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Work Sheet 6 Reinforcement Leaning – Chapter 4

Exercise 1

Dynamic Programming

This exercise relates to the Gambler's Problem (Example 4.3) from Chapter 4 of [1]. It examines different approaches for the calculation of the optimal policy based on dynamic programming.

- a) Implement the Iterative Poly Evaluation and Improvement algorithms to find the optimal policy for the Gambler's Problem using the parameters from Example 4.3
 - Can you reproduce the plots from Figure 4.3?
- b) Implement the Value Iteration algorithm to find the optimal policy for the Gambler's Problem using the parameters from Example 4.3
 - Again, can you reproduce the plots from Figure 4.3?
- c) Use your implementations from 1a) resp. 1b) and experiment with the following parameters:
 - Coin probabilities
 - Values for γ in the algorithms
 - Different rewards. Try, for example, $r \in \{0.1, 1.0\}$ or $r \in \{-0.1, 1.0\}$ instead of $r \in \{0, 1\}$.

Can you plausibly explain the calculated state values and policies?

References

[1] Richard S. Sutton and Andrew G. Barto. Reinforcement Learning: An Introduction. MIT Press, Cambridge, MA, 2018.