacent (const Graph * g, const char * from, const char * to)`

Checks if two nodes are adjacent.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Name of source node
<i>to</i>	Name of destination node

Returns

True if nodes are adjacent, false otherwise

5.10.3.11 `void Graph_print (const Graph * g)`

Prints graph to stdout.

Parameters

<i>g</i>	Graph to print
----------	----------------

5.11 graph/Graph.h File Reference

```
#include <stdbool.h>
```

```
#include <unistd.h>
```

Include dependency graph for Graph.h: This graph shows which files directly or indirectly include this file:

Typedefs

- typedef struct [graph](#) Graph

Functions

- `Graph * Graph_create` (void)
Create an empty graph structure.
- `bool Graph_addNode` (Graph *g, const char *name)
Adds a node to the graph (does not add duplicates)
- `bool Graph_addEdge` (Graph *g, const char *from, const char *to, double weight)
Adds an edge to the graph (does not add duplicates)
- `bool Graph_isAdjacent` (const Graph *g, const char *from, const char *to)
Checks if two nodes are adjacent.
- `ssize_t Graph_getNodes` (const Graph *g, char ***nodes)
provide list of nodes of a graph
- `ssize_t Graph_getNeighbors` (const Graph *g, const char *name, char ***neighbors)
provide list of neighbor's names for a given node
- `double Graph_getEdgeWeight` (const Graph *g, const char *from, const char *to)
Provide edge weight between two nodes.
- `void Graph_deleteNode` (Graph *g, const char *name)
Remove a node from the graph.
- `void Graph_deleteEdge` (Graph *g, const char *from, const char *to)
Remove an edge from the graph.
- `void Graph_print` (const Graph *g)
Prints graph to stdout.
- `void Graph_disassemble` (Graph *g)
Destroy the graph scaffolding without affecting the underlying data.

5.11.1 Typedef Documentation

5.11.1.1 typedef struct graph Graph

5.11.2 Function Documentation

5.11.2.1 `bool Graph_addEdge (Graph * g, const char * from, const char * to, double weight)`

Adds an edge to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>from</i>	Name of source node
<i>to</i>	Name of destination node
<i>weight</i>	Cost of the edge

Returns

true for successful add

5.11.2.2 `bool Graph_addNode (Graph * g, const char * name)`

Adds a node to the graph (does not add duplicates)

Parameters

<i>g</i>	Graph to modify
<i>name</i>	Name of new node

Returns

true for successful add

5.11.2.3 Graph* Graph_create (void)

Create an empty graph structure.

Returns

the graph structure, or NULL on error

5.11.2.4 void Graph_deleteEdge (Graph * g, const char * from, const char * to)

Remove an edge from the graph.

Parameters

<i>g</i>	Graph to alter
<i>from</i>	Starting node of edge
<i>to</i>	Ending node of edge

5.11.2.5 void Graph_deleteNode (Graph * g, const char * name)

Remove a node from the graph.

Parameters

<i>g</i>	Graph to alter
<i>name</i>	Name of node to remove

5.11.2.6 void Graph_disassemble (Graph * g)

Destroy the graph scaffolding without affecting the underlying data.

Parameters

<i>g</i>	Graph to disassemble
----------	----------------------

5.11.2.7 double Graph_getEdgeWeight (const Graph * *g*, const char * *from*, const char * *to*)

Provide edge weight between two nodes.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Starting node
<i>to</i>	neighbor node

Returns

weight of edge (NAN if edge does not exist)

5.11.2.8 ssize_t Graph_getNeighbors (const Graph * *g*, const char * *name*, char *** *neighbors*)

provide list of neighbor's names for a given node

Parameters

<i>g</i>	Graph to inspect
<i>name</i>	node's name to find neighbors for
<i>neighbors</i>	input parameter to store array of neighbors' names

Returns

number of neighbors found (-1 for error)

5.11.2.9 ssize_t Graph_getNodes (const Graph * *g*, char *** *nodes*)

provide list of nodes of a graph

Parameters

<i>g</i>	Graph to inspect
<i>nodes</i>	input parameter to store array of nodes' names

Returns

number of nodes found (-1 for error)

5.11.2.10 bool Graph_isAdjacent (const Graph * *g*, const char * *from*, const char * *to*)

Checks if two nodes are adjacent.

