mlp-week09

March 24, 2021

1 Machine Learning in Python - Workshop 9

In this week's workshop we will be returning to the NYC Parking Ticket data and exploring how to score and evaluate multiclass classification models as well as trying several addition modeling approaches for this type of data.

2 1. Setup

2.1 1.1 Packages

In the cell below we will load the core libraries we will be using for this workshop and setting some sensible defaults for our plot size and resolution.

```
[1]: # Data libraries
     import pandas as pd
     import numpy as np
     # Plotting libraries
     import matplotlib.pyplot as plt
     import seaborn as sns
     # Plotting defaults
     plt.rcParams['figure.figsize'] = (10,6)
     plt.rcParams['figure.dpi'] = 80
     # sklearn modules
     import sklearn
     import sklearn.linear model
     import sklearn.tree
     import sklearn.ensemble
     import sklearn.neighbors
     import sklearn.preprocessing
     from sklearn.pipeline import make_pipeline
```

2.2 1.2 Helper Functions

```
[2]: def plot_boundaries(bounds, x='lon', y='lat', group='precinct', n=5):

""" Draws boundary lines for a series of groups polygons in a dataframe

"""

sns.lineplot(x=x, y=y, hue=group, data=bounds,

sort=False, palette=['k']*n, legend=None)
```

```
[3]: def plot_pred_labels(res, pred = 'pred_label', truth = 'precinct'):
    """ Plots the predicted labels and true labels from a common data frame
    """
    plt.figure(figsize=(5,8))

    ax = sns.scatterplot(
        x='lon', y='lat', hue=pred, palette=precinct_pal, data=res
    )
    plot_boundaries(manh_bounds)

    acc = sklearn.metrics.accuracy_score(
        res[truth], res[pred]
    )

    ax.set_title("Predicted Labels (Accuracy {:.3f})".format(acc))
    plt.show()
```

2.3 1.3 Data

As described in the Week 7 workshop, these data comes from New York City's Open Data project. We have simplified the data somewhat and restricted the data to just include the five precincts (1st, 5th, 6th, 7th, and 9th) in the southern end of Manhattan. The following data files have been provided:

- manh_tickets.csv Geocoded parking tickets from the 5 southern most precincts in Manhattan
- manh_test.csv Points randomly sampled within the true boundaries of these precincts
- manh_bounds.csv boundaries of these precincts

As before, our goal is to use these parking tickets to develop a model which correctly predicts the boundaries of the police precincts in Manhattan based only on the locations where parking tickets have been issued. We will read in all the data sets using pandas,

```
[4]: manh_tickets = pd.read_csv("manh_tickets.csv")
manh_test = pd.read_csv("manh_test.csv")
manh_bounds = pd.read_csv("manh_bounds.csv")
```

and create our basic response vector and model matrix,

```
[5]: X = manh_tickets[['lon','lat']]
y = manh_tickets.precinct
```

Finally, we create labels and a color palette which will be used for across subsequent plots.

```
[6]: precincts = ['Precinct01', 'Precinct05', 'Precinct06', 'Precinct07',□

→'Precinct09']

precincts_short = ['P01', 'P05', 'P06', 'P07', 'P09']

precincts_pred = ["pred_" + p for p in precincts_short]

# Create a color palette for precincts based on the cols25 palette from R's□

→ pals package

precinct_pal = dict(

zip(precincts,

[(0.1215686, 0.47058824, 0.7843137), (1.0000000, 0.00000000, 0.0000000),
 (0.2000000, 0.62745098, 0.1725490), (0.4156863, 0.20000000, 0.7607843),
 (1.0000000, 0.49803922, 0.0000000)]

)
)
)
```

Using our new palette we can plot the original parking ticket data and add the precinct boundaries using plot_boundaries to make everything more readable.

```
[7]: # plt.figure(figsize=(5,8))

# sns.scatterplot(
# x='lon', y='lat', hue='precinct', palette=precinct_pal, data=manh_tickets
# ).set_title("Parking Tickets")
# plot_boundaries(manh_bounds)

# plt.show()
```

3 1.4. Review - Multiclass logistic (multinomial) regression

At the end of the Week 7 workshop we had fit a Logistic Regression model using multi_class=multinomial in order to obtain a probabilistically consistent predictive model, e.g. for any given prediction the probabilities of each class sum to one. We will begin by reconstructing this same model and using it as a point of comparison.

