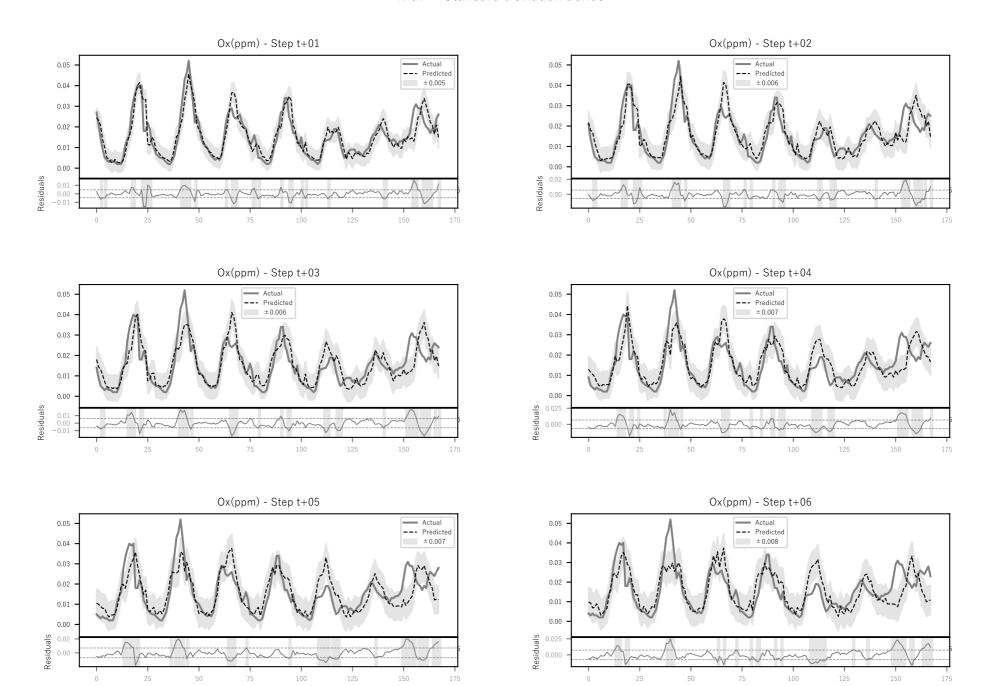
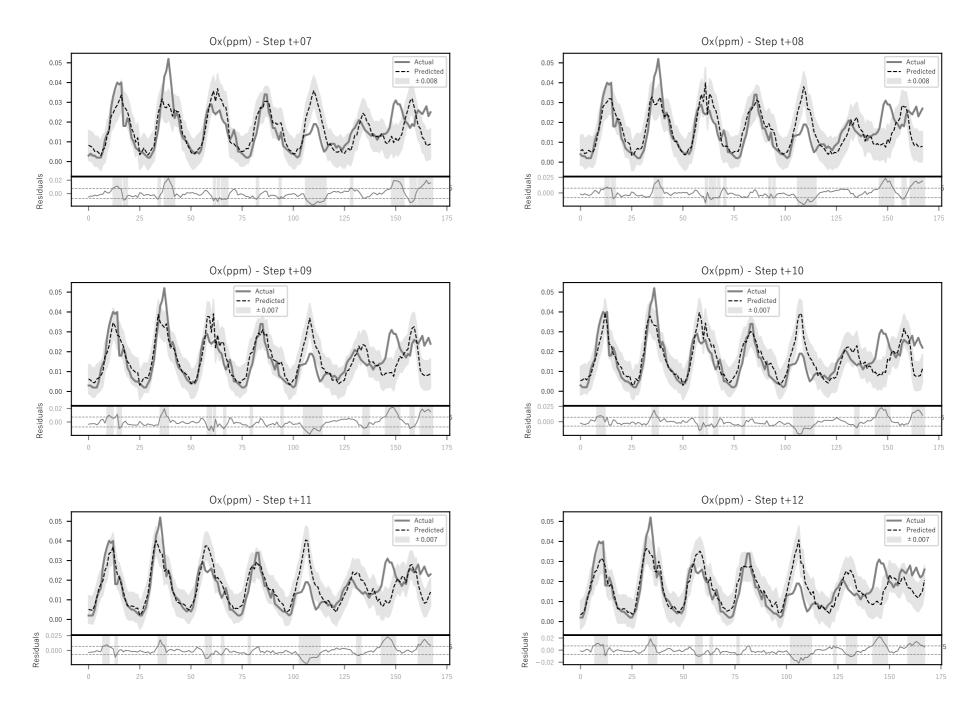
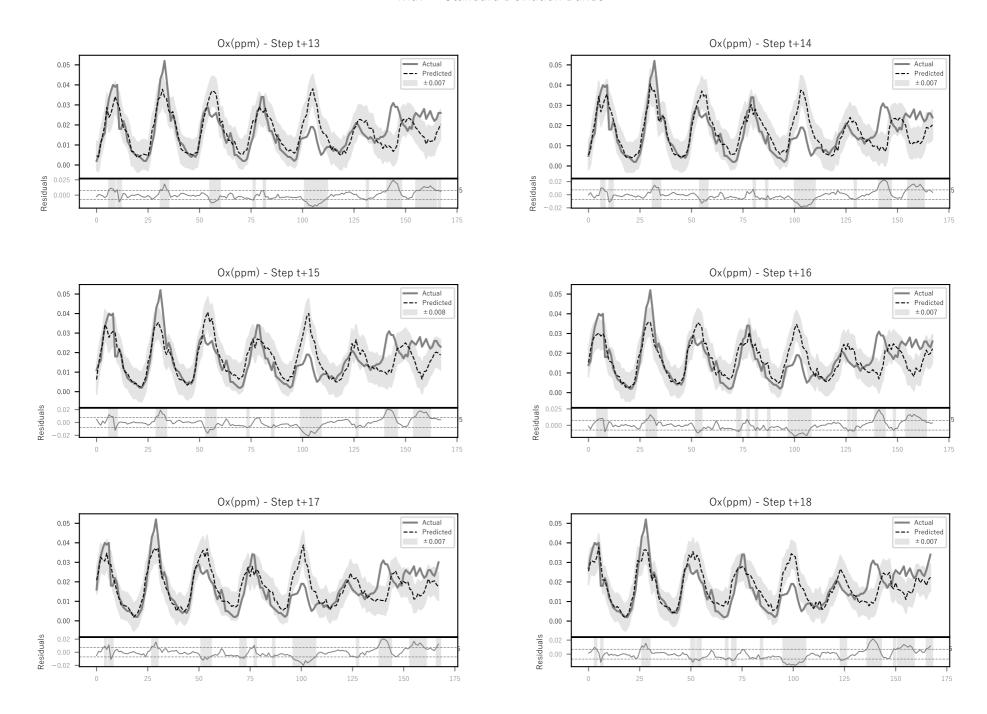
朝生田 - オキシダント予測の分析

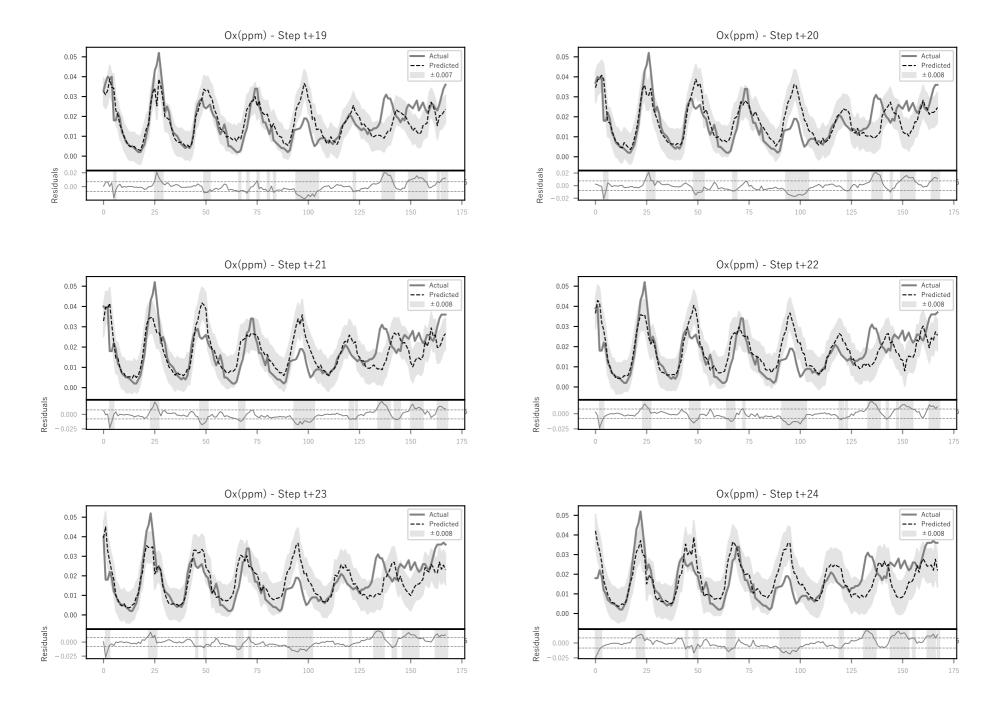
Model Parameters: Prefecture code: 38 Station code: 38201530 Station name: 朝生田 Target item: Ox(ppm) Number of data points in the train set: 13403 Number of data points in the test set: 5745 Forecast horizon (hours): 24 Model: LightGBM Objective: regression Boosting type: gbdt Number of estimators: 400 Learning rate: 0.04 Elapsed time: 0 min 33 sec Number of used features: 140 Features: NO(ppm), NO2(ppm), U, V, Ox(ppm)_lag1 Ox(ppm) lag2, Ox(ppm) lag3, Ox(ppm) lag4, Ox(ppm) lag5, Ox(ppm) lag6 Ox(ppm)_lag7, Ox(ppm)_lag8, Ox(ppm)_lag9, Ox(ppm)_lag10, Ox(ppm)_lag11 Ox(ppm) lag12, Ox(ppm) lag13, Ox(ppm) lag14, Ox(ppm) lag15, Ox(ppm) lag16 Ox(ppm)_lag17, Ox(ppm)_lag18, Ox(ppm)_lag19, Ox(ppm)_lag20, Ox(ppm)_lag21 Ox(ppm)_lag22, Ox(ppm)_lag23, NO(ppm)_lag1, NO(ppm)_lag2, NO(ppm)_lag3 NO(ppm)_lag4, NO(ppm)_lag5, NO(ppm)_lag6, NO(ppm)_lag7, NO(ppm)_lag8 