Autonomous Car

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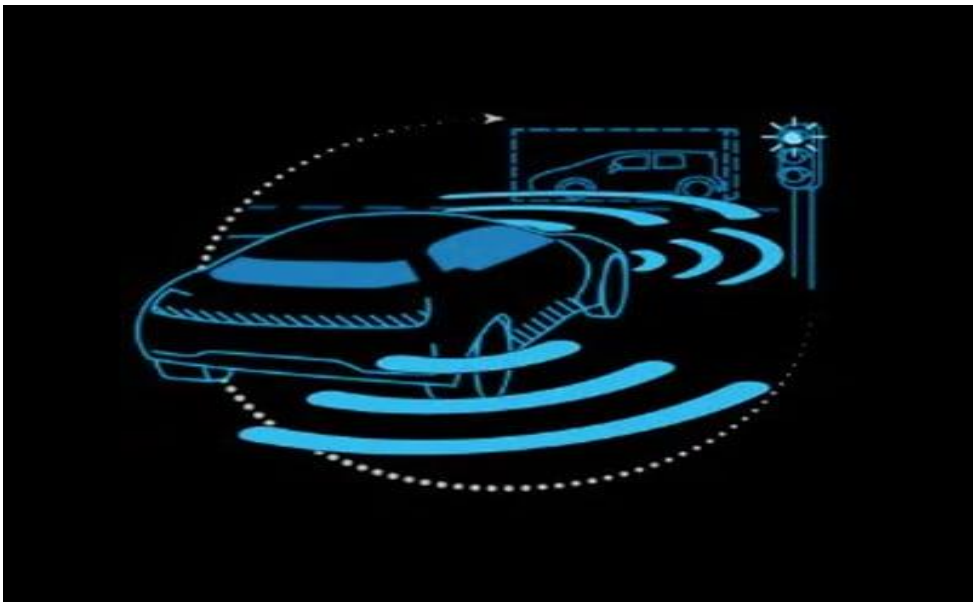
Autonomous Car



System Description

- This project aims to implement a self-driving Car that can avoid the obstacles with fast response.