This model is then used to predict both the class label for test location as well as the predicted probability for each precinct for all test locations, these results are then stored in the res_mn data frame.

```
[9]:
                                             pred_label
                                                         pred_P01
                                                                   pred_P05
             precinct
                             lon
                                        lat
     0
           Precinct01 -74.010330
                                  40.720485 Precinct01
                                                         0.996715
                                                                   0.002760
     1
           Precinct01 -74.005740
                                  40.708015 Precinct01
                                                         0.878555
                                                                   0.121173
           Precinct01 -74.001993
                                  40.707750 Precinct05
     2
                                                                    0.523614
                                                         0.465160
     3
           Precinct01 -74.005499
                                  40.706179
                                             Precinct01
                                                         0.837832
                                                                    0.161541
     4
           Precinct01 -74.009585
                                 40.726523 Precinct01
                                                         0.926785
                                                                   0.001993
     2495
          Precinct09 -73.993883
                                  40.725202 Precinct05
                                                         0.030168
                                                                    0.439143
     2496 Precinct09 -73.988460
                                  40.729783 Precinct09
                                                         0.000017
                                                                    0.002933
     2497
          Precinct09 -73.984370
                                  40.725988
                                             Precinct09
                                                         0.000001
                                                                   0.002990
     2498 Precinct09 -73.989221
                                  40.723938
                                                         0.000641
                                             Precinct09
                                                                    0.140995
     2499 Precinct09 -73.990723
                                  40.728558
                                            Precinct09
                                                         0.000381
                                                                   0.021947
               pred_P06
                             pred_P07
                                           pred_P09
     0
           5.245982e-04
                         2.601684e-08
                                       6.066956e-09
     1
           1.312997e-07
                         2.714364e-04
                                       1.333554e-09
     2
           2.073632e-07
                         1.122583e-02
                                       4.409586e-08
     3
           3.234373e-08
                        6.272248e-04 6.308147e-10
     4
                         7.586284e-09
           7.122160e-02
                                       3.263365e-07
     2495
          1.913318e-01
                         2.258760e-02 3.167692e-01
     2496
          2.501241e-02
                        1.313258e-03 9.707246e-01
     2497
                                       9.622564e-01
          3.716451e-04 3.438030e-02
     2498
          7.625062e-03
                         1.483359e-01
                                       7.024028e-01
          9.987098e-02 3.418434e-03 8.743825e-01
     [2500 rows x 9 columns]
```

3.0.1 Exercise 1

pred_P07

0.999825

Pick at least three random test locactions and using res_mn verify that the predicted label for each point corresponds to the class with the largest predicted probability and that the predicted probabilities are consistent (e.g. they add up to 1).

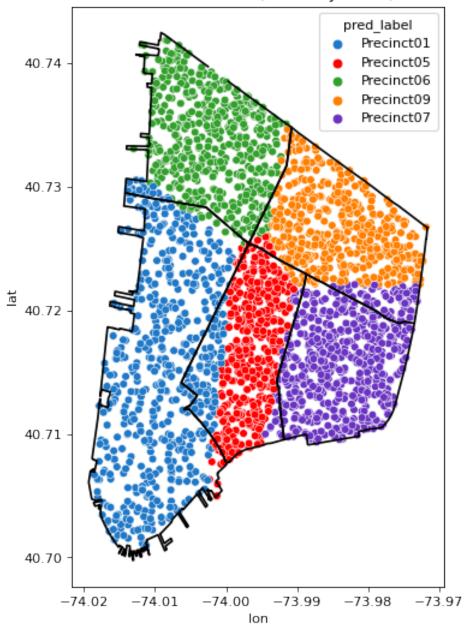
```
[10]: a = np.random.randint(0,2499,3)
     Initially a = [148, 1985, 357],
[11]: for i in a:
          print(i, "\n" , res_mn.iloc[i, :], "\n")
     1380
      precinct
                      Precinct06
     lon
                       -74.0024
     lat
                        40.7337
     pred_label
                     Precinct06
     pred_P01
                     0.00390627
     pred_P05
                    0.000199189
     pred_P06
                       0.995674
     pred_P07
                    1.02552e-08
     pred_P09
                     0.00022095
     Name: 1380, dtype: object
     1412
      precinct
                      Precinct06
     lon
                       -74.0037
                        40.7285
     lat
     pred_label
                     Precinct06
     pred_P01
                       0.256164
     pred_P05
                      0.0113583
     pred P06
                       0.732262
     pred_P07
                    8.70555e-07
     pred_P09
                    0.000215169
     Name: 1412, dtype: object
     1536
      precinct
                      Precinct07
     lon
                       -73.9787
     lat
                        40.7109
                     Precinct07
     pred_label
     pred_P01
                    3.67959e-10
     pred_P05
                    0.000111303
     pred_P06
                    6.39586e-12
```

We can clearly see that each point is labelled correctly corresponding to the highest probability.

We can also use the plot_pred_labels function, defined with the helper functions above, to visualize the predicted labels.

[12]: plot_pred_labels(res_mn)

Predicted Labels (Accuracy 0.895)



4 2. Additional scoring methods / tools for multiclass models

4.1 2.1 Confusion Matrix

As we saw in week 7, perhaps the most straight forward approach to assess a model is to use the label predictions directly to construct a confusion matrix which places the true labels along the rows and the predicted labels along the columns.

```
[13]: sklearn.metrics.confusion_matrix(res_mn.precinct, res_mn.pred_label)
[13]: array([[473, 15,
                         12,
                                0,
                                     0],
             [ 86, 379,
                           0,
                                     8],
                               27,
             [ 19,
                     0, 476,
                                     5],
             [ 0,
                     Ο,
                          0, 496,
                                     4],
                     7,
                             69, 414]])
             Γ 0.
                         10,
```

4.1.1 Exercise 4

Explain what information is given by the value 27 given in the 2nd row, 5th column of this confusion matrix.

This tells us that 27 points were classified by our model as lying in precinct 5 while they actually lie in precinct 7.

