Big Data Computing

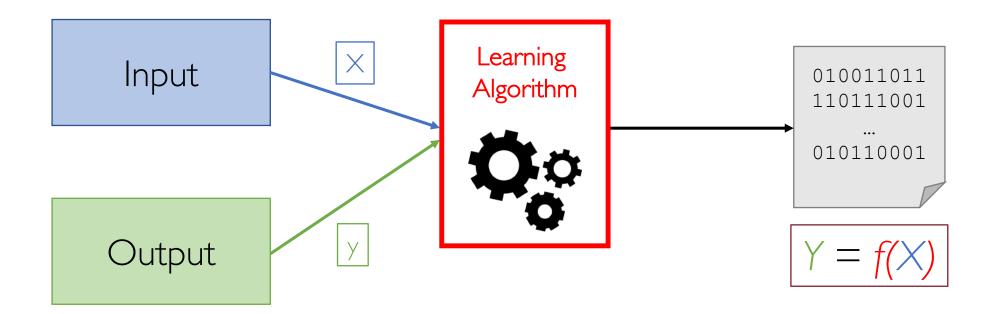
Master's Degree in Computer Science 2022-2023

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"Training" a Computer



Eventually, the function f is **learned** by the learning algorithm from a (large) set of **labeled data**

$$\mathcal{X} \subseteq \mathbb{R}^n$$

input feature space

 $\mathcal{X}\subseteq\mathbb{R}^n$ \mathcal{Y}

input feature space output space

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 \mathcal{Y}

$$\mathcal{Y}\subseteq\mathbb{R}$$

$$\mathcal{Y} = \{1, \dots, k\}$$

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real-value label (regression)

discrete-value label (k-ary classification)

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$$\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)\}\$$

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output space

real-value label (regression)

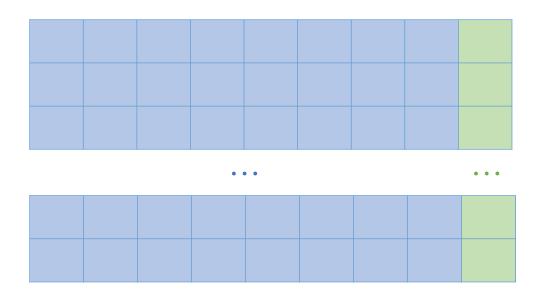
discrete-value label (k-ary classification)

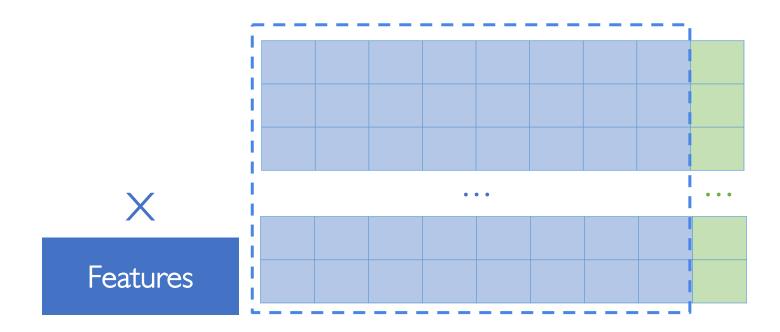
i-th labeled instance

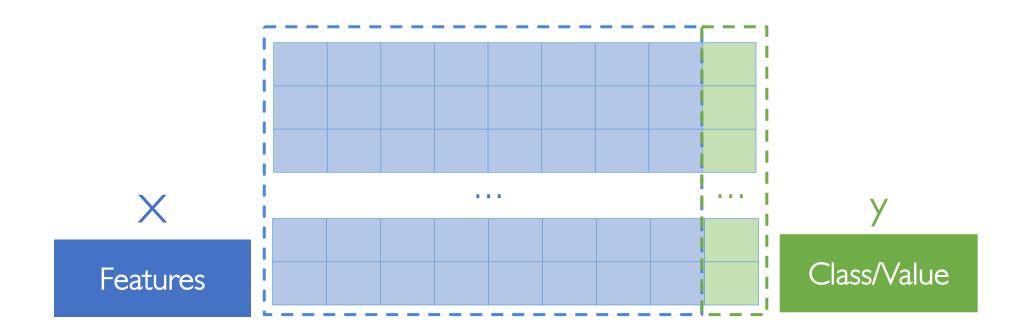
n-dimensional feature vector of the i-th instance