Parameters

<i>g</i>	Graph to inspect
<i>from</i>	Name of source node
<i>to</i>	Name of destination node

Returns

True if nodes are adjacent, false otherwise

5.11.2.11 void Graph_print (const Graph * g)

Prints graph to stdout.

Parameters

<i>g</i>	Graph to print
----------	----------------

5.12 graph/GraphSerializer.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "Graph.h"
#include "GraphSerializer.h"
Include dependency graph for GraphSerializer.c:
```

Macros

- `#define _GNU_SOURCE`

Functions

- void `GraphSerializer_toStdout` (const `Graph` *g)
Print out serialized version of graph.
- `Graph` * `GraphSerializer_fromFile` (FILE *fp, char ***mazeFromFile, size_t *maxLength, size_t *lineCount, char flags)
Deserializes Graph object from input.
- void `GraphSerializer_fromMaze` (`Graph` **g, char **maze, size_t *maxLength, size_t *lineCount, char flags)
Taking a 2d array will make nodes from each available space.

5.12.1 Macro Definition Documentation

5.12.1.1 #define _GNU_SOURCE

5.12.2 Function Documentation

5.12.2.1 Graph* GraphSerializer_fromFile (FILE * *fp*, char *** *mazeFromFile*, size_t * *maxLineLength*, size_t * *lineCount*, char *flags*)

Deserializes Graph object from input.

Parameters

<i>fp</i>	FILE * to read serialized Graph from
<i>mazeFromFile</i>	char *** to make the map read be available in main
<i>maxLineLength</i>	Tracking for mazeFromFile size (X axis)
<i>lineCount</i>	Tracking for mazeFromFile size (Y axis)
<i>flags</i>	Used to keep track of CLI arguments

Returns

Graph object (NULL on error)

5.12.2.2 void GraphSerializer_fromMaze (Graph ** *g*, char ** *maze*, size_t * *maxLength*, size_t * *lineCount*, char *flags*)

Taking a 2d array will make nodes from each available space.

Parameters

<i>g</i>	Graph ** to modify and produce graph from maze
<i>mazeFromFile</i>	char *** to parse and make the graph
<i>maxLineLength</i>	Tracking for mazeFromFile size (X axis)
<i>lineCount</i>	Tracking for mazeFromFile size (Y axis)
<i>flags</i>	Used to keep track of CLI arguments

5.12.2.3 void GraphSerializer_toStdout (const Graph * *g*)

Print out serialized version of graph.

Parameters

<i>g</i>	Graph object to print
----------	-----------------------

5.13 graph/GraphSerializer.h File Reference

This graph shows which files directly or indirectly include this file:

Functions

- void [GraphSerializer_toStdout](#) (const [Graph](#) *g)
Print out serialized version of graph.
- [Graph](#) * [GraphSerializer_fromFile](#) (FILE *fp, char ***mazeFromFile, size_t *maxLineLength, size_t *lineCount, char flags)
Deserializes Graph object from input.
- void [GraphSerializer_fromMaze](#) ([Graph](#) **g, char **maze, size_t *maxLength, size_t *lineCount, char flags)
Taking a 2d array will make nodes from each available space.

5.13.1 Function Documentation

5.13.1.1 [Graph](#)* [GraphSerializer_fromFile](#) (FILE * *fp*, char *** *mazeFromFile*, size_t * *maxLineLength*, size_t * *lineCount*, char *flags*)

Deserializes Graph object from input.

Parameters

<i>fp</i>	FILE * to read serialized Graph from
<i>mazeFromFile</i>	char *** to make the map read be available in main
<i>maxLineLength</i>	Tracking for mazeFromFile size (X axis)
<i>lineCount</i>	Tracking for mazeFromFile size (Y axis)
<i>flags</i>	Used to keep track of CLI arguments

Returns

Graph object (NULL on error)

5.13.1.2 void [GraphSerializer_fromMaze](#) ([Graph](#) ** *g*, char ** *maze*, size_t * *maxLength*, size_t * *lineCount*, char *flags*)

Taking a 2d array will make nodes from each available space.

Parameters

<i>g</i>	Graph ** to modify and produce graph from maze
<i>mazeFromFile</i>	char *** to parse and make the graph
<i>maxLineLength</i>	Tracking for mazeFromFile size (X axis)
<i>lineCount</i>	Tracking for mazeFromFile size (Y axis)
<i>flags</i>	Used to keep track of CLI arguments

5.13.1.3 void GraphSerializer_toStdout (const Graph * g)

Print out serialized version of graph.

Parameters

<i>g</i>	Graph object to print
----------	-----------------------

5.14 graph/test/test01.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "Graph.h"
#include "GraphSerializer.h"
Include dependency graph for test01.c:
```