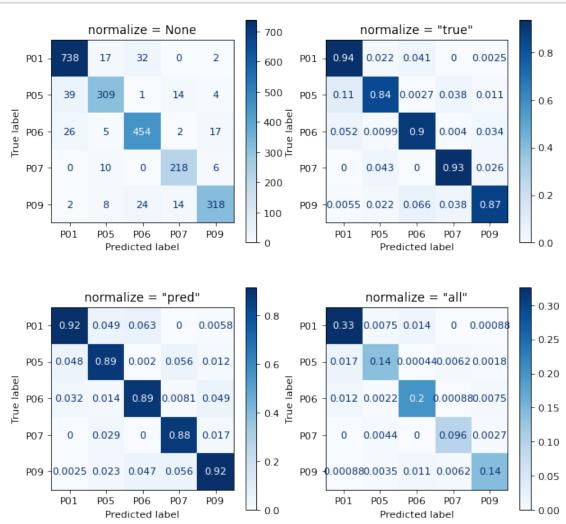
To expand on this idea, and to help scale this approach to cases when there are many classes sklearn provides a convenient plotting function for visualizing the confusion matrix which provides methods for normalizing by the rows ("true"), columns ("pred"), or all values.

```
[14]: fig = plt.figure(figsize=(9, 9))
    normalize=[None, 'true', 'pred', 'all']

for i in range(len(normalize)):
    ax = fig.add_subplot(221+i)

    if (normalize[i] is None):
        ax.set_title("normalize = None")
    else:
        ax.set_title("normalize = \"" + normalize[i] + "\"")
```

```
sklearn.metrics.plot_confusion_matrix(
    m_mn, X, y, include_values=True, ax=ax,
    normalize = normalize[i],
    display_labels = precincts_short,
    cmap = plt.cm.Blues
)
```



4.1.2 Exercise 2

Which normalization method appears to be is most useful for determining False Positives, what about False Negatives? Explain.

A False Positive is our model predicting that the location is on the diagonal when the location lies in another precinct. Therefore with the lowest probability off the diagonal. this is given by the lighest shading off the diagonal.

A False Negative occurs when the model predicts that the ticket doesn't lie on the diagonal, when in reality it does. That is, our model is predicting that the ticket lies in a different precinct than the diagonal, however it does lie in that precinct. Therefore with the ...

4.2 2.2 One-vs-rest ROC curves

Previously in the case of logistic regression (binary classification) we saw how this enabled us to consider all possible decision threshold values to generate a receiver operating characteristic (ROC) curve showing the trade off between possible true positive and false positive rates.

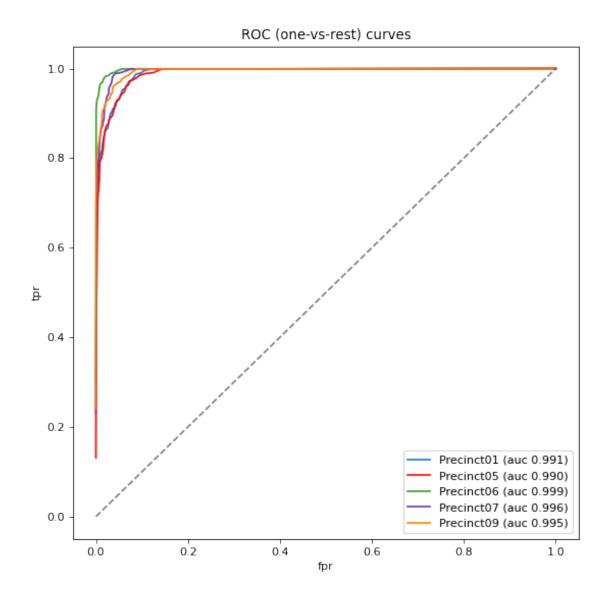
In the case of a classification model that produces probabilistic predictions we can extend this idea to the multiclass case but it is not without some significant drawbacks. Specifically, the concept of a decision threshold does not make sense in the multiclass setting since we need to make a choice among k classes. However, what we can do is consider a one-vs-rest approach where we take each class as the positive case and all other classes as the negative. In this way we can construct k different ROC curves using our original predicted probabilities. The function below implements this considering each class separately and calculating a unique ROC and AUC for each.

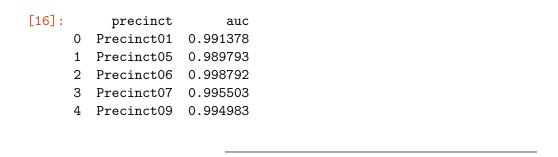
```
[15]: def ovr_roc_plot(y_true, y_pred):
          """ Draw ROC curves using one-vs-rest approach
          classes = y_true.unique()
          n_classes = len(y_true.unique())
          # Convert from n x 1 categorical matrix to n x k binary matrix
          y_true = pd.get_dummies(y_true).to_numpy()
          y_pred = y_pred.to_numpy()
          # Sanity Check
          if y_true.shape[1] != y_pred.shape[1]:
              raise ValueError("Truth and prediction dimensions do not match.")
          # Compute ROC curve and ROC area for each class
          rocs = dict()
          aucs = dict()
          for name, i in zip(classes, range(n_classes)):
              aucs[i] = pd.DataFrame({
                  'precinct': [name],
                  'auc': [sklearn.metrics.roc_auc_score(y_true[:, i], y_pred[:, i])]
              })
              rocs[i] = pd.DataFrame(
```

```
data = np.c_[sklearn.metrics.roc_curve(y_true[:, i], y_pred[:, i])],
           columns = ('fpr', 'tpr', 'threshold')
       ).assign(
           precinct = name
       )
  # Bind rows to create a single data frame for each
  roc = pd.concat(rocs, ignore_index=True)
  auc = pd.concat(aucs, ignore_index=True)
  # Create plot
  fig = plt.figure(figsize=(8, 8))
  sns.lineplot(x='fpr', y='tpr', hue='precinct', data=roc, ci=None, u
→palette=precinct_pal)
  plt.plot([0,1],[0,1], 'k--', alpha=0.5) # 0-1 line
  plt.title("ROC (one-vs-rest) curves")
  L = plt.legend()
  for precinct, auc_val, i in zip(auc.precinct, auc.auc, range(n_classes)):
      L.get_texts()[i].set_text("{} (auc {:.3f})".format(precinct, auc_val))
  plt.show()
   # Return the AUCs as a Data Frame
  return(auc)
```

We can then use this function to evaluate our class probability predictions.

```
[16]: ovr_roc_plot(res_mn.precinct, res_mn[precincts_pred])
```





4.2.1 Exercise 3

Does the ordering of the AUC values agree with your intuition about the models performance for the different precincts?

