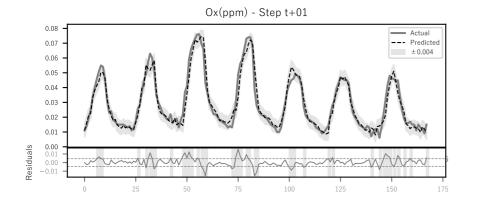
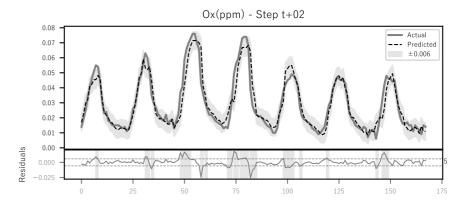
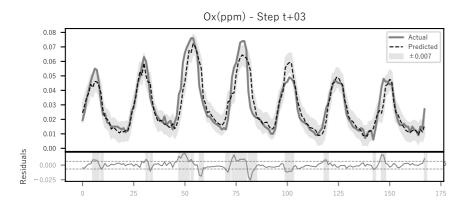
### 西条 - オキシダント予測の分析

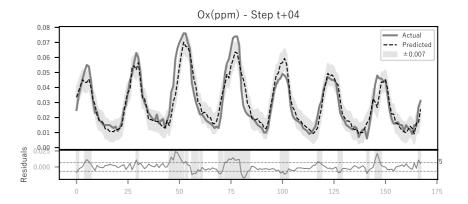
Model Parameters: Prefecture code: 38 Station code: 38206050 Station name: 西条 Target item: Ox(ppm) Number of data points in the train set: 13685 Number of data points in the test set: 5866 Forecast horizon (hours): 24 Model: LightGBM Objective: regression Boosting type: gbdt Number of estimators: 400 Learning rate: 0.04 Elapsed time: 0 min 23 sec Number of used features: 140 Features: NO(ppm), NO2(ppm), U, V, Ox(ppm)\_lag1 Ox(ppm) lag2, Ox(ppm) lag3, Ox(ppm) lag4, Ox(ppm) lag5, Ox(ppm) lag6 Ox(ppm)\_lag7, Ox(ppm)\_lag8, Ox(ppm)\_lag9, Ox(ppm)\_lag10, Ox(ppm)\_lag11 Ox(ppm) lag12, Ox(ppm) lag13, Ox(ppm) lag14, Ox(ppm) lag15, Ox(ppm) lag16 Ox(ppm)\_lag17, Ox(ppm)\_lag18, Ox(ppm)\_lag19, Ox(ppm)\_lag20, Ox(ppm)\_lag21 Ox(ppm)\_lag22, Ox(ppm)\_lag23, NO(ppm)\_lag1, NO(ppm)\_lag2, NO(ppm)\_lag3 NO(ppm)\_lag4, NO(ppm)\_lag5, NO(ppm)\_lag6, NO(ppm)\_lag7, NO(ppm)\_lag8 NO(ppm)\_lag9, NO(ppm)\_lag10, NO(ppm)\_lag11, NO(ppm)\_lag12, NO(ppm)\_lag13 NO(ppm)\_lag14, NO(ppm)\_lag15, NO(ppm)\_lag16, NO(ppm)\_lag17, NO(ppm)\_lag18 NO(ppm)\_lag19, NO(ppm)\_lag20, NO(ppm)\_lag21, NO(ppm)\_lag22, NO(ppm)\_lag23 NO2(ppm)\_lag1, NO2(ppm)\_lag2, NO2(ppm)\_lag3, NO2(ppm)\_lag4, NO2(ppm)\_lag5 NO2(ppm) lag6, NO2(ppm) lag7, NO2(ppm) lag8, NO2(ppm) lag9, NO2(ppm) lag10 NO2(ppm)\_lag11, NO2(ppm)\_lag12, NO2(ppm)\_lag13, NO2(ppm)\_lag14, NO2(ppm)\_lag15 NO2(ppm)\_lag16, NO2(ppm)\_lag17, NO2(ppm)\_lag18, NO2(ppm)\_lag19, NO2(ppm)\_lag20 NO2(ppm)\_lag21, NO2(ppm)\_lag22, NO2(ppm)\_lag23, U\_lag1, U\_lag2 U\_lag3, U\_lag4, U\_lag5, U\_lag6, U\_lag7 U\_lag8, U\_lag9, U\_lag10, U\_lag11, U\_lag12 U\_lag13, U\_lag14, U\_lag15, U\_lag11, U\_lag12 U\_lag13, U\_lag14, U\_lag20, U\_lag20, U\_lag21 U\_lag28, U\_lag19, U\_lag20, U\_lag21, U\_lag22 U\_lag23, V\_lag1, V\_lag2, V\_lag3, V\_lag4 V\_lag5, V\_lag6, V\_lag7, V\_lag8, V\_lag9 