NO(ppm)_lag9, NO(ppm)_lag10, NO(ppm)_lag11, NO(ppm)_lag12, NO(ppm)_lag13 NO(ppm)_lag14, NO(ppm)_lag15, NO(ppm)_lag16, NO(ppm)_lag17, NO(ppm)_lag18 NO(ppm)_lag19, NO(ppm)_lag20, NO(ppm)_lag21, NO(ppm)_lag22, NO(ppm)_lag23 NO2(ppm)_lag1, NO2(ppm)_lag2, NO2(ppm)_lag3, NO2(ppm)_lag4, NO2(ppm)_lag5 NO2(ppm) lag6, NO2(ppm) lag7, NO2(ppm) lag8, NO2(ppm) lag9, NO2(ppm) lag10 NO2(ppm)_lag11, NO2(ppm)_lag12, NO2(ppm)_lag13, NO2(ppm)_lag14, NO2(ppm)_lag15 NO2(ppm)_lag16, NO2(ppm)_lag17, NO2(ppm)_lag18, NO2(ppm)_lag19, NO2(ppm)_lag20 NO2(ppm)_lag21, NO2(ppm)_lag22, NO2(ppm)_lag23, U_lag1, U_lag2 U_lag3, U_lag4, U_lag5, U_lag6, U_lag7 U_lag8, U_lag9, U_lag10, U_lag11, U_lag12 U_lag13, U_lag14, U_lag15, U_lag11, U_lag12 U_lag13, U_lag14, U_lag20, U_lag20, U_lag21 U_lag28, U_lag19, U_lag20, U_lag21, U_lag22 U_lag23, V_lag1, V_lag2, V_lag3, V_lag4 V_lag5, V_lag6, V_lag7, V_lag8, V_lag9 V_lag10, V_lag11, V_lag12, V_lag13, V_lag14 V_lag15, V_lag16, V_lag17, V_lag18, V_lag19 V_lag20, V_lag21, V_lag22, V_lag23, Ox(ppm)_roll_mean_3 