UCB Math 128B, Spring 2016: Programming Assignment 3

Due April 14

1. Solve problem 10.2.13 in the textbook as it is written. Note that the expressions are considerably simplified by the fact that $\mu = 0$. Also note that if the array th contains the angles θ_n , for $n = 1, \ldots, N$, the shape of the chute can be plotted using the commands

```
x = [0; cumsum(dy*tan(th))];
y = -dy * (0:N)';
plot(x,y,'.-'), axis equal, drawnow
```

2. Write a Newton solver for the general case, not assuming $\mu = 0$. The Jacobian matrix is quite complicated, so compute it using numerical differentiation instead of deriving it. That is, for a given function F(x), set

$$J = rac{\partial m{F}}{\partial m{x}} pprox egin{bmatrix} m{a}_1 & m{a}_2 & \cdots & m{a}_n \end{bmatrix} \quad ext{with} \quad m{a}_j pprox rac{m{F}(m{x} + \delta m{e}_j) - m{F}(m{x} - \delta m{e}_j)}{2\delta}$$

Implement the function and the Jacobian matrix in MATLAB functions of the form

function
$$F = p13F(th, mu, X, dy, v0)$$

function $J = p13J(th, mu, X, dy, v0)$

Use the functions in Newton's method, and solve using the parameters

$$N = 50,$$
 $\mu = 0.2,$ $X = 2,$ $\Delta y = 0.05,$ $v_0 = 0.2$

with zero initial condition. Iterate until $\|\theta^{(k)} - \theta^{(k-1)}\|_{\infty} < 10^{-8}$. Output $\|\theta^{(k)} - \theta^{(k-1)}\|_{\infty}$ for each iteration k, and plot the final chute shape.

3. Try solving the problem in 2 again, with the parameter $\Delta y = 0.02$. Observe the convergence problems. To address this, implement a Runge-Kutta based continuation algorithm as described in Section 10.5 of the textbook, using $N = N_C$ steps (note: not the same N as before). Try your solver with $N_C = 1$, 2, and 4, and if it succeeds, perform a final solve for full accuracy using Newton's method. Report your convergence results and plot the final chute shape (for the correct solution).