Functions

- int [main](#) (void)

5.14.1 Function Documentation

5.14.1.1 int main (void)

5.15 graph/test/test02.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "Graph.h"
#include "GraphSerializer.h"
Include dependency graph for test02.c:
```

Functions

- int [main](#) (void)

5.15.1 Function Documentation

5.15.1.1 int main (void)

5.16 graph/test/test03.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "Graph.h"
#include "GraphSerializer.h"
Include dependency graph for test03.c:
```

Functions

- int [main](#) (void)

5.16.1 Function Documentation

5.16.1.1 int main (void)

5.17 map/hashtable.c File Reference

```
#include "map.h"  
#include <math.h>  
#include <stdint.h>  
#include <stdio.h>  
#include <stdlib.h>  
#include <string.h>  
#include <openssl/md5.h>  
Include dependency graph for hashtable.c:
```

Data Structures

- struct [entry](#)
- struct [_map](#)

Macros

- #define [_XOPEN_SOURCE](#) 500

Functions

- [map * map_create](#) (void)
Creates an empty map structure.
- bool [map_insert](#) ([map](#) *m, const char *key, double value)
Inserts new key and value into map.
- bool [map_exists](#) ([map](#) *m, const char *key)
Checks if key exists in map.
- double [map_lookup](#) ([map](#) *m, const char *key)
Returns Value of specified key.
- void [map_destroy](#) ([map](#) *m)
Breaks down map and frees memory.
- void [hashtable_print](#) ([map](#) *m)

5.17.1 Macro Definition Documentation

5.17.1.1 `#define _XOPEN_SOURCE 500`

5.17.2 Function Documentation

5.17.2.1 `void hashtable_print (map * m)`

5.17.2.2 `map* map_create (void)`

Creates an empty map structure.

Returns

Pointer to new map in memory

5.17.2.3 `void map_destroy (map * m)`

Breaks down map and frees memory.

Parameters

<i>m</i>	Map to destroy
----------	----------------

5.17.2.4 `bool map_exists (map * m, const char * key)`

Checks if key exists in map.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

True if found successfully, False if not found

5.17.2.5 `bool map_insert (map * m, const char * key, double value)`

Inserts new key and value into map.

Parameters

<i>m</i>	Map to insert into
<i>key</i>	Key value to add to map
<i>value</i>	Value for specified key

Returns

True if added successfully, False if failed

5.17.2.6 double map_lookup (map * m, const char * key)

Returns Value of specified key.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

Value at key specified

5.18 map/map.c File Reference

```
#include "map.h"
#include <math.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <openssl/md5.h>
Include dependency graph for map.c:
```

Data Structures

- struct [entry](#)
- struct [_map](#)

Macros

- `#define _XOPEN_SOURCE 500`

Functions

- `map * map_create (void)`
Creates an empty map structure.
- `bool map_insert (map *m, const char *key, double value)`
Inserts new key and value into map.
- `bool map_exists (map *m, const char *key)`
Checks if key exists in map.
- `double map_lookup (map *m, const char *key)`
Returns Value of specified key.
- `void map_destroy (map *m)`
Breaks down map and frees memory.
- `void hashtable_print (map *m)`

5.18.1 Macro Definition Documentation

5.18.1.1 `#define _XOPEN_SOURCE 500`

5.18.2 Function Documentation

5.18.2.1 `void hashtable_print (map * m)`

5.18.2.2 `map* map_create (void)`

Creates an empty map structure.

