



RTK GPS MEASUREMENT EXPERIMENTS

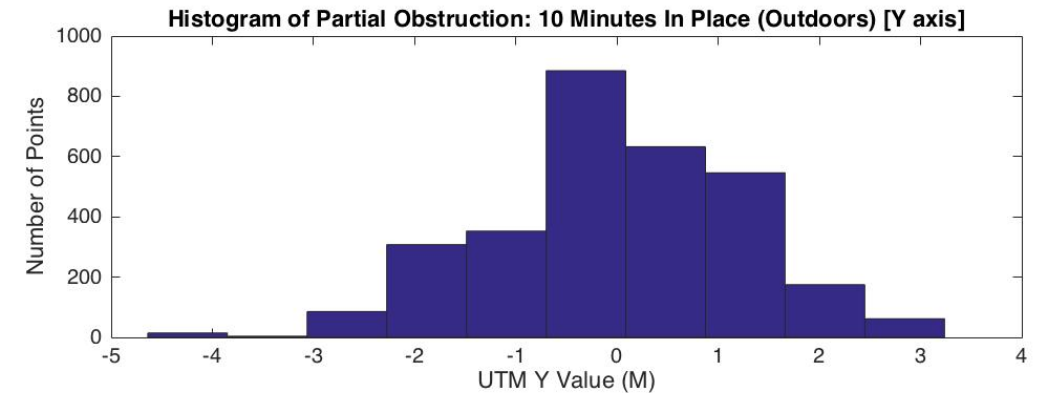
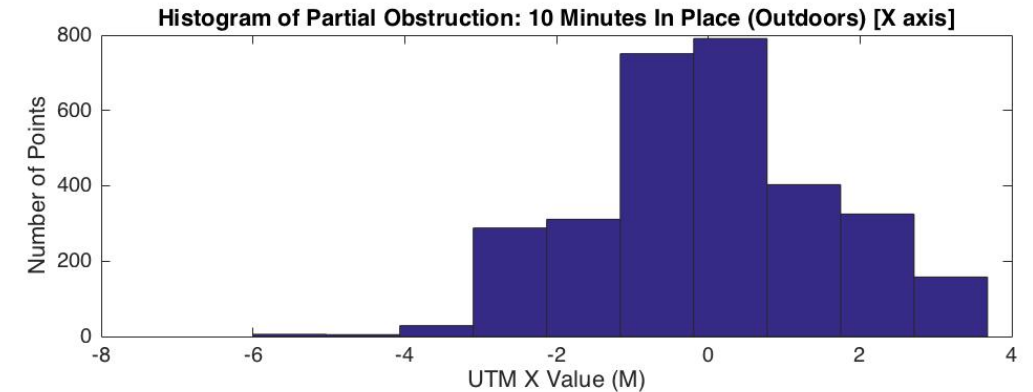
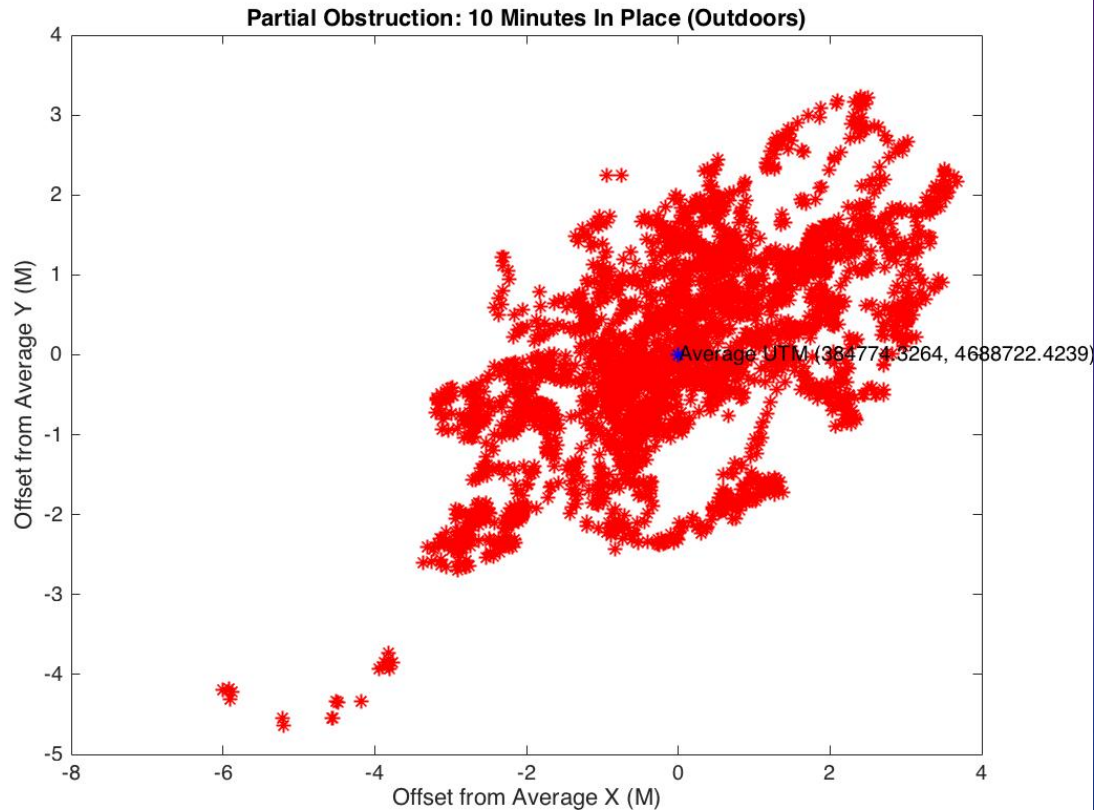
ANDREW TU

