

# Discretisation-free CBC

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## Week's goal

- ✂ Finish off redrafting paper
- ✂ Start working towards an *in-silico* CBC

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## Week's activities

- ✂ Finished off redrafting paper
- ✂ Started reading a paper for a single-cell model to test CBC on [1]
  - ▶ Krasi's cubic Lienard model, but with a parameter fixed, and coupled to a slow subsystem
  - ▶ Capable of modelling almost all known bursting behaviours
- ✂ Read some of Kuznetsov numerical bifurcation analysis
- ✂ Started thinking about CBC
  - ▶ This week's big idea: discretisation-free CBC

[1] Saggio, Maria Luisa, et al. "Fast-slow bursters in the unfolding of a high codimension singularity and the ultra-slow transitions of classes." *The Journal of Mathematical Neuroscience* 7.1 (2017): 7.

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## Continuation background: points

- ✂ Continuation works in a predictor corrector scheme
  - ▶ Predict the next point on the manifold from the local tangent vector
  - ▶ Correct it using a Newton iteration
  - ▶ An additional parameter appears – the arclength parameter – so require *predictor*  $\perp$  *corrector* to ensure a well-posed problem
- ✂ For equilibrium and equilibrium-bifurcation continuation, we have a finite-dimensional state
  - ▶ Tangent vector is of the same dimensionality, and is therefore finite
  - ▶ Predictor-corrector scheme is of finite – usually low – dimensionality, and is therefore computationally tractable

For points (equilibria, equilibrium bifurcations) everything works nicely

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## Continuation background: orbits

- ✿ A periodic orbit is some function  $f(t, \lambda)$ ,  $t \in [0, 1]$ 
  - ▶  $f$  exists in an infinite-dimensional Hilbert space
- ✿ Continuation of  $f$  in  $\lambda$  requires a discretisation, to produce a finite-dimensional approximation that we can apply standard continuation methods on
- ✿ There's a range of methods for discretisation
  - ▶ Orthogonal collocation seeks a set of orthogonal polynomials that satisfy the model at a selection of meshpoints; high accuracy; requires a model
  - ▶ Fourier decomposition decomposes a periodic signal into its harmonic components; model-free (important for CBC); sensitive to noise; will be high-dimensional for spiking signals
  - ▶ Wavelets, frames, splines, . . . , yet to be developed!

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## Issues with discretisation

- ✂ Can't use collocation methods without a model
- ✂ Spiking signals would need a lot of Fourier harmonics (quick-changing means lots of high-frequency energy); high dimensional continuation systems are hard
- ✂ Noise would greatly impair Fourier discretisation; can't filter it off without losing the high-frequency components of the signal required for fast spiking
- ✂ Wavelets, frames, splines haven't been developed yet (might also be noise-sensitive?)

Can we continue periodic orbits without discretisation?

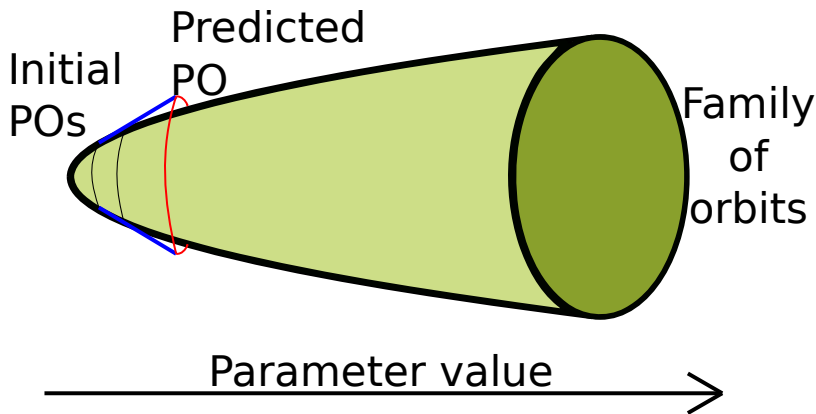
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## Discretisation-free method: benefits and issues

- ✦ By avoiding discretisation, we can deal with exceedingly fast-changing signals easily
- ✦ The learning step allows us to average out the noise, in a way that would be difficult using discretisation methods, meaning more numerical stability
- ✦ Uses some machine learning – a buzzword that seems to bring in citations. . .

