Name: Dat Truong U78042625

MAS 3105

Homework 8

Problem 1

1. T 2. T 3. T. 4. T 5. F

Problem 2

1. Not a linear transformation. $T(2I_2) \neq 2T(I_2)$

- 2. Is a linear transformation. Let $M = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$
 - Scalar-multiplicative: T(kA) = M(kA) = k(MA) = kT(A)
 - Additive: T(A + B) = M(A + B) = MA + MB = T(A) + T(B)
- 3. Is a linear transformation
 - Scalar-multiplicative: T(kf) = (kf)'' 2x(kf)' + kf = kf'' 2kxf' + kf = kT(f)
 - Additive: T(f+g) = (f+g)'' 2x(f+g)' + (f+g) = (f'' 2xf' + f) + (g'' 2xg' + g) = T(f) + T(g)
- 4. Is a linear transformation
 - Scalar-multiplicative: T(kf) = kf(0) = kT(f)
 - Additive: T(f+g) = (f+g)(0) = f(0) + g(0) = T(f) + T(g)

Problem 3

- 1. Are linearly independent
- 2. Are not linearly independent. $f_3 = \pi(f_1 + f_2)$
- 3. Are not linearly independent. $f_1 = 2f_2$

Problem 4

- 1. By Theorem 1, there exists a unique $f_1 \in \mathfrak{G}$ so that $f'_1(0) = 1$ and $f_1(0) = 0$, and a unique $f_2 \in \mathfrak{G}$ so that $f'_2(0) = 0$ and $f_2(0) = 1$
- 2. We assume they're linearly dependent, which means $\exists k, l \in \mathbb{R}\{0\} \ni kf_1 + lf_2 = 0$. However, $kf_1(0) + lf_2(0) = l \neq 0$, which is a contradiction. Similarly, their derivatives, f'_1, f'_2 , are not linearly dependent. Hence they are linearly independent. \square
- 3. Define $g(x) = f'(0) \cdot f_1(x) + f(0) \cdot f_2(x) = af_1(x) + bf_2(x), f \in \mathfrak{G}$

$$g'' - 3g' + 2g = (af_1'' + bf_2'') - 3(af_1' + bf_2') + 2(af_1 + bf_2)$$
$$= a(f_1'' - 3f_1' + 2f_1) + b(f_2'' - 3f_2' + 2f_2) = 0$$

g(0) = f(0) = a, g'(0) = f'(0) = b, hence $g \in \mathfrak{G}$, and $\mathfrak{G} = \text{Span}(f_1, f_2)$

5. $\lambda^2 - 3\lambda + 2 = 0$, so $\lambda = 1$ or $\lambda = 2$

 $g_1=e^x, g_2=e^{2x}$, and $\nexists k\in\mathbb{R}\ni g_1=kg_2$, so they are linearly independent. We have established in part 3 that $\dim(\mathfrak{G})=2$, so g_1 and g_2 form a basis of \mathfrak{G}

$$g_1(x) = f_1(x) + f_2(x), g_2(x) = 2f_1(x) + f_2(x)$$

- 6. From the explicit formulas in part 5, g_1 has coordinates $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and g_2 has coordinates $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$
- 7. f_1 has coordinates $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and f_2 has coordinates $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$