

# MARK JENNINGS

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www.makr.org

## Education – The University of Texas at Austin

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<b>MS Mechanical Engineering</b>	<b>2019 – Present</b>
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Dynamic Systems and Control, 3.95 GPA

<b>BS Mechanical Engineering</b>	<b>2015 – 2019</b>
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Robotics Certificate Program, 3.84 GPA

## Research Experience

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<b>Nuclear &amp; Applied Robotics Group</b>	<b>2019 – Present</b>
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*Graduate Research Assistant*

- Develop real-time controls for passively-balanced robotic arm
- Implement collaborative manufacturing and confined manipulation tasks

<b>Rehabilitation and Neuromuscular (ReNeu) Robotics Lab</b>	<b>2016 – 2019</b>
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*Undergraduate Research Assistant*

- Designed and manufactured parts for rehabilitation robots
- 3D printed and assembled prosthetic hand and prosthetic finger

## Work Experience

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<b>Sandia National Labs</b>	<b>Summer 2019</b>
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*R&D Intern*

- Proposed qualification procedure for additively manufactured metal parts
- Designed electronics housing and validated through mechanical testing
- Awarded first out of three teams in summer design challenge

<b>Apptronik Systems</b>	<b>Summer 2018</b>
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*Engineering Intern*

- Fabricated mechanical parts for lower-body powered exoskeleton
- Designed and validated actuator testbed product
- Developed forward kinematics for 10 DoF bipedal robot

## Leadership Experience

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<b>Capstone Engineering Project</b>	<b>Spring 2019</b>
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*Engineering Lead*

- Collaborated with 3 other seniors to redesign a feedstock hopper for an SLS printer
- Delivered final prototype with significantly improved powder retention and distribution

<b>UT Robotics &amp; Automation Society (RAS)</b>	<b>2015 – 2019</b>
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*Mentor, Officer*

- Assisted in community outreach events to introduce youth to robotics
- Mentored 3 teams of 5-6 students in annual robotics competition

## Technical Skills

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	<i>Proficient</i>	<i>Familiar</i>
<b>Programming</b>	C++, Robot Operating System (ROS), Linux	Python, MoveIt
<b>Software</b>	SolidWorks, MATLAB, MS Office	PTC Creo, LabVIEW
<b>Algorithms</b>	Manipulator control, Obstacle avoidance	SLAM, Point set registration
<b>Fabrication</b>	Manual machining, Additive manufacturing	CNC operation