## MATH 262 - Homework 3.3

2. The redundant column is  $\vec{v}_1 = \vec{0}$ . The nonredundant column

$$\vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

forms a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 1$ .

Using the redundant vector  $\vec{v}_1$ , a vector in the kernel of A can be generated.

Redundant Vector Relation Vector in Kernel of A

$$\vec{v}_1 = \vec{0}$$
  $\vec{v}_1 - 0\vec{v}_2 = \vec{0}$   $\vec{w}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ 

Vector  $\vec{w_1}$  constructed above forms a basis of the kernel of A. This can be verified by observing that  $\vec{w_1}$  is trivially linearly independent and that dim(ker A) = 1.

Finally,

$$\operatorname{im}(A) = \operatorname{span}\left\{\begin{bmatrix} 1\\2 \end{bmatrix}\right\}$$
  
 $\ker(A) = \operatorname{span}\left\{\begin{bmatrix} 1\\0 \end{bmatrix}\right\}$ 

6. The redundant column is  $\vec{v}_3 = \vec{v}_1 + 2\vec{v}_2$ . The nonredundant columns

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

form a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 2$ .

Using the redundant vector  $\vec{v}_3$ , a vector in the kernel of A can be generated.

$$\vec{v}_3 = \vec{v}_1 + 2\vec{v}_2$$
  $-\vec{v}_1 - 2\vec{v}_2 + \vec{v}_3 = \vec{0}$   $\vec{w}_3 = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$ 

Vector  $\vec{w}_3$  constructed above forms a basis of the kernel of A. This can be verified by observing that  $\vec{w}_3$  is trivially linearly independent and that dim(ker A) = 1.

Finally,

$$\operatorname{im}(A) = \operatorname{span}\left\{ \begin{bmatrix} 1\\2 \end{bmatrix}, \begin{bmatrix} 1\\1 \end{bmatrix} \right\}$$
$$\ker(A) = \operatorname{span}\left\{ \begin{bmatrix} -1\\-2\\1 \end{bmatrix} \right\}$$

8. The redundant column is  $\vec{v}_1 = \vec{0}$ . The nonredundant columns

$$\vec{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

form a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 2$ .

Using the redundant vector  $\vec{v}_1$ , a vector in the kernel of A can be generated.

Redundant Vector Relation Vector in Kernel of A

$$\vec{v}_1 = \vec{0}$$
  $\vec{v}_1 - 0\vec{v}_2 - 0\vec{v}_3 = \vec{0}$   $\vec{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ 

Vector  $\vec{w}_1$  constructed above forms a basis of the kernel of A. This can be verified by observing that  $\vec{w}_1$  is trivially linearly independent and that dim(ker A) = 1.

Finally,

$$\operatorname{im}(A) = \operatorname{span}\left\{ \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix} \right\}$$
$$\ker(A) = \operatorname{span}\left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix} \right\}$$

12. The redundant columns are  $\vec{v}_1 = \vec{0}$  and  $\vec{v}_3 = 2\vec{v}_2$ . The nonredundant column

$$\vec{v}_2 = \begin{bmatrix} 1 \end{bmatrix}$$

forms a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 1$ .

Using the redundant vector  $\vec{v}_1$ , two vectors in the kernel of A can be generated.

Vector in Kernel of A

$$\vec{v}_1 = \vec{0}$$
  $\vec{v}_1 - 0\vec{v}_2 - 0\vec{v}_3 = \vec{0}$   $\vec{w}_1 = \begin{bmatrix} 1\\0\\0 \end{bmatrix}$   $\vec{v}_3 = 2\vec{v}_2$   $-0\vec{v}_1 - 2\vec{v}_2 + \vec{v}_3 = \vec{0}$   $\vec{w}_3 = \begin{bmatrix} 0\\-2\\1 \end{bmatrix}$ 

Relation

Vectors  $\vec{w}_1$  and  $\vec{w}_3$  constructed above form a basis of the kernel of A. This can be verified by observing that they're linearly independent and that dim(ker A) = 2.

Finally,

Redundant Vector

$$\operatorname{im}(A) = \operatorname{span}\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$
$$\ker(A) = \operatorname{span}\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

16. The redundant columns are  $\vec{v}_2 = -2\vec{v}_1$  and  $\vec{v}_4 = -\vec{v}_1 + 5\vec{v}_3$ . The nonredundant columns

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_5 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

form a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 3$ .

Using the redundant vectors  $\vec{v}_2$  and  $\vec{v}_4$ , two vectors in the kernel of A can be generated.

