

COMPUTER & ROBOT VISION · ARTIFICIAL INTELLIGENCE

📳 (+39) 3791944042 | 💌 contact@marioavolio.it | 😭 marioavolio.it | 🖸 MarioAvolio | 🤝 MarioAvolio | 🛅 MarioAvolio

Education

University of Milano Bicocca

Milan (MI), Italy

M.S. IN COMPUTER SCIENCE (GRADE: 110/110 CUM LAUDE)

Sept. 2021 - March 2024

- Thesis title: Self-Supervised Learning And Model Adaptation For Facial Attribute Classification.
- Keywords: Facial Attribute Classification, MAAD-Face Dataset, CelebA Dataset, Self-Supervised Learning, DINOv2, Low-Rank Adaptation (LoRA), Parameter-efficient Model Adaptation for Vision Transformers (PEViT), Dataset Quantization (DQ).

University of Calabria Arcavacata (CS), Italy

B.S. IN COMPUTER SCIENCE (GRADE: 108/110)

Sept. 2018 - Sept. 2021

• Thesis title: From Vision to Action: Full-Stack Automated Reasoning Modules

• Keywords: Answer Set Programming (ASP), vision module, knowledge representation

Skills____

Programming Languages Python, Java, C++, C, MATLAB, Perl

Multilingual Named-Entity Recognition (CRFs, neural extensions), Topic Extraction (LDA, Neural Topic

Natural Language Processing Models), Question Answering (Retriever-Reader Architecture), Text Classification & Sentiment Analysis, Text

Summarization, Text Generation

Robot Localization & MappingBayesian filtering (Gaussian Filters, Nonparametric Filters), Robot Motion & Perception, SLAM (EKF, FAST,

GRAPH)

Computer VisionAdaptive algorithms (contrast, noise reduction, artifact removal), Image quality assessment, Object/image

recognition and classification (traditional and deep learning), Indexing and retrieval in multimedia systems

Frameworks/Libraries

TensorFlow, PyTorch, Keras, Scikit-learn, OpenCV, Matplotlib, Pandas, Numpy, Seaborn, Hugging Face

Transformers, Haystack, Plotly

Answer Set Programming DLV2

Optimization LINGO, OPL-CPLEX

Technologies/Tools Linux, Git, GNU tools, MPI, OpenMP, Android Studio, Unity3D, Jupyter Notebooks

Virtualization Docker, VirtualBox

Automation GitLab CI/CD, GitHub Actions, Make, Maven, Gradle, CMake, systemd

Databases MariaDB, SQLite, MySQL, PostgreSQL, MongoDB, SQL, Neo4J

Documentation MFX, AsciiDoc, Markdown

Languages English, Italian

Honors & Awards_

DOMESTIC AWARDS

July 2021 Best Students 2020 Award, Graduation Day

University of Calabria

Research Publications

From Vision to Execution: Enabling Knowledge Representation and Reasoning in Hybrid Intelligent Robots Playing Mobile Games

KR2023

Co-Author

Rhodes, Greece | September 2-8, 2023

- The paper explores the automation of interactions with touch surfaces, presenting a delta robot designed to engage in match-3 games and ball-sorting puzzles on mobile phones. This robot employs a vision module to identify objects by color and shape, and utilizes declarative models for decision-making based on game rules and strategies. By integrating AI techniques such as vision processing and answer set programming, the system simplifies motion control through its delta robot configuration. The authors detail the components of their robotic application, demonstrating its capabilities through implementations of various games. They suggest that this approach facilitates innovative combinations of knowledge representation and robotics, offering a controlled environment for experimenting with hybrid reasoning methods without the burden of technical implementation.
- Keywords: Applications of KR in robotics, Applications of KR Integrating symbolic and sub-symbolic approaches, KR related tools and systems.

An iterative abstraction and decision making pipeline for answer set programming in robots playing mobile games (submitted)

ICLP 2024

Co-Author

Dallas, Texas | 11-17 October, 2024

• Keywords: Applications of KR in robotics Applications of KR Integrating symbolic and sub-symbolic approaches KR related tools and systems.