EECE 5698 ROBOTICS SENSING AND NAVIGATION

NORTHEASTERN UNIVERSITY

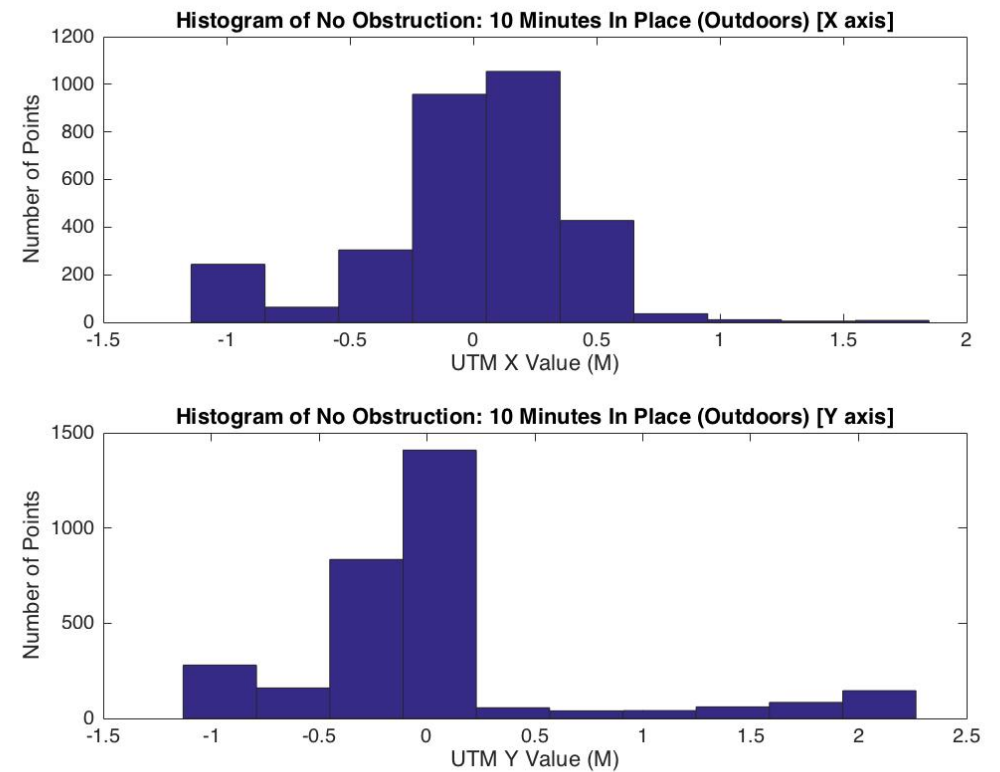
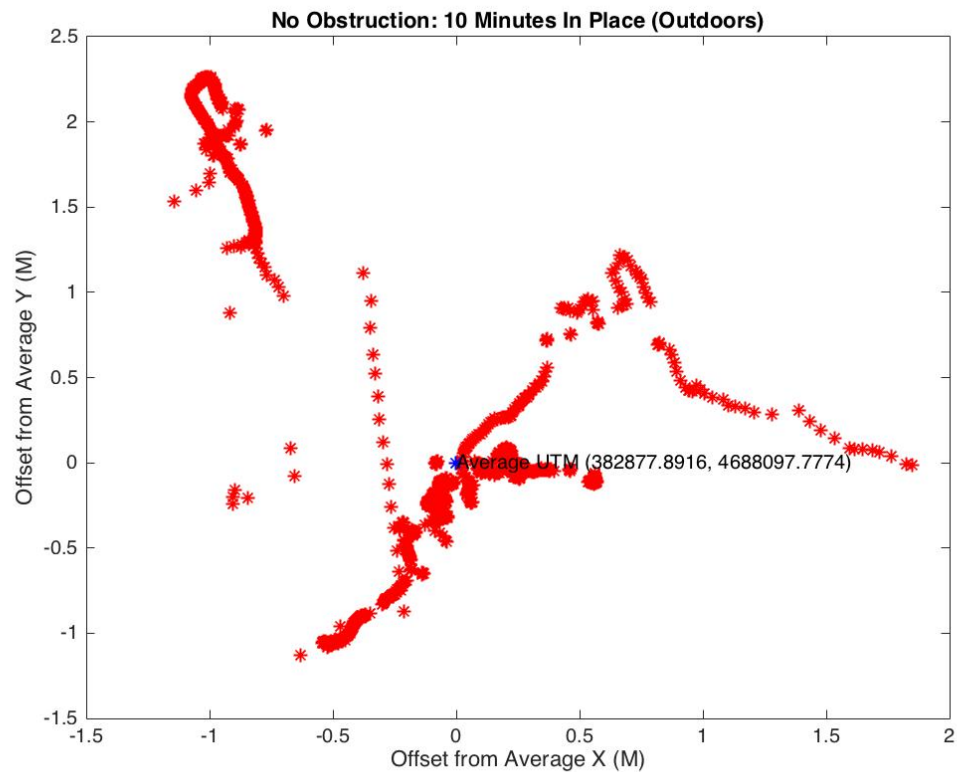
PARTIAL OBSTRUCTION: 10 MIN IN PLACE