V\_lag10, V\_lag11, V\_lag12, V\_lag13, V\_lag14 V\_lag15, V\_lag16, V\_lag17, V\_lag18, V\_lag19 V\_lag20, V\_lag21, V\_lag22, V\_lag23, Ox(ppm)\_roll\_mean\_3 Ox(ppm)\_roll\_std\_6, NO(ppm)\_roll\_mean\_3, NO(ppm)\_roll\_std\_6, NO2(ppm)\_roll\_mean\_3, NO2(ppm)\_roll\_std\_6 U\_roll\_mean\_3, U\_roll\_std\_6, V\_roll\_mean\_3, V\_roll\_std\_6, Ox(ppm)\_diff\_1
Ox(ppm)\_diff\_2, Ox(ppm)\_diff\_3, NO(ppm)\_diff\_3, NO2(ppm)\_diff\_3, U\_diff\_3 V\_diff\_3, hour\_sin, hour\_cos, dayofweek, is\_weekend Metrics per Forecast Step: Ox(ppm)\_t+01 - R2: 0.8991, MAE: 0.0037, RMSE: 0.0051 Ox(ppm)\_t+02 - R<sup>2</sup>: 0.8368, MAE: 0.0047, RMSE: 0.0064 Ox(ppm) t+03 - R<sup>2</sup>: 0.7868, MAE: 0.0054, RMSE: 0.0074 Ox(ppm)\_t+04 - R<sup>2</sup>: 0.7473, MAE: 0.0059, RMSE: 0.0080 Ox(ppm)\_t+05 - R<sup>2</sup>: 0.6966, MAE: 0.0065, RMSE: 0.0088 Ox(ppm) t+06 - R<sup>2</sup>: 0.6611, MAE: 0.0069, RMSE: 0.0093 Ox(ppm)\_t+07 - R<sup>2</sup>: 0.6252, MAE: 0.0072, RMSE: 0.0098 Ox(ppm) t+08 - R<sup>2</sup>: 0.5972, MAE: 0.0075, RMSE: 0.0101 Ox(ppm)\_t+09 - R<sup>2</sup>: 0.5787, MAE: 0.0076, RMSE: 0.0104 Ox(ppm)\_t+10 - R<sup>2</sup>: 0.5561, MAE: 0.0078, RMSE: 0.0106 Ox(ppm)\_t+11 - R<sup>2</sup>: 0.5509, MAE: 0.0079, RMSE: 0.0107 Ox(ppm)\_t+12 - R<sup>2</sup>: 0.5378, MAE: 0.0081, RMSE: 0.0109 Ox(ppm)\_t+13 - R<sup>2</sup>: 0.5106, MAE: 0.0083, RMSE: 0.0112 Ox(ppm)\_t+14 - R<sup>2</sup>: 0.4976, MAE: 0.0084, RMSE: 0.0113 Ox(ppm) t+15 - R<sup>2</sup>: 0.4893, MAE: 0.0084, RMSE: 0.0114 Ox(ppm)\_t+16 - R<sup>2</sup>: 0.4773, MAE: 0.0085, RMSE: 0.0116 Ox(ppm)\_t+17 - R<sup>2</sup>: 0.4638, MAE: 0.0087, RMSE: 0.0117 Ox(ppm)\_t+18 - R<sup>2</sup>: 0.4578, MAE: 0.0087, RMSE: 0.0118 Ox(ppm)\_t+19 - R<sup>2</sup>: 0.4516, MAE: 0.0088, RMSE: 0.0118 Ox(ppm) t+20 - R<sup>2</sup>: 0.4462, MAE: 0.0088, RMSE: 0.0119 Ox(ppm)\_t+21 - R<sup>2</sup>: 0.4395, MAE: 0.0088, RMSE: 0.0120 Ox(ppm)\_t+22 - R<sup>2</sup>: 0.4386, MAE: 0.0089, RMSE: 0.0120 Ox(ppm) t+23 - R<sup>2</sup>: 0.4395, MAE: 0.0089, RMSE: 0.0120