Redundant Vector

Relation

Vector in Kernel of A

$$\vec{v}_2 = -2\vec{v}_1 \qquad 2\vec{v}_1 + \vec{v}_2 - 0\vec{v}_3 - 0\vec{v}_4 - 0\vec{v}_5 = \vec{0} \qquad \vec{w}_2 = \begin{bmatrix} 2\\1\\0\\0\\0 \end{bmatrix}$$

$$\vec{v}_4 = -\vec{v}_1 + 5\vec{v}_3 \qquad \vec{v}_1 - 0\vec{v}_2 - 5\vec{v}_3 + \vec{v}_4 - 0\vec{v}_5 = \vec{0} \qquad \vec{w}_4 = \begin{bmatrix} 2\\1\\0\\0\\0\\1\\0 \end{bmatrix}$$

Vectors  $\vec{w}_2$  and  $\vec{w}_4$  constructed above form a basis of the kernel of A. This can be verified by observing that they're linearly independent and that dim(ker A) = 2.

Finally,

$$\operatorname{im}(A) = \operatorname{span} \left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$$
$$\ker(A) = \operatorname{span} \left\{ \begin{bmatrix} 2\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 1\\0\\0\\1 \end{bmatrix} \right\}$$

18. The redundant column is  $\vec{v}_3 = 3\vec{v}_1 + 2\vec{v}_2$ . The nonredundant columns

$$ec{v_1} = egin{bmatrix} 1 \ 0 \ 0 \ 0 \end{bmatrix}, ec{v_2} = egin{bmatrix} 1 \ 1 \ 1 \ 1 \end{bmatrix}, ec{v_4} = egin{bmatrix} 1 \ 2 \ 3 \ 4 \end{bmatrix}$$

form a basis of the image of A. Thus  $\dim(\operatorname{im} A) = 3$ .

Using the redundant vector  $\vec{v}_3$ , a vector in the kernel of A can be generated.

Redundant Vector

Relation

Vector in Kernel of A

$$\vec{v}_3 = 3\vec{v}_1 + 2\vec{v}_2 \qquad -3\vec{v}_1 - 2\vec{v}_2 + \vec{v}_3 - 0\vec{v}_4 = \vec{0} \qquad \qquad \vec{w}_3 = \begin{bmatrix} -3\\-2\\1\\0 \end{bmatrix}$$

Vector  $\vec{w}_3$  constructed above forms a basis of the kernel of A. This can be verified by observing that  $\vec{w}_3$  is trivially linearly independent and that dim(ker A) = 1.

Finally,

$$\operatorname{im}(A) = \operatorname{span} \left\{ \begin{bmatrix} 1\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3\\4 \end{bmatrix} \right\}$$
$$\ker(A) = \operatorname{span} \left\{ \begin{bmatrix} -3\\-2\\1\\0 \end{bmatrix} \right\}$$

24. Solve the linear system  $A\vec{x} = \vec{0}$  by Gaussian elimination.

$$B = \operatorname{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

 $A\vec{x} = \vec{0}$  can be solved by solving the simpler  $B\vec{x} = \vec{0}$ . The vectors in  $\ker(B)$  are of the form

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2q \\ q \\ r \\ s \\ t \end{bmatrix} = q \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + r \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + s \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_2}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_2}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{y_3}} + t \underbrace{\begin{bmatrix} 0 \\$$

where q, r, s, and t are arbitrary constants.

Note that  $\ker(A) = \ker(B)$ . The vectors  $\vec{w}_1$ ,  $\vec{w}_2$ ,  $\vec{w}_3$ , and  $\vec{w}_4$  form a basis of the kernel of A. The preceding equation,  $\vec{x} = q\vec{w}_1 + r\vec{w}_2 + s\vec{w}_3 + t\vec{w}_4$ , shows that these four vectors span the kernel. Furthermore, these vectors are linearly independent. Thus, the basis of the kernel of A is

$$\ker(A) = \operatorname{span} \left\{ \begin{bmatrix} -2\\1\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\0\\1 \end{bmatrix} \right\}$$

and  $\dim(\ker A) = 4$ .

To construct the basis of the image of A, find the redundant columns of A. Using B = rref(A), the redundant columns are the ones that lack a leading 1. The only redundant column is  $\vec{b}_2 = 2\vec{b}_1$ . Therefore,  $\vec{a}_2$  in matrix A is also redundant via the same relation. Thus, a basis of the image of A is

$$\operatorname{im}(A) = \operatorname{span} \left\{ \begin{bmatrix} 8 \\ 6 \\ 4 \\ 2 \end{bmatrix} \right\}$$

and  $\dim(\operatorname{im} A) = 1$ .

30.

$$S = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \middle| 2x_1 - x_2 + 2x_3 + 4x_4 = 0 \right\} \subseteq \mathbb{R}^4$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_1 \\ 2x_1 + 2x_3 + 4x_4 \\ x_3 \\ x_4 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 4 \\ 0 \\ 1 \end{bmatrix}$$

The basis for subspace S is

$$S = \operatorname{span} \left\{ \begin{bmatrix} 1\\2\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\2\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\4\\0\\1 \end{bmatrix} \right\}$$