From the figure, we see that the model is predicting "best" the precincts (in order) 1,5,6,7,9. Which we would not agree with generally, since it appears to be predicting precincts 6 and 7 pretty well. While the model looks to be doing a bad job with precincts 1 and 5, since they have a lot of overlapping locations. This is a surprising result, also given the auc scores are so high.

4.2.2 Exercise 4

We have already established that this is reasonable for predicting most of these police precincts (accuracy of 0.895), however the AUCs reported for our model look very very good (all are >0.99). Can you explain this discrepancy?

Hint - look at the definition of TPR and FPR and then think about what happens when we use the one-vs-rest approach.

From above we have that one-vs-rest performs the following action,

"" we take each class as the positive case and all other classes as the negative. In this way we can construct different ROC curves using our original predicted probabilities. The function below implements this considering each class separately and calculating a unique ROC and AUC for each.""

and that,

$$\mathrm{TPR} = \frac{\mathrm{TP}}{\mathrm{TP} + \mathrm{FN}}$$

$$FPR = \frac{FP}{FP + TN}$$

Since the one-vs-rest approach considers only one class as positive and the rest as negative, the False Negatives are much smaller than the True Positives resulting in a high TPR. Also the True Negatives are much larger than the False Positives, resulting in a very low FPR. These two factors give a very good roc curve.

5 3. Other multiclass classification models

For this section we will explore a number approaches to fitting and predict multiclass classification models. For the sake of uniformity we will assess the models in the same way:

- Plot all of the predicted labels and the true labels for a visual comparison and
- Show the classification report result for the predicted labels.

To avoid repeated code we will use the following helper function,

```
[17]: def model_test_assess(model, inc_report = True, inc_proba = False):
          # Use the model to predict test labels
          res = pd.concat(
              [ manh_test,
                pd.Series(
                    data = model.predict(manh_test[['lon','lat']]),
                    name = "pred label"
                )
              ],
              axis = 1
          )
          if (inc_proba):
              res = pd.concat(
                   [res,
                    pd.DataFrame(
                         data = model.predict_proba(manh_test[['lon','lat']]),
                         columns = precincts_pred
                    )
                  ],
                  axis = 1
              )
          # Plot labels
          plot_pred_labels(res)
          if inc_report: # Print report
              print(
                  sklearn.metrics.classification_report(
                      res.precinct, res.pred_label,
                      zero_division = 0
                  )
              )
```

5.1 3.1. Support Vector Machines

5.1.1 3.1.1 SVC

Standard Support Vector Classifier models are able to handle multiclass outcome vectors by fitting all of the one-to-one SVC models for each pair of classes. This therefore involves fitting $\binom{k}{2} = k(k-1)/2$ SVC models which can be slow. The labels are predicted based on using all $\binom{k}{2}$ generate binary predictions which are then tabulated and the label with the most votes is choosen. See here for more details.

Below we define a function for fitting and assess this model using different kernel and penalty values. As SVMs can be sensitive to scale of the features we include a pipeline that scales the latitude and logitude values before fitting the model.

5.1.2 Exercise 5

Using this function try different values of kernel and C, what seems to produce the best model? Explain why you think this model is performing better than the alternatives.

Hint - recommended kernels to try include rbd, poly, and linear.

```
The rbf kernel: -c=0.1 => 0.912 - c=1 => 0.908 - c=2 => 0.919 - c=5 => 0.920 - c=10 => 0.916 - c=50 => 0.898
```

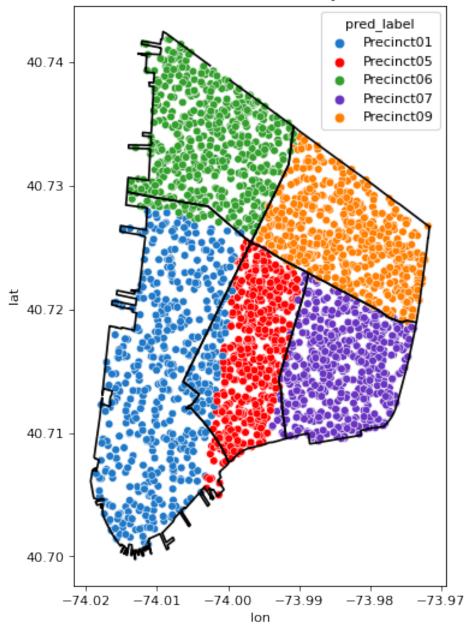
The linear kernel: - c=0.1 => 0.910 - c=1 => 0.925 - c=2 => 0.931 - c=5 => 0.935 - c=10 => 0.936 - c=50 => 0.937 - c=100 => 0.937

```
The poly kernel: - c=0.1 => 0.887 - c=1 => 0.900 - c=2 => 0.904 - c=5 => 0.910 - c=10 => 0.910 - c=100 => 0.910 - c=100 => 0.914
```

We would prefer the linear kernel with a value of c around 50, as increases in c make no change to the accuracy above 50.

```
[19]: fit_svc(kernel = "linear", C=50)
```