Returns

Pointer to new map in memory

5.18.2.3 `void map_destroy (map * m)`

Breaks down map and frees memory.

Parameters

<i>m</i>	Map to destroy
----------	----------------

5.18.2.4 `bool map_exists (map * m, const char * key)`

Checks if key exists in map.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

True if found successfully, False if not found

5.18.2.5 `bool map_insert (map * m, const char * key, double value)`

Inserts new key and value into map.

Parameters

<i>m</i>	Map to insert into
<i>key</i>	Key value to add to map
<i>value</i>	Value for specified key

Returns

True if added successfully, False if failed

5.18.2.6 double map_lookup (map * m, const char * key)

Returns Value of specified key.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

Value at key specified

5.19 map/map.h File Reference

```
#include <stdbool.h>
```

Include dependency graph for map.h: This graph shows which files directly or indirectly include this file:

Typedefs

- typedef struct [_map](#) map

Functions

- [map * map_create](#) (void)
Creates an empty map structure.
- bool [map_insert](#) (map *m, const char *key, double value)
Inserts new key and value into map.
- bool [map_exists](#) (map *m, const char *key)
Checks if key exists in map.
- double [map_lookup](#) (map *m, const char *key)
Returns Value of specified key.
- void [map_destroy](#) (map *m)
Breaks down map and frees memory.

5.19.1 Typedef Documentation**5.19.1.1 typedef struct _map map****5.19.2 Function Documentation****5.19.2.1 map* map_create (void)**

Creates an empty map structure.

Returns

Pointer to new map in memory

5.19.2.2 void map_destroy (map * *m*)

Breaks down map and frees memory.

Parameters

<i>m</i>	Map to destroy
----------	----------------

5.19.2.3 bool map_exists (map * *m*, const char * *key*)

Checks if key exists in map.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

True if found successfully, False if not found

5.19.2.4 bool map_insert (map * *m*, const char * *key*, double *value*)

Inserts new key and value into map.

Parameters

<i>m</i>	Map to insert into
<i>key</i>	Key value to add to map
<i>value</i>	Value for specified key

Returns

True if added successfully, False if failed

5.19.2.5 double map_lookup (map * *m*, const char * *key*)

Returns Value of specified key.

Parameters

<i>m</i>	Map to inspect
<i>key</i>	Key value to look for in map

Returns

Value at key specified

5.20 map/vmap.c File Reference

```
#include "vmap.h"
#include <math.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <openssl/md5.h>
Include dependency graph for vmap.c:
```

Data Structures

- struct [entry](#)
- struct [_vmap](#)

Macros

- `#define _XOPEN_SOURCE 500`

Functions

- `vmap * vmap_create (void)`
Creates an empty vmap structure.
- `bool vmap_insert (vmap *m, const char *key, void *value)`
Inserts new key and value into vmap.
- `bool vmap_exists (vmap *m, const char *key)`
Checks if key exists in vmap.
- `void * vmap_lookup (vmap *m, const char *key)`
Returns Value of specified key.
- `void vmap_destroy (vmap *m)`
Breaks down vmap and frees memory.

5.20.1 Macro Definition Documentation

5.20.1.1 `#define _XOPEN_SOURCE 500`

5.20.2 Function Documentation

5.20.2.1 `vmap* vmap_create (void)`

Creates an empty vmap structure.

Returns

Pointer to new vmap in memory

5.20.2.2 `void vmap_destroy (vmap * m)`

Breaks down vmap and frees memory.

Parameters

<i>m</i>	VMap to destroy
----------	-----------------

5.20.2.3 `bool vmap_exists (vmap * m, const char * key)`

Checks if key exists in vmap.

