Moth 314

Exam 2 practice problems

Solthians

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Name:

Math 314 Matrix Theory Exam 2

Show all work. How you get your answer is just as important, if not more important, than the answer itself. If you think it, write it!

1. (20 pts.) Find, using any method (other than psychic powers), the determinant of the matrix

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & 3 \\ 4 & 4 & 2 \end{pmatrix}$$

Is this matrix invertible?

$$-3 \left(\frac{121}{0-13} \right) - 3 \left(\frac{121}{0-14} \right)$$

$$Ad(A) = 1 \cdot (-1)(-14) = 14$$

$$Ad(A) \neq 0 \text{ so } A \text{ is invertible}$$

$$2dd(A) = 1 \left| \frac{13}{42} \right| - 0 \left| \frac{21}{42} \right| + 4 \left| \frac{21}{13} \right|$$

$$= 1 \left(-14 \right) + 4 \left| \frac{7}{7} \right| = \frac{14}{3}.$$

2. (15 pts.) Explain why the set of vectors

$$W = \{(x, y, z) \mid x + y + 2z = 1\}$$

is **not** a subspace of \mathbb{R}^3 .

How many reasons de you want?

0+0+2(0) = 0 +1 & (0,0,0) & W & trust be a subspace. (1,0,07, (0,1,0) & W but:

(a) unv = (1,1,0) has 1+1+2(0) = 2+1 so antw so t contlem.

(b) 2.u = (2,0,0) has 2+0+2(0)=2+1 so ZufW so it could be ...

-u= (-1,0,0) has (-1)+0+2(0)=-1+1 & + celt, be

IF Any one answe will do!

4.(20 pts.) For the matrix

$$A = \begin{pmatrix} 1 & 2 & 1 & 0 \\ 2 & 1 & 3 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

find bases for, and the dimensions of, the row, column, and null spaces of A.

$$A \longrightarrow \begin{pmatrix} 1210 \\ 0-312 \\ 0-101 \end{pmatrix} \longrightarrow \begin{pmatrix} 1210 \\ 010-1 \\ 0-312 \end{pmatrix}$$

$$= \begin{pmatrix} 1210 \\ 010-1 \\ 001-1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1012 \\ 010-1 \\ 001-1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1003 \\ 010-1 \\ 001-1 \end{pmatrix}$$

$$R(A) \mid basis = \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1003 \\ 010-1 \\ 001-1 \end{pmatrix}$$

$$C(A) \mid basis = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$X_1 + 3X_1 = 0 \qquad X_2 = X_1 \qquad X_2 = X_1 \qquad X_2 = X_1 \qquad X_1 = X_2 \qquad X_2 = X_1 \qquad X_2 = X_2 \qquad X_2 = X_1 \qquad X_2 = X_2 \qquad X_3 = X_1 = X_2 \qquad X_2 = X_1 \qquad X_3 = X_1 = X_2 \qquad X_2 = X_1 \qquad X_3 = X_1 = X_2 \qquad X_2 = X_1 \qquad X_3 = X_1 = X_2 \qquad X_2 = X_2 \qquad X_3 = X_1 = X_2 \qquad X_2 = X_1 \qquad X_3 = X_2 \qquad X_4 \qquad X_3 = X_4 \qquad X_4 = X_4 \qquad X_4 = X_4 \qquad X_5 = X_4 \qquad X_5 = X_4 \qquad X_5 = X_4 \qquad X_5 = X_5 \qquad X_6 = X_6 \qquad X_6 = X_6 \qquad X_6 = X_6 \qquad X_7 = X_8 \qquad X_8 = X_1 \qquad X_8 = X_1 \qquad X_8 = X_1 \qquad X_1 = X_1 \qquad X_2 = X_1 \qquad X_3 = X_4 \qquad X_4 \qquad X_5 = X_4 \qquad X_6 = X_1 \qquad X_6 = X_1 \qquad X_6 = X_1 \qquad X_8 = X_1 \qquad X_8 = X_1 \qquad X_8 = X_1 \qquad X_8 = X_1 \qquad X_1 = X_2 \qquad X_1 = X_1 \qquad X_2 = X_1 \qquad X_3 = X_4 \qquad X_4 \qquad X_6 = X_1 \qquad X_1 = X_2 \qquad X_1 = X_2 \qquad X_2 = X_3 \qquad X_4 \qquad X_1 = X_2 \qquad X_4 \qquad X_1 = X_2 \qquad X_4 \qquad X_5 \qquad X_6 \qquad X_6 = X_1 \qquad X_1 = X_2 \qquad X_1 = X_2 \qquad X_2 \qquad X_4 \qquad X_5 \qquad X_6 \qquad X_7 \qquad X_8 \qquad X_8$$

