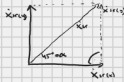


3.3) $\vec{r} = [4 \text{ cm} + (2.5 \text{ m/s}^2)t^2] \hat{i} + (5.0 \text{ cm/s})t \hat{j}$



- a) $\vec{x}_v(t=2s) = ?$, $dt=2s$
b) $\vec{x}(t=2s)$, $\vec{v}(t=2s)$, $\vec{a}(t=2s) = ?$

a) $\vec{r}(2) = (4 \text{ cm} + 10 \text{ cm}) \hat{i} + 10 \text{ cm} \hat{j}$ $\vec{r}'(t) = 4 \text{ cm} \hat{i}$

$\vec{r}'(2) = 4 \text{ cm} \hat{i} + 10 \text{ cm} \hat{j}$

$\vec{x}_v = \vec{r}'$

$\vec{x}_v(t) = \frac{dx}{dt} = \frac{d(4 \text{ cm} + 10 \text{ cm})}{dt} = 10 \text{ cm/s} \hat{j}$

$\vec{x}_v(t) = \sqrt{10^2 + 10^2} = \sqrt{200} \text{ cm/s} = 14.14 \text{ cm/s}$

b) $\vec{x} = \frac{d\vec{r}}{dt} = (5 \text{ cm/s}) \hat{i} + (5 \text{ cm/s}) \hat{j}$

$\vec{x}(t) = 0$, $\vec{x}_y(t) = 5 \text{ cm/s}$, $\vec{x} = 5 \text{ cm/s}$ (same as y)

$\vec{x}(t) = 5 \text{ cm/s}$, $\vec{x}_y(t) = 5 \text{ cm/s}$, $\vec{x} = 7.1 \text{ cm/s}$, $\alpha = 45^\circ$

$\vec{x}(t) = 10 \text{ cm/s}$, $\vec{x}_y(t) = 5 \text{ cm/s}$, $\vec{x} = 11.18 \text{ cm/s}$, $\tan \alpha = \frac{5}{10} = \frac{1}{2} \Rightarrow \alpha = \arctan(\frac{1}{2}) = 26.6^\circ$ $\alpha = 26.6^\circ$

3.16) $dt \rightarrow \log(t) = D = x(t)$

$\vec{x}_x(t) = \vec{x}_x(t) = \vec{x}(t)$

$dt \rightarrow \log(t) = 2.76 \text{ D} = x(t)$

$\vec{x}_y = ?$

$\vec{x}_y = -g$ $\frac{dy}{dt} = -g$ $dy = -g dt$ $y = -gt + C_1$ ($C_1 = \vec{x}(t)$) $\Rightarrow \vec{x}(t) = -gt + \vec{x}(t)$

$\frac{dy}{dt} = -gt + \vec{x}(t)$ $dy = dt (-gt + \vec{x}(t))$ $y = -\frac{1}{2}gt^2 + \vec{x}(t)t + C_2$ ($C_2 = 1$)

$y(t) = -\frac{1}{2}gt^2 + \vec{x}(t)t + 1$

$\frac{dx}{dt} = \vec{x}(t)$ $dx = \vec{x}(t) dt$ $x = \vec{x}(t)t + C_3$ ($C_3 = 0$) $\vec{x}(t) = \vec{x}(t)$ $\vec{x}(t) = \frac{D}{2 \log(t)}$

$y(t) = -\frac{1}{2}g \left(\frac{D^2}{x(t)^2} \right) + \vec{x}(t) \cdot \frac{D}{x(t)} + 1 = -\frac{1}{2}g \left(\frac{D^2}{x(t)^2} \right) + D + 1$

$\frac{dy}{dt} = \vec{x}_y$ $dy = \vec{x}_y dt$ $y = \vec{x}_y t + C_4$ ($C_4 = 0$)

$\vec{x}_y(t) = \vec{x}_y t$ $\frac{dy}{dt} = \vec{x}_y t$ $dy = dt (\vec{x}_y t)$ $y = \frac{1}{2} \vec{x}_y t^2 + C_5$ ($C_5 = 1$)

$y(t) = \frac{1}{2} \vec{x}_y t^2 + 1$

$\frac{dx}{dt} = \vec{x}(t)$ $dx = \vec{x}(t) dt$ $x = \vec{x}(t)t + C_6$ ($C_6 = 0$) $\vec{x}_x(t) = \vec{x}(t)t$ $\vec{x}_x(t) = \frac{x(t)}{x(t)}$

