

DATA STRUCTURES (AND ALGORITHMS)

Sorted Linked Lists. Linked Lists on Arrays.

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- Abstract Data Types
 - ADT Set
 - ADT Map
 - ADT Matrix

- Sorted Linked Lists
- Linked Lists on Array

Sorted Lists



A **sorted (or ordered) linked list** is a linked list in which the elements are ordered according to a **relation**.



The elements must be comparable and the relation can be an abstract relation.



Using an abstract relation give more flexibility:



It is easy to change the relation and have lists ordered by different relations.

The relation



The **relation** is a function defined on $\text{TComp} \times \text{TComp}$:

$$\text{relation}(c_1, c_2) = \begin{cases} \text{true}, & c_1 \leq c_2 \\ \text{false}, & \text{otherwise} \end{cases}$$



" $c_1 \leq c_2$ " means that c_1 should be in front of c_2 when ordering the two elements according to the *relation*.

Sorted List - representation



When we have a sorted list we will have a field that represents this relation in its representation.



In the following, we will discuss the **Sorted Singly Linked List**

- The representation and Pseudocode for the **Sorted Doubly Linked List** is very similar.

Sorted Singly Linked List - representation



We need two structures: one for the node (*Node* - *SSLLNode*) and one for the Sorted Singly Linked List - SSLL itself.



SSLL's node representation:

SSLLNode:

info: TComp

next: \uparrow SSLLNode



SSLL representation

SSLL:

head: \uparrow SSLLNode

rel: \uparrow Relation : TComp \times TComp $\rightarrow \{true, false\}$

SSLL - Initialization



The relation is passed as a parameter to constructor.



In this way, we can create multiple SSLLs with different relations.



Constructor of a SSLL:

subalgorithm init (ssll, rel) **is:**

//pre: rel is a relation

//post: ssll is an empty SSLL

ssll.head \leftarrow NIL

ssll.rel \leftarrow rel

end-subalgorithm

- Complexity: $\Theta(1)$



How can we insert an element into a SSLL?



How can we insert an element into a SSLL?



The list should remain sorted after insertion.



Since we have a singly-linked list we need to find the node *after* which to insert the new element.



The node we want to insert after is the first node whose successor is *greater than* the element we want to insert.



How can we insert an element into a SSLL?



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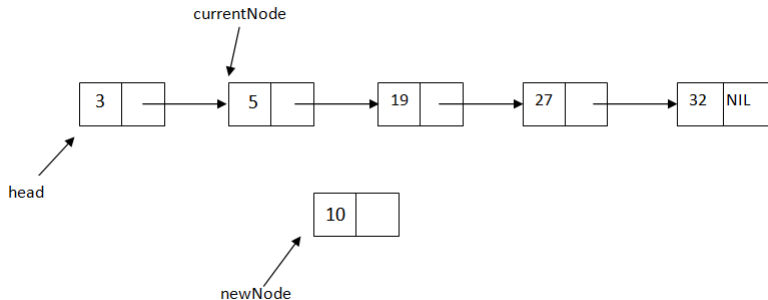
Special cases:

- the SSLL is empty
- we have to insert before the head

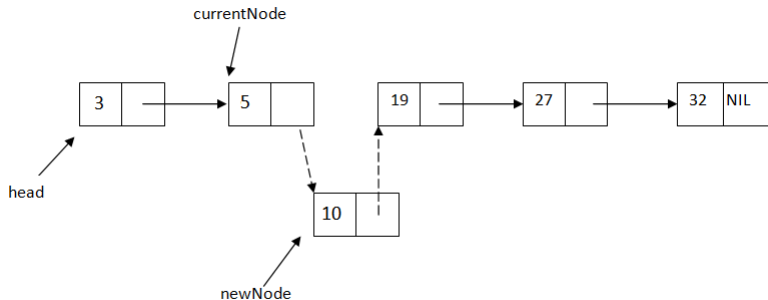
SSLL - Insert - Example



Suppose that we want to insert 10 in the following SSLL:



SSLL - Insert - Example





Inserting an element into a SSL:

subalgorithm insert (ssl, elem) **is:**

//pre: ssl is a SSL; elem is a TComp

//post: the element elem was inserted into ssl to where it belongs



Inserting an element into a SSLL:

subalgorithm insert (ssll, elem) **is:**

//pre: ssll is a SSLL; elem is a TComp

//post: the element elem was inserted into ssll to where it belongs

newNode \leftarrow allocate()

[newNode].info \leftarrow elem

[newNode].next \leftarrow NIL

if ssll.head = NIL **then**

//the list is empty

ssll.head \leftarrow newNode

else if ssll.rel(elem, [ssll.head].info) **then**

//elem is "less than" the info from the head

[newNode].next \leftarrow ssll.head

ssll.head \leftarrow newNode

else

//continued on the next slide...



Inserting an element into a SSLL:

```
currentNode ← ssl.head
while [currentNode].next ≠ NIL and ssl.rel(elem, [[currentNode].next].info) =
false execute
    currentNode ← [currentNode].next
end-while
//now insert after currentNode
[newNode].next ← [currentNode].next
[currentNode].next ← newNode
end-if
end-subalgorithm
```



What is the time complexity?



Inserting an element into a SSLL:

```
currentNode ← ssl.head
while [currentNode].next ≠ NIL and ssl.rel(elem, [[currentNode].next].info) =
false execute
    currentNode ← [currentNode].next
end-while
//now insert after currentNode
[newNode].next ← [currentNode].next
[currentNode].next ← newNode
end-if
end-subalgorithm
```



What is the time complexity?



$O(n)$

SLL - Other operations



The *search* operation is similar to the one for a SLL, except that we can stop when we get to the first element that is "greater than" the one we are looking for.

SLL - Other operations



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The *delete* operations are identical to the corresponding operations for a SLL, except that the search part can use the relation and stop sooner.

SLL - Other operations



The *search* operation is similar to the one for a SLL, except that we can stop when we get to the first element that is "greater than" the one we are looking for.



The *delete* operations are identical to the corresponding operations for a SLL, except that the search part can use the relation and stop sooner.



The operation for returning an element at a given integer position is identical to the corresponding operation for a SLL.

SSL - Other operations



The *search* operation is similar to the one for a SLL, except that we can stop when we get to the first element that is "greater than" the one we are looking for.



The *delete* operations are identical to the corresponding operations for a SLL, except that the search part can use the relation and stop sooner.



The operation for returning an element at a given integer position is identical to the corresponding operation for a SLL.



The iterator for a SSL is identical to the iterator to a SLL.

Linked Lists on Arrays



We can still implement linked data structures, without the explicit use of pointers, by using arrays and array indexes.

Linked Lists on Arrays



Usually, when we work with arrays, we store the elements starting from the leftmost slot and place them one after the other.



The order of the elements is given by the order in which they are placed into the array.

elems	46	78	11	6	59	19				
-------	----	----	----	---	----	----	--	--	--	--



Order of the elements: 46, 78, 11, 6, 59, 19

Linked Lists on Arrays



We can define a SLL on an array if we consider that the order of the elements is not given by their or relative positions in the array, but by integers numbers, one for each element, which gives the index of the next element.

elems	46	78	11	6	59	19				
next	5	6	1	-1	2	4				
head = 3										



Order of the elements: 11, 46, 59, 78, 19, 6

Linked Lists on Arrays - Delete - Example

elems	46	78	11	6	59	19				
next	5	6	1	-1	2	4				

head = 3

- Order of the elements: 11, 46, 59, 78, 19, 6



If we want to delete 46, we do not have to shift all the other elements to the left, but only to modify the links:

elems		78	11	6	59	19				
next		6	5	-1	2	4				

head = 3

- Order of the elements: 11, 59, 78, 19, 6

Linked Lists on Arrays - Insert - Example

elems		78	11	6	59	19				
next		6	5	-1	2	4				

head = 3

- Order of the elements: 11, 59, 78, 19, 6



If we want to insert 44 at the 3rd position in the list, we can put the element anywhere in the array, the essential being to set the links correctly:

elems		78	11	6	59	19		44		
next		6	5	-1	8	4		2		

head = 3

- Order of the elements: 11, 59, 44, 78, 19, 6

Linked Lists on Arrays (LLA)



What is the complexity of finding an empty position in the array?