Roughly +3/-5 M N/S variation
Roughly +4/-6 M N/S variation
Gaussian Error



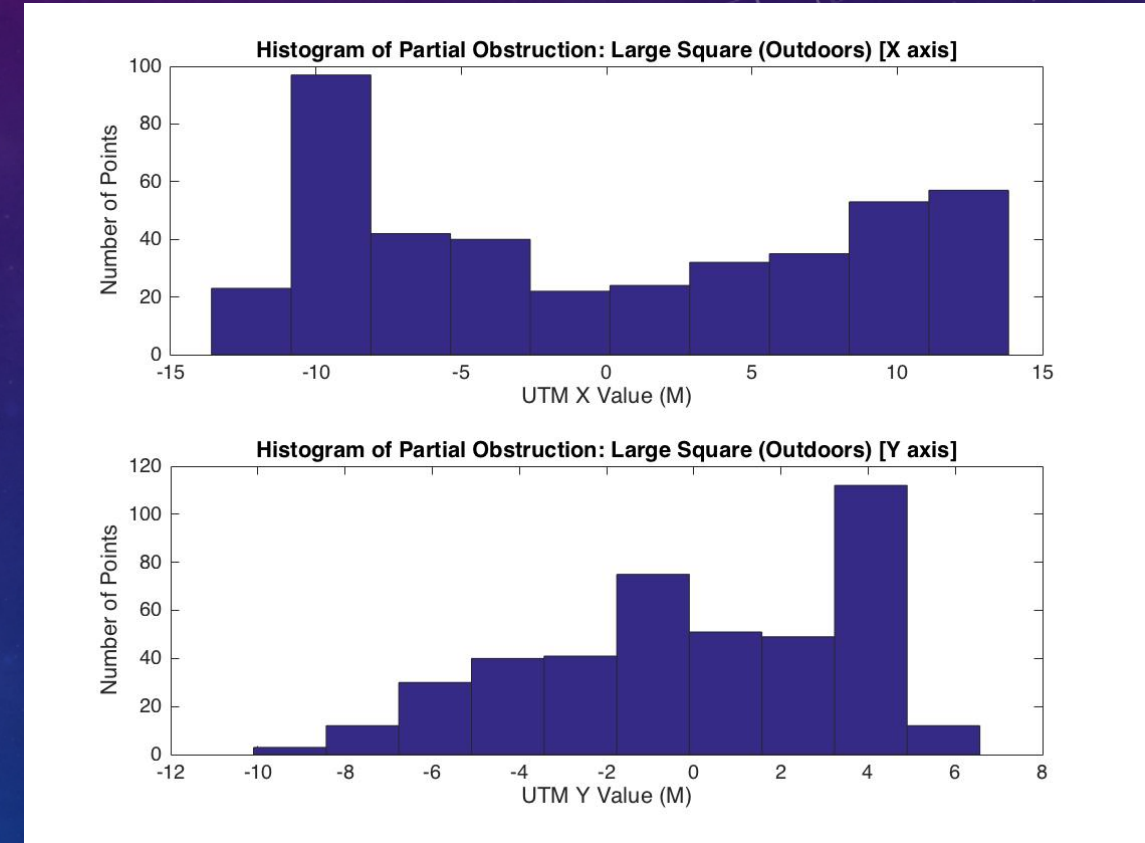
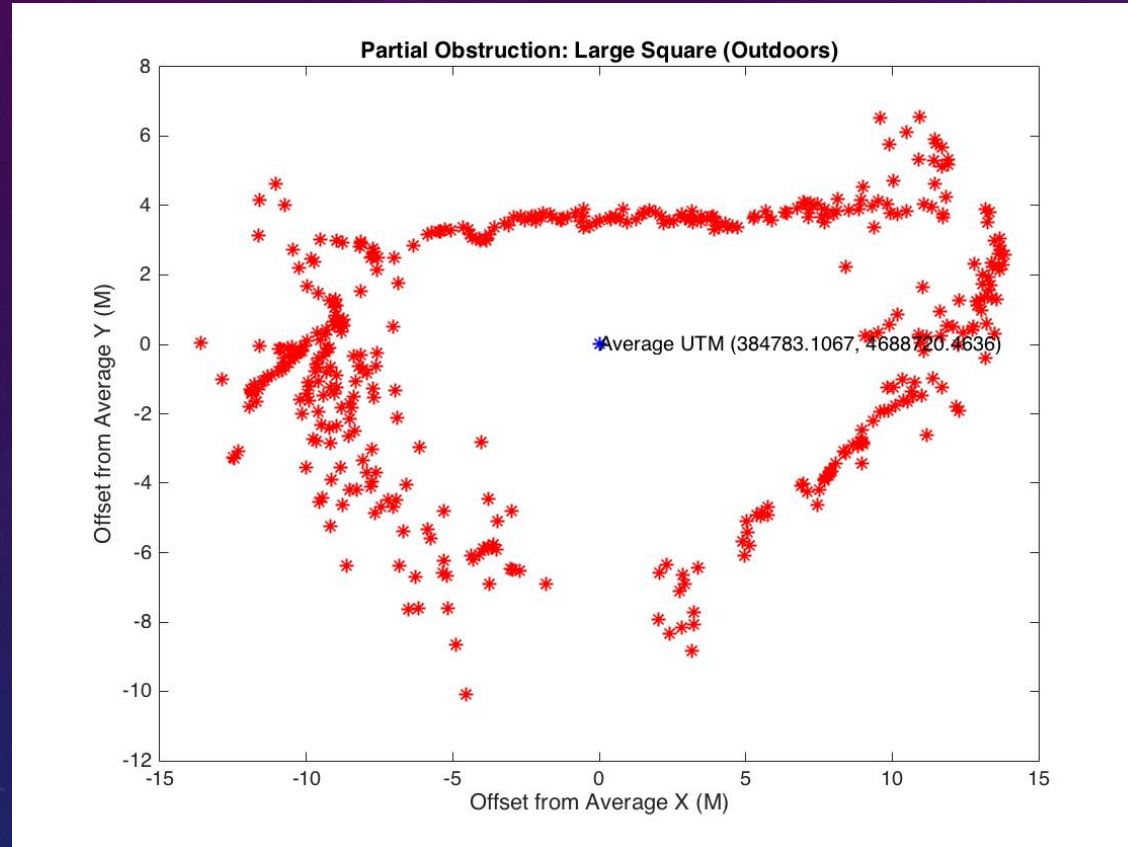
NO OBSTRUCTION: 10 MIN IN PLACE

