



Laplasova transformacija

Funkcija prenosa

LAPLASOVA TRANSFORMACIJA


- Prelazak iz vremenskog u frekventni (kompleksni) domen
- Ideja: pretvoriti diferencijalne jednačine u algebarske
- Osnovni izraz:

$$L\{f(t)\} = F(s) = \int_0^{\infty} f(t)e^{-st}dt$$

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$f(t)$ – funkcija u vremenskom domenu
 $F(s)$ – funkcija u kompleksnom domenu
 s – kompleksna promenljiva

$$s = \sigma \pm j\omega$$

PRIMER 2

- Odrediti rešenje diferencijalne jednačine $y(t)$, ako je $u(t) = \delta(t)$.

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 2. Rastaviti složeni izraz na sabirke (pronaći potrebne koeficijente)
 3. Nad svakim sabirkom primeniti inverznu Laplasovu transformaciju

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Primena LT

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REŠENJE:

$$y(t) = (e^{-2t} - e^{-3t}) * h(t)$$

PRIMER 3

- Odrediti inverznu Laplasovu transformaciju izraza:

$$F(s) = \frac{2}{(s+1)^2(s+2)}$$

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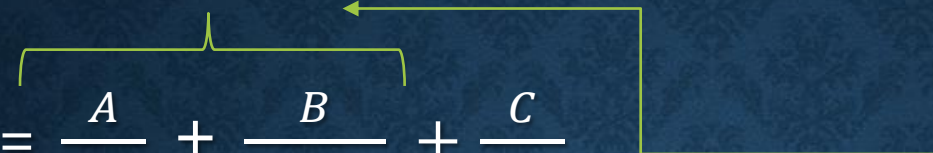
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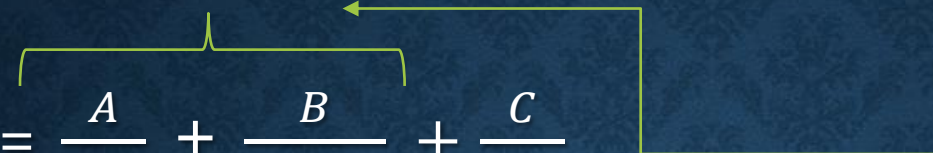
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Kao u prošlom zadatku, samo bez LT
(ovde već imamo izraz u kompleksnom domenu)

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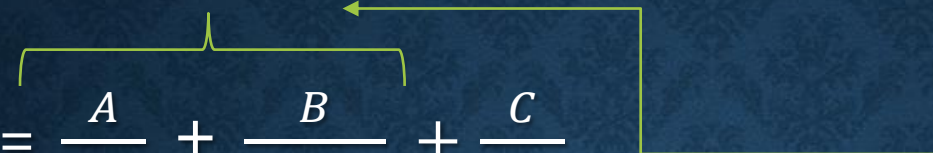
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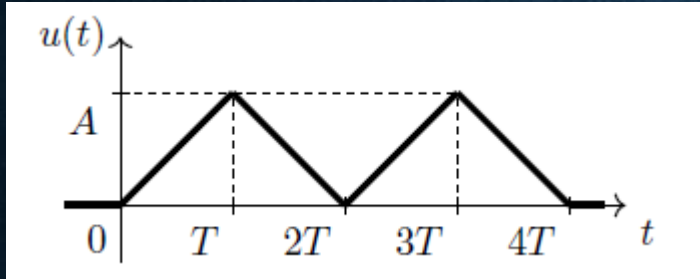
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t zbog $(s+1)^2$

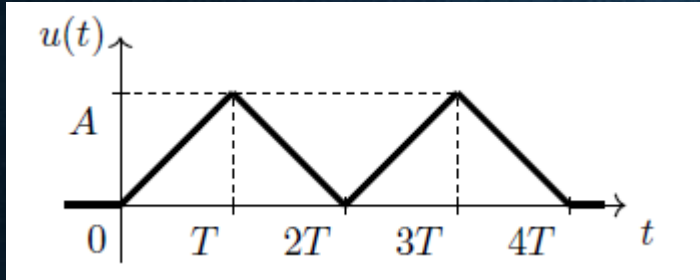
PRIMER 5

- Za signal sa slike odrediti $u(t)$ i $U(s)$.



PRIMER 5

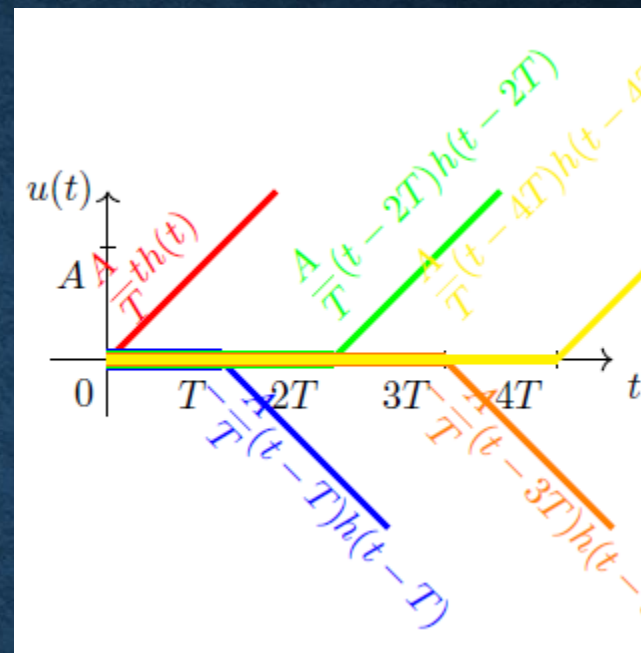
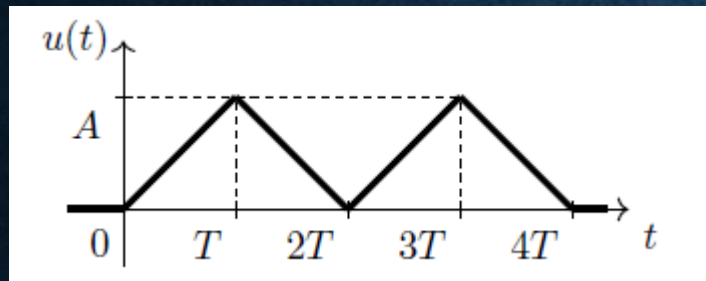
- Za signal sa slike odrediti $u(t)$ i $U(s)$.



