



# Step Size Selection in Frank-Wolfe Method

Paper Review and Replication

Higher School of Economics

## **Motivation and Problem:** Compare different step size selection methods for FW method

This project aims to explore, evaluate and conduct numerical comparison of the efficiency of step selection strategies in the Frank-Wolfe method on different problems with different dimensions and condition numbers. It can solve problems of the form  $\min_{x \in Q} f(x)$ ,

We consider four strategies for step size selection and compare corresponding Frank-Wolfe method performance on both real and synthetic data with different properties and constraints on the solution.

As other gradient-based methods, the FW algorithm depends on a step size parameter gamma. The following step size selection approaches were considered:

# Proposed methods for compare

- Predefined Decreased (Trivial)

$$\gamma^k = \frac{2}{k+2}$$

- Demyanov-Rubinov

$$\gamma^k = \min \left( \frac{g^k}{L \|d^k\|^2}, 1 \right)$$

- Exact Line-search

$$\gamma^k = \arg \min_{\gamma \in [0,1]} f(x^k + \gamma d^k)$$

- Armijo method

$$f(x^k + \gamma^k d^k) \leq f(x^k) + \sigma \gamma^k \nabla f(x^k)^T d^k$$

# Frank-Wolfe Algorithm

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**Algorithm 1** Frank-Wolfe algorithm

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**Input:** initial guess  $x_0$ , gap tolerance  $\delta > 0$   
**for**  $k = 0, 1, \dots$  **do**  
     $s^k \in \arg \max_{s \in Q} \langle -\nabla f(x^k), s \rangle$   
     $d^k = s^k - x^k$   
     $g^k = \langle -\nabla f(x^k), d^k \rangle$   
    **if**  $g^k < \delta$  **then**  
        return  $x^k$   
    **end if**  
    Set step size  $\gamma^k$  by the certain selection strategy  
     $x^{k+1} = x^k + \gamma^k d^k$   
**end for**  
return  $x^k$

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**Algorithm 2** Frank-Wolfe algorithm with backtracking line-search

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**Input:** initial guess  $x_0$ , gap tolerance  $\delta > 0$ , backtracking line-search parameters  $\tau > 1$ ,  $\eta \leq 1$ , initial guess for  $M^{-1}$ .  
**for**  $k = 0, 1, \dots$  **do**  
     $s^k \in \arg \max_{s \in Q} \langle -\nabla f(x^k), s \rangle$   
     $d^k = s^k - x^k$   
     $g^k = \langle -\nabla f(x^k), d^k \rangle$   
     $M^k = \eta M^{k-1}$   
     $\gamma^k = \min(\frac{g^k}{M^k \|d^k\|^2}, 1)$   
    **while**  $f(x^k + \gamma^k d^k) > Q^k(\gamma^k, M^k)$  **do**  
         $M^k = \tau M^k$   
    **end while**  
     $x^{k+1} = x^k + \gamma^k d^k$   
**end for**  
return  $x^k$

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$$Q^k(\gamma^k, M^k) = f(x^k) - \gamma^k g^k + \frac{(\gamma^k)^2 M^k}{2} \|d^k\|^2, \quad (9)$$

# Experiments: **Datasets**

1. **UCI Mushrooms** (binary classification dataset, contains descriptions of mushrooms (poisonous/edible), 8124 objects, 22 features)
2. **UCI Gisette** (binary classification dataset, contains engineered features of handwritten digits, 13500 objects, 5000 features)
3. **UCI Covertypes** (binary classification dataset, contains cartographic variables, 581012 objects, 54 features)
4. **Synthetic normal** (binary classification dataset, generated from scipy package, 5000 objects, 50 features)
5. **Synthetic ill-conditioned** (binary classification dataset, generated from scipy package, 5000 objects, 1024 features)
6. **Synthetic high-dimensional** (binary classification dataset, ill-conditioned, 5000 objects, 50 features)
7. **Rosenbrock function** 
$$f(x) = \sum_{i=1}^{n-1} (100(x_{i+1} - x_i^2)^2 + (1 - x_i)^2)$$

# Experiments: Setup and constraints

## Constraints

For constraint sets on the desired solution we considered I1 and I2 balls centered at 0, of radiuses  $R = 10, 100, 500$

## Setup

All the datasets were used without features changes, except instances labels were transformed into 1 and -1 values for positive and negative objects respectively. All the datasets were split on the train and test parts in proportion 8/2. The standard logistic regression objective was considered for the optimization convergence and performance criterion:

$$f(X, Y, w) = \sum_{i=1}^n \ell(w^T x_i, y_i), \quad (11)$$

$$\ell(z, y) = \ln(1 + e^{-yz}), \quad (12)$$

$x_1, \dots, x_n \in \mathbb{R}^d$  - data objects features,  $y_1, \dots, y_n \in \{-1, 1\}$   
- corresponding labels,  $w \in \mathbb{R}^d$  - logistic regression models weights.