Linked Lists on Arrays (LLA)



What is the complexity of finding an empty position in the array?



Finding an empty position has $O(n)$ complexity.



In order to avoid this, we can keep a linked list of the empty positions as well.

elems		78	11	6	59	19		44		
next	7	6	5	-1	8	4	9	2	10	-1

head = 3

firstEmpty = 1

- Empty positions: 1, 7, 9, 10.

SLL on Array - Representation (SLLA)



We can simulate a SLL on an array with:

- an array in which to store the elements
- an array in which to store the links
- the capacity of the arrays
- the index of the *head* of the list
- the index of the first empty position in the array

SLLA - Representation

- The representation of a SLL on an array is the following:



Representation of a SLL on an array;

SLLA:

```
elems: TElem[]  
next: Integer[]  
cap: Integer  
head: Integer  
firstEmpty: Integer
```



We can implement for a SLLA any operation that we can implement for a dynamically allocated SLL:

- constructor
- search for an element with a given value
- add an element (at the beginning, to the end, at a given position, after a given value)
- delete an element (from the beginning, from the end, from a given position, with a given value)
- get the element from a given position
- etc.



The constructor of a SLLA:

subalgorithm `init(slla)` **is:**

//pre: true; post: slla is an empty SLLA

`slla.cap` \leftarrow `INIT_CAPACITY`



The constructor of a SLLA:

subalgorithm `init(slla)` **is:**

//pre: true; post: slla is an empty SLLA

`slla.cap` \leftarrow `INIT_CAPACITY`

`slla.elems` \leftarrow @an array with `slla.cap` positions

`slla.next` \leftarrow @an array with `slla.cap` positions



The constructor of a SLLA:

subalgorithm `init(slla)` **is:**

//pre: true; post: slla is an empty SLLA

`slla.cap` \leftarrow `INIT_CAPACITY`

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The constructor of a SLLA:

subalgorithm init(slla) **is:**

//pre: true; post: slla is an empty SLLA

slla.cap \leftarrow INIT_CAPACITY

slla.elems \leftarrow @an array with slla.cap positions

slla.next \leftarrow @an array with slla.cap positions

slla.head \leftarrow -1

for $i \leftarrow 1, \text{slla.cap}-1$ **execute**

 slla.next[i] $\leftarrow i + 1$

end-for



The constructor of a SLLA:

subalgorithm init(slla) **is:**

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end-for

slla.firstEmpty \leftarrow 1



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slla.next \leftarrow @an array with slla.cap positions

slla.head \leftarrow -1

for $i \leftarrow 1, \text{slla.cap}-1$ **execute**

 slla.next[i] \leftarrow i + 1

end-for

slla.firstEmpty \leftarrow 1

slla.next[slla.cap] \leftarrow -1

end-subalgorithm



What is the time complexity?



The constructor of a SLLA:

subalgorithm init(slla) **is:**

//pre: true; post: slla is an empty SLLA

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slla.next \leftarrow @an array with slla.cap positions

slla.head \leftarrow -1

for $i \leftarrow 1, \text{slla.cap}-1$ **execute**

 slla.next[i] \leftarrow i + 1

end-for

slla.firstEmpty \leftarrow 1

slla.next[slla.cap] \leftarrow -1

end-subalgorithm



What is the time complexity?