Roughly +2.5/-1 m N/S variation
Roughly +2/-1.5 m W/E variation
Gaussian N/S error



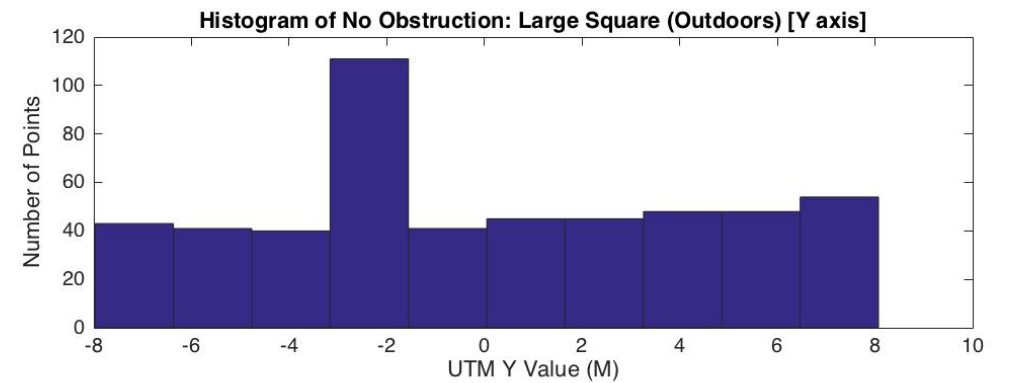
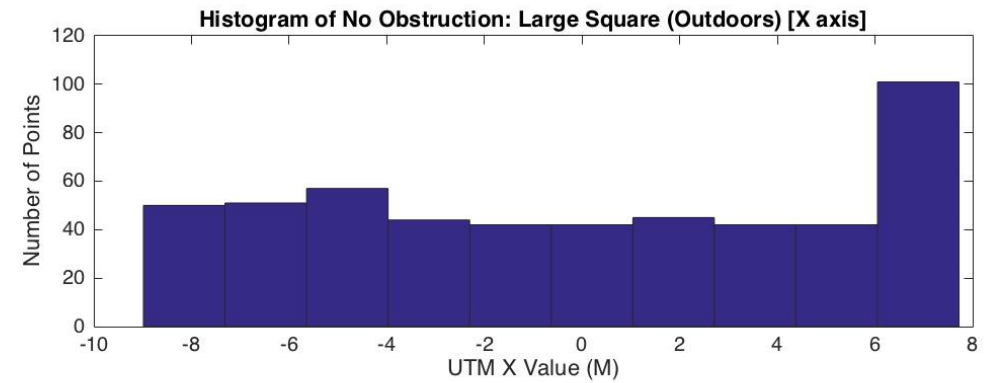
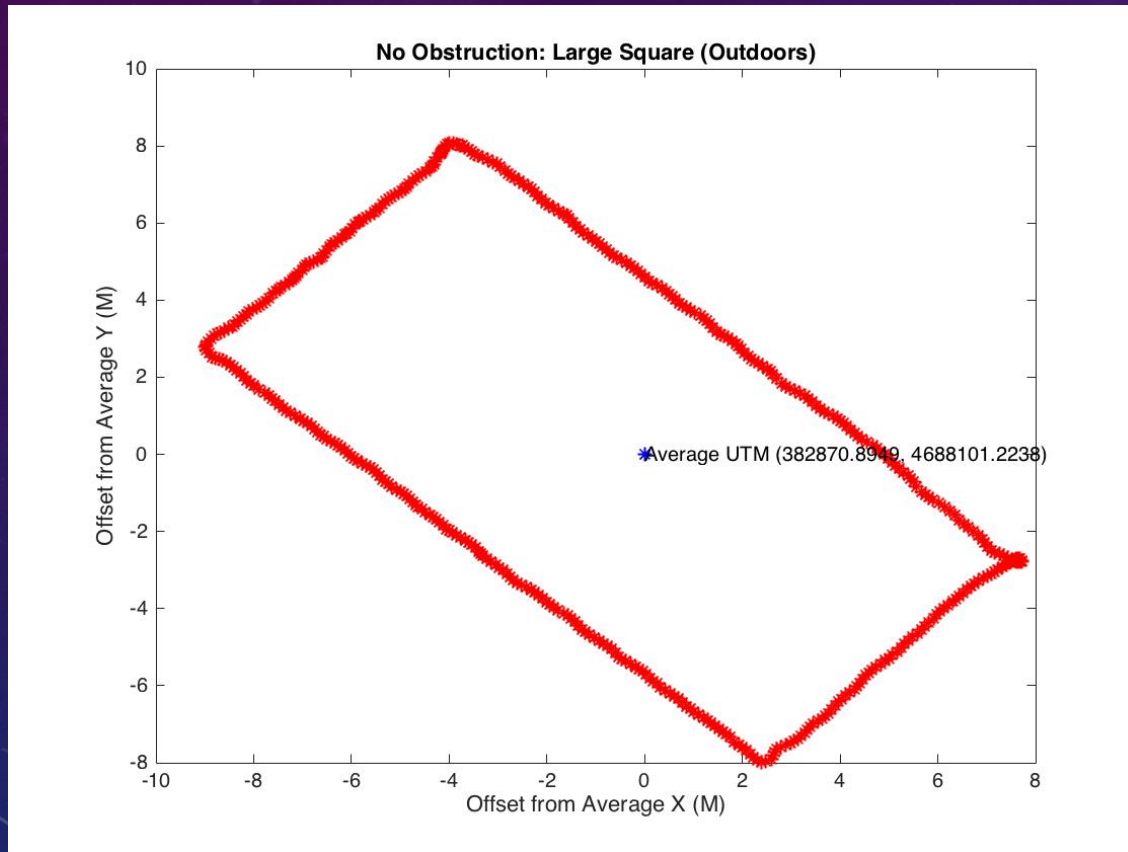
PARTIAL OBSTRUCTION: LARGE SQUARE

