

## ***Chapter 3: Single-stage Amplifiers***

**3.1 Applications**

**3.2 General Considerations**

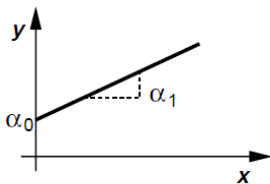
**3.3 Common-Source Stage**

**3.4 Source Follower**

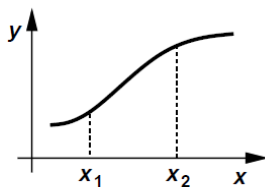
**3.5 Common-Gate Stage**

**3.6 Cascode Stage**

# Ideal vs Non-ideal Amplifier



(a)



(b)

- **Ideal amplifier (Fig. a)**

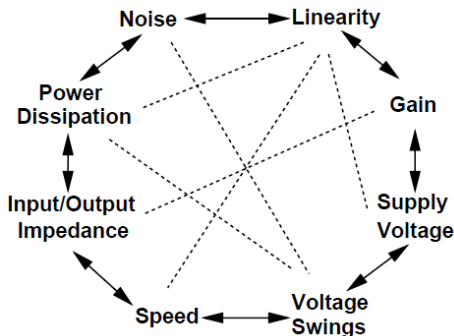
$$y(t) = \alpha_0 + \alpha_1 x(t)$$

- **Large-signal characteristic is a straight line**
- **$\alpha_1$  is the “gain”,  $\alpha_0$  is the “dc bias”**
- **Nonlinear amplifier (Fig. b)**

$$y(t) = \alpha_0 + \alpha_1 x(t) + \alpha_2 x^2(t) + \cdots + \alpha_n x^n(t)$$

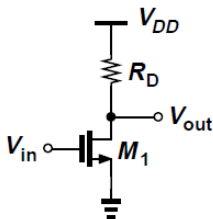
- **Large signal excursions around bias point**
- **Varying “gain”, approximated by polynomial**
- **Causes distortion of signal of interest**

# Analog Design Tradeoff



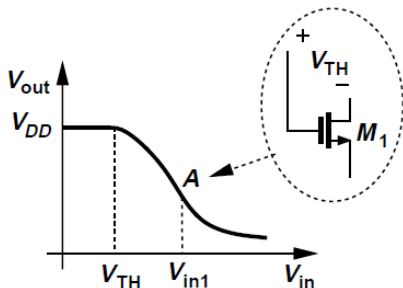
- Along with gain and speed, other parameters also important for amplifiers
- Input and output impedances decide interaction with preceding and subsequent stages
- Performance parameters trade with each other
- Multi-dimensional optimization problem

# Common-Source stage with Resistive load



- **Very high input impedance at low frequencies**
- **For  $V_{in} < V_{TH}$ ,  $M1$  is off and  $V_{out} = V_{DD}$**

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2$$



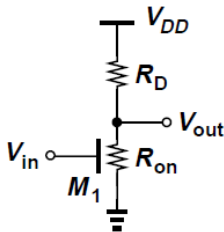
- **When  $V_{in} > V_{TH}$ ,  $M1$  turns on in saturation region,  $V_{out}$  falls**
- **When  $V_{in} > V_{in1}$ ,  $M1$  enters triode region**
- **At point A,  $V_{out} = V_{in1} - V_{TH}$**

$$V_{in1} - V_{TH} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in1} - V_{TH})^2$$

# Common-Source stage with Resistive load

- For  $V_{in} > V_{in1}$ ,

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} \left[ 2(V_{in} - V_{TH})V_{out} - V_{out}^2 \right]$$



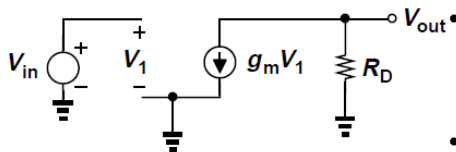
- If  $V_{in}$  is high enough to drive  $M_1$  into deep triode region so that  $V_{out} \ll 2(V_{in} - V_{TH})$ ,

$$\begin{aligned} V_{out} &= V_{DD} \frac{R_{on}}{R_{on} + R_D} \\ &= \frac{V_{DD}}{1 + \mu_n C_{ox} \frac{W}{L} R_D (V_{in} - V_{TH})} \end{aligned}$$

# Common-Source stage with Resistive load

$$\begin{aligned}A_v &= \frac{\partial V_{out}}{\partial V_{in}} \\&= -R_D \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH}) \\&= -g_m R_D.\end{aligned}$$

- Taking derivative of  $I_D$  equation in saturation region, small-signal gain is obtained



- Same result is obtained from small-signal equivalent circuit

$$V_{out} = -g_m V_1 R_D = -g_m V_{in} R_D$$

- $g_m$  and  $A_v$  vary for large input signal swings according to

$$g_m = \mu_n C_{ox} (W/L) (V_{GS} - V_{TH})$$

- This causes non-linearity

# Common-Source stage with Resistive load

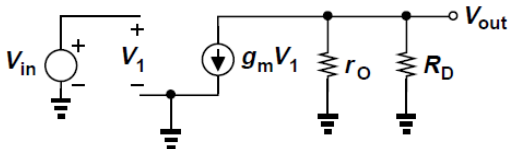
- For large values of  $R_D$ , channel-length modulation of  $M1$  becomes significant,  $V_{out}$  equation becomes

$$V_{out} = V_{DD} - R_D \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH})^2 (1 + \lambda V_{out})$$

- Voltage gain is

$$A_v = -g_m \frac{r_O R_D}{r_O + R_D}$$

- Above result is also obtained from small-signal equivalent circuit



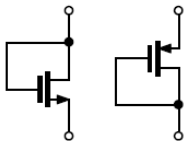
$$V_1 = V_{in}$$

$$g_m V_1 (r_O \parallel R_D) = -V_{out}$$

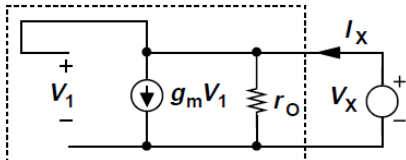
$$V_{out}/V_{in} = -g_m (r_O \parallel R_D)$$

# Diode-Connected MOSFET

- A MOSFET can operate as a small-signal resistor if its gate and drain are shorted, called a “diode-connected” device
- Transistor always operates in saturation



Diode-Connected Device



- Impedance of the device can be found from small-signal equivalent model

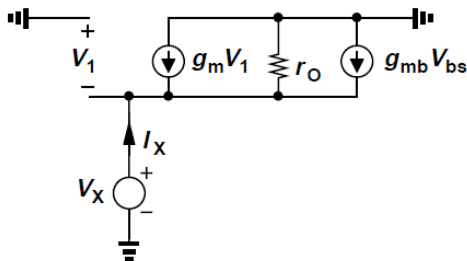
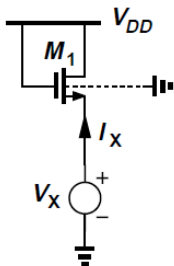
$$V_1 = V_X$$

$$I_X = V_X/r_O + g_m V_X$$

$$V_X/I_X = (1/g_m) \parallel r_O \approx 1/g_m$$



# Diode-Connected MOSFET



- Including body-effect, impedance “looking into” the source terminal of diode-connected device is found as

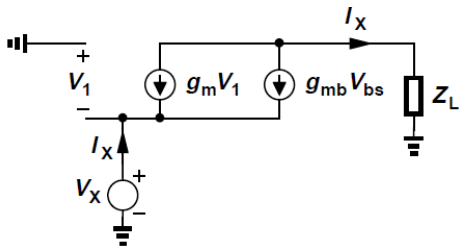
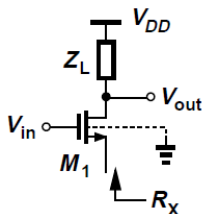
$$V_1 = -V_X \quad V_{bs} = -V_X$$

$$(g_m + g_{mb})V_X + \frac{V_X}{r_O} = I_X$$

$$\begin{aligned} \frac{V_X}{I_X} &= \frac{1}{g_m + g_{mb} + r_O^{-1}} \\ &= \frac{1}{g_m + g_{mb}} \parallel r_O \\ &\approx \frac{1}{g_m + g_{mb}}. \end{aligned}$$

# Diode-Connected MOSFET: Example

- Find  $R_X$  if  $\lambda = 0$



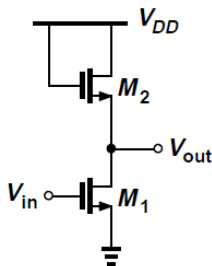
- Set in dependent sources to zero, apply  $V_X$  and find resulting  $I_X$   
 $V_1 = V_X$   
 $V_{bs} = -V_X$

$$(g_m + g_{mb})V_X = I_X$$

$$\frac{V_X}{I_X} = \frac{1}{g_m + g_{mb}}$$

- Loosely said that looking into source of MOSFET, we see  $1/g_m$  when  $\lambda = \gamma = 0$

# CS Stage with Diode-Connected Load



- Neglecting channel-length modulation, using impedance result for diode-connected device,

$$\begin{aligned} A_v &= -g_{m1} \frac{1}{g_{m2} + g_{mb2}} \\ &= -\frac{g_{m1}}{g_{m2}} \frac{1}{1 + \eta}, \end{aligned}$$

where,

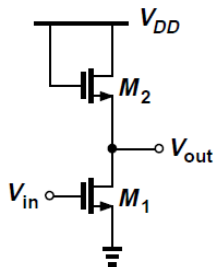
$$\eta = g_{mb2}/g_{m2}.$$

- Expressing  $g_{m1}$  and  $g_{m2}$  in terms of device dimensions,

$$A_v = -\sqrt{\frac{(W/L)_1}{(W/L)_2}} \frac{1}{1 + \eta}$$

- This shows that gain is a weak function of bias currents and voltages, i.e., relatively linear input-output characteristic