basis

5. (20 pts.) Find all of the solutions to the equation Ax = b, where

$$A = \begin{pmatrix} 1 & 2 & 2 & 1 \\ 2 & 4 & 3 & 3 \\ 1 & 2 & 1 & 2 \end{pmatrix} \text{ and } b = \begin{pmatrix} -2 \\ -2 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 2 & 1 & -2 \\ 2 & 4 & 3 & 3 & -2 \\ 1 & 2 & 1 & 2 & 0 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & 1 & -2 \\ 0 & 0 & -1 & 1 & 2 \\ 0 & 0 & -1 & 1 & 2 \end{pmatrix}$$

$$x_1 + 2x_2 + 3x_4 = 2$$
 $x_1 = 2 - 2x_2 - 3x_4$
 $x_3 - x_4 = -2$ $x_3 = -2 + x_4$

$$\begin{pmatrix} X_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ -2 \\ 0 \end{pmatrix} + X_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + X_4 \begin{pmatrix} -3 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

5. A friend of yours runs up to you and says 'Look I've found these three vectors v_1, v_2, v_3 in \mathbb{R}^2 that are linearly independent!' Explain how you know, without even looking at the vectors, that your friend is wrong (again).

Because if we wish them as almost a matrix and row reduce (hybrigs)=A -> P

Reacher proof in different rows, so how at most 2 pinots. Since R has 3 columns, the therefore has a free variable, so Axe 5 has a non-of how a free variable, so Axe 5 has a non-of solution. The grows a non-trivial linear contaration and theory dependent!

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M314 Matrix Theory Exam 2

Exams provide you the student with an opportunity to demonstrate your understanding of the techniques presented in the course. So:

Show all work. The steps you take to your answer are just as important, if not more important, than the answer itself. If you think it, write it!

1. (20 pts.) Find, using any method (other than psychic powers), the determinant of the matrix

$$A = \begin{pmatrix} -1 & 0 & 1 & 2 \\ 3 & -3 & 1 & 1 \\ 0 & 2 & 0 & 3 \\ 1 & -1 & 1 & 1 \end{pmatrix}$$

3.The system of equations

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 2 & 2 & 3 & 4 & 0 & 1 & 0 & 0 \\ 3 & 3 & -1 & -6 & 0 & 0 & 1 & 0 \\ 1 & 1 & 2 & 3 & 0 & 0 & 0 & 1 \end{pmatrix} \text{ row-reduces to } \begin{pmatrix} 1 & 1 & 0 & 0 & 14 & -5 & -1 & 0 \\ 0 & 0 & 1 & 0 & -24 & 9 & 2 & 0 \\ 0 & 0 & 0 & 1 & 11 & -4 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 11 & -4 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \end{pmatrix}.$$

If we call the left-hand side of the first pair of matrices A, use this row-reduction information to find the dimensions and bases for the subspaces Row(A), Nul(A), and $Row(A^T)$.

(o pts. for each subspace.)

Ranks) has basis (the dampses of) the non-T rows

of R, so (1), (1), (1), (1) are a basis for Rank AD

R has one free variable, so Miller) has one pass vector.

XY 15 free.

XY 20 gives 20 (1) is a basis for Miller)

Ranks) = CA(A), and CA(A)

Ranks (1), (1), (1), (1)

Ranks (1), (1),

3. Do the vectors
$$\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$$
, $\begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$, $\begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$, and $\begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix}$ span \mathbf{R}^3 ?

Are they linearly independent?

Can you find a subset of this collection of vectors which forms a basis for \mathbb{R}^3 ? (10 pts. for spanning, 10 pts. for lin indep, 5 pts. for basis.)

Both of the first 2 questions can be arrawed by randous $\begin{pmatrix} 1 & 2 & -1 & 1 \\ -1 & 0 & 1 & 3 \\ 3 & 2 & 1 & 5 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & 2 & 0 & 4 \\ 0 & -4 & 4 & 2 \end{pmatrix}$ $\rightarrow \begin{pmatrix} 12 & -11 \\ 0 & 102 \\ 0 & -442 \end{pmatrix} \rightarrow \begin{pmatrix} 12 & -11 \\ 0 & 102 \\ 0 & 04 & 10 \end{pmatrix}$ me have 3 pivots, 80 me home a part in every row, so they spen R3. We have a free veralle so they are not (in indep B) of we use only the first 3 vectors, then he have no free var, and we still home a part in each 100,80 $\left(\frac{1}{3}\right),\left(\frac{3}{2}\right),\left(\frac{1}{1}\right)$ Lath span and are in indep, so the are a basis for \mathbb{R}^3 .

