Solutions to Homework #10

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1. Directly use the construction given in the lectures (I only write down \delta):
    \delta(q_0, \Lambda, Z_0) = \{(q, SZ_0)\},\
    \delta(q, *_1, *_1) = \{(q, \Lambda)\}, *_1 = a, b.
    \delta(q, \Lambda, S) = \{(q, aaB), (q, bbA), (q, AB), (q, aabb)\} (This corresponds to
rule S \to aaB|bbA|AB|aabb)
    \delta(q, \Lambda, A) = \{(q, BA), (q, aB), (q, a)\}\ (This corresponds to rule A \rightarrow
BA|aB|a
    \delta(q, \Lambda, B) = \{(q, AB), (q, bA), (q, b)\} (This corresponds to rule B \to AB|bA|b)
    \delta(q, \Lambda, Z_0) = \{(q_1, Z_0)\}
A = \{q_1\}.
2. Directly use the construction given in the lectures:
     [q_0, *_2, *_3] \to *_1[q_0, *_1, *_4][*_4, *_2, *_3] for each *_3, *_4 \in Q, and *_1 = 0, 1, *_2 = 0
0, 1. (This corresponds to \delta(q_0, *_1, *_2) = \{(q_0, *_1 *_2)\} with *_1 = 0, 1, *_2 = 0, 1)
    [q_0, 1, *_1] \to \Lambda[q_{even}, 1, *_1] | \Lambda[q_{odd}, 1, *_1] for each *_1 \in Q (This corresponds
to \delta(q_0, \Lambda, 1) = \{(q_{even}, 1), (q_{odd}, 1)\}\)
    [q_0, 0, *_1] \to \Lambda[q_{even}, 0, *_1] | \Lambda[q_{odd}, 0, *_1] for each *_1 \in Q (This corresponds
to \delta(q_0, \Lambda, 0) = \{(q_{even}, 0), (q_{odd}, 0)\}
    [q_{odd}, *_2, *_3] \rightarrow *_1[q_{even}, *_2, *_3] for each *_3 \in Q and *_1 = 0, 1, *_2 = 0, 1
(This corresponds to \delta(q_{odd}, *_1, *_2) = \{(q_{even}, *_2)\} with *_1 = 0, 1, *_2 = 0, 1)
     [q_{even}, 1, q_{even}] \to 1 (This corresponds to \delta(q_{even}, 1, 1) = \{(q_{even}, \Lambda)\})
     [q_{even}, 0, q_{even}] \to 0 (This corresponds to \delta(q_{even}, 0, 0) = \{(q_{even}, \Lambda)\})
     [q_{even}, Z_0, q_2] \to \Lambda (This corresponds to \delta(q_{even}, \Lambda, Z_0) = \{(q_2, \Lambda)\})
     [q_0, Z_0, q_2] \to \Lambda (This corresponds to \delta(q_0, \Lambda, Z_0) = \{(q_2, \Lambda)\})
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3. Assume L_1 and L_2 are accepted by NFA M_1 and M_2 . Now we describe a PDA M_3 that accepts L_3 . M_3 works as follows on an input y. Using its finite control, M_3 simulates the NFA M_1 while reading y. During the simulation, M_3 pushes every input symbol it reads into its pushdown stack. At some moment, M_3 guesses it is the right time that M_3 should start to simulate M_2 . Then M_3 checks that M_1 is in an accepting state (otherwise M_3 aborts). After this, M_3 starts to simulate M_2 using its finite control and compares every input symbol M_3 reads with the top of the stack while popping the stack. M_3 accepts the input if after reading the entire input word y, M_2 is an accepting state and the stack is empty (Z_0 is the top).