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## Graphic representation





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## Basic strategy

- ✦ Learn a model of the periodic orbit surface
- ✦ Use that model to project forward to the next periodic orbit
  - ▶ Learning and projecting forms the predictor step
- ✦ Iterate down on to the surface
  - ▶ Iterating down forms the corrector step

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## A topology interlude

- ✿ A homotopy  $H$  is a continuous deformation  $H : X \times [0, 1] \rightarrow Y$  between two topological spaces  $X$  and  $Y$
- ✿ Consider a homotopy  $H$  between functions  $f_1, f_2$ , parameterised in some variable  $t$ 
  - ▶  $H(f_1, 0) = f_1$
  - ▶  $H(f_1, 1) = f_2$
  - ▶ Simple example:  $H = f_1 + t(f_2 - f_1)$

✿ Animation 1

✿ Animation 2

The overall goal is to learn a continuous homotopic transformation for the predictor/corrector, which can be applied to raw, undiscretised data

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## Mathematical representation

- ✿ Use machine learning to find a homotopy between successive orbits  
 $f(t, \lambda_{i-1}), f(t, \lambda_i)$
- ✿ Use this homotopy as a predictor for the next orbit
- ✿ Apply an orthogonal correction step
  - ▶ Prediction will be a smooth function estimating  $f(t, \lambda_1)$
  - ▶ Find a corrector family of  $f$  orthogonal to the homotopic step
  - ▶ Each  $f$  in this family is a control target, one of which is a periodic orbit of the open-loop system
  - ▶ 'Slide down' this family of periodic orbits, on to the corrected solution
  - ▶ 'Sliding down' is done by iteratively updating the control target, much like in Barton et al.
  - ▶ By selecting new targets from the corrector family, we're maintaining the orthogonality constraint

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## Learning a homotopy

1. Set  $\lambda = \lambda_0$
2. Record data for a while
3. Use  $F_0$  estimator to partition data into periods
4. Reconstruct the state space (?)
5. Let  $t \in [0, 1]$  measure how far through a period each reconstructed vector is
6. Learn a function  $f_0 : [0, 1] \rightarrow \mathbb{R}^n$ , giving the (reconstructed) state at time  $t$
7. Repeat this for  $\lambda = \lambda_1$ , learning function  $f_1$
8. Learn a homotopy  $H_1 : \mathcal{H} \times [0, 1] \rightarrow \mathcal{H}$ , where  $f_i \in \mathcal{H}$

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## The machine learning step

- ✿ Gaussian processes are the ideal tool for learning  $f_i, H_i$ 
  - ▶ Provide a nonparametric way of modelling arbitrary manifolds
  - ▶ Statistically rigorous
- ✿  $F_0$  estimation and state space reconstruction is much like that in my master's thesis
- ✿ Might even be able to get away without the state space reconstruction, but intuitively it seems like everything would work better doing it

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## Benefits and issues (again)

- ✖ By avoiding discretisation, we can deal with exceedingly fast-changing signals easily
- ✖ The learning step allows us to average out the noise, in a way that would be difficult using discretisation methods, meaning more numerical stability
- ✖ Uses some machine learning – a buzzword that seems to bring in citations. . .
- ✖ Prediction step should be fairly straightforward
- ✖ Correction step *might* be straightforward, but has the potential to be more challenging

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## Next steps

- ✂ Finish readings (Kuznetsov numerical bifurcation analysis, neuron model paper)
- ✂ Make any additional changes to the continuation paper
- ✂ Further programming marking
- ✂ Lab meeting Wednesday; make some slides for that
  - ▶ Current plan: present everything I've written in the paper
- ✂ Try implementing discretisation-free CBC on the Duffing code?