$y(t) = -\frac{1}{2}g \left(\frac{2.76 D^2}{x(t)^2} \right) + 1$

$-\frac{1}{2}g \left(\frac{2.76 D^2}{x(t)^2} \right) + 1 = 0 \Rightarrow 2 \log(t)^2$

$-\vec{x}_y (2.76 D^2) + 2 \vec{x}_y (t)^2 = 0$

$x(t)^2 = 2h = \vec{x}_y (2.76 D^2)$

$\vec{x}_y(t) = \frac{\vec{x}_y (2.76 D^2)}{2h} / \vec{x}_x(t) = \frac{g D^2}{2h}$

$\vec{x}_y (2.76 D^2) = \frac{g D^2}{2h}$

$\vec{x}_y = \frac{g}{2.76}$

$\vec{x}_y = 1.28 \text{ m/s}^2$

3.22) $\vec{x}(t) = 25 \text{ m/s}$

$L = 45 \text{ m}$

$t = 3s$

a) $\alpha = ?$

b) $\vec{x}(t) = ?$, $\vec{v}(t) = ?$

c) $h = ?$, $\vec{x}(t) = ?$

a) $\vec{x}(t) = 0$, $\vec{v}(t) = -g$

$\sin \alpha = \frac{\vec{x}(t)}{x(t)}$, $\cos \alpha = \frac{\vec{v}(t)}{v(t)}$ $\vec{x}(t) = \cos \alpha \cdot x(t)$

$\vec{x}(t) = 0$

$\frac{dx}{dt} = 0$ $dx = 0 dt$ $x = 0 t + C_1$ ($C_1 = \vec{x}(t)$)

$\vec{x}_x(t) = 0 t + \vec{x}(t)$

$\frac{dx}{dt} = 0 t + \vec{x}(t)$ $dx = (\vec{x}(t) + \vec{x}(t)) dt$ $x = \frac{1}{2} \vec{x}(t)^2 + \vec{x}(t)t + C_2$ ($C_2 = 0$)

$\vec{x}_v(t) = \frac{1}{2} \vec{x}(t)^2 + \vec{x}(t)t$

$\vec{x}_v(t) = \frac{1}{2} \vec{x}(t)^2 + \vec{x}(t)t \Rightarrow \cos \alpha \cdot \vec{x}(t) = \vec{x}_v(t) = \frac{1}{2} \vec{x}(t)^2 + \vec{x}(t)t = \frac{2 \vec{x}(t) - \vec{x}(t)^2}{2}$

$\vec{x}_v(t) = 15$

$\cos \alpha = \frac{\vec{x}_v(t)}{\vec{x}(t)t} = \frac{1}{t} \Rightarrow \alpha = 53.1^\circ$

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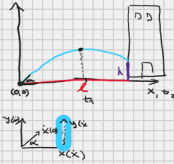
$\cos \alpha = \frac{\vec{x}_v(t)}{\vec{x}(t)t} = \frac{1}{t} \Rightarrow \alpha = 53.1^\circ$

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$\cos \alpha = \frac{\vec{x}_v(t)}{\vec{x}(t)t} = \frac{1}{t} \Rightarrow \alpha = 53.1^\circ$



b) $\vec{x}(t) = 0$, $\vec{y}(t) = -g$, $\vec{y}(t) = 0$

$\vec{x}(t) = \vec{x}(t) \cdot \cos(\alpha, t)$

$\vec{x}(t) = 15.0 \text{ m/s}$

$\vec{v}(t) = \sqrt{\vec{x}(t)^2 + \vec{y}(t)^2} = 15.0 \text{ m/s}$

$\vec{v}(t) = 15.0 \text{ m/s}$

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$\vec{v}(t) = 15.0 \text{ m/s}$

$\vec{x}(t) = g t^2 \cos \alpha \cdot \vec{x}(t)$

$\vec{x}(t) = 15 \text{ m/s}$

$\vec{x}(t) = -gt + \sin \alpha \cdot \vec{x}(t)$

$\vec{x}(t) = -3.13 \text{ m/s}$

$\vec{x}(t) = \sqrt{\vec{x}(t)^2 + \vec{y}(t)^2}$

$\vec{x}(t) = 13.7 \text{ m/s}$

$\vec{x}(t) = 13.7 \text{ m/s}$

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$\vec{x}(t) = 13.7 \text{ m/s}$