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Show all work. How you get your answer is just as important, if not more important, than the answer itself. If you think it, write it!

1. (20 pts.) Find the determinant of the matrix

$$A = \begin{pmatrix} 1 & 2 & 1 & -1 \\ 3 & -1 & 2 & 3 \\ 5 & 4 & 2 & 1 \\ 2 & 4 & 2 & -3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 1 & -1 \\ 3 & -1 & 2 & 3 \\ 5 & 4 & 2 & 1 \\ 2 & 4 & 2 & -3 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 & -1 \\ 0 & -7 & -1 & 6 \\ 0 & -6 & -3 & 6 \\ 0 & 0 & 0 & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 & -1 \\ 0 & -7 & -1 & 6 \\ 0 & 0 & 0 & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 & -1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 52 & -1 \\ 0 & 0 & 0 & -1 \end{pmatrix} = R$$

$$de(R) = (1)(1)(\frac{5}{2})(-1) = (-1)(\frac{-1}{6})det(A) \quad se$$

$$de(A) = (-1)(-6)(1)(1)(\frac{5}{2})(-1) = 6(\frac{-5}{2}) = (\frac{-30}{2}) = -15$$

2. (20 pts.) For the vector space \mathcal{P}_3 of polynomials of degree less than or equal to 3, let $T:\mathcal{P}_3\to\mathbf{R}$ be the function

$$T(p) = p(2) + p(3)$$
.

Show that T is a linear transformation, and find numbers a, b, and c so that

$$T(x+a) = T(x^2+b) = T(x^3+c) = 0$$
.

We want:
$$T(p+q) = T(p) + T(q)$$
, $T(cp) = cT(p)$
for CFIR, p.q. $CFIR$, p.q. $CFIR$

$$T(p+q) = (p+q)(x) + (p+q)(3)$$

= $(p(x) + q(x)) + (p(3) + q(3)) = (p(x) + p(3)) + (q(x) + q(3))$
= $T(p) + T(q)$

$$T(cp) = (cp)(2) + (cp)(3) = c(p(v) + c(p(3)))$$

$$= c(p(2) + p(3)) = cT(p)$$

So: T is a linear transformation.

$$T(x+q) = (2+a)+(3+a) = 2a+5 = 0$$
 for $a = \frac{-5}{2}$
 $T(x^2+b) = (4+b)+(9+b) = 2b+13 = 0$ for $b = -\frac{1}{2}$
 $T(x^2+c) = (8+c)+(27+c) = 2c+35 = 0$ for $c = -\frac{37}{2}$

4. (20 pts.) Show that the collection of vectors $W = \{(a \ b \ c)^T \in \mathbf{R}^3 : 3a - 2b + c = 0\}$ is a *subspace* of \mathbf{R}^3 , and find a *basis* for W.

Need:
$$\vec{v}, \vec{w} \in \mathcal{W} \Rightarrow \vec{v} + \vec{w} \in \mathcal{W}$$

 $\vec{v} \in \mathcal{W}$ ($\vec{v} \in \mathcal{W}$), $\vec{v} = (\vec{v} \in \mathcal{W})$
 $\vec{v} = (\vec{v} \in \mathcal{W})$, $\vec{v} = (\vec{v} \in \mathcal{W})$
 $\vec{v} = (\vec{v} \in \mathcal{W})$, $\vec{v} = (\vec{v} \in \mathcal{W})$
 $\vec{v} = (\vec{v} \in \mathcal{W})$, $\vec{v} = (\vec{v} \in \mathcal{W})$
 $\vec{v} = (\vec{v} \in \mathcal{W})$, $\vec{v} = (\vec{v} \in \mathcal{W})$

$$\frac{\delta e}{k \cdot k} \times \frac{1}{k \cdot k} = \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} = \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} = \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} = \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k} = \frac{1}{k \cdot k} \cdot \frac{1}{k \cdot k}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2/3y - /3z \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2/3y \\ 4 \end{pmatrix} + 2 \begin{pmatrix} -13 \\ 0 \\ 1 \end{pmatrix}$$

Basis!
$$\begin{pmatrix} 23 \\ 1 \end{pmatrix} \begin{pmatrix} -3 \\ 0 \end{pmatrix}$$

5. (15 pts.) If a 5×8 matrix C has rank equal to 4, what is the dimension of its nullspace (and why does it have that value?)?