Parameters

<i>m</i>	VMap to inspect
<i>key</i>	Key value to look for in vmap

Returns

True if found successfully, False if not found

5.20.2.4 `bool vmap_insert (vmap * m, const char * key, void * value)`

Inserts new key and value into vmap.

Parameters

<i>m</i>	VMap to insert into
<i>key</i>	Key value to add to vmap
<i>value</i>	Value for specified key

Returns

True if added successfully, False if failed

5.20.2.5 `void* vmap_lookup (vmap * m, const char * key)`

Returns Value of specified key.

Parameters

<i>m</i>	VMap to inspect
<i>key</i>	Key value to look for in vmap

Returns

Value at key specified

5.21 map/vmap.h File Reference

```
#include <stdbool.h>
```

Include dependency graph for `vmap.h`: This graph shows which files directly or indirectly include this file:

Typedefs

- typedef struct `_vmap` `vmap`

Functions

- `vmap * vmap_create` (void)
Creates an empty vmap structure.
- bool `vmap_insert` (`vmap *m`, const char *key, void *value)
Inserts new key and value into vmap.
- bool `vmap_exists` (`vmap *m`, const char *key)
Checks if key exists in vmap.
- void * `vmap_lookup` (`vmap *m`, const char *key)
Returns Value of specified key.
- void `vmap_destroy` (`vmap *m`)
Breaks down vmap and frees memory.

5.21.1 Typedef Documentation

5.21.1.1 typedef struct `_vmap` `vmap`

5.21.2 Function Documentation

5.21.2.1 `vmap* vmap_create (void)`

Creates an empty vmap structure.

Returns

Pointer to new vmap in memory

5.21.2.2 `void vmap_destroy (vmap * m)`

Breaks down vmap and frees memory.

Parameters

<i>m</i>	VMap to destroy
----------	-----------------

5.21.2.3 bool vmap_exists (vmap * *m*, const char * *key*)

Checks if key exists in vmap.

Parameters

<i>m</i>	VMap to inspect
<i>key</i>	Key value to look for in vmap

Returns

True if found successfully, False if not found

5.21.2.4 bool vmap_insert (vmap * *m*, const char * *key*, void * *value*)

Inserts new key and value into vmap.

Parameters

<i>m</i>	VMap to insert into
<i>key</i>	Key value to add to vmap
<i>value</i>	Value for specified key

Returns

True if added successfully, False if failed

5.21.2.5 void* vmap_lookup (vmap * *m*, const char * *key*)

Returns Value of specified key.

Parameters

<i>m</i>	VMap to inspect
<i>key</i>	Key value to look for in vmap

Returns

Value at key specified

5.22 maze.c File Reference

```
#include <ctype.h>
```

```
#include <time.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "Dijkstra.h"
#include "graph/Graph.h"
#include "graph/GraphSerializer.h"
```

Include dependency graph for maze.c:

Functions

- void [Maze_generate](#) (char ***customMaze, size_t maxLineLength, size_t lineCount)
Generates 2d array of a maze.
- int [main](#) (int argc, char *argv[])

5.22.1 Function Documentation

5.22.1.1 int main (int argc, char * argv[])

5.22.1.2 void Maze_generate (char *** customMaze, size_t maxLineLength, size_t lineCount)

Generates 2d array of a maze.

Parameters

<i>customMaze</i>	char *** to modify into a maze
<i>maxLineLength</i>	Size passed in on CLI
<i>lineCount</i>	Size passed in on CLI