# CS Stage with Diode-Connected Load



- From large-signal analysis,

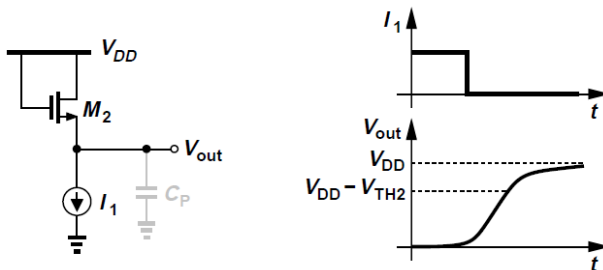
$$\frac{1}{2}\mu_n C_{ox} \left(\frac{W}{L}\right)_1 (V_{in} - V_{TH1})^2 = \frac{1}{2}\mu_n C_{ox} \left(\frac{W}{L}\right)_2 (V_{DD} - V_{out} - V_{TH2})^2$$

$$\sqrt{\left(\frac{W}{L}\right)_1} (V_{in} - V_{TH1}) = \sqrt{\left(\frac{W}{L}\right)_2} (V_{DD} - V_{out} - V_{TH2})$$

- If  $V_{TH2}$  does not vary much with  $V_{out}$ , input-output characteristic is relatively linear.
- Squaring function of  $M_1$  (from its input voltage to its drain current) and square root function of  $M_2$  (from its drain current to its overdrive) act as inverse functions

$$f^{-1}(f(x)) = x.$$

# CS Stage with Diode-Connected Load

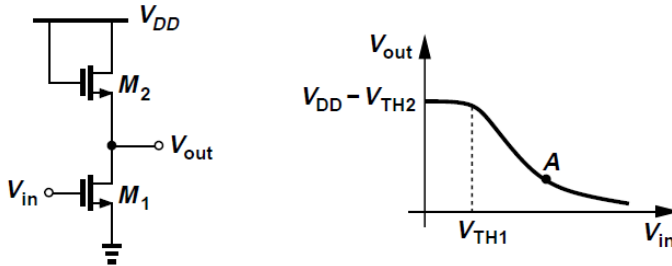


- As  $I_1$  falls, so does overdrive of  $M_2$  so that

$$V_{GS2} \approx V_{TH2} \quad V_{out} \approx V_{DD} - V_{TH2}$$

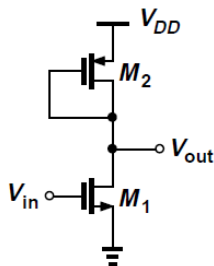
- Subthreshold conduction of  $M_2$  eventually brings  $V_{out}$  to  $V_{DD}$ , but at very low current levels, finite capacitance at output node  $C_P$  slows down the change in  $V_{out}$  from  $V_{DD} - V_{TH2}$  to  $V_{DD}$ .
- In high-frequency circuits,  $V_{out}$  remains around  $V_{DD} - V_{TH2}$  when  $I_1$  falls to small values.

# CS Stage with Diode-Connected Load



- For  $V_{in} < V_{TH1}$ ,  $V_{out} = V_{DD} - V_{TH2}$
- When  $V_{in} > V_{TH1}$ , previous large-signal analysis predicts that  $V_{out}$  approximately follows a single line
- As  $V_{in}$  exceeds  $V_{out} + V_{TH1}$  (to the right of point A),  $M_1$  enters the triode region and the characteristic becomes nonlinear.

# CS Stage with Diode-Connected PMOS device



- Diode-connected load can be implemented as a PMOS device, free of body-effect
- Small-signal voltage gain neglecting channel-length modulation

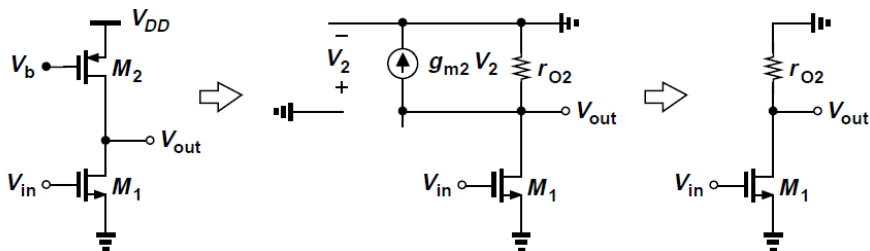
$$A_v = -\sqrt{\frac{\mu_n(W/L)_1}{\mu_p(W/L)_2}}$$

- Gain is a relatively weak function of device dimensions
- Since  $\mu_n \approx 2\mu_p$ , high gain requires “strong” input device (narrow) and “weak” load device (wide)
- This limits voltage swings since for  $\lambda = 0$ , we get

$$\frac{|V_{GS2} - V_{TH2}|}{V_{GS1} - V_{TH1}} = A_v$$

- For diode-connected loads, swing is constrained by both required overdrive voltage and threshold voltage, i.e., for small overdrive, output cannot exceed  $V_{DD} - |V_{TH}|$ .

# CS Stage with Current-Source Load

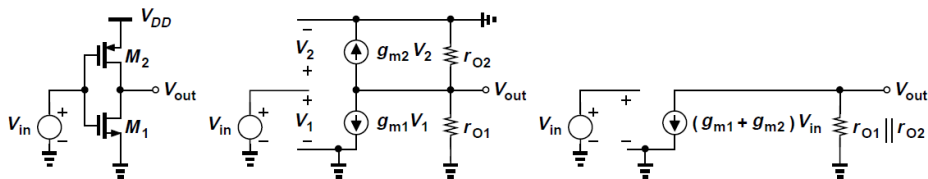


- Current-source load allows a high load resistance without limiting output swing
- Voltage gain is  $A_v = -g_{m1}(r_{O1}||r_{O2})$
- Overdrive of  $M_2$  can be reduced by increasing its width,  $r_{O2}$  can be increased by increasing its length
- Output bias voltage is not well-defined
- Intrinsic gain of  $M_1$  increases with  $L$  and decreases with  $I_D$

$$g_{m1}r_{O1} = \sqrt{2 \left( \frac{W}{L} \right)_1 \mu_n C_{ox} I_D} \frac{1}{\lambda I_D}$$



# CS Stage with Active Load



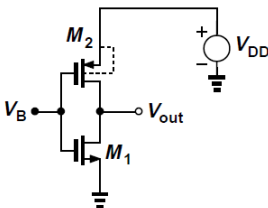
- Input signal is also applied to gate of load device, making it an “active” load
- $M1$  and  $M2$  operate in parallel and enhance the voltage gain
- From small-signal equivalent circuit,

$$-(g_{m1} + g_{m2})V_{in}(r_{O1} || r_{O2}) = V_{out}$$

$$A_v = -(g_{m1} + g_{m2})(r_{O1} || r_{O2})$$

- Same output resistance as CS stage with current-source load, but higher transconductance
- Bias current of  $M1$  and  $M2$  is a strong function of PVT

# CS Stage with Active Load: Supply sensitivity

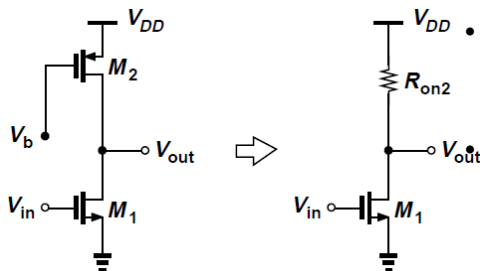


$$V_{GS1} + |V_{GS2}| = V_{DD}$$

- **Variations in  $V_{DD}$  or the threshold voltages directly translate to changes in the drain currents**
- **Supply voltage variations “supply noise” are amplified too**
- **Voltage gain from  $V_{DD}$  to  $V_{out}$  can be found to be**

$$\begin{aligned}\frac{V_{out}}{V_{DD}} &= \frac{g_{m2}r_{O2} + 1}{r_{O2} + r_{O1}}r_{O1} \\ &= \left(g_{m2} + \frac{1}{r_{O2}}\right)(r_{O1}||r_{O2})\end{aligned}$$

# CS Stage with Triode Load



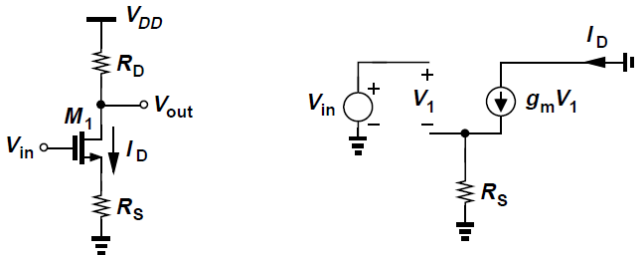
- A MOS device biased in the deep triode region acts as a resistive load in a CS stage
- $V_b$  is sufficiently low to ensure  $M_2$  is in deep triode region for all output voltage swings

- Voltage gain is  $A_v = -g_{m1}R_{on2}$ , where  $R_{on2}$  is the MOS ON resistance given by

$$R_{on2} = \frac{1}{\mu_p C_{ox} (W/L)_2 (V_{DD} - V_b - |V_{THP}|)}$$

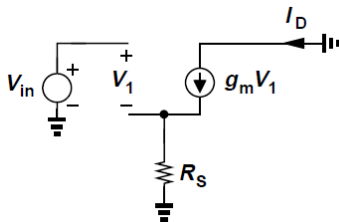
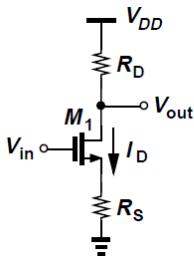
- $R_{on2}$  depends on  $\mu_p C_{ox}$ ,  $V_b$  and  $V_{THP}$  which vary with PVT
- Generating a precise value of  $V_b$  is complex, which makes circuit hard to use
- Triode loads consume lesser voltage headroom than diode-connected devices since  $V_{out,max} = V_{DD}$  for the former, whereas  $V_{out,max} = V_{DD} - |V_{THP}|$  for the latter.