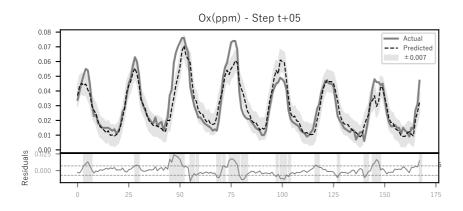
Ox(ppm)\_t+24 - R<sup>2</sup>: 0.4327, MAE: 0.0090, RMSE: 0.0120

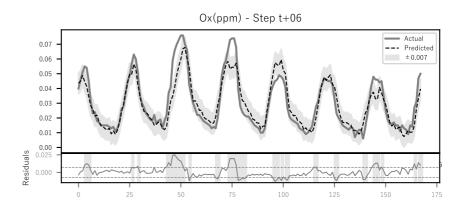


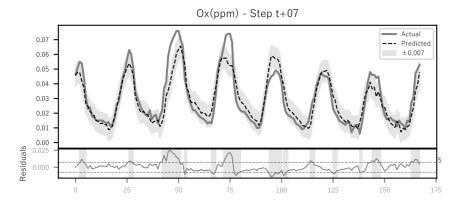


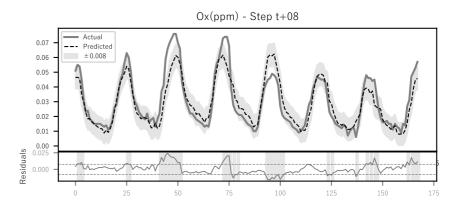


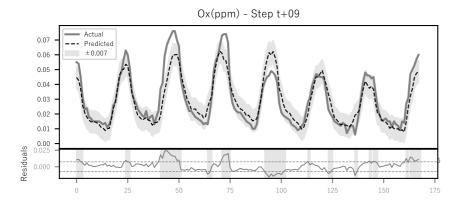


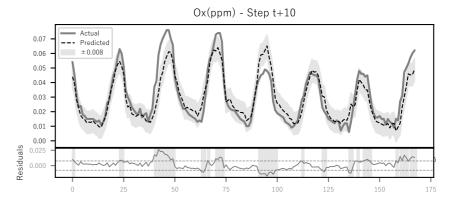


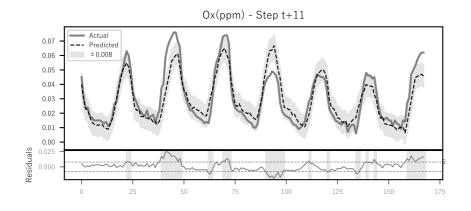


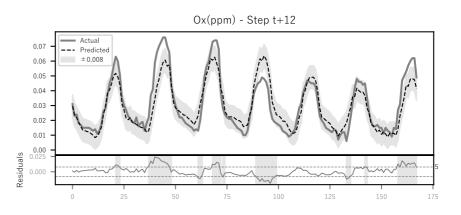


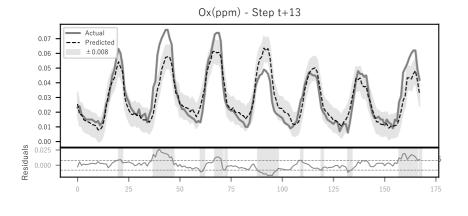


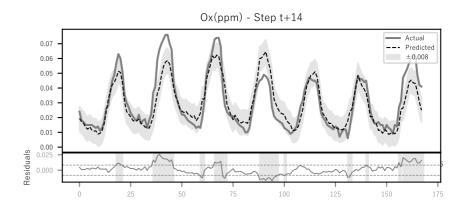


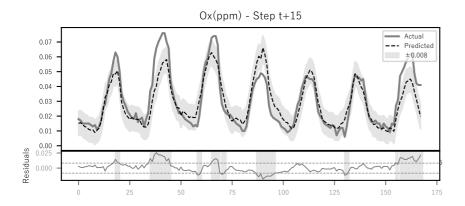


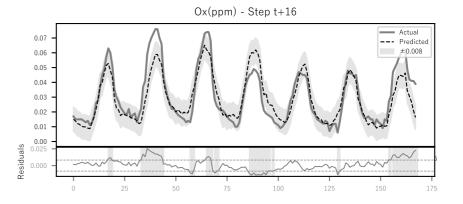


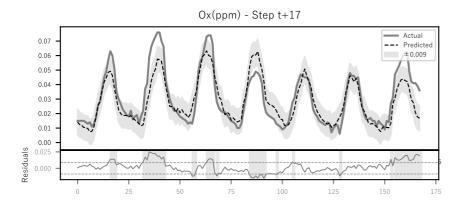


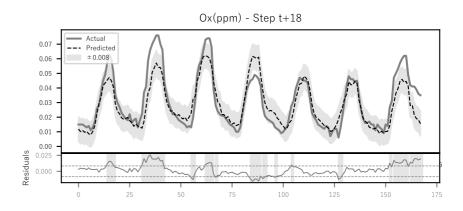


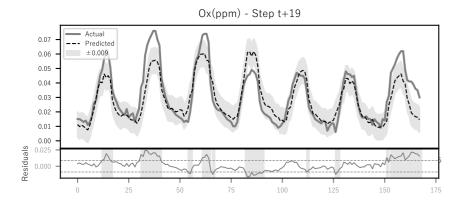


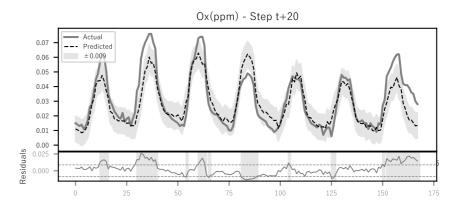


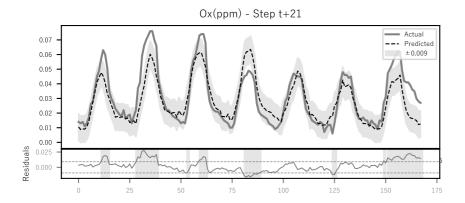


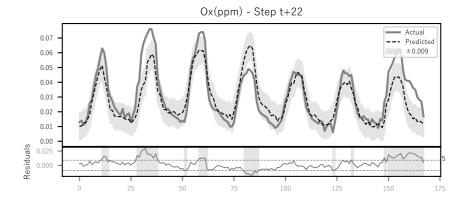


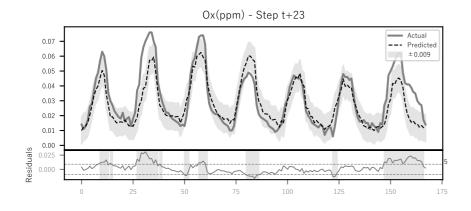


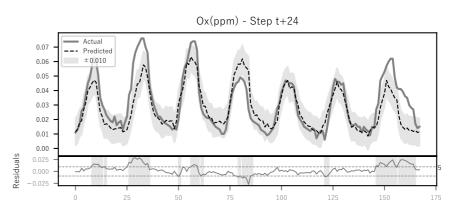