Predicted Labels (Accuracy 0.937)



	precision	recall	f1-score	support
Precinct01	0.85	0.91	0.88	500
Precinct05	0.94	0.81	0.87	500
Precinct06	0.94	0.99	0.97	500
Precinct07	0.96	0.99	0.97	500
Precinct09	0.99	0.98	0.98	500

accuracy			0.94	2500	
macro avg	0.94	0.94	0.94	2500	
weighted avg	0.94	0.94	0.94	2500	

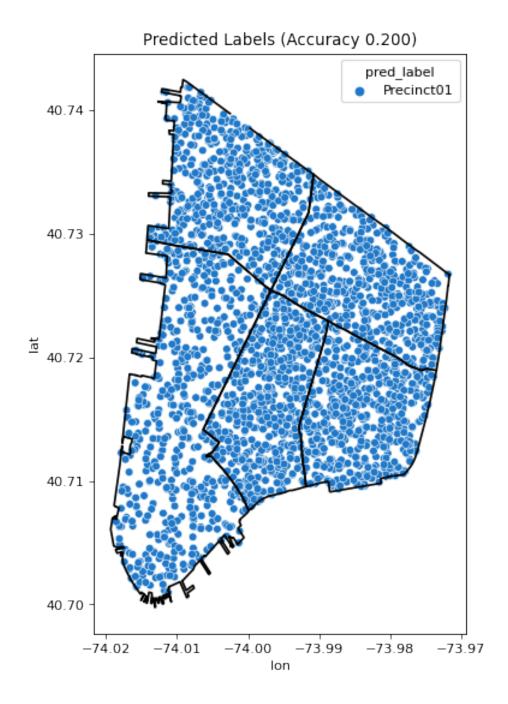
5.1.3 Exercise 6

Comment out the line of code that includes the StandardScaler in the pipeline below. What happens to the models predictive performance? Try adjusting C and or kernel to see if you can improve things.

In this case, the model's performance reduces dramatically to around 0.717 accuracy from above 0.9 in the example above. The polynomial kernel predicts every location as being in precinct 1.

```
[20]: m_svc2 = make_pipeline(
    #sklearn.preprocessing.StandardScaler(),
    sklearn.svm.SVC(C=100, kernel="poly")
).fit(X,y)

model_test_assess(m_svc2, inc_report=False)
```



5.1.4 3.1.2 LinearSVC

An alternative to the one-vs-one behavior of SVC is to instead fit a one-vs-rest model, in sklearn this is only supported by the LinearSVC classifier model. This modeling approach needs to only fit k SVM models, and is therefore usually much faster for large k. However, due to implementation

details of the underlying fitting library it does not support non-linear kernels. As with other SVM models it is important to scale our data before fitting.

5.1.5 Exercise 7

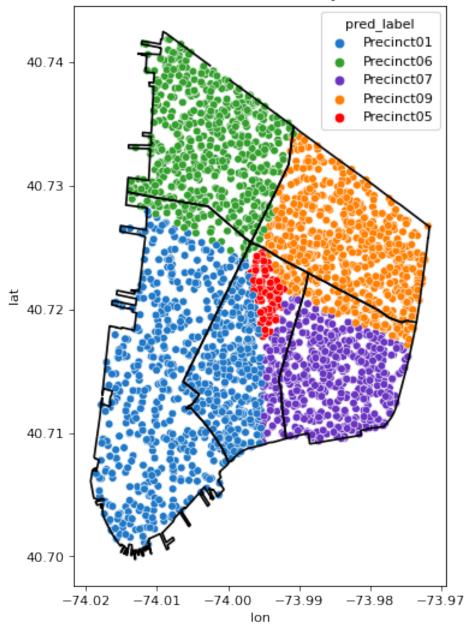
Using this function try different values of C to tune the model, how does its performance compare to the SVC model?

```
We try the following values of c: - c=0.01 => 0.775 - c=0.1 => 0.813 - c=1 => 0.811 - c=2 => 0.812 - c=5 => 0.812 - c=10 => 0.813 - c=50 => 0.812
```

Different values of C do not change the accuracy a great deal, and the accuracy of this model is much worse than for the SVC model.

```
[22]: fit_lsvc(C=0.01)
```

Predicted Labels (Accuracy 0.775)



	precision	recall	f1-score	support
Precinct01	0.60	0.91	0.73	500
Precinct05	1.00	0.14	0.25	500
Precinct06	0.89	1.00	0.94	500
Precinct07	0.82	0.84	0.83	500
Precinct09	0.82	0.98	0.89	500

accuracy			0.78	2500
macro avg	0.83	0.78	0.73	2500
weighted avg	0.83	0.78	0.73	2500

5.2 3.2 Tree based methods

5.2.1 3.2.1 DecisionTreeClassifier

This model fits a decision tree model that attempts to classify observations by constructing a binary decision tree on the features provided. In the case of binary and multiclass classification the predicted label is based on the most common label within the terminal node. For fitting this model for these data we will solely focus on the use of the max_depth parameter which determines the number of branchs within the tree. Keep in mind that each additional layer added to the tree potentially increases the number of nodes by a factor of 2.