Ox(ppm)_roll_std_6, NO(ppm)_roll_mean_3, NO(ppm)_roll_std_6, NO2(ppm)_roll_mean_3, NO2(ppm)_roll_std_6 U_roll_mean_3, U_roll_std_6, V_roll_mean_3, V_roll_std_6, Ox(ppm)_diff_1
Ox(ppm)_diff_2, Ox(ppm)_diff_3, NO(ppm)_diff_3, NO2(ppm)_diff_3, U_diff_3 V_diff_3, hour_sin, hour_cos, dayofweek, is_weekend Metrics per Forecast Step: Ox(ppm)_t+01 - R²: 0.8629, MAE: 0.0040, RMSE: 0.0056 Ox(ppm)_t+02 - R²: 0.7927, MAE: 0.0051, RMSE: 0.0068 Ox(ppm) t+03 - R2: 0.7349, MAE: 0.0058, RMSE: 0.0077 Ox(ppm)_t+04 - R²: 0.6698, MAE: 0.0066, RMSE: 0.0086 Ox(ppm)_t+05 - R²: 0.6085, MAE: 0.0072, RMSE: 0.0094 Ox(ppm) t+06 - R²: 0.5476, MAE: 0.0078, RMSE: 0.0101 Ox(ppm)_t+07 - R²: 0.5241, MAE: 0.0079, RMSE: 0.0103 Ox(ppm) t+08 - R²: 0.4966, MAE: 0.0081, RMSE: 0.0106 Ox(ppm)_t+09 - R²: 0.4567, MAE: 0.0085, RMSE: 0.0110 Ox(ppm)_t+10 - R²: 0.4625, MAE: 0.0084, RMSE: 0.0110 Ox(ppm)_t+11 - R²: 0.4467, MAE: 0.0085, RMSE: 0.0111 Ox(ppm)_t+12 - R²: 0.4515, MAE: 0.0084, RMSE: 0.0111 Ox(ppm)_t+13 - R²: 0.4466, MAE: 0.0085, RMSE: 0.0111 Ox(ppm)_t+14 - R²: 0.4390, MAE: 0.0086, RMSE: 0.0112 Ox(ppm) t+15 - R²: 0.4344, MAE: 0.0086, RMSE: 0.0113 Ox(ppm)_t+16 - R²: 0.4295, MAE: 0.0087, RMSE: 0.0113 Ox(ppm)_t+17 - R²: 0.4254, MAE: 0.0087, RMSE: 0.0114 Ox(ppm)_t+18 - R²: 0.4215, MAE: 0.0087, RMSE: 0.0114 Ox(ppm)_t+19 - R²: 0.4164, MAE: 0.0088, RMSE: 0.0115 Ox(ppm) t+20 - R²: 0.4052, MAE: 0.0089, RMSE: 0.0116 Ox(ppm)_t+21 - R²: 0.3930, MAE: 0.0089, RMSE: 0.0117 Ox(ppm)_t+22 - R2: 0.3912, MAE: 0.0089, RMSE: 0.0117 Ox(ppm) t+23 - R²: 0.3815, MAE: 0.0090, RMSE: 0.0118

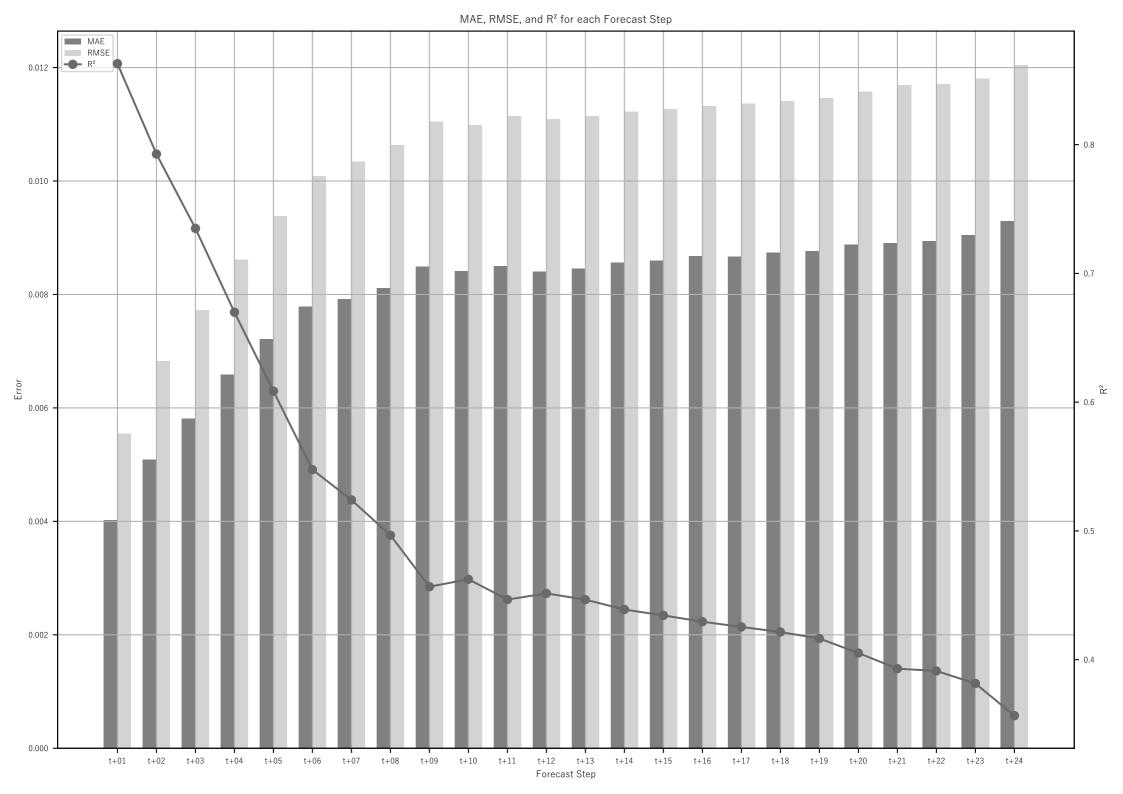
Ox(ppm)_t+24 - R²: 0.3565, MAE: 0.0093, RMSE: 0.0120











Normalized Feature Importance (per feature) 1.0 $Ox(ppm)_lag1 - 1.00$ 1.00 1.00 1.00 1.00 | 1.00 | 1.00 1.00 1.00 0.92 0.71 0.71 | 0.70 0.63 0.34 0.16 0.17 0.17 0.57 | 0.78 | 0.76 0.60 0.57 | 0.72 dayofweek - 0.00 0.06 0.05 0.04 0.08 0.14 0.23 0.34 0.71 0.82 0.81 1.00 0.89 0.95 0.93 1.00 1.00 1.00 1.00 1.00 1.00 1.00 0.8 1.00 1.00 0.59 | 0.71 Normalized Importance (per feature) V_roll_std_6 - 0.14 0.16 0.20 