

Collocation, collocation, collocation

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Week's work

✦ Collocation methods for standard continuation

✦ Annual review

✦ Brainwave: collocation methods for CBC

Annual review

Very positive! Main take-aways:

1. It's worth looking into how collocation could be used in CBC
2. Differentiation matrices, spectral, pseudospectral methods might let us find a Jacobian without finite differences
3. Next project should work towards some grand unifying goal
 - ▶ Physiologists have lots of good experimental techniques for studying neurons; a CBC project would need to find a physiologically useful question to answer
 - ▶ Alternatively, could explore the theoreticals of CBC – noise-robustness, efficiency, accuracy, higher-codimension continuation, etc., to work answer an experimental nonlinear dynamics question
 - ▶ Challenge is to find an overall question to answer that is useful its target community

Collocation

- ✂ Deriving collocation equations for generic boundary value problems
- ✂ Re-read Kuznetsov Elements; realised I'm making things harder than they need to be
- ✂ Wikipedia suggested scalar coefficients, separate BSpline basis functions for each dimension
- ✂ More standard method: vector coefficients, scalar basis funcs shared across dimensions
- ✂ Re-deriving the collocation equations with scalar basis funcs
- ✂ Realising CBC could use collocation
- ✂ Deriving CBC collocation equations

Discretisations

CBC discretisation:

1. Project the input signal onto a set of basis functions
2. Project the output signal onto a set of basis functions
3. Solve for equality between input and output coefficients

AUTOesque discretisation:

1. Construct a boundary-value problem for the periodic orbit
2. Construct a mesh across the domain of the independent variable
3. Construct an approximate BVP solution-form
4. Find the basis func. coeff's s.t. the BVP is solved exactly at the meshpoints

Generalisations

Collocation doesn't seem applicable to CBC

- ✂ It's a method for solving differential equations
- ✂ We don't have access to any differential equations, only the IO map
- ✂ Consider the CBC IO map
 - ▶ Maps some periodic control-target to some periodic system response
 - ▶ We can consider the controlled system as some nonlinear operator on the space of periodic functions
 - ▶ We seek a function that solves the operator's fixed-point problem
- ✂ Consider the boundary value problem
 - ▶ The ODE represents some (possibly nonlinear) differential operator
 - ▶ We seek a function that satisfies the differential operator, and some boundary conditions
- ✂ More abstract'ly: collocation helps solve an operator problem; CBC gives us an operator problem

Collocation for CBC

Choose some points along our control target; find coefficients s.t. those points remain unchanged by the IO map

- ✂ Let C_T be the space of T -periodic functions
- ✂ Let $N : C_T \rightarrow C_T$ be a nonlinear operator defined by the controlled system
- ✂ We seek $x(t)$ s.t. $N(x(Tt)) = x(Tt)$, $t \in [0, 1]$
- ✂ Define a collocation mesh $\xi_1 = 0 < \xi_2 < \dots < \xi_n = 1$
- ✂ Assume a solution of form $x(t) = \sum \beta_i B_i(t)$
- ✂ Mandate solution correctness at collocation points
 - $N(\sum \beta_i B_i(\xi_i)) = \sum \beta_i B_i(\xi_i)$, $i \in \{1, 2, \dots, n\}$
- ✂ Solve for β_i satisfying the above

We're free to choose basis func's B_i ; lots of collocation literature, lots of basis func. choices.....

Collocation vs the standard method

Standard method: basis func. coeff's are the object of interest; input and output functions are a means to an end

- ✖ We seek the basis function coefficients that remain unchanged when passed through the IO map
- ✖ We don't really care what the input and output functions are, because if their coefficients are the same, so are the signals
- ✖ This ceases to solve the undiscretised problem when we have any discretisation error

Collocation: coefficients are a means to an end; input and output functions are the object of interest

- ✖ We seek coefficients s.t. chosen points remain unchanged by the IO map
- ✖ Coefficients are just the parameters we adjust to find this fixed-point; we don't care about their values
- ✖ The discretisation can be inexact and we can still find a solution!

Why doubt the standard method?

- ✦ The standard method is valid when the discretisation and un-discretisation operators are each other's inverse
 - ▶ Can transform between functions, discretisations, and back, with zero error
 - ▶ We assume the solution to a discretised map is representative of a solution to the undiscretised map
 - ▶ We can prove *[quite easily]* that this assumption breaks when there's discretisation error
- ✦ Not been an issue so far, as Fourier discretisation can be made exact to working precision on the comparatively simple signals used so far
- ✦ Bonus: collocation is thoroughly tried-and-tested; accepted method because it's very accurate and computationally efficient

Challenges of collocation

✶ Noise-robustness

- ▶ We're requiring the signals to be exactly equal at the collocation points; this removes all the noise-filtering abilities of the basis functions
- ▶ Surrogates would fix this!
- ▶ Alternatively: collocate statistically – model noise and find the statistically optimal coefficients

✶ Differentiation

- ▶ Perhaps there's alternative methods to finite-differences?
- ▶ Differentiation matrices? Spectral methods? Generalised secant methods?

Interesting aside: take the infinite limit of number of collocation points; we then get the 'minimally invasive' control reformulation I've discussed previously

Next steps

- ✦ Take a break from *[but don't abandon!]* standard-continuation, BSpline discretisation using the 'standard' CBC discretisation method
- ✦ Try CBC BSpline discretisation using collocation
- ✦ Compare collocation basis functions
- ✦ Then... numerical methods
 - ▶ Efficient collocation-system solvers, Jacobian estimation

Target result: demonstrate efficient CBC discretisation using collocation methods
