

Mario Avolio

COMPUTER & ROBOT VISION · ARTIFICIAL INTELLIGENCE

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Education

University of Milano Bicocca

Milan (MI), Italy

M.S. IN COMPUTER SCIENCE (GRADE: 110/110 CUM LAUDE)

Sept. 2021 - March 2024

- Thesis title: *Self-Supervised Learning And Model Adaptation For Facial Attribute Classification*.
- Keywords: Facial Attribute Classification, MAAD-Face Dataset, CelebA Dataset, Self-Supervised Learning, DINOv2, Low-Rank Adaptation (LoRA), Parameter-efficient Model Adaptation for Vision Transformers (PEViT), Dataset Quantization (DQ).

University of Calabria

Arcavacata (CS), Italy

B.S. IN COMPUTER SCIENCE (GRADE: 108/110)

Sept. 2018 - Sept. 2021

- Thesis title: *Dalla visione all'azione: moduli di ragionamento automatico full-stack*
- Keywords: Answer Set Programming (ASP), DLV2, OpenCV, Knowledge Representation, Sense-Think-Act paradigm

I.I.S. Silvio Lopiano

Cetraro (CS), Italy

SCIENTIFIC HIGH SCHOOL DIPLOMA

Sept. 2013 - July 2018

Skills

Programming Languages

Python, Java, C++, C, MATLAB, Perl

Frameworks/Libraries

TensorFlow, PyTorch, Keras, Scikit-learn, OpenCV, Matplotlib, Pandas, Numpy, Seaborn, Hugging Face Transformers, Haystack, Plotly, EmbASP

Natural Language Processing

Text Classification & Sentiment Analysis, Multilingual Named-Entity Recognition (CRFs, neural extensions), Topic Extraction (LDA, Neural Topic Models), Text Summarization, Text Generation, Question Answering (Retriever-Reader Architecture)

Robot Localization & Mapping

Bayesian filtering (Gaussian Filters, Nonparametric Filters), Robot Motion & Perception, SLAM (EKF, FAST, GRAPH)

Computer Vision

Adaptive algorithms (contrast, noise reduction, artifact removal), Image quality assessment, Object/image recognition and classification (traditional and deep learning), Indexing and retrieval in multimedia systems

Answer Set Programming

DLV2

Optimization

LINGO, OPL-CPLEX

Technologies/Tools

Linux, Git, GNU tools, MPI, OpenMP, Android Studio, Unity3D, Jupyter Notebooks

Virtualization

Docker, VirtualBox

Automation

GitLab CI/CD, GitHub Actions, Make, Maven, Gradle, CMake, systemd

Databases

MariaDB, SQLite, MySQL, PostgreSQL, MongoDB, SQL, Neo4J

Documentation

TEX, AsciiDoc, Markdown

Languages

English, Italian

Honors & Awards

DOMESTIC AWARDS

July 2021 **Best Students 2020 Award**, Graduation Day

University of
Calabria

Research Publications

From Vision to Execution: Enabling Knowledge Representation and Reasoning in Hybrid Intelligent Robots Playing Mobile Games

KR2023

Co-AUTHOR

Rhodes, Greece | September 2-8, 2023

- The paper explores the automation of interactions with touch surfaces, presenting a delta robot designed to engage in match-3 games and ball-sorting puzzles on mobile phones. This robot employs a vision module to identify objects by color and shape, and utilizes declarative models for decision-making based on game rules and strategies. By integrating AI techniques such as vision processing and answer set programming, the system simplifies motion control through its delta robot configuration. The authors detail the components of their robotic application, demonstrating its capabilities through implementations of various games. They suggest that this approach facilitates innovative combinations of knowledge representation and robotics, offering a controlled environment for experimenting with hybrid reasoning methods without the burden of technical implementation.
- Keywords: Applications of KR in robotics, Applications of KR Integrating symbolic and sub-symbolic approaches, KR related tools and systems.

An iterative abstraction and decision making pipeline for answer set programming in robots playing mobile games (submitted)

ICLP 2024

Co-AUTHOR

Dallas, Texas | 11-17 October, 2024

- An extension of the paper *"From Vision to Execution: Enabling Knowledge Representation and Reasoning in Hybrid Intelligent Robots Playing Mobile Games"*, providing a brief overview of the robot's components, its runtime and design-time workflows, and its interactions with mobile phone games.
- Keywords: Applications of KR in robotics, Applications of KR Integrating symbolic and sub-symbolic approaches, KR related tools and systems.