label of the i-th instance

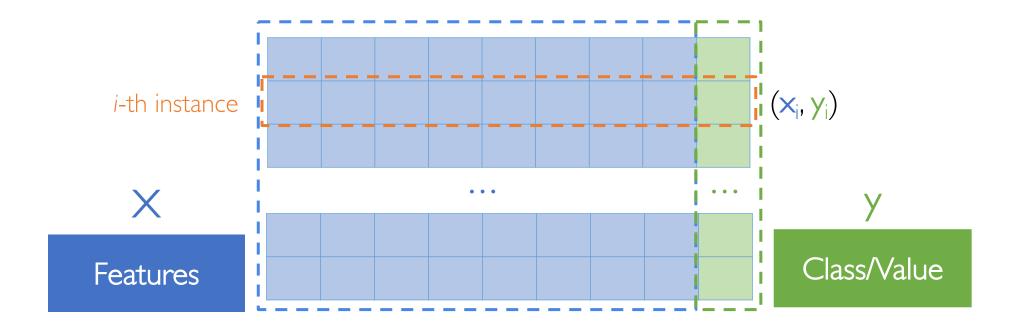
dataset of m i.i.d. labeled instances







Each instance comes with the class label (classification) or the value (regression) we want to predict



Model Training: Intuition

<u>Idea</u>

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Problem

We cannot write down an algorithm which just implements f

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- h^* is chosen among a family of functions H called **hypothesis space** by specifying two components:
 - loss function: measures the error of using h^* instead of the true f
 - learning algorithm: explores the hypothesis space to pick the function which minimizes the loss on the observed data

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Trade-off

Put some constraints on H, e.g., limit the search space only to linear functions

The Loss Function

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• This in-sample error (a.k.a. empirical loss) is an estimate of the out-of-sample error (a.k.a. expected loss or risk)

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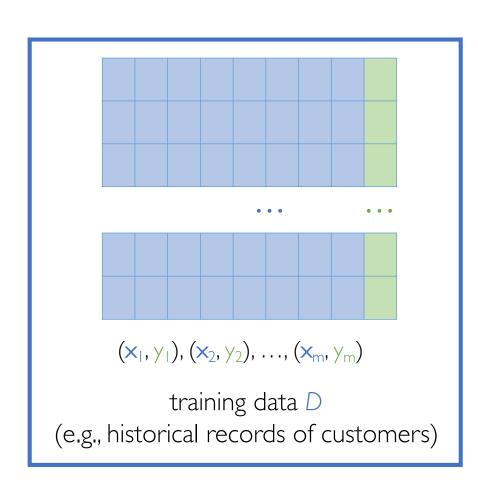
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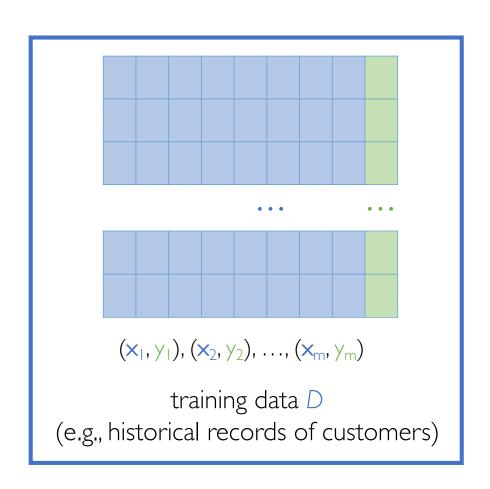
$$h^* = \operatorname{argmin}_{h \in \mathcal{H}} L(h, \mathcal{D})$$