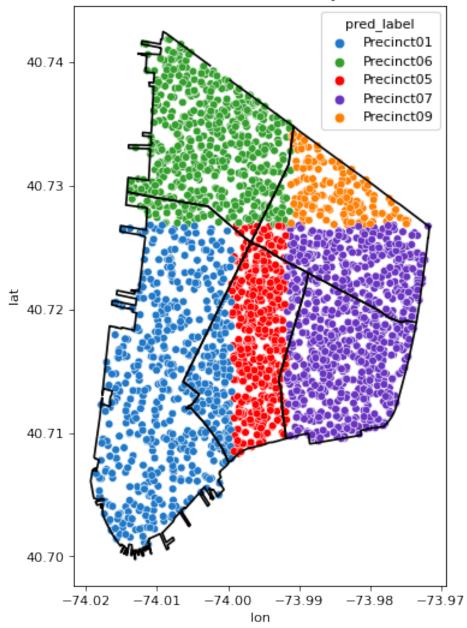
```
[23]: def fit_dt(max_depth):
    m_dt = sklearn.tree.DecisionTreeClassifier(
         max_depth = max_depth
    ).fit(X,y)

    model_test_assess(m_dt)
```

Use the following code chunk to explore the effect of different max depths on the tree model.

```
[24]: fit_dt(max_depth = 3)
```

Predicted Labels (Accuracy 0.771)



	precision	recall	f1-score	support
Precinct01	0.77	0.91	0.84	500
Precinct05	0.87	0.67	0.76	500
Precinct06	0.89	0.99	0.93	500
Precinct07	0.60	0.98	0.74	500
Precinct09	0.99	0.31	0.47	500

accuracy			0.77	2500
macro avg	0.82	0.77	0.75	2500
weighted avg	0.82	0.77	0.75	2500

5.2.2 Exercise 8

Using max_depth=1 how many different classes are reflected in the predictions? Using max_depth=2? Based on this and given there are 5 classes we are attempting to classify, what is the minimum depth of tree should we be using?

Using max_depth=1, two classes are reflected in the predictions, precincts 1 and 5. Using max_depth=2, we have 4 classes represented. So we should be using at least max_depth=3, since we have 5 categories.

5.2.3 Exercise 9

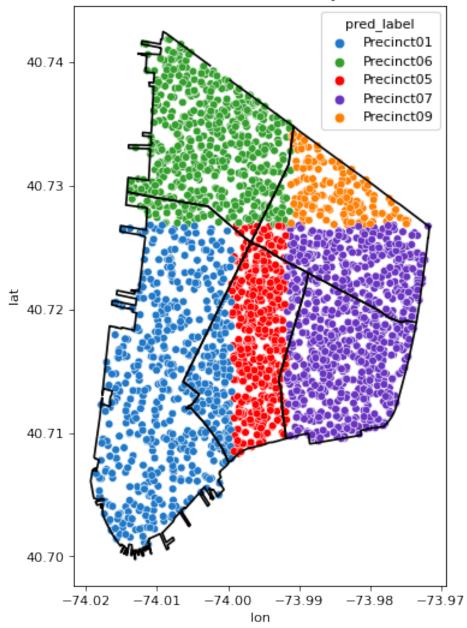
Examine the boundaries being created by the model (particularly evident with small max_depth values), what shape do they have? Is the potentially problematic for the task at hand?

The boundaries are always linear, and the real boundaries between precincts in the map are non-linear. So we will struggle to classify points correctly unless we use a high depth.

The issue we've just seem is similar to the issue we saw with the original single precinct logistic regression model from Week 7, and we can somewhat address it in the same way by introducing an interaction feature between lat and lon before fitting our model by adding a PolynomialFeature step before fitting the tree model.

```
[26]: fit_dt_int(max_depth = 3)
```

Predicted Labels (Accuracy 0.771)



	precision	recall	f1-score	support
Precinct01	0.77	0.91	0.84	500
Precinct05	0.87	0.67	0.76	500
Precinct06	0.89	0.99	0.93	500
Precinct07	0.60	0.98	0.74	500
Precinct09	0.99	0.31	0.47	500

accuracy			0.77	2500	
macro avg	0.82	0.77	0.75	2500	
weighted avg	0.82	0.77	0.75	2500	

5.2.4 Exercise 10

What has changed about the boundaries being created by the model (particularly evident with small max_depth values), what shape do they have? Does this improve model performance?

The boundaries created by the model are now slightly curved which improves model performance as better approximating the boundaries between precincts. However, we would still prefer more non-linear boundaries.

5.2.5 Exercise 11

For either model, for what values of max_depth do you start seeing clear evidence of overfitting?

At max_depth=5, we see overfitting as some locations inside precinct 9 are predicted as belonging to precint 7 and there are many points in precinct 7 being predicted as in precinct 9.

5.2.6 3.2.2 RandomForestClassifier

As discussed in lecture, this class of model is an extension of the decision tree frame work whereby a number decision tree models are fit to random sub-sample (i.e. bootstrap sample) of the features. When making predictions each tree predicts a label and the most common label across all of the trees is used as the final prediction. For now we will just examine the effect of n_estimators which corresponds to the number of trees and max_depth which is the maximum depth of the trees.