Y = ronk(c) = dm (Gl(c)) = # of puts in(R) RFF

of C. C how 8 columnos, so with 4 product this
means to how 4 free variables in (R) REF.

But dm(M(C)) = # of free variables in (R) REF,

But dm(M(C)) = # of free variables in (R) REF,

But dm(M(C)) = # of free variables in (R) REF,

3. (25 pts.) Find bases for the column, row, and nullspaces of the matrix

$$B = \begin{pmatrix} 1 & 2 & 1 & -1 \\ 3 & -1 & 2 & 3 \\ -3 & 8 & -1 & -9 \\ 5 & 3 & 4 & 1 \end{pmatrix}.$$

Raw reduce!

$$\begin{pmatrix}
1 & 2 & 1 & -1 \\
3 & -1 & 2 & 3 \\
-3 & 8 & -1 & -9 \\
5 & 3 & 4 & 1
\end{pmatrix}
\rightarrow
\begin{pmatrix}
1 & 2 & 1 & -1 \\
0 & -7 & -1 & 6 \\
0 & 14 & 2 & -12 \\
0 & -7 & -1 & 6
\end{pmatrix}
\rightarrow
\begin{pmatrix}
1 & 2 & 1 & -1 \\
0 & -7 & -1 & 6 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{pmatrix}$$

$$\delta = \begin{pmatrix} 1 \\ 3 \\ -3 \\ 5 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \\ 8 \end{pmatrix} = base & Col(B)$$

$$\begin{pmatrix} 1 \\ 0 \\ 94 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 1/7 \\ 92 \end{pmatrix} = basis & Raw(B)$$

$$\begin{pmatrix} -47 \\ -1/2 \\ 1 \\ 0 \end{pmatrix}$$
 = bon for NJ(B)

$$\begin{pmatrix} x \\ y \\ z \\ \omega \end{pmatrix} = \begin{pmatrix} -47 - 40 \\ -47 + 69 \\ \omega \end{pmatrix}$$

Math 314 Matrix Theory

Exam 2 Solutions

Show all work. How you get your answer is just as important, if not more important, than the answer itself. If you think it, write it!

1. (20 pts.) For which value(s) of x is the matrix $A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & x & 2 \\ 1 & 1 & x \end{pmatrix}$ not invertible?

We can row reduce the matrix, and look for a column without a pivot (for some values of x):

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & x & 2 \\ 1 & 1 & x \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & x - 4 & 0 \\ 0 & -1 & x - 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & x - 1 \\ 0 & x - 4 & 0 \end{pmatrix}$$
$$\longrightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 - x \\ 0 & x - 4 & 0 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 - x \\ 0 & 0 & (1 - x)(4 - x) \end{pmatrix}$$

This has three pivots, <u>unless</u> (1-x)(4-x) = 0, that is, unless x = 1 or x = 4. So for these values of x the matrix will not be invertible; for any other value of x is <u>will</u> be invertible.

Or: we can use the fact that A is invertible $\Leftrightarrow \det(A) \neq 0$. So we compute:

$$\det(A) = (1)\det\begin{pmatrix} x & 2 \\ 1 & x \end{pmatrix} - (2)\det\begin{pmatrix} 2 & 2 \\ 1 & x \end{pmatrix} + (1)\det\begin{pmatrix} 2 & x \\ 1 & 1 \end{pmatrix} = (1)(x^2 - 2) - (2)(2x - 2) + (1)(2 - x) = x^2 - 2 - 4x + 4 + 2 - x = x^2 - 5x + 4,$$
so A is not invertible precisely when $x^2 - 5x + 4 = 0$.

But since $x^2 - 5x + 4 = (x - 1)(x - 4) = 0$ for x = 1 and x = 4, we have A is not invertible precisely when x = 1 or x = 4.

2. (20 pts.) Does the collection of vectors

$$W = \left\{ \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} : x - 2y + 4z + 3w = 0 \right\}$$

form a vector space (using the usual addition and scalar multiplication of vectors)? Explain why or why not.