$$f = X \rightarrow Y$$

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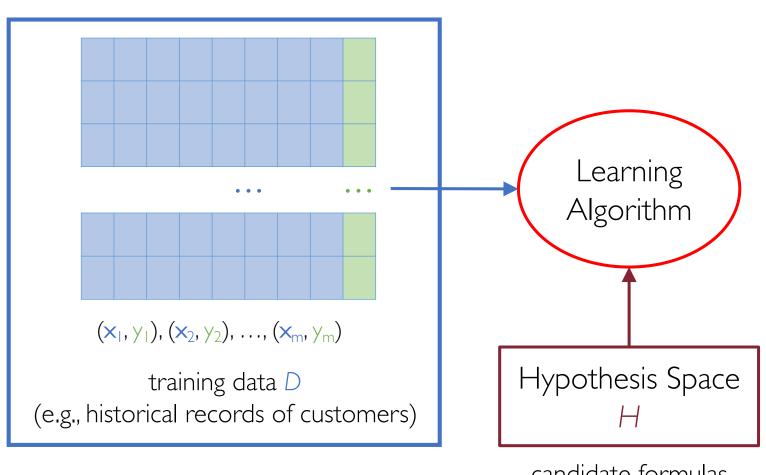
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Hypothesis Space H

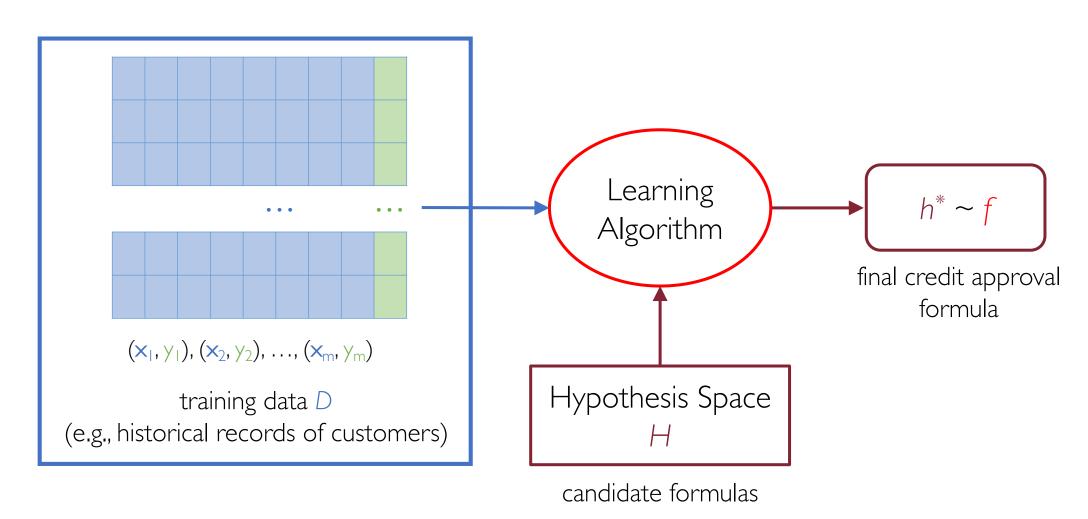
candidate formulas

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- Those choices are usually "mathematically convenient": e.g., convex
 objective functions are guaranteed to have a unique global minimum
- Even though closed-form solutions to the optimization problem rarely exist, there are numerical methods which work: e.g., gradient descent

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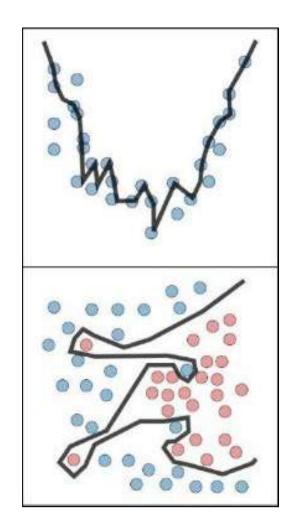
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- If we pick a hypothesis which just memorizes all the training instances, we will obtain a 0 in-sample error but this is not learning!
- At the same time we do not want h^* to perform poorly on D

Overfitting (High Variance)