$\Theta(\text{INIT_CAPACITY})$



Searching for an element into a SLLA:

function search (slla, elem) **is:**

//pre: slla is a SLLA, elem is a TElem

//post: returns True is elem is in slla, False otherwise



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function search (slla, elem) **is:**

//pre: slla is a SLLA, elem is a TElem

//post: returns True is elem is in slla, False otherwise

current \leftarrow slla.head

while current \neq -1 **and** slla.ellems[current] \neq elem **execute**

current \leftarrow slla.next[current]

end-while

if current \neq -1 **then**

search \leftarrow True

else

search \leftarrow False

end-if

end-function



What is the time complexity?



Searching for an element into a SLLA:

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//pre: slla is a SLLA, elem is a TElem

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end-while

if current \neq -1 **then**

search \leftarrow True

else

search \leftarrow False

end-if

end-function



What is the time complexity?



$O(n)$



Adding an element at the beginning of a SLLA:

subalgorithm insertFirst(slla, elem) **is:**

//pre: slla is an SLLA, elem is a TElem

//post: the element elem is added at the beginning of slla

SLLA - InsertFirst



Adding an element at the beginning of a SLLA:

subalgorithm insertFirst(slla, elem) **is:**

//pre: slla is an SLLA, elem is a TElem

//post: the element elem is added at the beginning of slla

if slla.firstEmpty = -1 **then**

newElems \leftarrow @an array with slla.cap * 2 positions

newNext \leftarrow @an array with slla.cap * 2 positions

for $i \leftarrow 1, \text{slla.cap}$ **execute**

newElems[i] \leftarrow slla.elems[i]

newNext[i] \leftarrow slla.next[i]

end-for

for $i \leftarrow \text{slla.cap} + 1, \text{slla.cap} * 2 - 1$ **execute**

newNext[i] $\leftarrow i + 1$

end-for

newNext[slla.cap*2] $\leftarrow -1$

//continued on the next slide...



Adding an element at the beginning of a SLLA:

//free slla.elems and slla.next if necessary

$\text{slla.elems} \leftarrow \text{newElems}$

$\text{slla.next} \leftarrow \text{newNext}$

$\text{slla.firstEmpty} \leftarrow \text{slla.cap} + 1$

$\text{slla.cap} \leftarrow \text{slla.cap} * 2$

end-if

$\text{newPosition} \leftarrow \text{slla.firstEmpty}$

$\text{slla.elems}[\text{newPosition}] \leftarrow \text{elem}$

$\text{slla.firstEmpty} \leftarrow \text{slla.next}[\text{slla.firstEmpty}]$

$\text{slla.next}[\text{newPosition}] \leftarrow \text{slla.head}$

$\text{slla.head} \leftarrow \text{newPosition}$

end-subalgorithm



What is the time complexity?



Adding an element at the beginning of a SLLA:

//free slla.elems and slla.next if necessary

$\text{slla.elems} \leftarrow \text{newElems}$

$\text{slla.next} \leftarrow \text{newNext}$

$\text{slla.firstEmpty} \leftarrow \text{slla.cap} + 1$

$\text{slla.cap} \leftarrow \text{slla.cap} * 2$

end-if

$\text{newPosition} \leftarrow \text{slla.firstEmpty}$

$\text{slla.elems}[\text{newPosition}] \leftarrow \text{elem}$

$\text{slla.firstEmpty} \leftarrow \text{slla.next}[\text{slla.firstEmpty}]$

$\text{slla.next}[\text{newPosition}] \leftarrow \text{slla.head}$

$\text{slla.head} \leftarrow \text{newPosition}$

end-subalgorithm



What is the time complexity?



$\Theta(1)$ amortized



Inserting an element at a given position into a SLLA:

subalgorithm insertPosition(slla, elem, pos) **is:**

//pre: slla is an SLLA, elem is a TElem, pos is an integer number

//post: the element elem is inserted into slla at position pos



Inserting an element at a given position into a SLLA:

subalgorithm insertPosition(slla, elem, pos) **is:**

//pre: slla is an SLLA, elem is a TElem, pos is an integer number

//post: the element elem is inserted into slla at position pos

if (pos < 1) **then**

 @error, invalid position

end-if

if slla.firstEmpty = -1 **then**

 @resize

end-if

if pos = 1 **then**

 insertFirst(slla, elem)

else

 currentPos \leftarrow 1

 current \leftarrow slla.head

//continued on the next slide...



