# **MARK JENNINGS**

markjennings@utexas.edu (254)760-5530 | www.makr.org

## Education – The University of Texas at Austin

MS Mechanical Engineering

2019 - Present

Dynamic Systems and Control, Nuclear Engineering, 3.95 GPA

**BS Mechanical Engineering** 

2015 - 2019

Robotics Certificate Program, 3.84 GPA

## **Work Experience**

#### **Sandia National Labs**

**Summer 2019** 

**R&D** Intern

- Proposed qualification procedure for additively manufactured metal parts
- Designed electronics housing and validated through mechanical testing
- Awarded first out of three teams in summer design challenge

Apptronik Systems Summer 2018

**Engineering Intern** 

- Fabricated mechanical parts for lower-body powered exoskeleton
- Designed and validated actuator testbed product
- Developed forward kinematics for 10 DoF bipedal robot

# **Research Experience**

# **Nuclear & Applied Robotics Group**

2019 - Present

Graduate Research Assistant

- Develop real-time controls for passively-balanced robotic arm
- Implement collaborative manufacturing and confined manipulation tasks

#### Rehabilitation and Neuromuscular (ReNeu) Robotics Lab

2016 - 2019

Undergraduate Research Assistant

- Designed and manufactured parts for rehabilitation robots
- 3D printed and assembled prosthetic hand and prosthetic finger

# **Leadership Experience**

## **Capstone Engineering Project**

**Spring 2019** 

**Engineering Lead** 

- Collaborated with 3 other seniors to redesign a feedstock hopper for an SLS printer
- Delivered final prototype with significantly improved powder retention and distribution

# **UT Robotics & Automation Society (RAS)**

2015 - 2019

Mentor, Officer

- Assisted in community outreach events to introduce youth to robotics
- Mentored 3 teams of 5-6 students in annual robotics competition

## **Technical Skills**

	Proficient	Familiar
Software	SolidWorks, MATLAB, MS Office	PTC Creo, LabVIEW
Programming	C++, Robot Operating System (ROS), Linux	Python, HTML, CSS
Fabrication	Manual machining, Additive manufacturing	CNC operation, CAM software