Use the following code chunk to explore the effect of different values of max_depth and n_estimators on the model's performance.

```
[0.3836 0.3836 0.3836 0.3844 0.3856 0.3864 0.394 0.3968 0.3968 0.4136
0.4144 0.4168 0.5076 0.5336 0.5348 0.5628 0.5684 0.6196 0.6264 0.63
0.6324 0.6332 0.6368 0.6512 0.7056 0.7284 0.7416 0.7708 0.782 0.7856
0.792 0.7996 0.8016 0.804 0.8092 0.814 0.8204 0.8244 0.8256 0.8288
0.8292 0.83
              0.8332 0.8356 0.8368 0.8368 0.8396 0.84
                                                        0.8436 0.8444
0.8456 0.8456 0.8468 0.8512 0.852 0.8544 0.8544 0.8548 0.8556 0.8564
0.8576 0.8576 0.8584 0.8592 0.8596 0.86
                                         0.8604 0.8616 0.862 0.864
0.8652 0.8656 0.8656 0.866 0.8664 0.8668 0.8672 0.8684 0.8684 0.8684
0.8688 0.8688 0.8696 0.8696 0.87
                                   0.87
                                         0.87
                                                0.8704 0.8708 0.8724
0.8728 0.8728 0.8732 0.8748 0.8748 0.8752 0.876 0.8768 0.8768 0.8768
0.8768 0.878 0.878 0.8792 0.8792 0.8796 0.8804 0.8808 0.8812 0.8816
0.8816 0.882 0.8824 0.8828 0.8828 0.8828 0.884 0.8844 0.8872 0.8876
0.8876 0.8876 0.888 0.8884 0.8888 0.89
                                         0.8904 0.8904 0.8916 0.8916
0.8924 0.8928 0.8928 0.8936 0.894 0.894 0.8952 0.8952 0.8956 0.896
                                   0.9004 0.9016 0.9048 0.9068 0.9072
0.8968 0.8972 0.898 0.8996 0.9
0.908 0.9084 0.9084 0.9112 0.9124 0.9136 0.914 0.914 0.9144 0.9148
```

```
0.9152 0.9164 0.9164 0.9176 0.9176 0.918 0.9184 0.9212 0.9212 0.9212 0.9216 0.9216 0.922 0.9224 0.9224 0.9232 0.924 0.9252 0.9252 0.9264 0.9268 0.9272 0.9276 0.9276 0.9276 0.9284 0.93 0.9304 0.9316 0.9316 0.932 0.9352 0.936 0.9376 0.9376 0.9388 0.9408]
```

```
[29]: \#for\ i\ in\ range(1,15):
\#\ for\ j\ in\ range(1,15):
\#\ print("n\_estimators = " + str(i), "max\_depth = " + str(j), "order to the structure of the
```

5.2.7 Exercise 12

Which combination of n_estimators and max_depth seems to produce the best model performance? How does it compare to the other models considered.

The best model performance is n_estimators = 10 and max_depth = 6 from the cell above. However the best values change with each version of the random forrest and it is not easy to pick exact best values. The model performance is good, around 0.94 accuracy, that is comparible to the linear SVC model with a C=50. We would prefer the linear svc model for its interpretability.

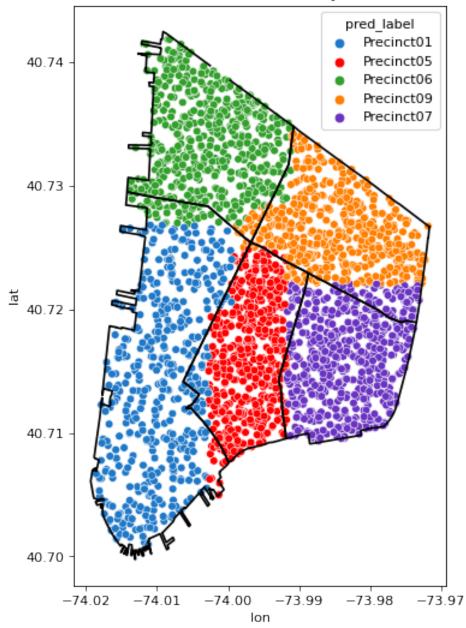
5.2.8 Exercise 13

For a given max_depth (e.g. 4) compare the performance of a single decision tree model to random forrest models with different values of n_estimators, how do they compare?

We can see the performance of the single decision tree model with max_depth=4,

```
[30]: fit_dt(max_depth = 4)
```

Predicted Labels (Accuracy 0.906)



	precision	recall	f1-score	support
Precinct01	0.93	0.88	0.90	500
Precinct05	0.92	0.86	0.89	500
Precinct06	0.92	0.97	0.94	500
Precinct07	0.85	0.97	0.91	500
Precinct09	0.92	0.84	0.88	500

```
accuracy 0.91 2500 macro avg 0.91 0.91 0.91 2500 weighted avg 0.91 0.91 0.91 2500
```

Now, we alter the fit_rf function to have a fixed max_depth=4 and return the accuracy,

```
[31]: def fit_rf_fixed_depth(n_estimators):
          m_rf = sklearn.ensemble.RandomForestClassifier(
              n_estimators=n_estimators, max_depth=4
          ).fit(X,y)
          res = pd.concat(
              [ manh_test,
                pd.Series(
                    data = m_rf.predict(manh_test[['lon','lat']]),
                    name = "pred_label"
                )
              ],
              axis = 1
          )
          acc = sklearn.metrics.accuracy_score(
              res['precinct'], res['pred_label']
          )
          return acc
```

Now, we try all values of n_estimators from 1 to 100,

```
[32]: best = np.array([])

for i in range(1,100):
    best = np.append(best, fit_rf_fixed_depth(i))
print(np.amax(best))
```

0.8912

we can see that for values of n_estimators up to 100, we cannot get an accuracy above 0.9, that is achieved by the single decision tree model.

5.2.9 Exercise 14

Do you think the inclusion of an interaction feature would help or hurt this model's performance? Explain.