# CS Stage with Source Degeneration



- Degeneration resistor  $R_S$  in series with source terminal makes input device more linear
  - As  $V_{in}$  increases, so do  $I_D$  and the voltage drop across  $R_S$
  - Part of the change in  $V_{in}$  appears across  $R_S$  rather than gate-source overdrive, making variation in  $I_D$  smoother
- Gain is now a weaker function of  $g_m$

# CS Stage with Source Degeneration



- **Nonlinearity of circuit is due to nonlinear dependence of  $I_D$  upon  $V_{in}$**
- **Equivalent transconductance  $G_m$  of the circuit can be defined as**  $G_m = \partial I_D / \partial V_{in}$

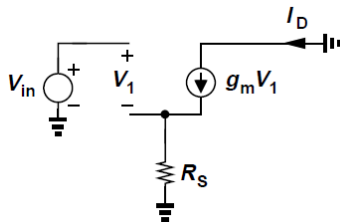
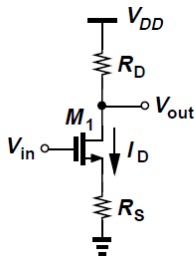
$$V_{out} = V_{DD} - I_D R_D$$

$$\partial V_{out} / \partial V_{in} = -(\partial I_D / \partial V_{in}) R_D$$

$$I_D = f(V_{GS})$$

$$\begin{aligned} G_m &= \frac{\partial I_D}{\partial V_{in}} \\ &= \frac{\partial f}{\partial V_{GS}} \frac{\partial V_{GS}}{\partial V_{in}} \end{aligned}$$

# CS Stage with Source Degeneration



$$V_{GS} = V_{in} - I_D R_S$$

$$\partial V_{GS} / \partial V_{in} = 1 - R_S \partial I_D / \partial V_{in}$$

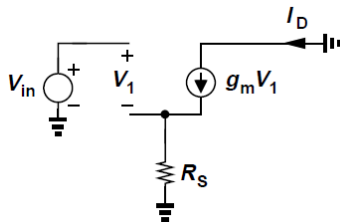
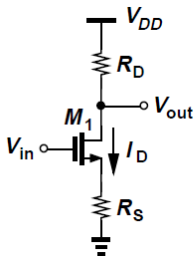
$$G_m = \left( 1 - R_S \frac{\partial I_D}{\partial V_{in}} \right) \frac{\partial f}{\partial V_{GS}}$$

$$G_m = \frac{g_m}{1 + g_m R_S}$$

- **$g_m$  is the transconductance of  $M1$**
- **Small-signal voltage gain  $A_v$  is then given by**

$$\begin{aligned} A_v &= -G_m R_D \\ &= \frac{-g_m R_D}{1 + g_m R_S} \end{aligned}$$

# CS Stage with Source Degeneration



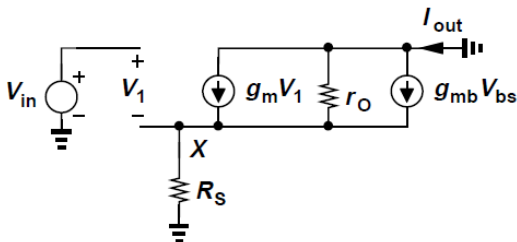
- Same result for  $G_m$  is obtained from small-signal equivalent circuit, by noting that

$$V_{in} = V_1 + I_D R_S$$

$$I_D = g_m V_1$$

- As  $R_S$  increases,  $G_m$  becomes a weaker function of  $g_m$  and hence  $I_D$
- For  $R_S \gg 1/g_m$ ,  $G_m \approx 1/R_S$ , i.e.,  $\Delta I_D \approx \Delta V_{in}/R_S$
- Most of the change in  $v_{in}$  across  $R_S$  and drain current becomes a “linearized” function of input voltage

# CS Stage with Source Degeneration



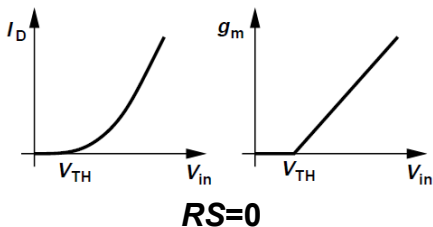
- Including body-effect and channel-length modulation,  $G_m$  is found from modified small-signal equivalent circuit

$$\begin{aligned}
 V_{in} &= V_1 + I_{out} R_S \\
 I_{out} &= g_m V_1 - g_{mb} V_X - \frac{I_{out} R_S}{r_O} \\
 &= g_m (V_{in} - I_{out} R_S) + g_{mb} (-I_{out} R_S) - \frac{I_{out} R_S}{r_O} \\
 G_m &= \frac{I_{out}}{V_{in}} \\
 &= \frac{g_m r_O}{R_S + [1 + (g_m + g_{mb}) R_S] r_O}
 \end{aligned}$$

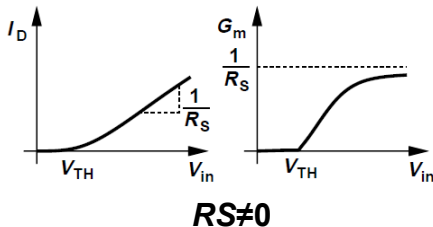


# CS Stage with Source Degeneration

## Large-signal behavior



- $I_D$  and  $g_m$  vary with  $V_{in}$  as derived in calculations in Chapter 2



- At low current levels, turn-on behavior is similar to when  $R_S = 0$  since  

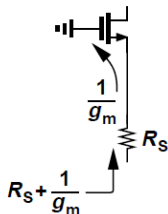
$$\text{and } 1/g_m \gg R_S$$
- As overall  $G_m \approx g_m$  increases, effect of  $R_S$  becomes more significant

## CS Stage with Source Degeneration

- Small-signal derived previously can be written as

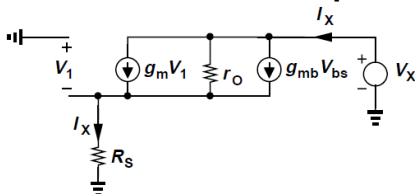
$$A_v = -\frac{R_D}{\frac{1}{g_m} + R_S}$$

- Denominator = Series combination of inverse transconductance + explicit resistance seen from source to ground
- Called “resistance seen in the source path”
- Magnitude of gain = Resistance seen at the drain/ Total resistance seen in the source path



# CS Stage with Source Degeneration

- Degeneration causes increase in output resistance



- Ignoring  $R_D$  and  $r_O$ , the small-signal equivalent model,

$$V_1 = -I_X R_S$$

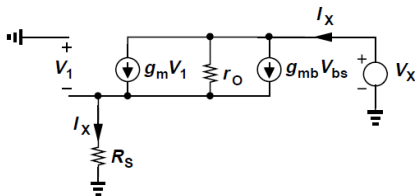
$$I_X - (g_m + g_{mb})V_1 = I_X + (g_m + g_{mb})R_S I_X$$

$$R_{out} = [1 + (g_m + g_{mb})R_S]r_O + R_S$$

- $r_O$  is boosted by a factor of  $[1 + (g_m + g_{mb})R_S]$  and then added to  $R_S$
- Alternatively,  $R_S$  is boosted by a factor of  $\{1 + (g_m + g_{mb})r_O\}$  and then added to  $r_O$

# CS Stage with Source Degeneration

- Compare  $R_S = 0$  with  $R_S > 0$

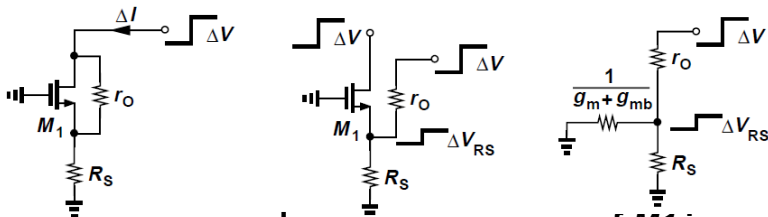


- If  $R_S = 0$ ,  $g_m V_1 = g_{mb} V_{bs} = 0$  and  $I_X = V_X / r_o$
- If  $R_S > 0$ ,  $I_X R_S > 0$  and  $V_1 < 0$ , obtaining negative  $g_m V_1$  and  $g_{mb} V_{bs}$
- Thus, current supplied by  $V_X$  is less than  $V_X / r_o$  and hence output impedance is greater than  $r_o$

# CS Stage with Source Degeneration

## Intuitive understanding of increased output impedance

- Apply voltage change  $\Delta V$  at output and measure resulting change  $\Delta I$  in output current, which is also the change in current through  $R_S$

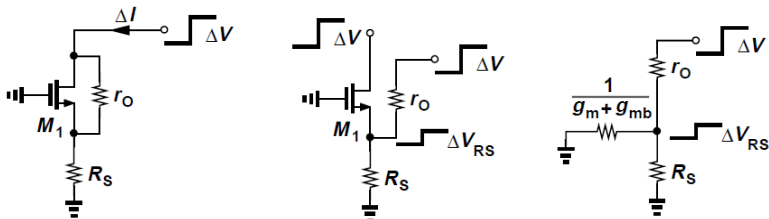


- Resistance seen looking into the source of  $M_1$  is  $1/(g_m + g_{mb})$
- Voltage change across  $R_S$  is

$$\Delta V_{RS} = \Delta V \frac{\frac{1}{g_m + g_{mb}} \parallel R_S}{\frac{1}{g_m + g_{mb}} \parallel R_S + r_O}$$

# CS Stage with Source Degeneration

## Intuitive understanding of increased output impedance



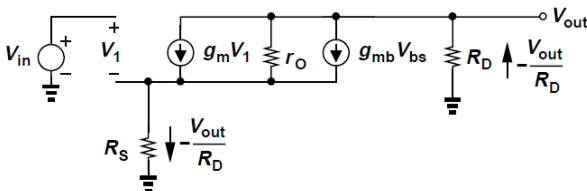
•Change in current across  $R_S$  is

$$\begin{aligned}\Delta I &= \frac{\Delta V_{RS}}{R_S} \\ &= \Delta V \frac{1}{[1 + (g_m + g_{mb})R_S]r_O + R_S}.\end{aligned}$$

