

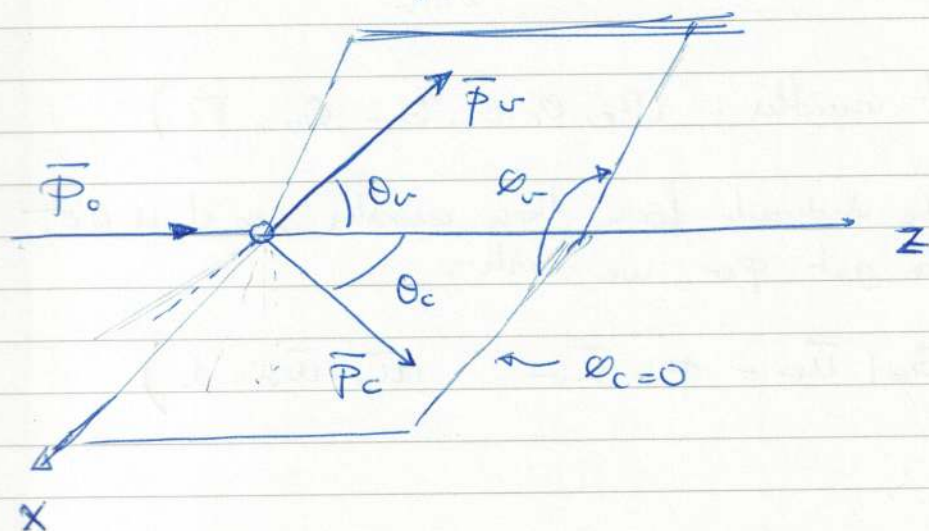
# Kinematics for 2-body breakup with core/target excitations

Relevant momenta:

$$a(c+r) + t \rightarrow c + r + t$$

$$\vec{p}_0 + \vec{p}_t^{(a)} \rightarrow \vec{p}_c + \vec{p}_r + \vec{p}_t$$

For lab frame:  $\vec{p}_t^{(a)} = 0$



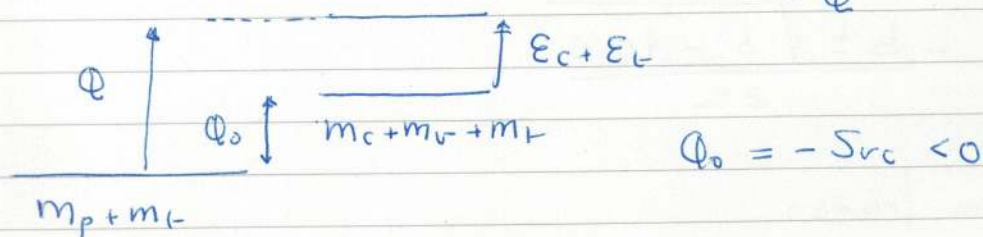
Following Tostevin '01,  $\bar{x}\bar{z}$  plane defined by  $\vec{p}_0 - \vec{p}_c$  vectors so, in this frame,  $\theta_c = 0$  and  $\phi_r$  is then the angle between the  $\vec{p}_0 - \vec{p}_r$  plane and the  $\vec{p}_0 - \vec{p}_c$  plane.

Energy conservation: (LAB)

$$T_p + m_p + m_t = T_c + E_c + T_r + T_t + E_t + m_r + m_c + m_t$$

$$T_p = T_c + T_r + T_t + \underbrace{(m_r + m_c + m_p)}_{S_{rc} = -Q_0} + E_c + E_t$$

$-Q$



Using the momentum and energy conservation equations, we can eliminate the dependence on the target variables:

$$\vec{p}_t = \vec{p}_0 - \vec{p}_c - \vec{p}_r \equiv \vec{p}_f - \vec{p}_r$$

$$T_t = \frac{p_t^2}{2m_t} = \frac{1}{2m_t} [\vec{p}_f - \vec{p}_r]^2 = \frac{1}{2m_t} [p_f^2 + p_r^2 - 2\vec{p}_f \cdot \vec{p}_r]$$

$$\frac{1}{2m_t} [p_f^2 + p_r^2 - 2\vec{p}_f \cdot \vec{p}_r] + T_c + \frac{p_r^2}{2m_r} - Q = T_p \quad (I)$$

Independent variables:  $(\theta_c, \theta_c=0, \theta_r, \phi_r, p_c)$

$p_r$  can be deduced from these variables, so it is NOT independent. To get  $p_r$ , we write:

$$\vec{p}_r \equiv |\vec{p}_r| \vec{u}_r = p_r \vec{u}_r \quad (\vec{u}_r \cdot \vec{u}_r = 1)$$

From (I):

$$\frac{1}{2} \left( \frac{1}{m_r} + \frac{1}{m_t} \right) p_r^2 - \frac{\vec{p}_f \cdot \vec{u}_r}{m_t} p_r + \frac{p_f^2}{2m_t} - T_p + T_c - Q = 0$$

Define:

$$\begin{cases} a = \frac{1}{2} \left( \frac{1}{m_r} + \frac{1}{m_t} \right) \\ b = -\frac{1}{m_t} \vec{p}_f \cdot \vec{u}_r \\ c = \frac{p_f^2}{2m_t} - T_p + T_c - Q = \frac{p_f^2}{2m_t} + \frac{p_c^2}{2m_c} - (T_p + Q) \end{cases}$$

$$p_r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

N.b.: In chosen frame:

$$\vec{p}_0 = \begin{pmatrix} 0 \\ 0 \\ p_0 \end{pmatrix} \quad \vec{p}_c = p_c \begin{pmatrix} \sin \theta_c \\ 0 \\ \cos \theta_c \end{pmatrix} \quad \vec{p}_r = p_r \begin{pmatrix} \sin \theta_r \cos \phi_r \\ \sin \theta_r \sin \phi_r \\ \cos \theta_r \end{pmatrix}$$