Inserting an element at a given position into a SLLA:

while $\text{current} \neq -1$ **and** $\text{currentPos} < \text{pos} - 1$ **execute**

$\text{currentPos} \leftarrow \text{currentPos} + 1$

$\text{current} \leftarrow \text{slla.next}[\text{current}]$

end-while

if $\text{current} \neq -1$ **then**

$\text{newElemIndex} \leftarrow \text{slla.firstEmpty}$

$\text{slla.firstEmpty} \leftarrow \text{slla.next}[\text{firstEmpty}]$

$\text{slla.elems}[\text{newElemIndex}] \leftarrow \text{elem}$

$\text{slla.next}[\text{newElemIndex}] \leftarrow \text{slla.next}[\text{current}]$

$\text{slla.next}[\text{current}] \leftarrow \text{newElemIndex}$

else

//continued on the next slide...



Inserting an element at a given position into a SLLA:

@error, invalid position

end-if

end-if

end-subalgorithm



What is the time complexity?



Inserting an element at a given position into a SLLA:

@error, invalid position

end-if

end-if

end-subalgorithm



What is the time complexity?



$O(n)$



Deleting an element from a SLLA:

subalgorithm deleteElement(slla, elem) **is:**

//pre: slla is a SLLA; elem is a TElem

//post: the element elem is deleted from SLLA



Deleting an element from a SLLA:

subalgorithm deleteElement(slla, elem) **is:**

//pre: slla is a SLLA; elem is a TElem

//post: the element elem is deleted from SLLA

currentIndex \leftarrow slla.head

previousIndex \leftarrow -1

while currentIndex \neq -1 **and** slla.elems[currentIndex] \neq elem **execute**

 previousIndex \leftarrow currentIndex

 currentIndex \leftarrow slla.next[currentIndex]

end-while

if currentIndex \neq -1 **then**

if currentIndex = slla.head **then**

 slla.head \leftarrow slla.next[slla.head]

else

 slla.next[previousIndex] \leftarrow slla.next[currentIndex]

end-if

//continued on the next slide...

SLLA - DeleteElement



Deleting an element from a SLLA:

//add the currentIndex position to the list of empty spaces

slla.next[currentIndex] \leftarrow slla.firstEmpty

slla.firstEmpty \leftarrow currentIndex

else

@the element does not exist

end-if

end-subalgorithm



What is the time complexity?

SLLA - DeleteElement



Deleting an element from a SLLA:

//add the currentIndex position to the list of empty spaces

slla.next[currentIndex] \leftarrow slla.firstEmpty

slla.firstEmpty \leftarrow currentIndex

else

@the element does not exist

end-if

end-subalgorithm



What is the time complexity?



$O(n)$



Since the elements are stored in an array, the cursor will be an index.



Since we have a linked list, going to the next element will not be done by incrementing the cursor, but by following the *next* link.



Also, the cursor will be initialized with the head index, not with 1.



We can represent a DLL on more arrays, as well.



In the following, we are going to structure the data differently, in a way more similar to the dynamic allocation.



We can define a structure to represent a node, even if we are working with arrays.



A DLLA node contains the information and links towards the previous and the next nodes:



DLLA's node representation:

DLLANode:

info: TElem

next: Integer

prev: Integer



Having defined the *DLLANode* structure, we only need one array, which will contain *DLLANodes*.



Since we have a doubly linked list, we keep both the head and the tail of the list.



DLLA representation:

DLLA:

nodes: *DLLANode*[]

cap: Integer

head: Integer

tail: Integer

firstEmpty: Integer

size: Integer *//it is not mandatory, but useful*

DLLA - Allocate and free

- To make the implementation even more similar to a dynamically allocated linked list, we can define the *allocate* and *free* functions as well.