5.23 README.md File Reference

5.24 tests/door-water.txt File Reference

5.25 tests/door.txt File Reference

5.26 tests/map01.txt File Reference

5.27 tests/map02.txt File Reference

5.28 tests/map03.txt File Reference

5.29 tests/map04.txt File Reference

5.30 tests/map05.txt File Reference

5.31 tests/water.txt File Reference

Index

- `_GNU_SOURCE`
 - `GraphSerializer.c`, [31](#)
 - `_XOPEN_SOURCE`
 - `adjlist.c`, [19](#)
 - `Graph.c`, [23](#)
 - `hashtable.c`, [35](#)
 - `map.c`, [37](#)
 - `vmap.c`, [40](#)
 - `_item`, [7](#)
 - `data`, [7](#)
 - `priority`, [7](#)
 - `_map`, [7](#)
 - `capacity`, [8](#)
 - `data`, [8](#)
 - `size`, [8](#)
 - `_pqueue`, [8](#)
 - `capacity`, [8](#)
 - `cmp`, [8](#)
 - `data`, [8](#)
 - `size`, [8](#)
 - `_vmap`, [8](#)
 - `capacity`, [9](#)
 - `data`, [9](#)
 - `size`, [9](#)
- `adjlist.c`
 - `_XOPEN_SOURCE`, [19](#)
 - `edge_`, [19](#)
 - `Graph_addEdge`, [19](#)
 - `Graph_addNode`, [20](#)
 - `Graph_create`, [20](#)
 - `Graph_deleteEdge`, [20](#)
 - `Graph_deleteNode`, [20](#)
 - `Graph_disassemble`, [20](#)
 - `Graph_getEdgeWeight`, [21](#)
 - `Graph_getNeighbors`, [21](#)
 - `Graph_getNodes`, [21](#)
 - `Graph_isAdjacent`, [22](#)
 - `Graph_print`, [22](#)
 - `node_`, [19](#)
- `capacity`
 - `_map`, [8](#)
 - `_pqueue`, [8](#)
 - `_vmap`, [9](#)
- `cmp`
 - `_pqueue`, [8](#)
- `data`
 - `_item`, [7](#)
- `_map`, [8](#)
- `_pqueue`, [8](#)
- `_vmap`, [9](#)
- `Dijkstra.c`, [13](#)
- `Dijkstra.h`, [13](#)
 - `Dijkstra_path`, [13](#)
 - `Dijkstra_solveMaze`, [14](#)
- `Dijkstra_path`
 - `Dijkstra.h`, [13](#)
- `Dijkstra_solveMaze`
 - `Dijkstra.h`, [14](#)
- `dpqueue/driver.c`, [14](#)
 - `heap_print`, [14](#)
 - `main`, [14](#)
- `dpqueue/heap.c`, [15](#)
- `dpqueue/pqueue.c`, [16](#)
- `dpqueue/pqueue.h`, [17](#)
- `edge_`, [9](#)
 - `adjlist.c`, [19](#)
 - `Graph.c`, [23](#)
 - `next`, [9](#)
 - `to`, [9](#)
 - `weight`, [9](#)
- `edges`
 - `node_`, [11](#)
- `entry`, [9](#)
 - `key`, [10](#)
 - `next`, [10](#)
 - `value`, [10](#)
- `Graph`
 - `Graph.h`, [27](#)
- `graph`, [10](#)
 - `root`, [10](#)
- `Graph.c`
 - `_XOPEN_SOURCE`, [23](#)
 - `edge_`, [23](#)
 - `Graph_addEdge`, [23](#)
 - `Graph_addNode`, [24](#)
 - `Graph_create`, [24](#)
 - `Graph_deleteEdge`, [24](#)
 - `Graph_deleteNode`, [24](#)
 - `Graph_disassemble`, [25](#)
 - `Graph_getEdgeWeight`, [25](#)
 - `Graph_getNeighbors`, [25](#)
 - `Graph_getNodes`, [25](#)
 - `Graph_isAdjacent`, [26](#)
 - `Graph_print`, [26](#)
 - `node_`, [23](#)