0.23 0.16 0.26 0.23 0.32 0.42 0.63 0.89 hour_sin - 0.12 0.15 0.23 0.32 0.51 0.63 0.64 0.79 | 1.00 | 1.00 1.00 | 1.00 0.00 0.00 0.00 0.00 0.00 0.21 0.68 0.64 0.43 Ox(ppm) roll std 6 - 0.14 0.11 0.09 0.11 0.12 0.22 0.12 0.16 0.31 0.56 0.40 0.41 0.54 0.95 1.00 0.99 0.96 hour $\cos - 0.43$ 0.32 | 0.25 | 0.21 | 0.32 | 0.28 | 0.00 | 0.00 | 0.00 | 0.10 | 0.17 0.36 0.00 0.00 0.00 0.00 0.37 0.46 0.33 0.57 | 0.74 0.65 0.79 0.82 NO(ppm) roll std 6 - 0.10 0.12 0.10 0.04 0.01 0.00 0.00 0.00 0.23 0.35 0.36 0.28 0.78 0.29 - 0.2 U_roll_std_6 - 0.10 0.15 0.06 0.00 0.08 0.17 0.20 0.27 0.37 0.18 0.00 0.19 0.14 0.43 0.17 0.43 $Ox(ppm)_roll_mean_3 - 0.03$ 0.00 0.00 0.06 0.06 0.17 0.04 0.12 0.27 0.00 0.16 0.18 0.16 0.00 0.37 0.25 - 0.0 Ox(ppm)_t+10 t+20 Dx(ppm)_t+04 0x(ppm)_t+12 Ox(ppm)_t+ Forecast Step Normalized Feature Importance (per step) 1.0 $Ox(ppm)_lag1 - 1.00$ 0.85 0.82 0.72 0.35 | 0.23 | 0.22 | 0.22 | 0.18 | 0.16 | 0.16 | 0.15 | 0.09 | 0.05 | 0.09 | 0.00 | 0.12 | 0.27 | 0.30 dayofweek - 0.00 0.20 0.25 0.28 0.40 0.42 0.68 0.63 0.71 