$\vec{x}(t) = 13.7 \text{ m/s}$

3.26) $L = 3.4 \text{ m}$

$\alpha_k = \frac{v^2}{R}$

$T = \frac{1}{\alpha_k t_s}$

$R = L = 3.4 \text{ m}$

$550 \text{ rpm} = \frac{550}{60} \text{ rev/s} = 9.166 \text{ rev/s} \Rightarrow T = \frac{1}{9.166} = 0.109 \text{ s}$

a) $\varphi = ?$ $\varphi = \frac{2\pi R}{T} \rightarrow \text{brzina tačice u kružnici}$ $\varphi = 135.98 \text{ m/s}$

b) $\alpha_k = ?$ $\alpha_k = 112.96 \text{ m/s}^2 = 11.5 g$



3.27) $R = 350 \text{ m}$

$\alpha_{rad} = 5.5 g$

$\varphi = ?$

$\alpha_{rad} = \frac{v^2}{R}$ $\varphi = \alpha_{rad} R$ $\varphi = \sqrt{\alpha_{rad} R}$ $\varphi = 13.7 \text{ m/s}$

3.33) $\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = 0.5 \text{ m/s}$ (v)

$\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = 0.4 \text{ m/s}$

$\vec{v}_r = \vec{v}_r + \vec{v}_r$

$\vec{v}_r = \frac{0.4}{\sqrt{2}} = 0.28 \text{ m/s}$

$\vec{v}_r = -\vec{v}_r + \frac{0.4}{\sqrt{2}} = -0.28 \text{ m/s}$

$\vec{v}_r = \sqrt{\vec{v}_r^2 + \vec{v}_r^2} = 0.39 \text{ m/s}$

$\vec{v}_r = \sqrt{\vec{v}_r^2 + \vec{v}_r^2} = 0.39 \text{ m/s}$

$\vec{$

Modul 3 - Zadaci

Saturday, November 18, 2023 10:59 AM

3.49) $l = 50\text{m} = R$

$v_{\max} = ?$

$a_{\text{rad}} = g$

$a_{\text{rad}} = \frac{v^2}{R} \quad v^2 = a_{\text{rad}} \cdot R \quad v = \sqrt{a_{\text{rad}} R}$

$v = 22.14\text{ m/s}$



$R = \frac{v_0^2 \sin 2\alpha}{g}$

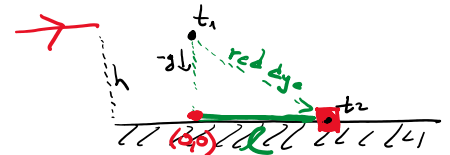
3.53)

$h = 90\text{m}$

$\dot{x}(t) = 64\text{m/s}$

$g = 10\text{m/s}^2$

$l = ?$



$\dot{x}_r(t_1) = \dot{x}(t) \quad \frac{dx_r}{dt} = \dot{x}(t_1) \quad dx_r = \dot{x}(t_1) dt \quad x_r = \dot{x}(t_1)t + C_1 \quad (C_1 = 0)$

$\dot{y}_r(t_1) = 0$

$\ddot{x}_r(t_1) = 0$

$\ddot{y}_r(t_1) = -g$

$x_r(t) = \dot{x}(t_1)t$

$x_r(t_2) = l, \quad x_r(t_1) = 0$

$x_r(t_2) = \dot{x}_r(t_1)t_2$

$l = \dot{x}_r(t_1)t_2$

$\frac{dy}{dt} = -g \quad dy = -g dt \quad y = -gt + C_1 \quad (C_1 = 0)$

$\dot{y}(t) = -gt \quad \frac{dy}{dt} = -gt \quad dy = -gt dt \quad y = -\frac{1}{2}gt^2 + C_2 \quad (C_2 = h)$

$y(t) = -\frac{1}{2}gt^2 + h \quad y(t_2) = 0, \quad y(t_1) = h$

$y(t_2) = -\frac{1}{2}gt_2^2 + h = 0 \quad gt_2^2 = 2h$

$t_2 = \sqrt{\frac{2h}{g}} = 4.24\text{s}$

$l = 271.36\text{m}$

3.60) $2R = D$

$h = 2D$

$\alpha = 45^\circ$

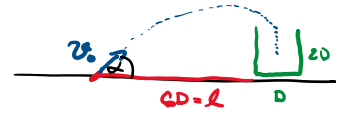
$l = ?$



$$\alpha = 45^\circ$$

$$l = 6D$$

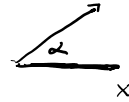
$$v_0 = ? \text{ (da ubacuje :)}$$



$$\ddot{x}(0) = 0, \ddot{y}(t) = -g$$

$$\cos \alpha = \frac{\dot{x}(0)}{v_0} = \frac{\text{nulegla}}{\text{hipot.}} \quad \dot{x}(0) = v_0 \cos \alpha$$