- Graph.h
 - Graph, [27](#)
 - Graph_addEdge, [27](#)
 - Graph_addNode, [27](#)
 - Graph_create, [28](#)
 - Graph_deleteEdge, [28](#)
 - Graph_deleteNode, [28](#)
 - Graph_disassemble, [28](#)
 - Graph_getEdgeWeight, [29](#)
 - Graph_getNeighbors, [29](#)
 - Graph_getNodes, [29](#)
 - Graph_isAdjacent, [29](#)
 - Graph_print, [30](#)
- graph/Graph.c, [22](#)
- graph/Graph.h, [26](#)
- graph/GraphSerializer.c, [30](#)
- graph/GraphSerializer.h, [32](#)
- graph/adjlist.c, [18](#)
- graph/driver.c, [14](#)
 - main, [15](#)
- graph/test/test01.c, [33](#)
- graph/test/test02.c, [33](#)
- graph/test/test03.c, [33](#)
- Graph_addEdge
 - adjlist.c, [19](#)
 - Graph.c, [23](#)
 - Graph.h, [27](#)
- Graph_addNode
 - adjlist.c, [20](#)
 - Graph.c, [24](#)
 - Graph.h, [27](#)
- Graph_create
 - adjlist.c, [20](#)
 - Graph.c, [24](#)
 - Graph.h, [28](#)
- Graph_deleteEdge
 - adjlist.c, [20](#)
 - Graph.c, [24](#)
 - Graph.h, [28](#)
- Graph_deleteNode
 - adjlist.c, [20](#)
 - Graph.c, [24](#)
 - Graph.h, [28](#)
- Graph_disassemble
 - adjlist.c, [20](#)
 - Graph.c, [25](#)
 - Graph.h, [28](#)
- Graph_getEdgeWeight
 - adjlist.c, [21](#)
 - Graph.c, [25](#)
 - Graph.h, [29](#)
- Graph_getNeighbors
 - adjlist.c, [21](#)
 - Graph.c, [25](#)
 - Graph.h, [29](#)
- Graph_getNodes
 - adjlist.c, [21](#)
 - Graph.c, [25](#)
- Graph.h, [29](#)
- Graph_isAdjacent
 - adjlist.c, [22](#)
 - Graph.c, [26](#)
 - Graph.h, [29](#)
- Graph_print
 - adjlist.c, [22](#)
 - Graph.c, [26](#)
 - Graph.h, [30](#)
- GraphSerializer.c
 - _GNU_SOURCE, [31](#)
 - GraphSerializer_fromFile, [31](#)
 - GraphSerializer_fromMaze, [31](#)
 - GraphSerializer_toStdout, [31](#)
- GraphSerializer.h
 - GraphSerializer_fromFile, [32](#)
 - GraphSerializer_fromMaze, [32](#)
 - GraphSerializer_toStdout, [32](#)
- GraphSerializer_fromFile
 - GraphSerializer.c, [31](#)
 - GraphSerializer.h, [32](#)
- GraphSerializer_fromMaze
 - GraphSerializer.c, [31](#)
 - GraphSerializer.h, [32](#)
- GraphSerializer_toStdout
 - GraphSerializer.c, [31](#)
 - GraphSerializer.h, [32](#)
- hashtable.c
 - _XOPEN_SOURCE, [35](#)
 - hashtable_print, [35](#)
 - map_create, [35](#)
 - map_destroy, [35](#)
 - map_exists, [35](#)
 - map_insert, [35](#)
 - map_lookup, [36](#)
- hashtable_print
 - hashtable.c, [35](#)
 - map.c, [37](#)
 - map/driver.c, [15](#)
- heap.c
 - heap_print, [16](#)
 - pqueue_create, [16](#)
 - pqueue_dequeue, [16](#)
 - pqueue_destroy, [16](#)
 - pqueue_enqueue, [16](#)
 - pqueue_reprioritize, [16](#)
 - pqueue_search, [16](#)
 - pqueue_size, [16](#)
- heap_print
 - dpqueue/driver.c, [14](#)
 - heap.c, [16](#)
 - pqueue.c, [17](#)
- key
 - entry, [10](#)
- main
 - dpqueue/driver.c, [14](#)