•Output resistance is thus

$$\frac{\Delta V}{\Delta I} = [1 + (g_m + g_{mb})R_S]r_O + R_S$$

# CS Stage with Source Degeneration



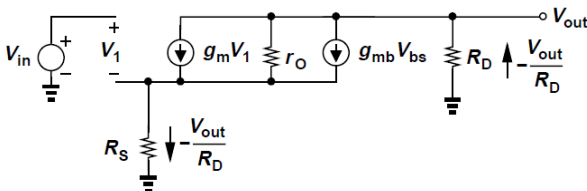
- To compute gain in the general case including body effect and channel-length modulation, consider above small-signal model
- From KVL at input,

$$V_1 = V_{in} + V_{out} R_S / R_D$$

- KCL at output gives

$$\begin{aligned} I_{r_O} &= -\frac{V_{out}}{R_D} - (g_m V_1 + g_{mb} V_{bs}) \\ &= -\frac{V_{out}}{R_D} - \left[ g_m \left( V_{in} + V_{out} \frac{R_S}{R_D} \right) + g_{mb} V_{out} \frac{R_S}{R_D} \right] \end{aligned}$$

# CS Stage with Source Degeneration



- Since voltage drops across  $r_O$  and  $R_S$  must add up to  $V_{out}$

$$\begin{aligned}
 V_{out} &= I_{r_O} r_O - \frac{V_{out}}{R_D} R_S \\
 &= -\frac{V_{out}}{R_D} r_O - \left[ g_m \left( V_{in} + V_{out} \frac{R_S}{R_D} \right) + g_{mb} V_{out} \frac{R_S}{R_D} \right] r_O - V_{out} \frac{R_S}{R_D}
 \end{aligned}$$

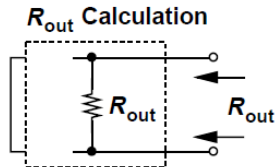
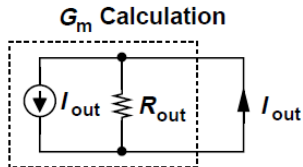
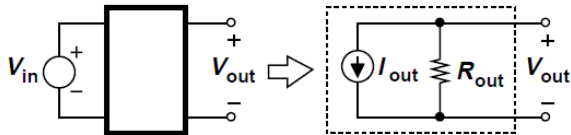
- Voltage gain is therefore

$$\frac{V_{out}}{V_{in}} = \frac{-g_m r_O R_D}{R_D + R_S + r_O + (g_m + g_{mb}) R_S r_O}$$

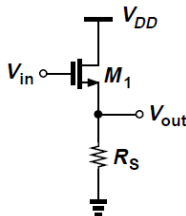


# Lemma

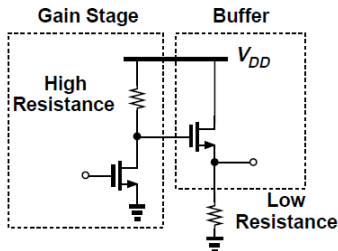
- In a linear circuit, the voltage gain is equal to  $-G_m R_{out}$ 
  - $G_m$  denotes the transconductance of the circuit when output is shorted to ground
  - $R_{out}$  represents the output resistance of the circuit when the input voltage is set to zero
- Norton equivalent of a linear circuit



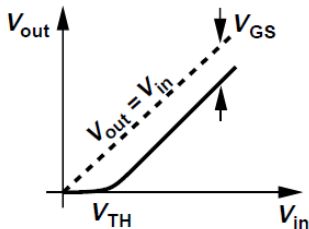
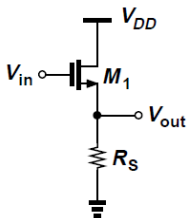
# Source Follower



- Source follower (also called “common-drain” stage) senses the input at the gate and drives load at the source
- It presents a high input impedance, allowing source potential to “follow” the gate voltage
- Acts as a voltage buffer



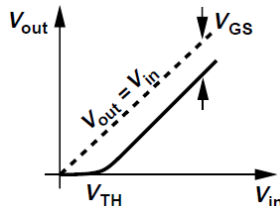
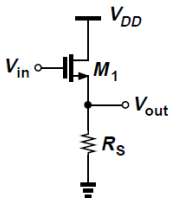
# Source Follower



- For  $V_{in} < V_{TH}$ ,  $M1$  is off and  $V_{out} = 0$
- As  $V_{in}$  exceeds  $V_{TH}$ ,  $M1$  turns on in saturation since  $V_{DS} = V_{DD}$  and  $V_{GS} - V_{TH} \approx 0$  and  $I_{D1}$  flows through  $R_S$
- As  $V_{in}$  increases further,  $V_{out}$  follows the input with a difference (level shift) equal to  $V_{GS}$
- Input-output characteristic neglecting channel-length modulation can be expressed as

$$\frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH} - V_{out})^2 R_S = V_{out}$$

# Source Follower



- For  $V_{in} < V_{TH}$ ,  $M1$  is off and  $V_{out} = 0$
- Differentiating both sides of large-signal equation for  $V_{out}$ ,

$$\frac{1}{2}\mu_n C_{ox} \frac{W}{L} 2(V_{in} - V_{TH} - V_{out}) \left(1 - \frac{\partial V_{TH}}{\partial V_{in}} - \frac{\partial V_{out}}{\partial V_{in}}\right) R_S = \frac{\partial V_{out}}{\partial V_{in}}$$

- Since  $\partial V_{TH} / \partial V_{in} = (\partial V_{TH} / \partial V_{SB})(\partial V_{SB} / \partial V_{in}) = \eta \partial V_{out} / \partial V_{in}$

- Therefore, 
$$\frac{\partial V_{out}}{\partial V_{in}} = \frac{\mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH} - V_{out}) R_S}{1 + \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH} - V_{out}) R_S (1 + \eta)}$$

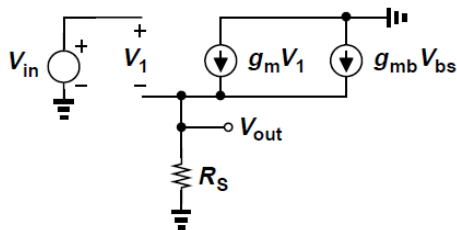
- Note that 
$$g_m = \mu_n C_{ox} \frac{W}{L} (V_{in} - V_{TH} - V_{out})$$

- Therefore,

$$A_v = \frac{g_m R_S}{1 + (g_m + g_{mb}) R_S}$$

# Source Follower

- Small-signal gain can be obtained more easily using small-signal equivalent model



- We have,  $V_{in} - V_1 = V_{out}, V_{bs} = -V_{out}$

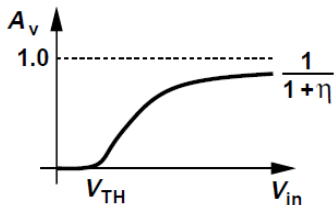
- KVL:

$$g_m V_1 - g_{mb} V_{out} = V_{out} / R_S$$

- KCL:

- Therefore,  $V_{out} / V_{in} = g_m R_S / [1 + (g_m + g_{mb}) R_S]$

# Source Follower

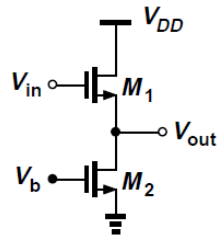
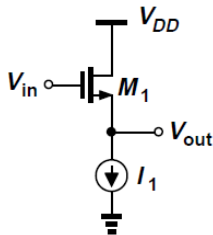
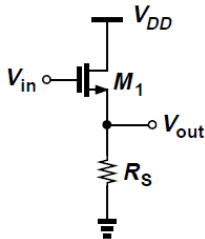


- Voltage gain begins from zero for  $V_{in} \approx V_{TH}$  ( $g_m \approx 0$ ), and monotonically increases
- As drain current and  $g_m$  increase,  $A_v$  approaches

$$g_m / (g_m + g_{mb}) = 1 / (1 + \eta)$$

- Since  $\eta$  itself slowly decreases with  $V_{out}$ ,  $A_v$  would eventually become equal to unity, but for typical allowable source-bulk voltages,  $\eta$  remains greater than roughly than 0.2
- Even if  $R_S = \infty$ , voltage gain of a source follower is not equal to one

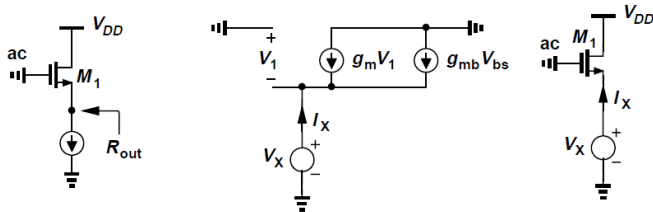
# Source Follower



- Drain current of  $M_1$  depends heavily of input dc level
- Even if  $V_{TH}$  is relatively constant, the increase in  $V_{GS}$  means that  $V_{out}$  ( $=V_{in}-V_{GS}$ ) does not follow  $V_{in}$  faithfully, incurring nonlinearity
- To alleviate this issue, the resistor can be replaced by a constant current source
- Current source is itself is implemented as an NMOS transistor operating in the saturation region

# Source Follower

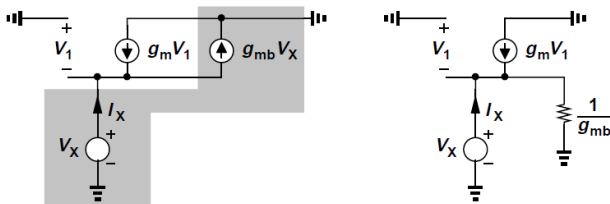
## Calculation of output impedance



- From small-signal equivalent circuit,  $V_X = -V_{bs}$
- It follows that  $I_X - g_m V_X - g_{mb} V_X = 0$  and  $R_{out} = \frac{1}{g_m + g_{mb}}$
- Body effect decreases output resistance of source followers
- If  $V_X$  decreases by  $\Delta V$  so the drain current increases
  - w/o body effect,  $V_{GS}$  increases by  $\Delta V$
  - with body effect,  $V_{TH}$  decreases as well, thus  $(V_{GS} - V_{TH})^2$  and  $I_{D1}$  increase by a greater amount, hence lower output impedance