0.70 0.77 0.72 0.74 0.76 0.83 0.78 0.80 0.88 0.94 0.95 1.00 - 0.8 0.56 0.93 0.72 0.64 0.99 0.89 V_roll_std_6 - 0.00 0.19 0.32 0.66 0.65 1.00 0.77 Normalized Importance (per step) hour_sin **-** 0.27 0.38 0.72 0.94 1.00 0.87 0.89 0.92 0.97 0.91 0.83 | 0.81 0.61 0.31 0.00 0.11 0.27 0.34 Ox(ppm) roll std 6 - 0.00 0.03 0.05 0.29 0.52 0.69 0.42 0.29 0.41 0.76 0.63 0.82 0.88 0.85 0.77 0.88 0.83 0.95 1.00 0.89 0.87 Feature 0.70 0.64 hour_cos - 0.97 1.00 0.91 0.80 0.72 0.74 0.66 0.86 0.95 0.95 0.88 0.22 0.12 0.27 0.39 0.63 0.27 0.00 0.10 0.23 NO2(ppm)_roll_std_6 - 0.00 0.03 0.12 0.33 0.33 0.73 0.83 0.79 0.79 0.80 0.90 1.00 0.93 0.77 0.86 0.71 0.79 0.82 1.00 0.92 0.79 0.72 0.74 0.74 0.77 NO(ppm)_roll_std_6 - 0.00 0.19 0.24 0.18 0.26 0.13 0.23 0.02 0.32 0.30 0.74 0.62 0.71 0.68 - 0.2 0.94 $U_roll_std_6 - 0.00$ 0.21 0.08 0.63 | 0.79 | 0.89 0.88 1.00 0.96 0.69 1.00 1.00 0.74 0.93 0.71 0.80 0.95 0.57 1.00 0.95 0.82 Ox(ppm) roll mean 3 - 0.00 0.08 0.23 0.43 0.86 0.95 0.93 - 0.0 10 t+15 16 Ox(ppm)_t+12 0x(ppm)_t+14 Ox(ppm)_

Target