We can approach this two ways: the short way is to note that W is the nullspace of the matrix $\begin{pmatrix} 1 & -2 & 4 & 3 \end{pmatrix}$, and a nullspace <u>is</u> a subspace (of \mathbf{R}^4), and so is a vector space. Or we do it the longer way:

1

If
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}$$
 and $\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$ are both in W , then $x-2y+4z+3w=0$ and $a-2b+4c+3d=0$, so $(x+a)-2(y+b)+4(z+c)+3(w+d)=(x-2y+4z+3w)+(a-2b+4c+3d)=0+0=0$, so $\begin{pmatrix} x+a \\ y+b \\ z+c \\ w+d \end{pmatrix}=\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}+\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$ is in W , and so W is closed under vector addition.

Similarly, if
$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$
 is in W and $c \in \mathbf{R}$, then

$$(cx) - 2(cy) + 4(cz) + 3(cw) = c(x - 2y + 4z + 3w) = c(0) = 0, \text{ so } \begin{pmatrix} cx \\ cy \\ cz \\ cw \end{pmatrix} = c \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$
 is in W , and so W is closed under scalar multiplication.

Since W is closed under both vector addition and scalar multiplication, W is a subspace of \mathbb{R}^4 , and so is a vector space.

3. (25 pts.) Use a superaugmented matrix to express the column space of the matrix

$$A = \begin{pmatrix} 1 & 2 & 4 \\ 2 & 1 & 5 \\ 2 & 2 & 6 \end{pmatrix}$$

as the nullspace of another matrix B, and use this to decide if the systems of equations $A\vec{x} = \vec{b}$ are consistent, for the vectors \vec{b} equal to

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$
, $\begin{pmatrix} 1 \\ 5 \\ 4 \end{pmatrix}$, and $\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$.

We start by row reducing $(A|I_3)$:

$$A = \begin{pmatrix} 1 & 2 & 4 & | & 1 & 0 & 0 \\ 2 & 1 & 5 & | & 0 & 1 & 0 \\ 2 & 2 & 6 & | & 0 & 0 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 4 & | & 1 & 0 & 0 \\ 0 & -3 & -3 & | & -2 & 1 & 0 \\ 0 & -2 & -2 & | & -2 & 0 & 1 \end{pmatrix}$$

$$\longrightarrow \begin{pmatrix} 1 & 2 & 4 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 2/3 & -1/3 & 0 \\ 0 & -2 & -2 & | & -2 & 0 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 4 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 2/3 & -1/3 & 0 \\ 0 & 0 & 0 & | & -2/3 & -2/3 & 1 \end{pmatrix}$$

$$\longrightarrow \begin{pmatrix} 1 & 2 & 4 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 2/3 & -1/3 & 0 \\ 0 & 0 & 0 & | & -2 & -2 & 3 \end{pmatrix}$$

This tells us that $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$ will give a consistent system of equations precisely when

$$(\quad -2 \quad -2 \quad 3\,) \begin{pmatrix} a \\ b \\ c \end{pmatrix} = (-2a-2b+3c) = (0),$$
 i.e.,
$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \text{ is in the nullspace of } B=(\quad -2 \quad -2 \quad 3\,).$$

So the column space of A is the nullspace of B = (-2 -2 3).

Using this, we can test the three vectors we were given:

(
$$-2$$
 -2 3) $\begin{pmatrix} 1\\2\\3\\ \end{pmatrix} = -2 - 4 + 9 = -6 + 9 = 3 \neq 0,$ so this does not give a consistent system of equations.
(-2 -2 3) $\begin{pmatrix} 1\\5\\4\\ \end{pmatrix} = -2 - 10 + 12 = -12 + 12 = 0,$ so this gives a consistent system of equations.
(-2 -2 3) $\begin{pmatrix} 3\\2\\1\\ \end{pmatrix} = -6 - 4 + 3 = -10 + 3 = -7 \neq 0,$ so this does not give a consistent system of equations.

4. (25 pts.) Find a collection from among the vectors

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix}$$

that forms a basis for \mathbb{R}^3 , and express the <u>remaining</u> vectors as linear combinations of your chosen basis vectors.

[Hint: your work for the first part should tell you how to answer the second part!]