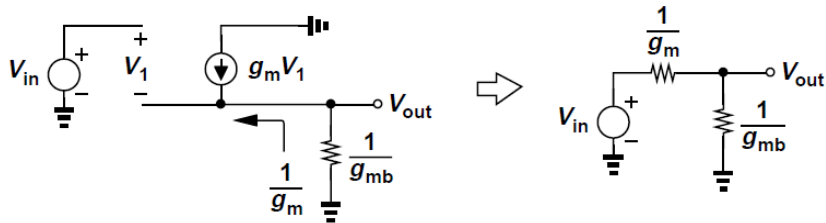
# Source Follower



- Magnitude of the current source  $g_{mb}V_{bs} = g_{mb}V_X$  is linearly proportional to the voltage across it, can be modelled by a resistor equal to  $1/g_{mb}$  (valid only for source followers)
- This appears in parallel with the output, decreasing the overall output resistance
- Since without  $1/g_{mb}$ , the output resistance is  $1/g_m$ , we conclude that

$$\begin{aligned}
 R_{out} &= \frac{1}{g_m} \parallel \frac{1}{g_{mb}} \\
 &= \frac{1}{g_m + g_{mb}}
 \end{aligned}$$

# Source Follower

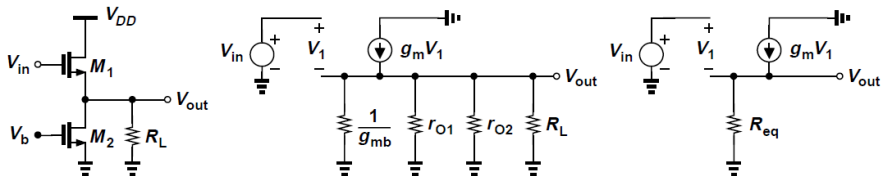


- Modelling effect of  $g_{mb}$  by a resistor helps explain lower than unity gain for  $R_S = \infty$
- From the Thevenin equivalent circuit

$$\begin{aligned} A_v &= \frac{\frac{1}{g_{mb}}}{\frac{1}{g_m} + \frac{1}{g_{mb}}} \\ &= \frac{g_m}{g_m + g_{mb}}. \end{aligned}$$

# Source Follower

- Small-signal equivalent circuit with a finite load resistance and channel-length modulation is shown



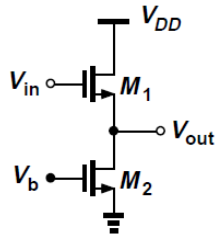
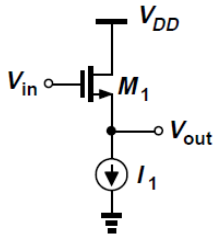
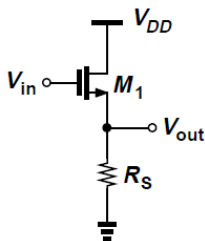
- $1/g_{mb}$ ,  $r_{O1}$ ,  $r_{O2}$  and  $R_L$  are in parallel, therefore,

$$R_{eq} = (1/g_{mb}) || r_{O1} || r_{O2} || R_L$$

- It follows that

$$A_v = \frac{R_{eq}}{R_{eq} + \frac{1}{g_m}}$$

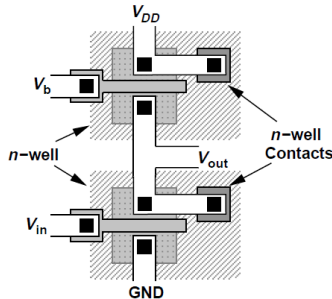
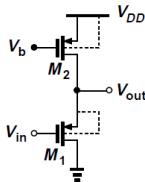
# Issues with Source Follower



- Source followers exhibit high input impedance and moderate output impedance, but at the cost of
  - Nonlinearity
  - Voltage headroom limitation
- Even when biased by ideal current source, there is input-output nonlinearity due to nonlinear dependence of  $V_{TH}$  on the source potential
- In submicron technologies,  $r_O$  changes substantially with  $V_{DS}$  and introduces additional variation in small-signal gain

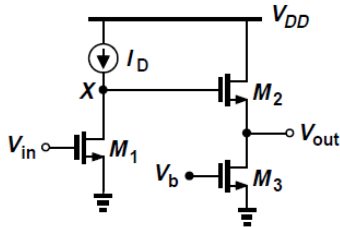
# Issues with Source Follower

- Nonlinearity can be eliminated if the bulk is tied to the source
- Possible only for PFETs since all NFETs usually share the same substrate
- PMOS source follower employing two separate n-wells can eliminate the body effect of  $M_1$
- Lower mobility of PFETs yields a higher output impedance than that available in the NMOS counterpart



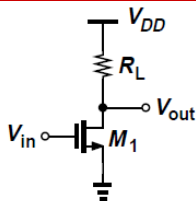
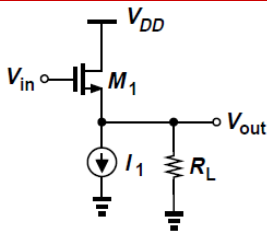
# Issues with Source Follower

- Source followers also shift the dc level of the signal by  $V_{GS}$ , thereby consuming voltage headroom



- In the cascode of source follower shown above,
  - w/o source follower, minimum allowable value of  $V_X$  would be  $V_{GS1} - V_{TH1}$  (for  $M_1$  to remain in saturation)
  - with source follower,  $V_X$  must be greater than  $V_{GS2} + (V_{GS3} - V_{TH3})$  so that  $M_3$  is saturated
- For comparable overdrive voltages in  $M_1$  and  $M_3$ , allowable swing at  $X$  is reduced by  $V_{GS2}$

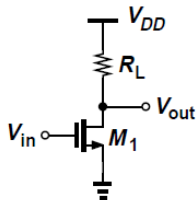
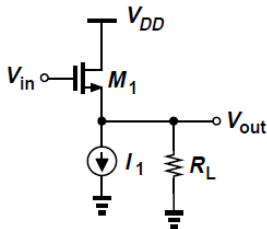
# Comparison of CS stage and Source Follower



- Comparing the gain of source followers and CS stage with a low load impedance
  - E.g., driving an external 50-Ω termination in a high-frequency environment
- When load is driven by a source follower, overall voltage gain is

$$\begin{aligned}\frac{V_{out}}{V_{in}}|_{SF} &\approx \frac{R_L}{R_L + 1/g_{m1}} \\ &\approx \frac{g_{m1}R_L}{1 + g_{m1}R_L}.\end{aligned}$$

# Comparison of CS stage and Source Follower



- Load can be included as part of a common-source stage, providing a gain of

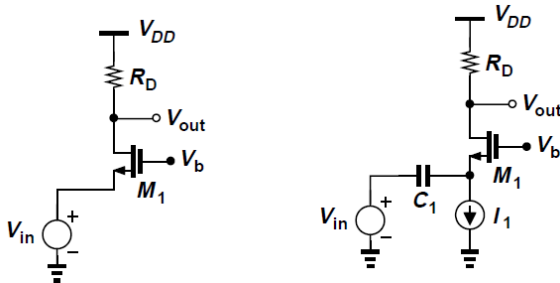
$$\frac{V_{out}}{V_{in}}|_{CS} \approx -g_{m1}R_L$$

- Key difference between the two topologies is the achievable voltage gain for a given bias current
- For example, if  $1/g_{m1} \approx R_L$ , source follower exhibits a gain of at most 0.5 whereas the common-source stage provides a gain close to unity
- Thus, source followers are not efficient drivers



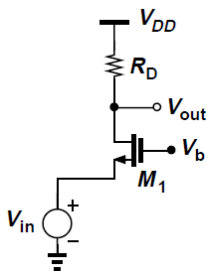
# Common-Gate Stage

- A common-gate (CG) stage senses the input at the source and produces the output at the drain
- Gate is biased to establish proper operating conditions



- Bias current of  $M_1$  flows through the input signal source
- Alternatively,  $M_1$  can be biased by a constant current source, with the signal capacitively coupled to the circuit

# Common-Gate Stage: Large-signal behavior



- Assume  $V_{in}$  decreases from a large positive value and that  $\lambda=0$
- For  $V_{in} \geq V_b - V_{TH}$ ,  $M1$  is off and  $V_{out} = V_{DD}$
- For lower values of  $V_{in}$ , if  $M1$  is in saturation

$$I_D = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_b - V_{in} - V_{TH})^2$$

- As  $V_{in}$  decreases further, so does  $V_{out}$  driving  $M1$  into the triode region if

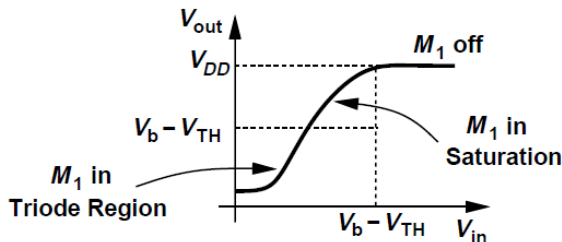
$$V_{DD} - \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_b - V_{in} - V_{TH})^2 R_D = V_b - V_{TH}$$

- In the region where  $M1$  is saturated, we can express the output voltage as

$$V_{out} = V_{DD} - \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_b - V_{in} - V_{TH})^2 R_D$$

# Common-Gate Stage

## Input-output characteristic



- For  $M1$  in saturation,  $V_{out} = V_{DD} - \frac{1}{2}\mu_n C_{ox} \frac{W}{L} (V_b - V_{in} - V_{TH})^2 R_D$
- Small-signal gain can thus be obtained

$$\frac{\partial V_{out}}{\partial V_{in}} = -\mu_n C_{ox} \frac{W}{L} (V_b - V_{in} - V_{TH}) \left( -1 - \frac{\partial V_{TH}}{\partial V_{in}} \right) R_D$$