# Mushrooms + synthetic results

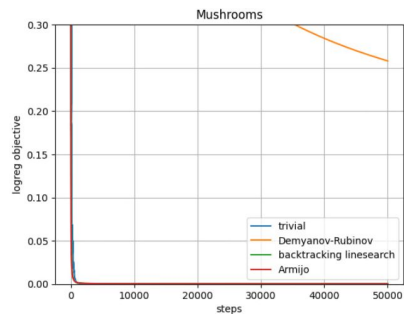


Figure 1. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Mushrooms dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

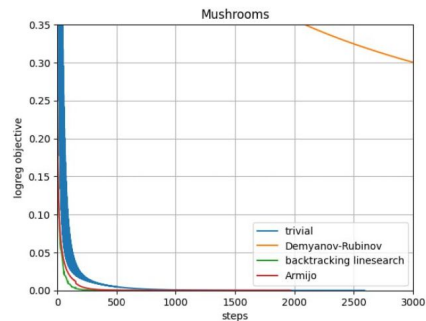


Figure 3. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Mushrooms dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$

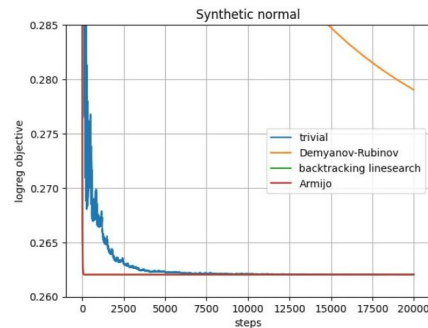


Figure 13. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, synthetic normal dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

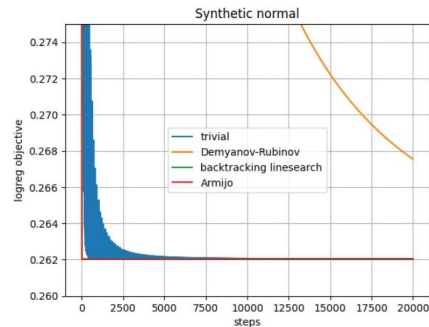


Figure 15. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, synthetic normal dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$

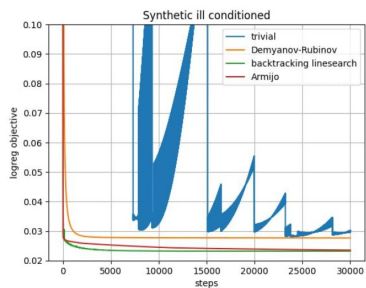


Figure 21. Values of convergence criterion (logreg objective) by iterations number for different Frank-Wolfe method step size values, synthetic ill-conditioned dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

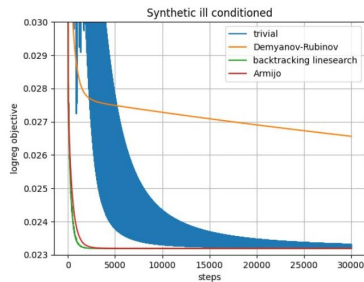


Figure 23. Values of convergence criterion (logreg objective) by iterations number for different Frank-Wolfe method step size values, synthetic ill-conditioned dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$

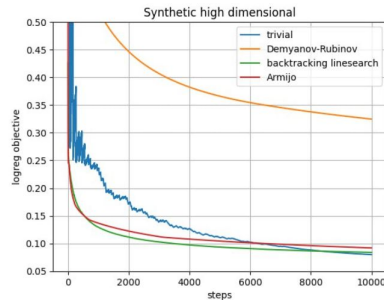


Figure 17. Values of convergence criterion (logreg objective) by iterations number for different Frank-Wolfe method step size values, synthetic high-dimensional dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

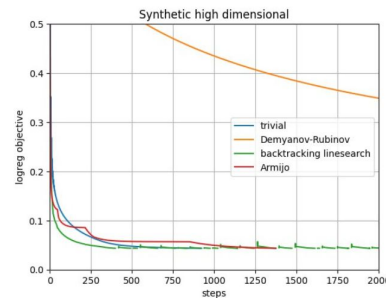


Figure 19. Values of convergence criterion (logreg objective) by iterations number for different Frank-Wolfe method step size values, synthetic high-dimensional dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$

# Gisette + Covtype

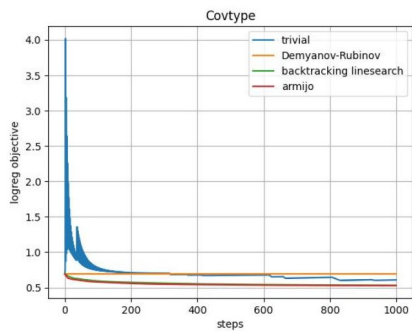


Figure 9. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Covtype dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

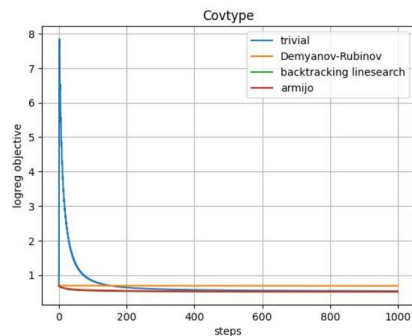


Figure 11. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Covtype dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$