Large error readings to the west
(corresponding to the location
of the building)
Error is not Gaussian



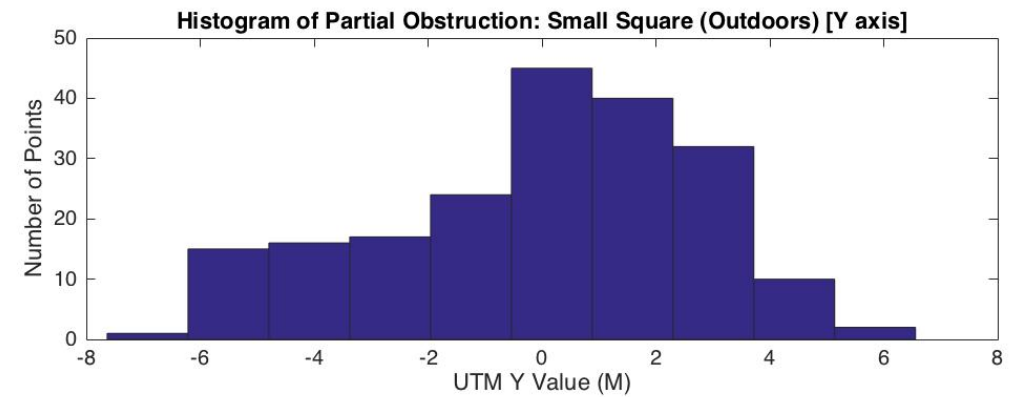
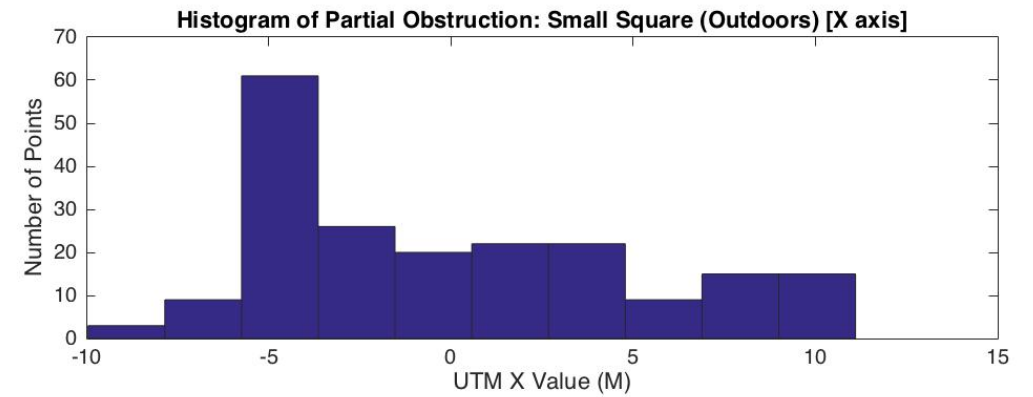
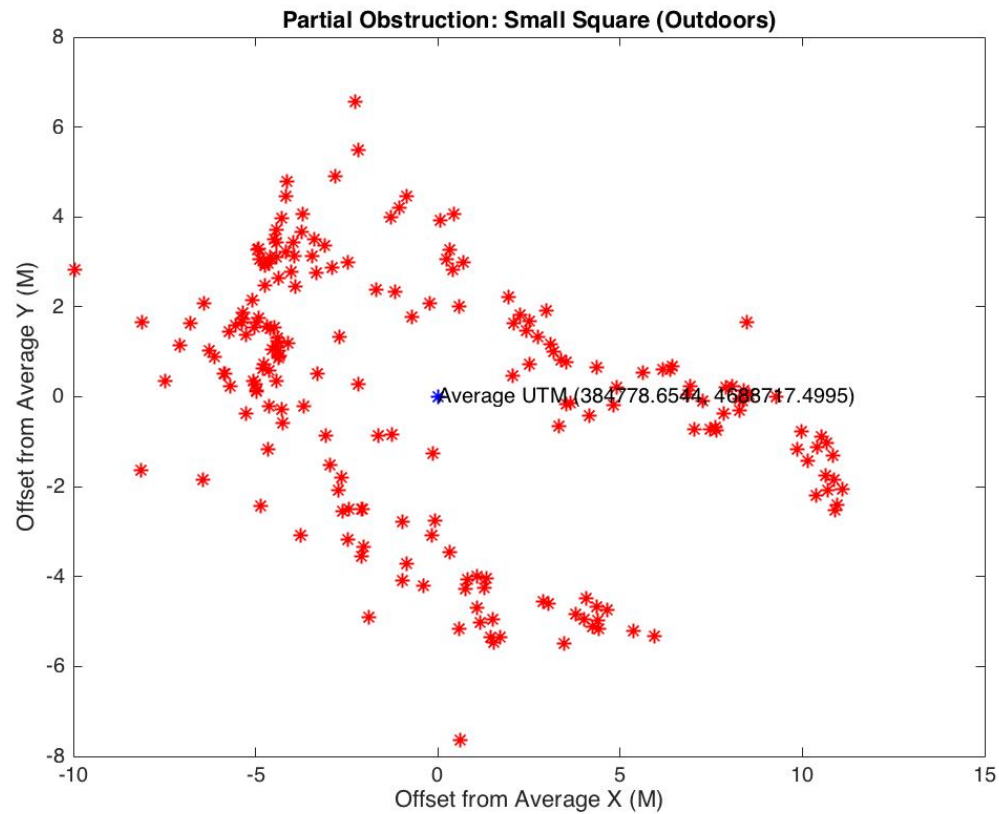
Very clean lines, very little variation.
Start/end position is within .1 m

NO OBSTRUCTION: LARGE SQUARE



PARTIAL OBSTRUCTION: SMALL SQUARE

Large error readings to the west
(corresponding to the location
of the building)
Error is Gaussian in N/S
direction (no obstructions)



Very clean lines, very little variation.
Start/end position is within .1 m

NO OBSTRUCTION: SMALL SQUARE