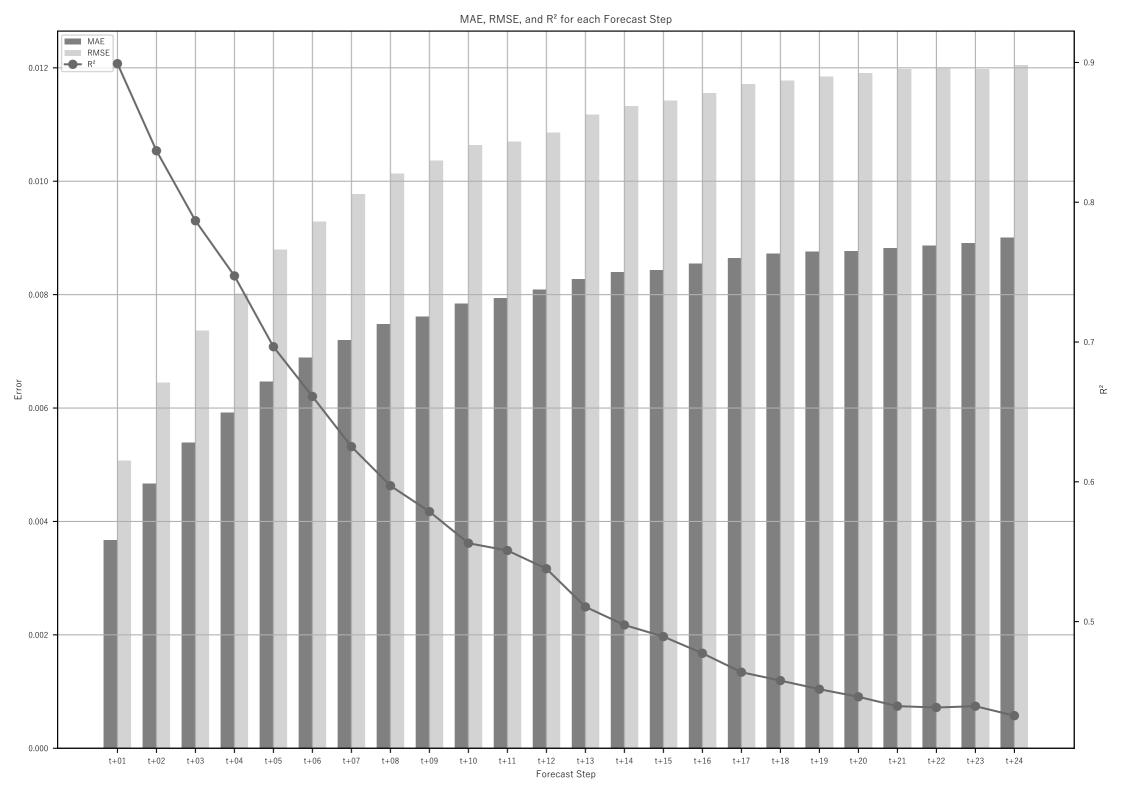












### Normalized Feature Importance (per feature) 1.0 1.00 1.00 | 1.00 1.00 1.00 | 1.00 1.00 | 1.00 | 0.87 0.49 0.68 0.26 0.57 0.33 0.05 0.00 0.00 0.06 0.05 0.16 0.62 0.85 Ox(ppm)\_lag1 0.01 0.03 0.07 0.14 0.22 0.30 0.41 0.67 1.00 1.00 1.00 1.00 1.00 | 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 0.99 0.8 0.74 0.52 0.55 0.83 Normalized Importance (per feature) U\_roll\_std\_6 - 0.10 0.12 0.16 0.21 0.30 0.40 0.24 0.29 0.50 0.55 0.43 0.70 0.70 0.82 1.00 0.68 | 0.69 0.68 0.65 0.63 0.63 0.72 0.77 0.73 hour\_sin **-** 0.09 0.04 0.17 0.31 0.73 0.66 0.67 0.00 0.00 0.00 0.00 0.43 0.29 0.28 0.35 0.40 0.26 | 0.24 | 0.19 | 0.18 | 0.19 | 0.11 | 0.00 | 0.00 | 0.00 | 0.27 | 0.18 | 0.33 | 0.60 U **-** 0.70 0.21 0.15 0.29 0.00 0.00 0.00 0.00 0.00 $V_{-roll\_std\_6} - 0.11 \quad 0.05 \quad 0.09 \quad 0.03 \quad 0.01 \quad 0.00 \quad 0.00 \quad 0.00 \quad 0.21 \quad 0.39 \quad 0.23 \quad 0.12 \quad 0.40 \quad 0.18 \quad 