- graph/driver.c, 15
- map/driver.c, 15
- maze.c, 44
- test01.c, 33
- test02.c, 33
- test03.c, 34
- map
 - map.h, 38
- map.c
 - _XOPEN_SOURCE, 37
 - hashtable_print, 37
 - map_create, 37
 - map_destroy, 37
 - map_exists, 37
 - map_insert, 37
 - map_lookup, 38
- map.h
 - map, 38
 - map_create, 38
 - map_destroy, 38
 - map_exists, 39
 - map_insert, 39
 - map_lookup, 39
- map/driver.c, 15
 - hashtable_print, 15
 - main, 15
- map/hashtable.c, 34
- map/map.c, 36
- map/map.h, 38
- map/vmap.c, 40
- map/vmap.h, 42
- map_create
 - hashtable.c, 35
 - map.c, 37
 - map.h, 38
- map_destroy
 - hashtable.c, 35
 - map.c, 37
 - map.h, 38
- map_exists
 - hashtable.c, 35
 - map.c, 37
 - map.h, 39
- map_insert
 - hashtable.c, 35
 - map.c, 37
 - map.h, 39
- map_lookup
 - hashtable.c, 36
 - map.c, 38
 - map.h, 39
- maze.c, 43
 - main, 44
 - Maze_generate, 44
- Maze_generate
 - maze.c, 44
- name
 - node_, 11
- next
 - edge_, 9
 - entry, 10
 - node_, 11
- node_, 10
 - adjlist.c, 19
 - edges, 11
 - Graph.c, 23
 - name, 11
 - next, 11
- pqueue
 - pqueue.h, 18
- pqueue.c
 - heap_print, 17
 - pqueue_create, 17
 - pqueue_dequeue, 17
 - pqueue_destroy, 17
 - pqueue_enqueue, 17
 - pqueue_reprioritize, 17
 - pqueue_search, 17
 - pqueue_size, 17
- pqueue.h
 - pqueue, 18
 - pqueue_create, 18
 - pqueue_dequeue, 18
 - pqueue_destroy, 18
 - pqueue_enqueue, 18
 - pqueue_reprioritize, 18
 - pqueue_search, 18
 - pqueue_size, 18
- pqueue_create
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_dequeue
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_destroy
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_enqueue
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_reprioritize
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_search
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18
- pqueue_size
 - heap.c, 16
 - pqueue.c, 17
 - pqueue.h, 18

- priority
 - [_item](#), 7
- [README.md](#), 44
- root
 - [graph](#), 10
- size
 - [_map](#), 8
 - [_pqueue](#), 8
 - [_vmap](#), 9
- [test01.c](#)
 - [main](#), 33
- [test02.c](#)
 - [main](#), 33
- [test03.c](#)
 - [main](#), 34
- [tests/door-water.txt](#), 44
- [tests/door.txt](#), 44
- [tests/map01.txt](#), 44
- [tests/map02.txt](#), 44
- [tests/map03.txt](#), 44
- [tests/map04.txt](#), 45
- [tests/map05.txt](#), 45
- [tests/water.txt](#), 45
- to
 - [edge_](#), 9
- value
 - [entry](#), 10
- [vmap](#)
 - [vmap.h](#), 42
- [vmap.c](#)
 - [_XOPEN_SOURCE](#), 40
 - [vmap_create](#), 40
 - [vmap_destroy](#), 40
 - [vmap_exists](#), 41
 - [vmap_insert](#), 41
 - [vmap_lookup](#), 41
- [vmap.h](#)
 - [vmap](#), 42
 - [vmap_create](#), 42
 - [vmap_destroy](#), 42
 - [vmap_exists](#), 42
 - [vmap_insert](#), 43
 - [vmap_lookup](#), 43
- [vmap_create](#)
 - [vmap.c](#), 40
 - [vmap.h](#), 42
- [vmap_destroy](#)
 - [vmap.c](#), 40
 - [vmap.h](#), 42
- [vmap_exists](#)
 - [vmap.c](#), 41
 - [vmap.h](#), 42
- [vmap_insert](#)
 - [vmap.c](#), 41
 - [vmap.h](#), 43
- [vmap_lookup](#)
 - [vmap.c](#), 41
 - [vmap.h](#), 43
- weight
 - [edge_](#), 9