COMPUTER & ROBOT VISION · ARTIFICIAL INTELLIGENCE

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### Education

#### **University of Milano Bicocca**

Milan (MI). Italy

M.S. IN COMPUTER SCIENCE (GRADE: 110/110 CUM LAUDE)

Sept. 2021 - March 2024

• Thesis title: Self-Supervised Learning And Model Adaptation For Facial Attribute Classification

- **Project**: Developed an advanced framework using Self-Supervised Learning and Model Adaptation to enhance facial attribute classification, achieving high accuracy on diverse datasets.
- Keywords: Facial Attribute Classification, MAAD-Face Dataset, CelebA Dataset, Self-Supervised Learning, DINOv2, Low-Rank Adaptation (LoRA), Parameter-efficient Model Adaptation for Vision Transformers (PEViT), Dataset Quantization (DQ)

University of Calabria Arcavacata (CS), Italy

B.S. IN COMPUTER SCIENCE (GRADE: 108/110)

Sept. 2018 - Sept. 2021

- Thesis title: Dalla visione all'azione: moduli di ragionamento automatico full-stack
- **Project**: Developed "BrainyBot", a robotic system capable of autonomously solving complex mobile games like Candy Crush Saga and Ball Sort Puzzle through touch screen interaction.
- Keywords: Answer Set Programming (DLV2), Object & Image Recognition, Knowledge Representation, Sense-Think-Act paradigm

I.I.S. Silvio Lopiano Cetraro (CS), Italy

SCIENTIFIC HIGH SCHOOL DIPLOMA Sept. 2013 - July 2018

## Skills\_\_\_\_

**Programming Languages** Python, Java, C++, C, MATLAB, Perl, Bash

Frameworks & Libraries

TensorFlow, PyTorch, Keras, Scikit-learn, OpenCV, Matplotlib, Pandas, Numpy, Seaborn, Hugging Face

Transformers, Haystack, LangChain, Plotly, EmbASP

Computer Vision Adaptive Algorithms (contrast, noise reduction, artifact removal), Image Quality Assessment, Object & Image

Recognition (Traditional & Deep Learning), Multimedia Indexing & Retrieval

**Robot Localization & Mapping**Bayesian Filtering (Gaussian Filters, Nonparametric Filters), Robot Motion & Perception, SLAM (EKF, FAST,

Graph-Based)

Text Classification & Sentiment Analysis, Named-Entity Recognition (CRFs, neural extensions), Topic

**Natural Language Processing** Extraction (LDA, Neural Topic Models), Text Summarization, Text Generation, Question Answering

(Retriever-Reader Architectures)

**Answer Set Programming** DLV2

**Optimization** LINGO, OPL-CPLEX

**Technologies & Tools** Linux, Git, GNU Tools, MPI, OpenMP, Android Studio, Unity3D, Jupyter Notebooks

Virtualization Docker, VirtualBox

**Automation & CI/CD** GitLab CI/CD, GitHub Actions, Make, Maven, Gradle, CMake, systemd

**Databases** MariaDB, SQLite, MySQL, PostgreSQL, MongoDB, SQL, Neo4J

**Documentation Tools** MEX, AsciiDoc, Markdown

Languages English, Italian

# Research Publications \_\_\_\_\_

# From Vision to Execution: Enabling Knowledge Representation and Reasoning in Hybrid Intelligent Robots Playing Mobile Games

KR2023

Rhodes, Greece | September 2-8, 2023

Co-Author

- The paper explores the automation of interactions with touch surfaces, presenting a delta robot designed to engage in match-3 games and ball-sorting puzzles on mobile phones. This robot employs a vision module to identify objects by color and shape, and utilizes declarative models for decision-making based on game rules and strategies. By integrating AI techniques such as vision processing and answer set programming, the system simplifies motion control through its delta robot configuration. The authors detail the components of their robotic application, demonstrating its capabilities through implementations of various games. They suggest that this approach facilitates innovative combinations of knowledge representation and robotics, offering a controlled environment for experimenting with hybrid reasoning methods without the burden of technical implementation.
- Keywords: Applications of KR in robotics, Applications of KR Integrating symbolic and sub-symbolic approaches, KR related tools and systems.

## **Honors & Awards**

**DOMESTIC AWARDS** 

July 2021 Best Students 2020 Award, Graduation Day

University of Calabria