- Since  $\partial V_{TH} / \partial V_{in} = \partial V_{TH} / \partial V_{SB} = \eta$  we have

$$\begin{aligned} \frac{\partial V_{out}}{\partial V_{in}} &= \mu_n C_{ox} \frac{W}{L} R_D (V_b - V_{in} - V_{TH}) (1 + \eta) \\ &= g_m (1 + \eta) R_D. \end{aligned}$$

# Common-Gate Stage

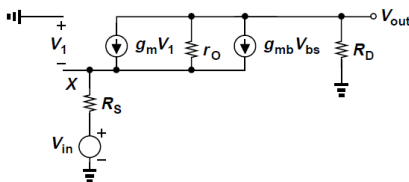
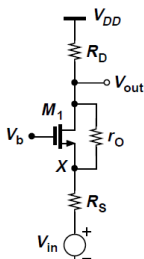
- **Gain of the common-gate (CG) stage is positive**

$$\begin{aligned}\frac{\partial V_{out}}{\partial V_{in}} &= \mu_n C_{ox} \frac{W}{L} R_D (V_b - V_{in} - V_{TH})(1 + \eta) \\ &= g_m (1 + \eta) R_D.\end{aligned}$$

- **Body effect increases the effective transconductance of the stage**
- **For a given bias current and supply voltage (i.e., a given power budget), voltage gain of the CG stage can be maximized by**
  - **Increasing  $g_m$  by widening the input device, eventually reaching subthreshold operation [ $g_m = I_D / \zeta V_T$ ]**
  - **Increasing  $R_D$  and inevitably, the dc drop across it**
- **The minimum allowable value of  $V_{out}$  is  $V_{GS} - V_{TH} + V_{I1}$ , where  $V_{I1}$  denotes the minimum voltage required by  $I_1$**

# Common-Gate Stage

- Consider output impedance of transistor and impedance of the signal source



- In small-signal equivalent circuit, since current flowing  $RS$  is  $-V_{out}/R_D$ ,

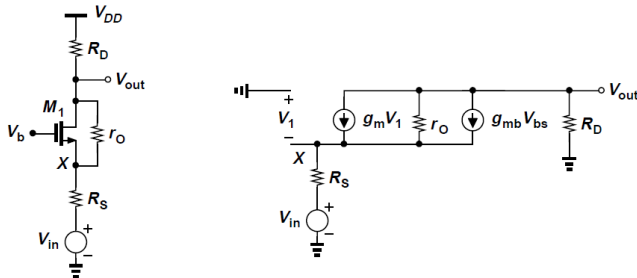
$$V_1 - \frac{V_{out}}{R_D} R_S + V_{in} = 0 \quad (1)$$

- Moreover, since current through  $r_O$  is

$$-V_{out}/R_D - g_m V_1 - g_{mb} V_1$$

$$r_O \left( \frac{-V_{out}}{R_D} - g_m V_1 - g_{mb} V_1 \right) - \frac{V_{out}}{R_D} R_S + V_{in} = V_{out}$$

# Common-Gate Stage



- Substituting  $V_1$  from (1) in (2),

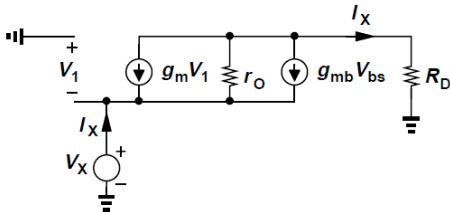
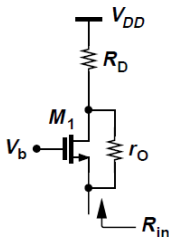
$$r_O \left[ \frac{-V_{out}}{R_D} - (g_m + g_{mb}) \left( V_{out} \frac{R_S}{R_D} - V_{in} \right) \right] - \frac{V_{out} R_S}{R_D} + V_{in} = V_{out}$$

- Therefore,

$$\frac{V_{out}}{V_{in}} = \frac{(g_m + g_{mb})r_O + 1}{r_O + (g_m + g_{mb})r_O R_S + R_S + R_D} R_D$$

- The voltage gain expression is similar to that of a degenerated CS stage

# Common-Gate Stage: Input Impedance



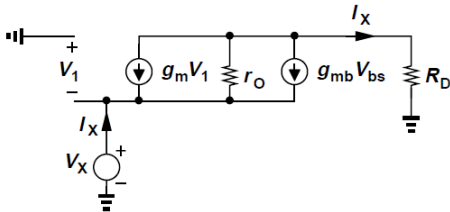
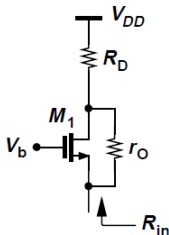
- From the small-signal equivalent circuit for finding input impedance, we have

$$V_1 = -V_X$$

- The current through  $r_O$  is equal to  $I_X + g_m V_1 + g_m b V_1 = I_X - (g_m + g_m b) V_X$
- Voltages across  $r_O$  and  $R_D$  can be added and equated to

$$R_D I_X + r_O [I_X - (g_m + g_m b) V_X] = V_X$$

# Common-Gate Stage: Input Impedance



- Thus,

$$\frac{V_X}{I_X} = \frac{R_D + r_O}{1 + (g_m + g_{mb})r_O}$$

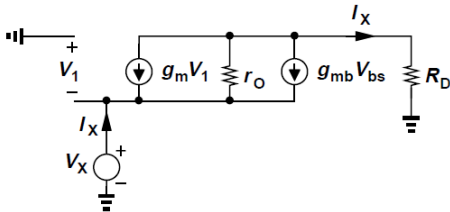
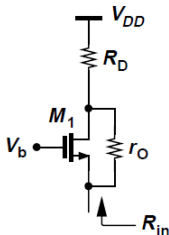
$$\approx \frac{R_D}{(g_m + g_{mb})r_O} + \frac{1}{g_m + g_{mb}}$$

If  $(g_m + g_{mb})r_O \gg 1$ ,

- The drain impedance is divided by  $(g_m + g_{mb})r_O$  when seen at the source
- Important in short-channel devices because of their low intrinsic gain



# Common-Gate Stage: Input Impedance

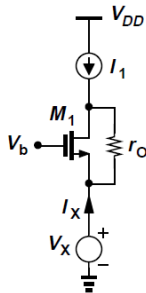


- Suppose  $R_D = 0$ , then

$$\begin{aligned} \frac{V_X}{I_X} &= \frac{r_O}{1 + (g_m + g_{mb})r_O} \\ &= \frac{1}{\frac{1}{r_O} + g_m + g_{mb}}, \end{aligned}$$

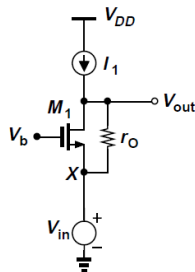
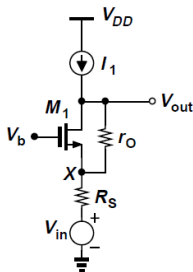
- This is the impedance seen at the source of a source follower, a predictable result since with  $R_D = 0$  the circuit configuration is the same as a source follower

# Common-Gate Stage: Input Impedance



- If  $R_D$  is replaced with an ideal current source, earlier result predicts that input impedance approaches infinity
- Total current through the transistor is fixed and is equal to  $I_1$
- Therefore, a change in the source potential cannot change the device current, and hence  $I_x = 0$
- The input impedance of a CG stage is relatively low *only* if the load impedance connected to the drain is small

# Common-Gate Stage

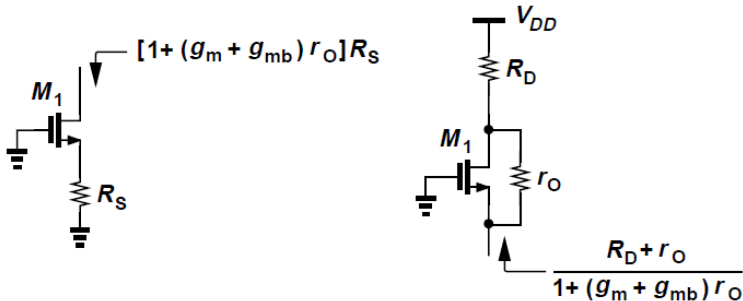


- In a CG stage with a current source load, substituting  $RD=\infty$  in the voltage gain equation, we get

$$A_v = (g_m + g_{mb})r_O + 1$$

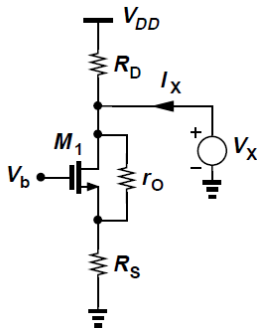
- Gain does not depend on  $RS$
- From the foregoing discussion, if  $RD \rightarrow \infty$ , so does the impedance seen at the source of  $M_1$ , and the small-signal voltage at node  $X$  becomes equal to  $V_{in}$

# Common-Gate Stage



- In a degenerated CS stage, we loosely say that a transistor transforms its source resistance *up*
- In a CG stage, the transistor transforms its drain resistance *down*
- The MOS transistor can thus be viewed as an resistance transformer

## Common-Gate Stage: Output Impedance



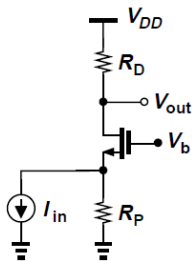
- From the above small-signal equivalent circuit, we can find output impedance as

$$R_{out} = \{[1 + (g_m + g_{mb})r_O]R_S + r_O\} || R_D$$

- Result is similar to that obtained for a degenerated CS stage

## Common-Gate Stage

- Input signal of a common-gate stage may be a current rather than a voltage as shown below



- Input current source ~~exists~~ **exists** output impedance of  $R_P$
- To find the “gain”  $V_{out}/I_{in}$ , replace  $I_{in}$  and  $R_P$  with a Thevenin equivalent and use derived result to write