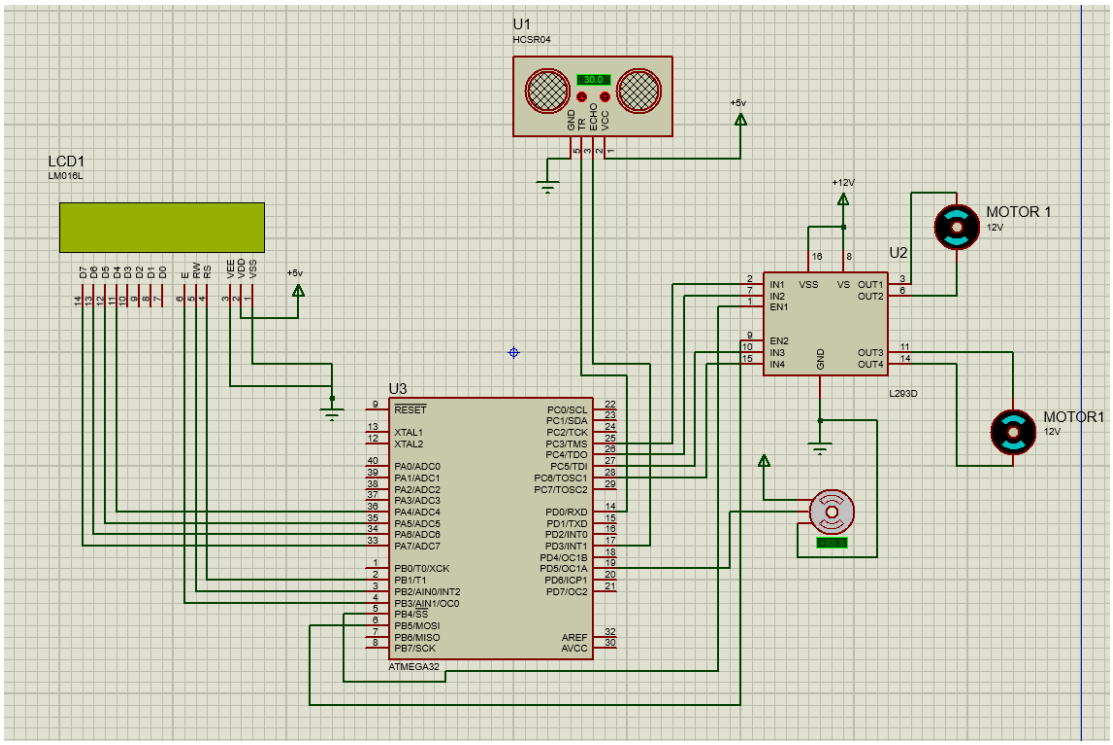
System Design

- **The system hardware is designed of**

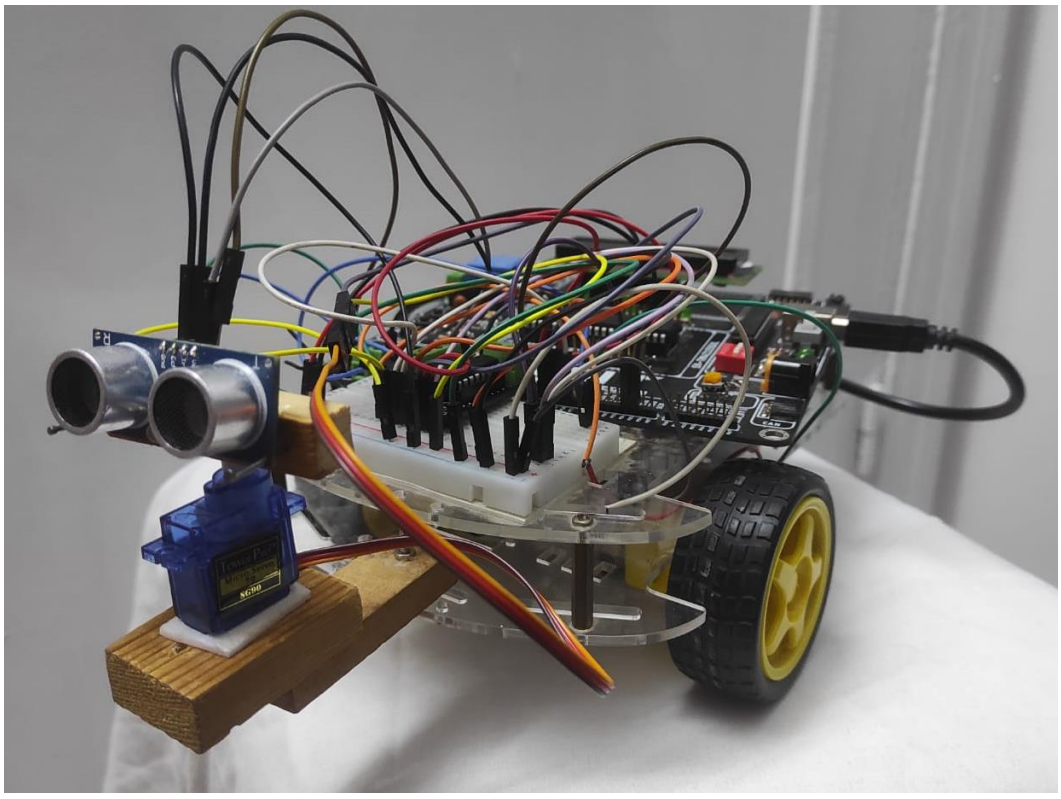
- Microcontroller in this case (Atmega 32A)
  - **Used peripherals**
    1. Timers
    2. Interrupt (internal, external)

- Ultrasonic sensor (HCSR04)
- Two DC motors
- Lcd (LM016L)
- Servo motor (SG90)
- H bridge (L293D)
- Power bank to charge the microcontroller
- Lithium batteries to charge the motors

Proteus simulation:



Hardware Implantation:



System Flowchart