Regression

Classification

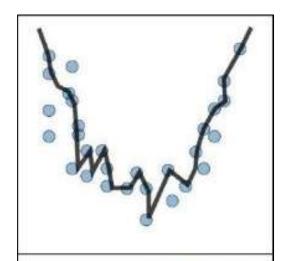


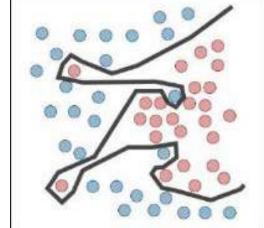
The hypothesis h^* is not learning the true f but it mimics its noise

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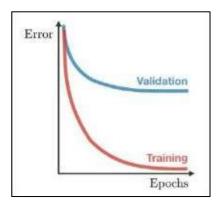
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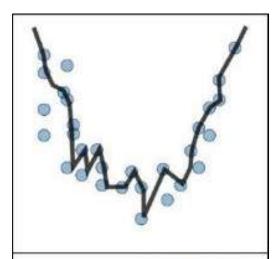


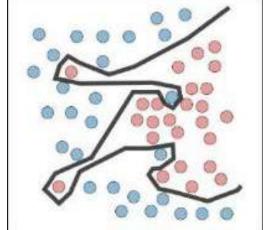
low in-sample error high out-of-sample error

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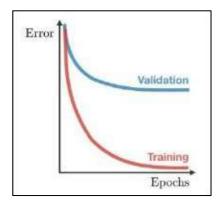
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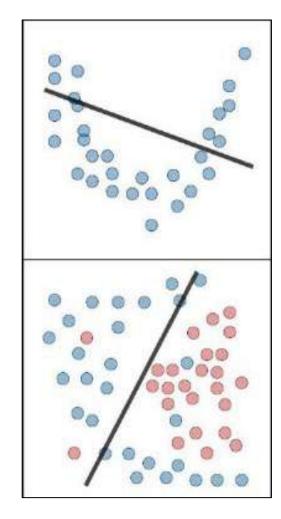
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- Regularization
- Get more data

Underfitting (High Bias)

Regression

Classification

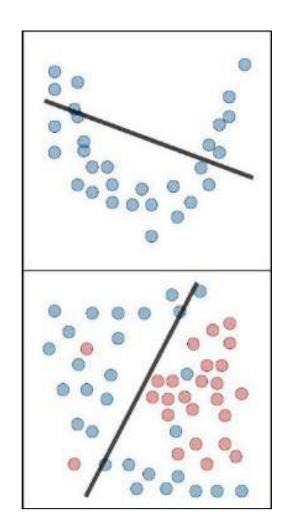


The hypothesis h^* is too "simple" for approximating the true f

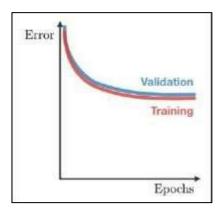
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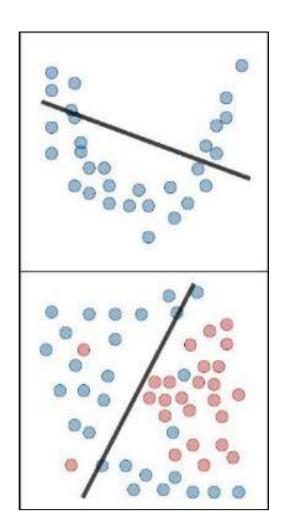


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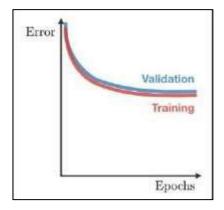
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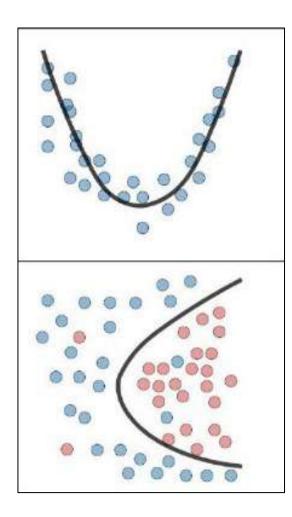
- Increase model complexity
- Add more features