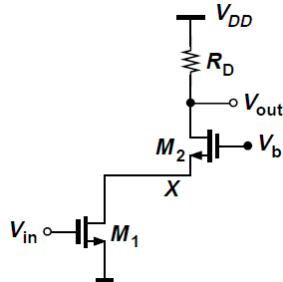
$$\frac{V_{out}}{I_{in}} = \frac{(g_m + g_{mb})r_O + 1}{r_O + (g_m + g_{mb})r_O R_P + R_P + R_D} R_D R_P$$

- Output impedance is simply given by

$$R_{out} = \{[1 + (g_m + g_{mb})r_O]R_P + r_O\} \parallel R_D$$

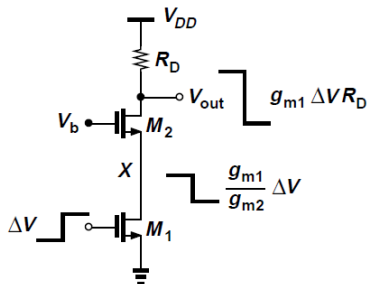
# Cascode Stage

- The cascade of a CS stage and a CG stage is called a cascode topology



- $M_1$  generates a small-signal drain current proportional to the small-signal input  $V_{in}$  and  $M_2$  simply routes the current to  $R_D$
  - $M_1$  is called the input device and  $M_2$  the cascode device
  - $M_1$  and  $M_2$  in this example carry equal bias and signal currents
- Topology also called as “telescopic cascode”

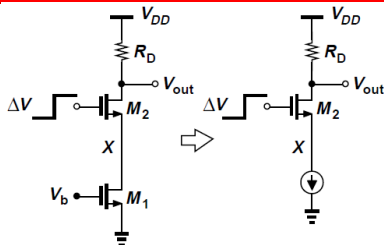
# Cascode Stage: Qualitative Analysis



- Assume both transistors are in saturation and  $\lambda = \gamma = 0$
- If  $V_{in}$  rises by  $\Delta V$ , then  $ID1$  increases by  $g_{m1}\Delta V$
- This change in current flows through the impedance seen at  $X$ , i.e., the impedance seen at the source of  $M_2$ , which is equal to  $1/g_{m2}$
- Thus,  $V_X$  falls by an amount given by  $g_{m1}\Delta V \cdot (1/g_{m2})$
- This change in  $ID1$  also flows through  $R_D$ , producing a drop of  $g_{m1}\Delta V R_D$  in  $V_{out}$ , just as in a simple CS stage

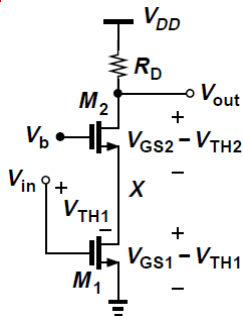


# Cascode Stage: Qualitative Analysis



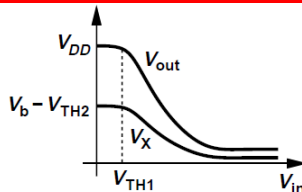
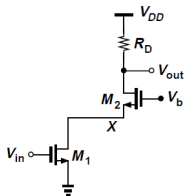
- Consider the case when  $V_{in}$  is fixed and  $V_b$  increases by  $\Delta V$
- Since  $V_{GS1}$  is constant and  $r_{O1} = \infty$ ,  $M_1$  can be replaced by an ideal current source
- For node  $X$ ,  $M_2$  operates as a source follower, it senses an input  $\Delta V$  at its gate and generates an output at  $X$
- With  $\lambda = \gamma = 0$ , the small-signal voltage of the follower is unity regardless of  $R_D$
- $V_X$  rises by  $\Delta V$ , but  $V_{out}$  does not change since  $I_{D2} = I_{D1} = \text{constant}$ , thus voltage gain from  $V_b$  to  $V_{out}$  is zero

# Cascode Stage: Bias Conditions



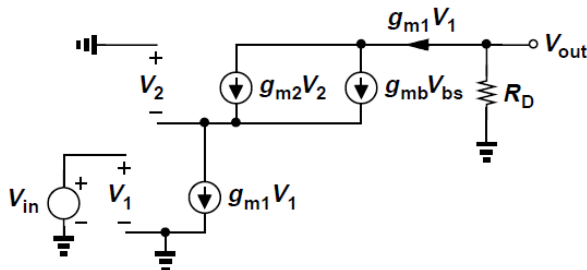
- For  $M1$  to operate in saturation, we must have  $V_X \geq V_{in} - V_{TH1}$
- If  $M1$  and  $M2$  are both in saturation,  $M2$  operates as a source follower and  $V_X$  is primarily determined by  $V_b$ :  $V_X = V_b - V_{GS2}$
- Thus,  $V_b - V_{GS2} \geq V_{in} - V_{TH1}$  and hence  $V_b > V_{in} + V_{GS2} - V_{TH1}$
- For  $M2$  to be saturated,  $V_{out} \geq V_b - V_{TH2}$
- Thus, 
$$V_{out} \geq V_{in} - V_{TH1} + V_{GS2} - V_{TH2}$$
$$= (V_{GS1} - V_{TH1}) + (V_{GS2} - V_{TH2})$$
if  $V_b$  is chosen to place  $M1$  at the edge of saturation
- Minimum output level for which both transistors are in saturation is equal to the sum of overdrives of  $M1$  and  $M2$
- Addition of  $M2$  to the circuit reduces the output voltage swing by at least its overdrive voltage

# Cascode Stage: Large-Signal Behavior



- For  $V_{in} \leq V_{TH1}$ ,  $M1$  and  $M2$  are off,  $V_{out} = V_{DD}$ , and  $V_X \approx V_b - V_{TH2}$
- As  $V_{in}$  exceeds  $V_{TH1}$ ,  $M1$  draws current, and  $V_{out}$  drops
- Since  $I_{D2}$  increases,  $V_{GS2}$  must increase as well, causing  $V_X$  to fall
- As  $V_{in}$  becomes sufficiently large, two effects can occur:
  - $V_X$  falls below  $V_{in}$  by  $V_{TH1}$ , forcing  $M1$  into the triode region
  - $V_{out}$  drops below  $V_b$  by  $V_{TH2}$ , driving  $M2$  into triode region
- Depending on device dimensions and  $R_D$  and  $V_b$ , one effect may occur before the other

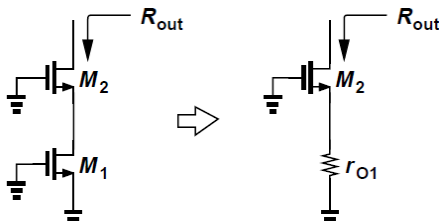
# Cascode Stage: Small-signal characteristics



- Assume both transistors operate in saturation and  $\lambda=0$
- Voltage gain is equal to that of a common-source stage because the drain current produced by the input device must flow through the cascode device
- This result is independent of the transconductance and body effect of  $M2$ , the cascode device
- Can be verified using  $A_v = -G_m R_{out}$

# Cascode Stage: Output Impedance

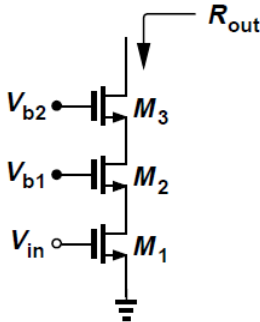
- Important property of the cascode structure is its high output impedance



- For calculation of  $R_{out}$ , the circuit can be viewed as a common-source stage with a degeneration resistor equal to  $r_{O1}$
- Thus,
- Assuming  $R_{out} = [1 + (g_{m2} + g_{mb2})r_{O2}]r_{O1} + r_{O2}$
- M2 boosts the output impedance  $R_{out} \approx (g_{m2} + g_{mb2})r_{O2}r_{O1} + (g_{m2} + g_{mb2})r_{O2}$

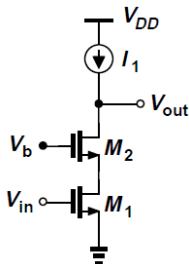
# Triple Cascode

- **Cascodeing can be extended to three or more stacked devices to achieve higher output impedance**
- **But required additional voltage headroom makes it less attractive**
- **For a triple cascode, the minimum output voltage is equal to the sum of three overdrive voltages**



## Cascode stage with current source load

- Voltage gain can be maximized by maximizing  $G_m$  and/or  $R_{out}$
- Since  $G_m$  is typically determined by the transconductance of a transistor and has trade-offs with the bias current and device capacitances, it is desirable to increase voltage gain by maximizing  $R_{out}$



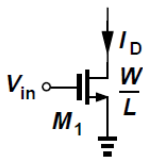
$$G_m \approx g_{m1}$$

$$R_{out} \approx (g_{m2} + g_{mb2})r_{O2}r_{O1}$$

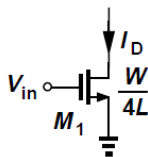
$$A_v = (g_{m2} + g_{mb2})r_{O2}g_{m1}r_{O1}$$

- If both  $M1$  and  $M2$  operate in saturation, and  $\gamma_{eff} \rightarrow 0$ , yielding

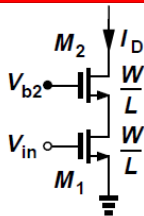
# Cascode Stage vs Increasing Length



(a)



(b)

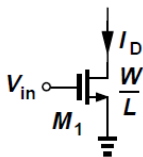


(c)

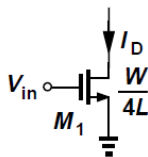
- Increasing length of the input transistor for a given bias current increases the output impedance
- Suppose the length of the input transistor is quadrupled while the width remains constant
- Since  $I_D = (1/2)\mu_n C_{ox}(W/L)(V_{GS} - V_{TH})^2$ , the overdrive voltage is doubled and the transistor consumes the same amount of voltage headroom as does a cascode stage, i.e., circuits in (b) and (c) impose equal voltage swing constraints



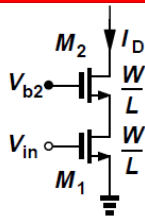
# Cascode Stage vs Increasing Length



(a)