Allocating a new "node" in DLLA:

function allocate(dlla) **is:**

//pre: dlla is a DLLA

//post: a new element will be allocated and its position returned

newElemIndex \leftarrow dlla.firstEmpty

if newElemIndex \neq -1 **then**

 dlla.firstEmpty \leftarrow dlla.nodes[dlla.firstEmpty].next

if dlla.firstEmpty \neq -1 **then**

 dlla.nodes[dlla.firstEmpty].prev \leftarrow -1

end-if

 dlla.nodes[newElemIndex].next \leftarrow -1

 dlla.nodes[newElemIndex].prev \leftarrow -1

end-if

allocate \leftarrow newElemIndex

end-function



Freeing a "node" in a DLLA:

subalgorithm free (dlla, pos) **is:**

//pre: dlla is a DLLA, pos is an integer number

//post: the position pos was freed

dlla.nodes[pos].next \leftarrow dlla.firstEmpty

dlla.nodes[pos].prev \leftarrow -1

if dlla.firstEmpty \neq -1 **then**

 dlla.nodes[dlla.firstEmpty].prev \leftarrow pos

end-if

dlla.firstEmpty \leftarrow pos

end-subalgorithm



Inserting an element at a given position into a DLLA:

subalgorithm insertPosition(dlla, elem, pos) **is:**

//pre: dlla is a DLLA, elem is a TElem, pos is an integer number

//post: the element elem is inserted in dlla at position pos

DLLA - InsertPosition



Inserting an element at a given position into a DLLA:

subalgorithm insertPosition(dlla, elem, pos) **is:**

//pre: dlla is a DLLA, elem is a TElem, pos is an integer number

//post: the element elem is inserted in dlla at position pos

if pos < 1 **OR** pos > dlla.size + 1 **execute**

 @throw exception

end-if



Inserting an element at a given position into a DLLA:

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if pos < 1 **OR** pos > dlla.size + 1 **execute**

 @throw exception

end-if

newElemIndex \leftarrow allocate(dlla)



Inserting an element at a given position into a DLLA:

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if pos < 1 **OR** pos > dlla.size + 1 **execute**

 @throw exception

end-if

newElemIndex \leftarrow allocate(dlla)

if newElemIndex = -1 **then**

 @resize

 newElemIndex \leftarrow allocate(dlla)

end-if



Inserting an element at a given position into a DLLA:

subalgorithm insertPosition(dlla, elem, pos) **is:**

//pre: dlla is a DLLA, elem is a TElem, pos is an integer number

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if pos < 1 **OR** pos > dlla.size + 1 **execute**

 @throw exception

end-if

newElemIndex \leftarrow allocate(dlla)

if newElemIndex = -1 **then**

 @resize

 newElemIndex \leftarrow allocate(dlla)

end-if

dlla.nodes[newElemIndex].info \leftarrow elem



Inserting an element at a given position into a DLLA:

subalgorithm insertPosition(dlla, elem, pos) **is:**

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if pos < 1 **OR** pos > dlla.size + 1 **execute**

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end-if

newElemIndex \leftarrow allocate(dlla)

if newElemIndex = -1 **then**

 @resize

 newElemIndex \leftarrow allocate(dlla)

end-if

dlla.nodes[newElemIndex].info \leftarrow elem

if pos = 1 **then**

if dlla.head = -1 **then**

 dlla.head \leftarrow newElemIndex

 dlla.tail \leftarrow newElemIndex

else

//continued on the next slide...