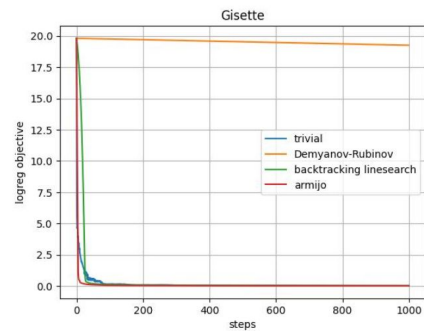


Figure 5. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Gisette dataset, constraint on the  $\ell_1$  ball of radius  $R = 100$

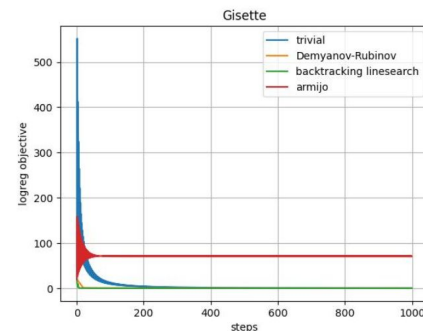


Figure 7. Values of convergence criterion (logreg objective) by iteration number for different Frank-Wolfe method step size values, Gisette dataset, constraint on the  $\ell_2$  ball of radius  $R = 100$



# Rosenbrock Results

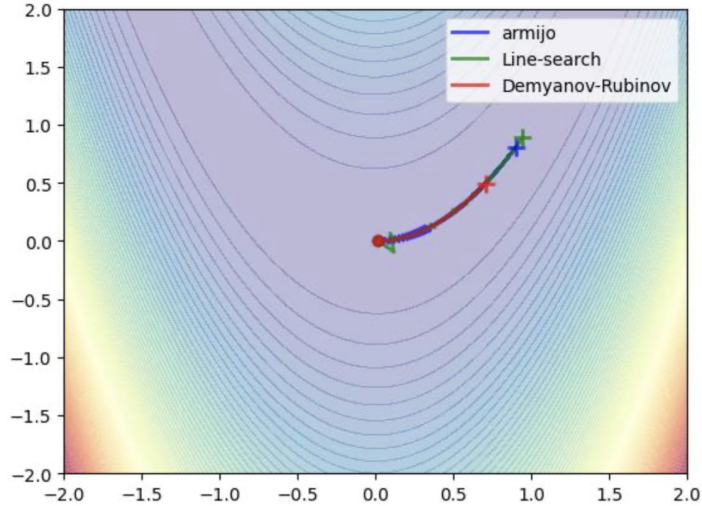


Figure 24. Landscape of convergence for Rosenbrock function for different Frank-Wolfe method step size values, constraint on the  $\ell_2$  ball of radius  $R = 100$

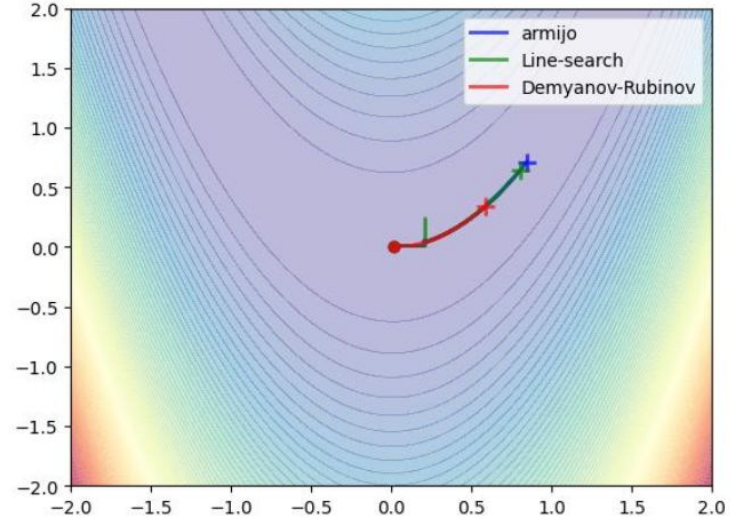


Figure 25. Landscape of convergence for Rosenbrock function for different Frank-Wolfe method step size values, constraint on the  $\ell_1$  ball of radius  $R = 100$

# Conclusion

- Backtracking line search has the best performance
- Armijo has the same performance
- Demyanov Rubinov method sometimes even worse than trivial, but on datasets with low  $L$ -Lipschitz and low features amount
- High-dimensional dataset leads to unstable convergence
- Functions with complex landscape leads to the bad performance with the trivial approach

**Our GitHub:** [github.com/MarioAuditore/frank\\_wolfe\\_step\\_selection](https://github.com/MarioAuditore/frank_wolfe_step_selection)



## Our Team



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Core algorithm development,  
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Experiments



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Theory Research,  
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