To find a basis, we need linear independence and spanning \mathbb{R}^3 , so we put the vectors together in a matrix and row reduce!

$$A = \begin{pmatrix} 1 & 2 & 2 & 3 \\ 2 & 1 & 2 & 1 \\ 3 & 1 & 3 & 2 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & 3 \\ 0 & -3 & -2 & -5 \\ 0 & -5 & -3 & -7 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & 3 \\ 0 & 1 & 2/3 & 5/3 \\ 0 & -5 & -3 & -7 \end{pmatrix}$$
$$\longrightarrow \begin{pmatrix} 1 & 2 & 2 & 3 \\ 0 & 1 & 2/3 & 5/3 \\ 0 & 0 & 1/3 & 4/3 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & 3 \\ 0 & 1 & 2/3 & 5/3 \\ 0 & 0 & 1 & 4 \end{pmatrix}$$

So in row echelon form, there are pivots in the first three columns, so those three columns of A are linearly independent. They also span (a pivot in every row, or 3 linearly independent vectors in \mathbb{R}^3 !), so the first three columns form a basis for \mathbb{R}^3 . To write the remaining vector as a linear combination, we can note that we have done most of the work of solving the needed linear system; just insert a vertical bar before the fourth column!

$$\begin{pmatrix} 1 & 2 & 2 & | & 3 \\ 2 & 1 & 2 & | & 1 \\ 3 & 1 & 3 & | & 2 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & | & 3 \\ 0 & 1 & 2/3 & | & 5/3 \\ 0 & 0 & 1 & | & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 2 & | & 3 \\ 0 & 1 & 0 & | & -1 \\ 0 & 0 & 1 & | & 4 \end{pmatrix}$$

Another approach, which many of you followed, is to find a basis for the nullspace of this matrix A. From the RREF, we have $x_1 - 3x_4 = 0$, $x_2 - x_4 = 0$, and $x_3 + 4x_4 = 0$, so

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 3x_4 \\ x_4 \\ -4x_4 \\ x_4 \end{pmatrix} = x_4 \begin{pmatrix} 3 \\ 1 \\ -4 \\ 1 \end{pmatrix}, \text{ so } \begin{pmatrix} 3 \\ 1 \\ -4 \\ 1 \end{pmatrix} \text{ is a basis for the nullspace of } A. \text{ But }$$
this means that

$$(3) \begin{pmatrix} 1\\2\\3 \end{pmatrix} + (1) \begin{pmatrix} 2\\1\\1 \end{pmatrix} + (-4) \begin{pmatrix} 2\\2\\3 \end{pmatrix} + (1) \begin{pmatrix} 3\\1\\2 \end{pmatrix} = \vec{0},$$
which means that
$$\begin{pmatrix} 3\\1\\2 \end{pmatrix} = (-3) \begin{pmatrix} 1\\2\\3 \end{pmatrix} + (-1) \begin{pmatrix} 2\\1\\1 \end{pmatrix} + (4) \begin{pmatrix} 2\\2\\3 \end{pmatrix}.$$

5. (10 pts.) Show why if A and B are matrices so that AB makes sense, and the matrix AB has <u>linearly independent</u> columns, then B must have linearly independent columns.

[Hint: What does the conclusion, about B, say about systems of linear equations?]

We want to say that B has linearly independent columns, which means that the only linear combination of the columns that equals the vector $\vec{0}$ is the all-0 linear combination. In matrix terms, if $B\vec{x} = \vec{0}$, then we must have $\vec{x} = \vec{0}$.

But if we then suppose that $B\vec{x} = \vec{0}$, then $A(B\vec{x}) = A\vec{0} = \vec{0}$. But $A(B\vec{x}) = (AB)\vec{x}$, and so we know that $(AB)\vec{x} = \vec{0}$. But the columns of AB are linearly independent!, and so the same line of reasoning shows that we must have $\vec{x} = \vec{0}$.

So, if $B\vec{x} = \vec{0}$ then $((AB)\vec{x} = \vec{0})$, and so $\vec{x} = \vec{0}$, showing that the columns ob B are linearly independent.

An alternate approach, taken by some, is to think of matrix multiplication as a linear transformation T_A , etc., and note that $T_{AB} = T_A \circ T_B$. Having linearly independent columns amounts (by essentially the same reasoning as above) to saying that T_{AB} is a one-to-one function $[T_{AB}(\vec{x}) = T_{AB}(\vec{y}) \text{ means } T_{AB}(\vec{x} - \vec{y}) = \vec{0}$, so $\vec{x} - \vec{y} = \vec{0}$, so $\vec{x} = \vec{y}$.] But if T_B is not one-to-one, then $T_A \circ T_B$ cannot be; $T_B(\vec{x}) = T_B(\vec{y})$ means that $T_{AB}(\vec{x}) = T_A(T_B(\vec{x})) = T_A(T_B(\vec{y})) = T_{AB}(\vec{y})$. So T_{AB} one-to-one implies that T_B must be one-t-one, so B has linearly independent columns.