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Bias-Variance Tradeoff

Regression

Classification



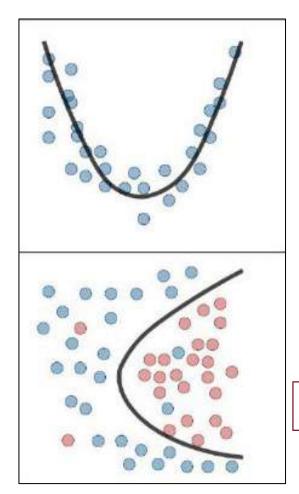
The hypothesis h^* is just right: the simplest one explaining the data

Occam's razor

Bias-Variance Tradeoff

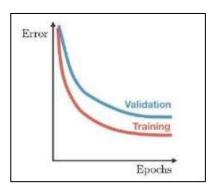
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Estimating Generalization Performance

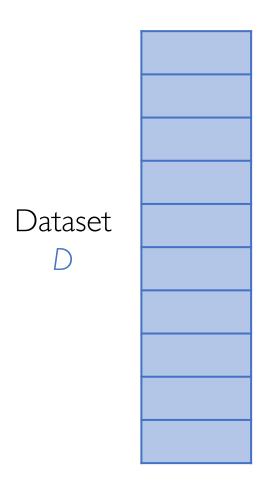
 Measuring the generalization (i.e., out-of-sample) performance online may be too risky

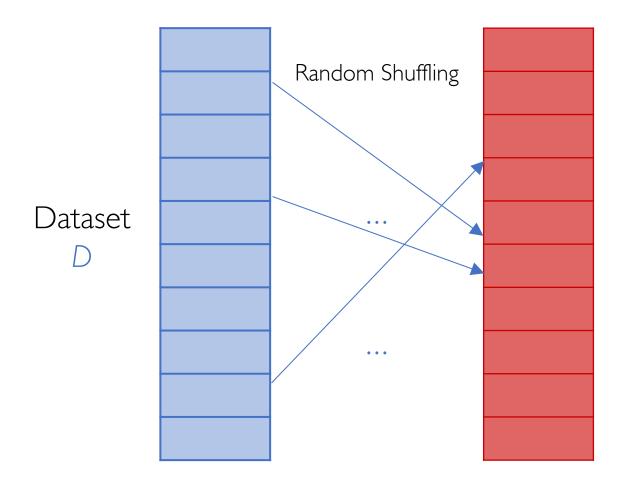
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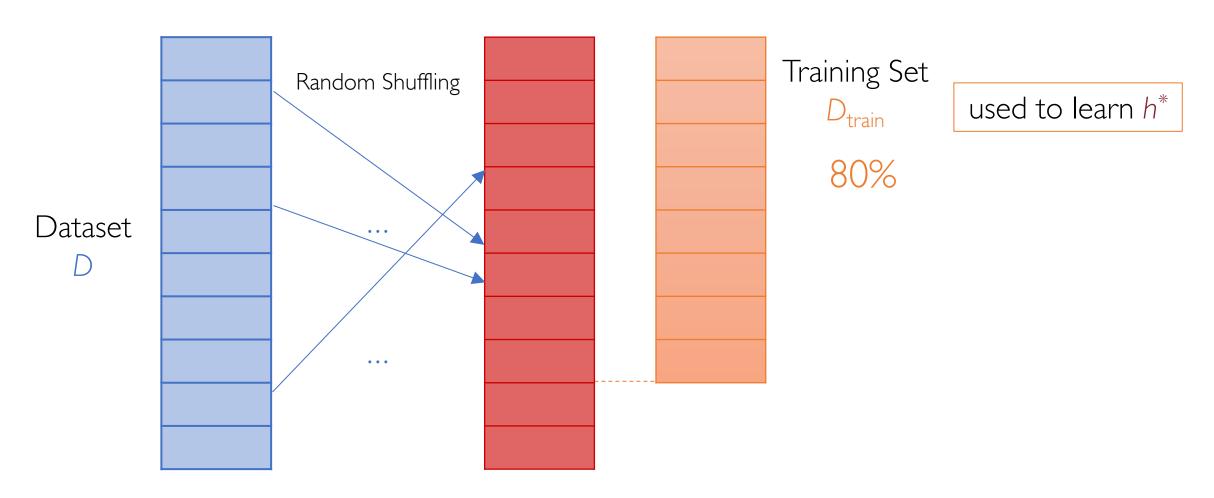
- Measuring the generalization (i.e., out-of-sample) performance online may be too risky
- Example: Don't want to deploy your new spam classifier in production knowing only its training (i.e., in-sample) performance