Inserting an element at a given position into a DLLA:

`dlla.nodes[newElemIndex].next \leftarrow dlla.head`

`dlla.nodes[dlla.head].prev \leftarrow newElemIndex`

`dlla.head \leftarrow newElemIndex`

end-if



Inserting an element at a given position into a DLLA:

```
dlla.nodes[newElemIndex].next  $\leftarrow$  dlla.head  
dlla.nodes[dlla.head].prev  $\leftarrow$  newElemIndex  
dlla.head  $\leftarrow$  newElemIndex
```

end-if

else

```
currentIndex  $\leftarrow$  dlla.head  
posC  $\leftarrow$  1  
while currentIndex  $\neq$  -1 and posC < pos - 1 execute  
    currentIndex  $\leftarrow$  dlla.nodes[currentIndex].next  
    posC  $\leftarrow$  posC + 1  
end-while
```



Inserting an element at a given position into a DLLA:

```
dlla.nodes[newElemIndex].next  $\leftarrow$  dlla.head  
dlla.nodes[dlla.head].prev  $\leftarrow$  newElemIndex  
dlla.head  $\leftarrow$  newElemIndex
```

end-if

else

```
currentIndex  $\leftarrow$  dlla.head
```

```
posC  $\leftarrow$  1
```

while $\text{currentIndex} \neq -1$ **and** $\text{posC} < \text{pos} - 1$ **execute**

```
currentIndex  $\leftarrow$  dlla.nodes[currentIndex].next
```

```
posC  $\leftarrow$  posC + 1
```

end-while

if $\text{currentIndex} \neq -1$ **then** *//it should never be -1, the position is correct*

```
nextNode  $\leftarrow$  dlla.nodes[currentIndex].next
```

```
dlla.nodes[newElemIndex].next  $\leftarrow$  nextNode
```

```
dlla.nodes[newElemIndex].prev  $\leftarrow$  currentIndex
```

```
dlla.nodes[currentIndex].next  $\leftarrow$  newElemIndex
```

//continued on the next slide...



Inserting an element at a given position into a DLLA:

```
if nextNode = -1 then
    dlla.tail ← newElemIndex
else
    dlla.nodes[nextNode].prev ← newElemIndex
end-if
end-if
end-subalgorithm
```



What is the time complexity?



Inserting an element at a given position into a DLLA:

```
if nextNode = -1 then
    dlla.tail ← newElemIndex
else
    dlla.nodes[nextNode].prev ← newElemIndex
end-if
end-if
end-subalgorithm
```



What is the time complexity?



$O(n)$

- The iterator for a DLLA contains as *cursor* the index of the current node from the array.



The representation of an Iterator over a DLLA:

DLLAIterator:

list: DLLA

currentIndex: Integer



The constructor of an Iterator over a DLLA:

subalgorithm init(it, dlla) **is:**

//pre: dlla is a DLLA

//post: it is a DLLAterator for dlla

it.list \leftarrow dlla

it.currentIndex \leftarrow dlla.head

end-subalgorithm



For a (dynamic) array, *currentIndex* is set to 1 when an iterator is created. For a DLLA we need to set it to the head of the list (which might be position 1, but it might be a different position as well).



Complexity: $\Theta(1)$



The *getCurrent* function of an iterator over a DLLA:

function getCurrent(it) **is:**

//pre: it is a DLLAterator, it is valid

//post: e is a TElem, e is the current element from it

//throws exception if the iterator is not valid

if it.currentIndex = -1 **then**

 @throw exception

end-if

 getCurrent \leftarrow it.list.nodes[it.currentIndex].info

end-function



Complexity: $\Theta(1)$



The *next* operation of an Iterator over a DLLA:

subalgorithm next(it) **is:**

//pre: it is a DLLAIterator, it is valid

//post: the current elements from it is moved to the next element

//throws exception if the iterator is not valid

if it.currentIndex = -1 **then**

 @throw exception

end-if

it.currentIndex \leftarrow it.list.nodes[it.currentIndex].next

end-subalgorithm



In case a (dynamic) array, going to the next element means incrementing the *currentIndex*. For a DLLA we need to follow the links.



Complexity: $\Theta(1)$



The *valid* function of an Iterator over a DLLA:

function valid (it) **is:**

//pre: it is a DLLAlterator

//post: valid return true is the current element is valid, false otherwise

if it.currentIndex = -1 **then**

 valid \leftarrow False

else

 valid \leftarrow True

end-if

end-function



Complexity: $\Theta(1)$



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Thank you

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