$$\dot{y}(0) = v_0 \sin \alpha$$



$$\sin \alpha = \frac{\dot{y}(0)}{v_0}$$

$$\frac{d\dot{y}(t)}{dt} = -g \quad d\dot{y}(t) = -g dt \quad \int \dot{y}(t) = -gt + C_1 \quad (C_1 = v_0 \sin \alpha)$$

$$\boxed{\dot{y}(t) = -gt + v_0 \sin \alpha}$$

$$\frac{dy(t)}{dt} = -gt + v_0 \sin \alpha \quad dy(t) = (-gt + v_0 \sin \alpha) dt \quad \int y(t) = -\frac{1}{2}gt^2 + v_0 \sin \alpha t + C_2 \quad (C_2 = 0)$$

$$\boxed{y(t) = -\frac{1}{2}gt^2 + v_0 \sin \alpha t} \quad y(t_1) = 2D$$

$$\frac{d\dot{x}(t)}{dt} = \ddot{x}(0) \quad d\dot{x}(t) = \ddot{x}(0) dt \quad \int \dot{x}(t) = \ddot{x}(0)t + C_1 \quad (C_1 = v_0 \cos \alpha)$$

$$\boxed{\dot{x}(t) = \ddot{x}(0)t + v_0 \cos \alpha}$$

$$\frac{dx}{dt} = \ddot{x}(0)t + v_0 \cos \alpha \quad dx = dt(\ddot{x}(0)t + v_0 \cos \alpha) \quad \int$$

$$x = \frac{1}{2}\ddot{x}(0)t^2 + v_0 \cos \alpha t + C_2 \quad (C_2 = 0)$$

$$x(t) = \frac{1}{2}\ddot{x}(0)t^2 + v_0 \cos \alpha t$$

$$\boxed{x(t) = v_0 \cos \alpha t} \quad x(t_1) = 6D$$

$$x(t_1) = v_0 \cos \alpha t_1 \quad \boxed{t_1 = \frac{6D}{v_0 \cos \alpha}}$$

$$y(t_1) = -\frac{1}{2}gt_1^2 + v_0 \sin \alpha t_1 = -\frac{1}{2}g \frac{36D^2}{v_0^2 \cos^2 \alpha} + v_0 \cdot \frac{6D}{v_0 \cos \alpha} \sin \alpha = -\frac{18D^2g}{v_0^2 \cos^2 \alpha} + 6D \tan \alpha \quad | \cdot v_0^2$$

$$v_0^2 y(t_1) = -\frac{18D^2g}{\cos^2 \alpha} + v_0^2 6D \tan \alpha$$

$$\frac{18D^2g}{\cos^2 \alpha} = v_0^2 (6D \tan \alpha - y(t_1)) \quad v_0^2 = \frac{18D^2g}{(\cos^2 \alpha) (6D \tan \alpha - y(t_1))}$$

$$v_0^2 = \frac{18D^2g}{\frac{2}{4}(6D - 2D)} = \frac{18D^2g}{\frac{8D}{4}} = \frac{4 \cdot 18D^2g}{8D} = 9gD \quad \boxed{v_0 = \sqrt{9gD} = 3\sqrt{gD}}$$

$$v_s = \frac{\dot{s}}{\frac{2}{4}(6D-2D)} = \frac{\dot{s}D}{2D} = \frac{v_{\text{max}}}{2} = \frac{1}{2}v_{\text{max}} = \frac{1}{2} \sqrt{2gD} \quad \left| \quad v_s = \sqrt{gD} = \sqrt{2gD} \right|$$

3.74) $h, \dot{x}(0), \ddot{x}(t) = a, g$

$h = ?$

$\ddot{x}(t) = -a$

$$\frac{d\dot{x}}{dt} = -a \quad d\dot{x} = -a dt \quad \int \dot{x} = -at + C_1 \quad (C_1 = \dot{x}(0))$$

$$\boxed{\dot{x}(t) = -at + \dot{x}(0)}$$

$$\frac{dx}{dt} = -at + \dot{x}(0) \quad dx = dt(-at + \dot{x}(0)) \quad \int$$

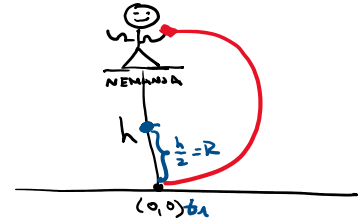
$$x = -\frac{1}{2}at^2 + \dot{x}(0)t + C_2 \quad (C_2 = 0)$$