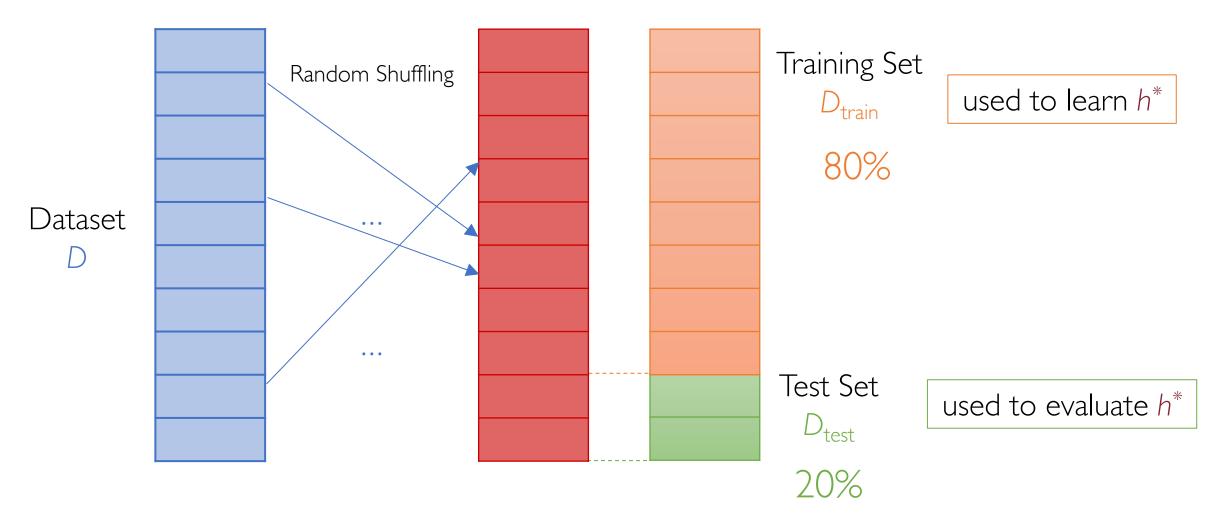
Estimating Generalization Performance

- Measuring the generalization (i.e., out-of-sample) performance online may be too risky
- Example: Don't want to deploy your new spam classifier in production knowing only its training (i.e., in-sample) performance
- Solution: Estimate the generalization performance using training set
 - As long as it holds true the assumption that training and test instances are both drawn from the same probability distribution (i.i.d. assumption)



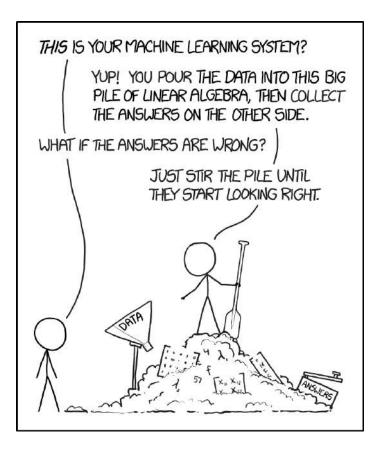






How Much Data Do We Need?