In theory, the inclusion of interaction features should help the model performance since it allows for non-linear decision boundaries that will be able to better fit the non-linear shapes of our real life precinct boundaries.

```
[33]: def fit_rf_pipeline(n_estimators, max_depth):
          m_rf = make_pipeline(
              sklearn.preprocessing.PolynomialFeatures(
                  degree=2, interaction_only=True, include_bias=False
              ),
              sklearn.ensemble.RandomForestClassifier(
                  n_estimators=n_estimators, max_depth=max_depth
          ).fit(X,y)
          res = pd.concat(
              [ manh_test,
                pd.Series(
                    data = m_rf.predict(manh_test[['lon','lat']]),
                    name = "pred_label"
                )
              ],
              axis = 1
          )
          acc = sklearn.metrics.accuracy_score(
              res['precinct'], res['pred_label'])
          return acc
[34]: perform = np.array([])
      for i in range (1,15):
          for j in range(1,15):
              \#print("n_estimators = " + str(i), "max_depth = " + str(j), "
       \rightarrow fit_rf2(n_estimators = i, max_depth = j))
              perform = np.append(perform, fit_rf_pipeline(n_estimators = i,__
       \rightarrowmax_depth = j))
      #fit_rf(n_estimators = 5, max_depth = 4)
      print(np.sort(perform))
     [0.3608 0.3612 0.3888 0.3892 0.396 0.3968 0.3988 0.4084 0.4132 0.4172
      0.4492 0.4584 0.4632 0.5112 0.5452 0.558 0.5808 0.6192 0.6236 0.6328
      0.636  0.6736  0.6748  0.6788  0.6824  0.696  0.7088  0.7336  0.7344  0.764
      0.7716 0.776 0.778 0.7876 0.7892 0.7932 0.8008 0.808 0.812 0.818
                                 0.8332 0.8336 0.8352 0.8372 0.8376 0.8392
      0.8248 0.8284 0.83
                           0.83
             0.8448 0.848 0.8516 0.8528 0.854 0.8576 0.8584 0.8588 0.8596
      0.8596 0.8604 0.8612 0.8616 0.8644 0.8692 0.8708 0.8708 0.8712 0.8732
      0.8744 0.8744 0.8768 0.878 0.8788 0.8788 0.8792 0.88
                                                                0.8804 0.8808
      0.8816 0.8816 0.8816 0.8816 0.884 0.8848 0.8868 0.8872 0.8876 0.888
      0.8884 0.8904 0.8908 0.892 0.8924 0.8932 0.8936 0.8936 0.894 0.8944
```

```
0.8948 0.8956 0.8964 0.8964 0.8972 0.8976 0.8976 0.898 0.9004 0.9008 0.9032 0.9044 0.9048 0.9052 0.906 0.906 0.9068 0.9068 0.9068 0.9072 0.9092 0.9096 0.91 0.9104 0.9104 0.9104 0.9108 0.9112 0.9116 0.9116 0.9116 0.912 0.912 0.9136 0.9136 0.9148 0.9152 0.9152 0.9156 0.9156 0.9164 0.9164 0.9164 0.9172 0.9176 0.9184 0.9184 0.9188 0.9192 0.9192 0.9196 0.9196 0.92 0.92 0.9212 0.9216 0.922 0.9224 0.9228 0.9232 0.924 0.924 0.9244 0.9244 0.9248 0.9252 0.9252 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.926 0.938 0.9312 0.9324 0.9328 0.9332 0.9332 0.934 0.9344 0.9348 0.9348 0.9352 0.9352 0.9352 0.9356 0.9368 0.9404]
```

However, in practise, it appears that this change doesn't have a dramatic influence on the final accuracy of the model. We can note here, however, that more of the trees have an accuracy above 0.9 than in the model without interaction terms, so we could argue this is an improvement.

5.3 3.3 Comparisons

5.3.1 Exercise 15

You have now been given the opportunity to experiment with a number of different multiclass classification models. Based on your experience with this data set which model do you think is best for this particular classification task? Justify your answer.

You answer should contain some discussion of the potential for overfitting.

From week 7, we firstly used the multiclass logistic regression model using one-versus-rest with multi_class = 'ovr'. This model gave fairly unsatsfactory decision boundaries that do not approximate the precincts well.

We then fitted a mulitnomial model that has much better decision boundaries than the first model,

This multiclass logistic (multinomial) regression has an accuracy of 0.895, slightly lower than the models we used this week.

The best model with support vector machines was the linear model with a large C value (greater than 50) as shown here, with an accuracy of 0.937.

We note that the linear SVC models used this week are very poor and lead to a lot of overfitting, hence we would not prefer this to other methods. The random forrest method also provided an accuracy of around 0.94, however, we would not prefer this method since it only performs slightly better than our linear support vector model and is much more complex.

Therefore, the preffered model for this task would be the linear support vector model due to its relative simplicity and high accuracy of 0.937.

5.4 4. Competing the worksheet

At this point you have hopefully been able to complete all the preceding exercises. Now is a good time to check the reproducibility of this document by restarting the notebook's kernel and

rerunning all cells in order.

Once that is done and you are happy with everything, you can then run the following cell to generate your PDF and turn it in on gradescope under the mlp-week09 assignment.

[35]: !jupyter nbconvert --to pdf mlp-week09.ipynb

```
[NbConvertApp] Converting notebook mlp-week09.ipynb to pdf
[NbConvertApp] Support files will be in mlp-week09_files/
[NbConvertApp] Making directory ./mlp-week09_files
[NbConvertApp] Writing 94152 bytes to ./notebook.tex
[NbConvertApp] Building PDF
[NbConvertApp] Running xelatex 3 times: ['xelatex', './notebook.tex', '-quiet']
[NbConvertApp] Running bibtex 1 time: ['bibtex', './notebook']
[NbConvertApp] WARNING | bibtex had problems, most likely because there were no
citations
[NbConvertApp] PDF successfully created
[NbConvertApp] Writing 1308746 bytes to mlp-week09.pdf
```

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