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| MARK  JENNINGS | [www.makr.org](http://www.makr.org)  [markjennings97@gmail.com](mailto:markjennings97@gmail.com)  254.760.5530 |
| | Work Experience |  Nuclear & Applied Robotics Group  *Graduate Researcher* | *2019 – 2021*   * Developed intuitive controller for novel passively-balanced manipulator * Refactored codebase for custom robot arm to leverage open-source libraries   Sandia National Labs  *R&D Intern* | *Summer 2019*   * Designed and qualified additively-manufactured metal components * Received 1st place intern presentation   Apptronik, Inc.  *Engineering Intern* | *Summer 2018*   * Derived forward kinematic equations for 10DoF humanoid bipedal robot * Updated actuator testbed product to achieve higher payloads with lower fabrication costs   ReNeu Robotics Lab  *Undergraduate Researcher* | *2016 - 2019*   * Designed and fabricated components for rehabilitation robotics * 3D-printed and assembled custom hand and finger prosthetics | | Technical Skills |    Proficient:   * ROS * C++ * MATLAB * SolidWorks * Additive Manufacturing * Machining/CNC   Familiar:   * Python * Simulink, LabVIEW * HTML, CSS, JavaScript |
| | Education |  MS Mechanical Engineering  *UT Austin* | *2019 – 2021* | *3.96 GPA*   * Research: Robotic Manipulators   BS Mechanical Engineering  *UT Austin* | *2015 – 2019* | *3.84 GPA*  Coursework topics:   * Autonomous Robots * Manipulator Algorithms * Classical & Modern Control * Robot Mechanism Design |