In general, the more data we have the better we learn



04/04/2023 source: https://xkcd.com/1838/

• A generalization of the training/test splitting seen before

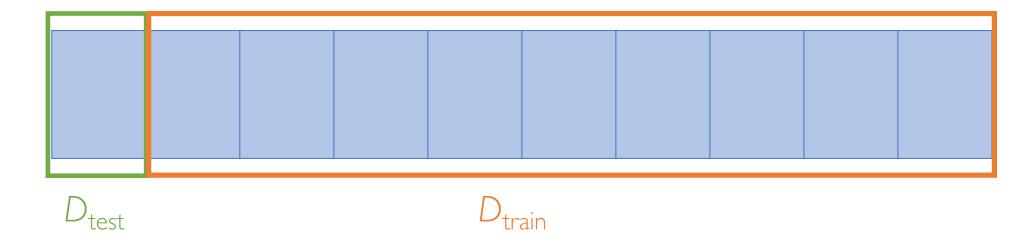
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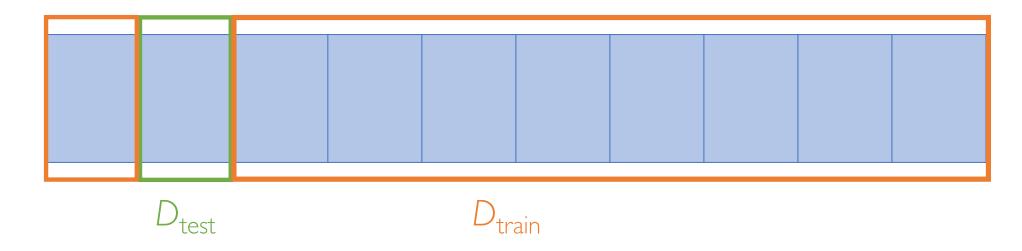
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- Divide your dataset D into K distinct folds
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- The estimate of generalization error is the average across the K test folds of all the K rounds

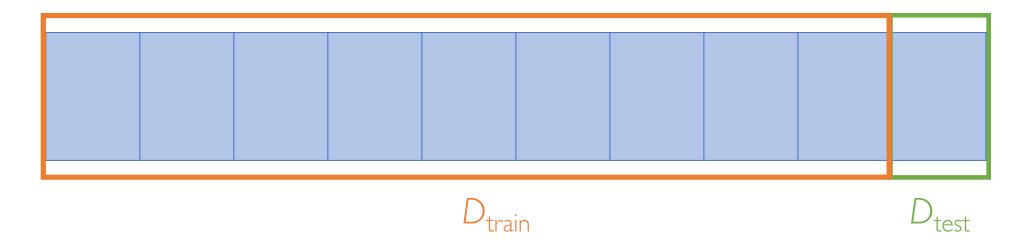
Round k = 1



Round k = 2



Round k = 10



Model Selection/Evaluation

Several different learning models to achieve the same task



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Each learning model has its own set of hyperparameters (e.g., the number k of neighbors in kNN)

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Model Selection/Evaluation

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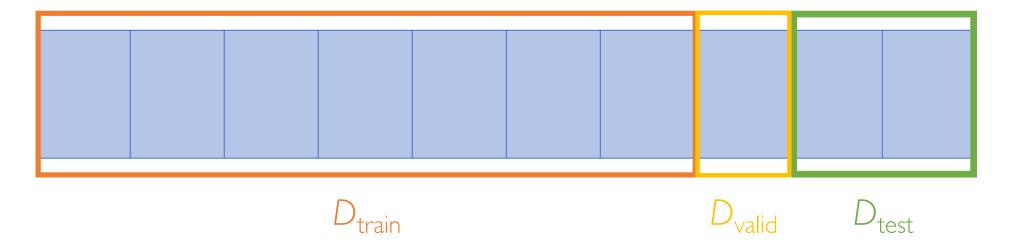
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How do we select the best model?

Model Selection/Evaluation: Validation Set

Separate hyperparameter selection from model evaluation

D_{valid} is used to validate hyperparameters



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- 2) Measure the error of each model on the validation set (e.g., 10%)

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Note:

The strategy above can also be extended to K-fold Cross Validation

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 - Hypothesis space (assumption)
 - Loss Function (objective)
 - Learning Algorithm (optimizer)

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Suggested reading: https://homes.cs.washington.edu/~pedrod/papers/cacm12.pdf