0.60$ 0.37 0.59 NO2(ppm) roll mean 3 - 0.10 0.00 0.05 0.00 0.00 0.12 0.13 0.27 0.34 0.41 0.04 0.41 0.38 0.25 0.30 0.38 0.56 0.40 - 0.2 U\_roll\_mean\_3 - 0.16 | 0.15 | 0.07 | 0.08 | 0.17 | 0.19 | 0.23 | 0.19 | 0.13 0.23 0.11 0.29 0.33 0.21 0.30 0.21 0.25 0.08 0.10 0.10 0.28 Ox(ppm) roll mean 3 - 0.000.01 0.00 0.11 0.09 0.05 0.15 0.02 0.25 0.86 0.73 0.00 0.00 0.02 0.42 0.37 0.21 0.20 0.13 0.25 0.88 0.31 0.30 - 0.0 00 )x(ppm)\_t+02 0x(ppm)\_t+03 0x(ppm)\_t+12 0x(ppm)\_t+13 Ox(ppm)\_t+ Forecast Step Normalized Feature Importance (per step) 1.0 $Ox(ppm)_lag1 - 1.00$ 0.96 0.92 0.85 0.77 0.41 | 0.28 | 0.22 | 0.28 | 0.20 | 0.14 | 0.14 | 0.06 | 0.09 | 0.02 | 0.01 | 0.00 | 0.05 | 0.09 | 0.29 | 0.35 dayofweek - 0.00 0.14 0.28 0.39 0.71 0.69 0.71 0.78 0.76 0.74 0.82 0.89 0.81 0.84 0.88 0.97 0.99 1.00 0.97 0.88 0.8 0.69 0.80 0.55 0.59 U\_roll\_std\_6 - 0.00 0.26 0.45 0.58 0.63 0.35 0.37 0.27 0.59 0.70 0.74 0.95 0.94 1.00 Normalized Importance (per step) NO2(ppm)\_roll\_std\_6 - 0.00 0.03 0.17 0.26 0.36 0.27 0.43 0.43 0.60 0.75 0.68 0.79 0.84 0.92 0.90 | 1.00 0.92 0.87 0.91 0.60 0.64 hour\_sin **-** 0.23 0.28 0.54 | 0.74 | 1.00 0.56 | 0.63 0.36 0.00 0.08 0.37 0.42 ∪ - 1.00 0.43 | 0.35 | 0.31 | 0.29 | 0.22 | 0.24 | 0.22 | 0.23 | 0.30 | 0.23 | 0.28 | 0.28 | 0.27 | 0.25 | 0.15 | 0.22 | 0.01 | 0.09 | 0.06 0.08 0.00 $V_{roll_std_6} - 0.00$ 0.09 0.40 0.35 0.29 0.25 0.22 0.23 0.67 0.46 0.65 0.40 0.83 0.94 1.00 0.94 NO2(ppm) roll mean 3 - 0.05 0.00 0.35 0.34 0.34 0.53 | 0.72 | 0.85 | 0.78 0.77 0.72 0.65 0.68 0.58 | 0.71 0.74 0.85 1.00 0.73 - 0.2 0.77 | 0.78 U\_roll\_mean\_3 - 0.06 0.30 0.53 | 0.85 0.58 | 0.67 1.00 0.62 0.42 0.20 0.22 0.03 0.00 0.06 0.20 0.36 0.59 0.71 1.00 0.39 Ox(ppm) roll mean 3 - 0.000.20 0.29 0.41 0.73 0.41 0.36 0.36 0.33 0.37 0.37 0.32 0.38 - 0.0 -09 0x(ppm)\_t+10 t + 19-20 0x(ppm)\_t+02 0x(ppm)\_t+12 Ox(ppm)\_t+13 0x(ppm)\_t+16 0x(ppm)\_t+24 Ox(ppm)\_t+

Target