



# Lagrange multiplier and KKT condition

陳弘軒 Hung-Hsuan Chen

https://www.ncu.edu.tw/~hhchen

中央大學資訊工程學系

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#### Toy example

- Maximize  $5x_1x_2$  subject to  $2x_1 + x_2 = 100$
- Can we solve the optimization problem by gradient descent/ascent?
  - Probably not, because we have extra constraints



#### Toy example

- Maximize  $5x_1x_2$  subject to  $2x_1 + x_2 = 100$

$$\rightarrow$$
  $(x_1, x_2) = (25, 50)$ 

- The maximum value of  $5x_1x_2$  is 6250
- If the constraints are not complicated, such a method is manageable



#### Lagrange multiplier

- Lagrange multipliers is a strategy for finding the extreme value of a function *subject to equality constraints*
- Finding the maximum value of y = f(x) subject to  $g_i(x) = 0, i = 1, 2, ..., m$ 
  - Lagrange function (a.k.a. Lagrangian)

• 
$$y_{\lambda} = f(x) + \lambda_1 g_1(x) + \lambda_2 g_2(x) + \dots + \lambda_m g_m(x)$$





### Solving the problem

- Lagrange function:  $\mathcal{L}(x_1, ..., x_n, \lambda_1, ..., \lambda_m) = f(x) + \sum_{i=1}^m \lambda_i g_i(x)$
- Take the derivative of the Lagrange function to every variable (i.e., all the x's and the  $\lambda$ 's)

$$\Rightarrow \begin{cases} \frac{\partial \mathcal{L}(x_1, \dots, x_n, \lambda_1, \dots, \lambda_m)}{\partial x_j} = 0 \ \forall j \\ \frac{\partial \mathcal{L}(x_1, \dots, x_n, \lambda_1, \dots, \lambda_m)}{\partial \lambda_i} = 0 \ \forall i \end{cases}$$

• Test each solution set. Whichever gives the greatest (or the smallest) value is the maximum (or minimum) point



### Solving the toy example

• Maximize  $5x_1x_2$  subject to  $2x_1 + x_2 = 100$  $f(x_1, x_2) = 5x_1x_2, g(x_1, x_2) = 2x_1 + x_2 - 100$  $\mathcal{L}(x_1, x_2, \lambda_1) = 5x_1x_2 + \lambda_1(2x_1 + x_2 - 100)$  $\begin{cases} \frac{\partial \mathcal{L}(x_1, x_2, \lambda_1)}{\partial x_1} = 5x_2 + 2\lambda_1 \coloneqq 0 \\ \frac{\partial \mathcal{L}(x_1, x_2, \lambda_1)}{\partial x_2} = 5x_1 + \lambda_1 \coloneqq 0 \\ \frac{\partial \mathcal{L}(x_1, x_2, \lambda_1)}{\partial x_2} = 2x_1 + x_2 - 100 \coloneqq 0 \end{cases}$  $\Rightarrow$   $(x_1, x_2, \lambda_1) = (25, 50, -125)$ 



#### Generalized Lagrange multiplier

- Lagrange multipliers is generalized to include the <u>inequality constraints</u> under the Karush–Kuhn–Tucker (KKT) condition
- Standard form problem

Minimize 
$$f(x)$$
 subject to  $g_i(x) \le 0$   $(i = 1, ..., p)$  and  $h_j(x) = 0$   $(j = 1, ..., m)$ 

- If the task is to maximize f(x), transform the problem into minimize -f(x)
- Lagrangian



$$\mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}, \boldsymbol{\mu}) = f(\mathbf{x}) + \sum_{i=1}^{p} \lambda_i g_i(\mathbf{x}) + \sum_{j=1}^{m} \mu_j h_j(\mathbf{x})$$

## Necessary (not sufficient!) optimal condition (KKT condition)

- If  $x^*$  is the optimal solution to the standard form problem, then there exist KKT multipliers  $\lambda$  and  $\mu$  such that

  - Primal feasibility  $g_i(x^*) \le 0 \ \forall i ----- (2)$   $h_i(x^*) = 0 \ \forall j ----- (3)$
  - Dual feasibility  $\lambda_i \geq 0 \ \forall i ------- (4)$



Complementary slackness

$$\lambda_i g_i(\mathbf{x}^*) = 0 \ \forall i ---- - (5)$$

#### Example

• Minimize  $f(x_1, x_2) = x_1^2 + 2x_2^2$  subject to  $x_1 + x_2 \ge 3$  and  $x_2 - x_1^2 \ge 1$  $x_2 - x_1 \ge 1$   $\mathcal{L}(\mathbf{x}, \lambda, \mu) = x_1^2 + 2x_2^2 + \lambda_1(3 - x_1 - x_2) + \lambda_2(1 + x_1^2 - x_2)$ 

$$\Rightarrow \begin{cases} \frac{\partial \mathcal{L}}{\partial x_1} = 0 \\ \frac{\partial \mathcal{L}}{\partial x_2} = 0 \\ \frac{\partial \mathcal{L}}{\partial \lambda_1} = 0 \end{cases} \Rightarrow (x_1, x_2, \lambda_1, \lambda_2) = (-2, 5, 12, -8) \text{ or } (1, 2, 6, 2)$$
$$\Rightarrow \begin{pmatrix} \frac{\partial \mathcal{L}}{\partial \lambda_2} = 0 \\ \frac{\partial \mathcal{L}}{\partial \lambda_2} = 0 \end{pmatrix}$$
$$\Rightarrow (-2, 5, 12, -8) \text{ does not follow the KKT condition (4)}$$



$$\Rightarrow \min f(x_1, x_2) = f(1,2) = 1^2 + 2 \cdot 2^2 = 9$$



#### Summary

- When we have constraints on an optimization problem, gradient descent/ascent may not be applicable
- Lagrange multiplier is a useful tool to solve the optimization problem with equality and inequality constraints