$$\boxed{x(t) = -\frac{1}{2}at^2 + \dot{x}(0)t}$$

$\ddot{y}(t) = -g$

$$\frac{dy}{dt} = -g \quad dy = -g dt \quad \int \quad y = -gt + C_3 \quad (C_3 = 0)$$

$$\boxed{y(t) = -gt}$$



$$\frac{dy}{dt} = -gt \quad dy = -gt dt \quad \int$$

$$y = -\frac{1}{2}gt^2 + C_4 \quad (C_4 = h)$$

$$\boxed{y(t) = -\frac{1}{2}gt^2 + h}$$

$$0 = -\frac{1}{2}at_1^2 + \dot{x}(0)t_1 \quad | \quad y(t_1) = -\frac{1}{2}gt_1^2 + h \quad y(t_1) = 0$$

$$x(t_1) = 0$$

$$\frac{1}{2}at_1^2 = \dot{x}(0)t_1 \quad | \quad \cdot 2$$

$$\boxed{h = \frac{1}{2}gt_1^2}$$

$at_1 = 2\dot{x}(0)$

$$\boxed{t_1 = \frac{2\dot{x}(0)}{a}}$$

$$\frac{2\dot{x}(0)}{a} = \sqrt{\frac{2h}{g}} \quad | \quad \cdot \frac{a}{2}$$

$$\frac{\dot{x}(0)}{a} = \sqrt{\frac{2h}{g}} \quad | \quad \cdot \frac{a}{2}$$

$$\boxed{h = \frac{2g\dot{x}(0)^2}{a^2}}$$

$t_1^2 g = 2h$

$t_1^2 = \frac{2h}{g}$

$$\boxed{t_1 = \sqrt{\frac{2h}{g}}}$$

3.79) $x(t) = R(\omega t - \sin(\omega t)) \quad R = \text{const}, \omega = \text{const.}$

$y(t) = R(1 - \cos(\omega t))$

a) skica trajektorije

h = maks. = ut. \dot{x} i \dot{y} i

b) $x(t) = R(\omega t - \sin(\omega t))$

$\dot{x}(t) = R\omega - R\omega \cos(\omega t)$

$\dot{y}(t) = R\omega - R\omega \cos(\omega t)$

$(R\sin(\omega t))' = \cos(\omega t) \omega R$

a) skica trajektorije

b) projekcije u t $\dot{x}, \dot{y}, \ddot{x}, \ddot{y}$

c) $t_x = ?$ $\ddot{x} = 0 \wedge \ddot{y} = 0$ $(x, y) = ?$, $\dot{x} = ?$, $\dot{y} = ?$

d) da li $\sqrt{\ddot{x}^2 + \ddot{y}^2}$ zavisi od t

c) $\ddot{x}(t) = \ddot{y}(t) = 0$

$$R\omega(1 - \cos(\omega t)) = \sin(\omega t) R\omega$$

$$1 - \cos(\omega t) = \sin(\omega t)$$

$$\cos(\omega t) = 1$$

$$\omega t = 2\pi$$

$$t = \frac{2\pi}{\omega} \Rightarrow t_x = \left\{0, \frac{2\pi}{\omega}, \frac{4\pi}{\omega}, \frac{6\pi}{\omega}, \dots\right\}$$

$$y(t_x) = 0 \text{ (vek)} \quad x(t_x) = \{0, 2\pi R, 4\pi R, 6\pi R, \dots\}$$

$$\boxed{\ddot{x}(t_x) = 0} \quad \boxed{\ddot{y}(t_x) = \omega^2 R}$$

d) $a = \sqrt{0^2 + (\omega^2 R)^2} = \omega^2 R \Rightarrow \text{ne zavisi}$

3.81) $\dot{x}_z(t) = 220 \text{ km/h}$ brz/vaz
 $t_A = 0,5 \text{ h}$

a) $\dot{x}_v(t) = 20 \text{ km/h}$

$$\dot{y}_v(t) = 40 \text{ km/h}$$

$$v_v = \sqrt{20^2 + 40^2} = 44,72 \text{ km/h}$$



b) $v = \sqrt{220^2 + 40^2}$
 $v = 223,6 \text{ km/h}$

$$\cos \alpha = \frac{220}{223,6}$$

$$\alpha = \arccos\left(\frac{220}{223,6}\right) = 10,30^\circ$$

$$\boxed{\alpha = 10,30^\circ} \text{ (severozapad)}$$