(b)



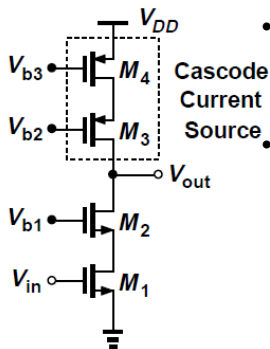
(c)

- Since

$$g_m r_O = \sqrt{2\mu_n C_{ox} \frac{W}{L} I_D} \frac{1}{\lambda I_D}$$

- And  $\lambda \propto 1/L$ , quadrupling  $L$  only doubles the value of  $g_m r_O$  while cascoding results in an output impedance of roughly  $g_m r_O^2$
- Transconductance of  $M1$  in (b) is only half of that in (c), degrading the performance
- For a given voltage headroom, the cascode structure provides a higher output impedance

# Cascode Structure as Current Source



- High output impedance of cascode structure yields a current source closer to the ideal, but at the cost of voltage headroom
- The current source load in a cascode stage can be implemented as a PMOS cascode, exhibiting an impedance equal to

$$[1 + (g_{m3} + g_{mb3})r_{O3}]r_{O4} + r_{O3}$$

- To find the voltage gain,  $G_m \approx g_{m1}$
- $R_{out}$  is the parallel combination of the NMOS and PMOS cascode output impedances

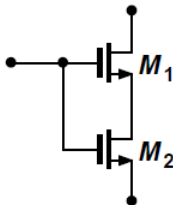
$$R_{out} = \{[1 + (g_{m2} + g_{mb2})r_{O2}]r_{O1} + r_{O2}\} || \{[1 + (g_{m3} + g_{mb3})r_{O3}]r_{O4} + r_{O3}\}$$

- The gain is given by  $|A_v| \approx g_{m1}R_{out}$
- For typical values, this is approximated as

$$|A_v| \approx g_{m1}[(g_{m2}r_{O2}r_{O1}) || (g_{m3}r_{O3}r_{O4})]$$

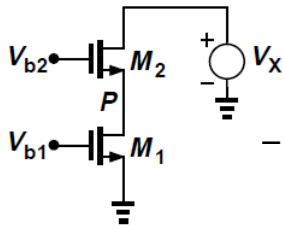
## Poor Man's Cascode

- A “minimalist” cascode current source omits the bias voltage necessary for the cascode device



- Called “poor man's cascode”,  $M_2$  is placed in the triode region because  $V_{GS1} > V_{TH1}$  and  $V_{DS2} = V_{GS2} - V_{GS1} < V_{GS2} - V_{TH2}$
- If  $M_1$  and  $M_2$  have the same dimensions, the structure is equivalent to a single transistor having twice the length—not really a cascode
- In modern CMOS technologies, transistors with different threshold voltages are allowable, allowing  $M_2$  to operate in saturation if  $M_1$  has a lower threshold than  $M_2$

## Poor Man's Cascode: Shielding Property



- High output impedance arises from the fact that if the output node voltage is changed by  $\Delta V$ , the resulting change at the source of the cascode device is much less

Cascode transistor “shields” the input device from voltage variations at the output

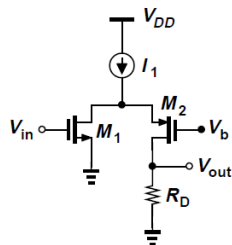
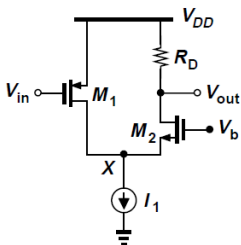
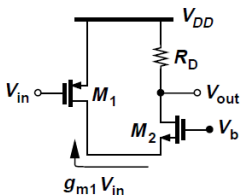
- Shielding property diminishes if cascode device enters triode region
- In above circuit, as  $V_X$  falls below  $V_{b2} - V_{TH2}$ ,  $M_2$  enters triode region and requires a greater gate-source overdrive to sustain the current drawn by  $M_1$ , therefore

$$I_{D2} = \frac{1}{2} \mu_n C_{ox} \left( \frac{W}{L} \right)_2 [2(V_{b2} - V_P - V_{TH2})(V_X - V_P) - (V_X - V_P)^2]$$

- As  $V_X$  decreases,  $V_P$  also drops to keep  $I_{D2}$  constant so variation of  $V_X$  is less attenuated as it appears at  $P$

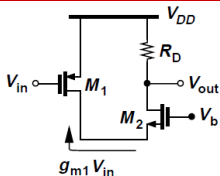
# Folded Cascode

- The input device and the cascode device in a cascode structure need not be of the same type

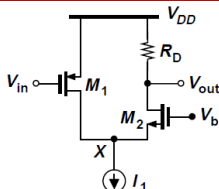


- In the figure above, (a) shows a PMOS-NMOS cascode combination that performs the same function as a telescopic cascode
- In order to bias  $M1$  and  $M2$ , a current source must be added as shown in (b)
- $|ID1| + ID2$  is equal to  $I1$  and hence constant
- (c) shows an NMOS-PMOS folded cascode

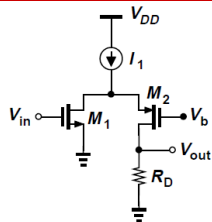
# Folded Cascode: Small-signal operation



(a)



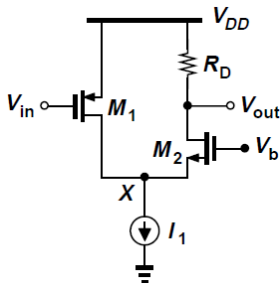
(b)



(c)

- If  $V_{in}$  becomes more positive,  $|ID1|$  decreases, forcing  $ID2$  to increase and hence  $V_{out}$  to drop
- The voltage gain and output impedance can be obtained as calculated for the NMOS-NMOS cascode shown earlier
- (b) and (c) are called “folded cascode” stages because the small-signal current is “folded” up [in (b)] or down [in (c)]
- In the telescopic cascode, the bias current is reused whereas those of  $M1$  and  $M2$  add up to  $I1$  in (b) and (c), leading to a higher bias current

# Folded Cascode: Large-signal operation

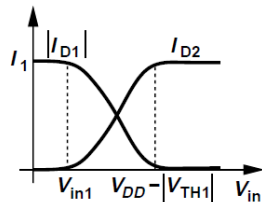
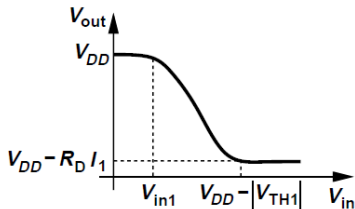
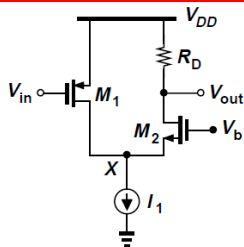


- Suppose  $V_{in}$  decreases from  $V_{DD}$  to zero
- For  $V_{in} > V_{DD} - |V_{TH1}|$ ,  $M1$  is off and  $M2$  carries all of  $I_1$ , yielding  $V_{out} = V_{DD} - I_1 R_D$
- For  $V_{in} < V_{DD} - |V_{TH1}|$ ,  $M1$  turns on in saturation, giving

$$I_{D2} = I_1 - \frac{1}{2} \mu_p C_{ox} \left( \frac{W}{L} \right)_1 (V_{DD} - V_{in} - |V_{TH1}|)^2.$$

- As  $V_{in}$  drops,  $I_{D2}$  decreases further, falling to zero if  $I_{D1} = I_1$

# Folded Cascode: Large-signal operation



- This occurs at  $V_{in} = V_{in1}$  if

$$\frac{1}{2} \mu_p C_{ox} \left( \frac{W}{L} \right)_1 (V_{DD} - V_{in1} - |V_{TH1}|)^2 = I_1$$

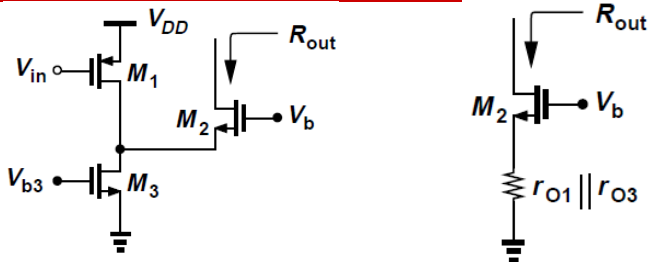
- Thus,

$$V_{in1} = V_{DD} - \sqrt{\frac{2I_1}{\mu_p C_{ox} (W/L)_1}} - |V_{TH1}|$$

- If  $V_{in}$  falls below this level,  $I_{D1}$  tends to be greater than  $I_1$  and  $M1$  enters the triode region to ensure  $I_{D1} = I_1$
- As  $I_{D2}$  drops,  $V_X$  rises, reaching  $V_b - V_{TH2}$  for  $I_{D2} = 0$
- As  $M1$  enters the triode region,  $V_X$  approaches  $V_{DD}$



# Folded Cascode: Output Impedance



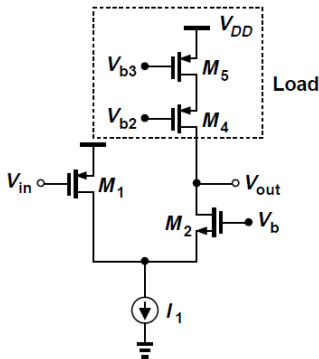
- $M_3$  operates as the bias current source
- Using earlier results,

$$R_{out} = [1 + (g_{m2} + g_{mb2})r_{O2}](r_{O1} || r_{O3}) + r_{O2}$$

- The circuit exhibits a lower output impedance than a nonfolded (telescopic) cascode

## Folded Cascode with cascode load

- To achieve a high voltage gain, the load of a folded cascode can be implemented as a cascode itself



- Increasing the output impedance of the amplifier to obtain a high gain may make the speed of the circuit susceptible to the load capacitance
- A high output impedance itself does not pose a serious issue if the amplifier is placed in a proper feedback loop