## **SEMINAR 11**

1) Give a necessary and sufficient condition for the vectors  $v_1 = (a_1, b_1)$ ,  $v_2 = (a_2, b_2)$  to form a basis for the  $\mathbb{R}$ -vector space  $\mathbb{R}^2$ . What does this condition mean from geometrical point of view? Using the condition established, find infinitely many bases for  $\mathbb{R}^2$ . Is there any basis of  $\mathbb{R}^2$  for which the coordinates of a vector v = (x, y) are exactly x and y? Show that  $v_1 = (1, 0)$  and  $v_2 = (1, 1)$  form a basis of  $\mathbb{R}^2$  and find the coordinates of v = (x, y) in this basis.

**Homework:** Formulate and solve a similar problem for the  $\mathbb{R}$ -vector space  $\mathbb{R}^3$ .

- 2) Show that the vectors (1, 2, -1), (3, 2, 4), (-1, 2, -6) from  $\mathbb{R}^3$  are linearly dependendent and find a dependency relation between them.
- 3) Determine the values of  $a \in \mathbb{R}$  for which the vectors  $v_1 = (a, 1, 1), v_2 = (1, a, 1), v_3 = (1, 1, a)$  form a basis of  $\mathbb{R}^3$ .

**Homework:** Which of the following systems of vectors from  $\mathbb{R}^3$ :

- a) ((1,0,-1),(2,5,1),(0,-4,3));
- b) ((2, -4, 1), (0, 3, -1), (6, 0, 1));
- c) ((1,2,-1),(1,0,3),(2,1,1));
- d) ((-1,3,1),(2,-4,-3),(-3,8,2));
- e) ((1, -3, -2), (-3, 1, 3), (-2, -10, -2))

are bases for the  $\mathbb{R}$ -vector space  $\mathbb{R}^3$ ?

4) Show that in the  $\mathbb{R}$ -vector space  $M_2(\mathbb{R})$  the matrices

$$E_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \ E_2 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \ E_3 = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \ E_4 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

form a basis and determine the coordinates of  $A=\begin{pmatrix} -2 & 3 \\ 4 & -2 \end{pmatrix}$  in this basis.

5) In the  $\mathbb{Q}$ -vector space  $\mathbb{Q}^3$  we consider the vectors

$$a = (-2, 1, 3), b = (3, -2, -1), c = (1, -1, 2), d = (-5, 3, 4), e = (-9, 5, 10).$$

Does the following equality  $\langle a, b \rangle = \langle c, d, e \rangle$  hold?

- 6) In the  $\mathbb{R}$ -vector space  $\mathbb{R}^4$  one considers the subspaces:
- a)  $S = \langle u_1, u_2 \rangle$ , with  $u_1 = (1, 1, 0, 0), u_2 = (1, 0, 1, 1),$  $T = \langle v_1, v_2 \rangle$ , with  $v_1 = (0, 0, 1, 1), v_2 = (0, 1, 1, 0);$
- b)  $S = \langle u_1, u_2, u_3 \rangle$ , with  $u_1 = (1, 2, -1, -2)$ ,  $u_2 = (3, 1, 1, 1)$ ,  $u_3 = (-1, 0, 1, -1)$ ,  $T = \langle v_1, v_2 \rangle$ , with  $v_1 = (-1, 2, -7, -3)$ ,  $v_2 = (2, 5, -6, -5)$ :
- c)  $S = \langle u_1, u_2 \rangle$ , with  $u_1 = (1, 2, 1, 0), u_2 = (-1, 1, 1, 1),$ 
  - $T = \langle v_1, v_2 \rangle$ , with  $v_1 = (2, -1, 0, 1), v_2 = (1, -1, 3, 7).$
- d) (optional)  $S = \langle u_1, u_2, u_3 \rangle$ , cu  $u_1 = (1, 2, 1, -2), u_2 = (2, 3, 1, 0), u_3 = (1, 2, 2, -3), T = \langle v_1, v_2, v_3 \rangle$ , cu  $v_1 = (1, 1, 1, 1), v_2 = (1, 0, 1, -1), v_3 = (1, 3, 0, -3).$

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Find a basis and the dimension for each of the subspaces S, T, S + T and  $S \cap T$ .