- IDEJA: Posmatrati i „nadovezivati“ deo po deo signala

PRIMER 5

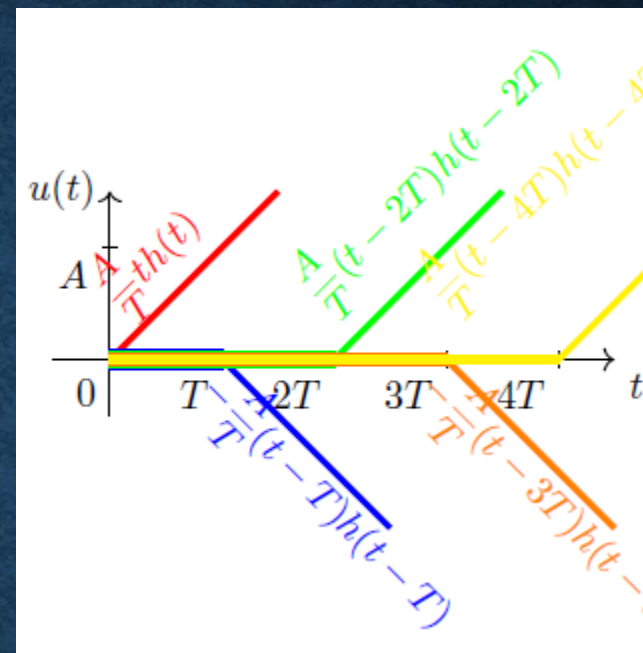
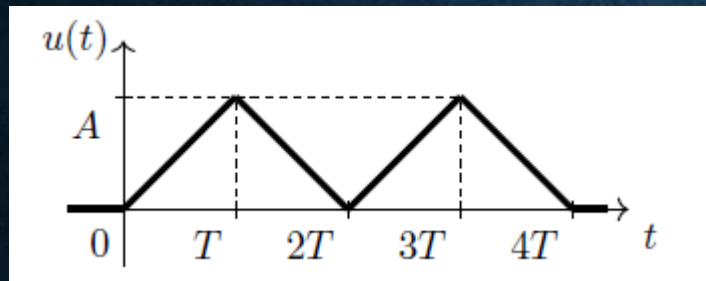
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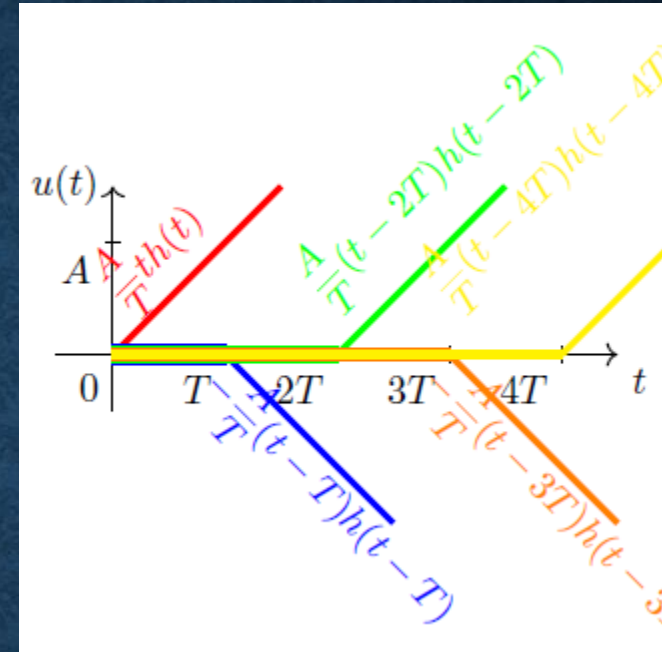
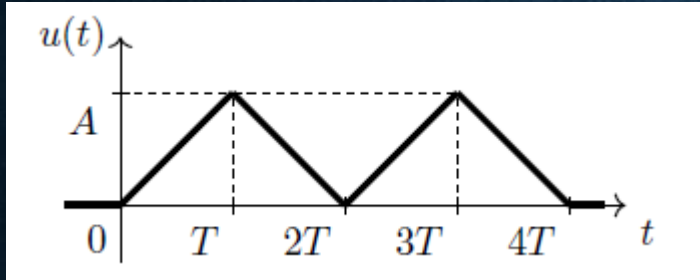
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- IDEJA: Posmatrati i „nadovezivati“ deo po deo signala
- $u(t) =$

PRIMER 5

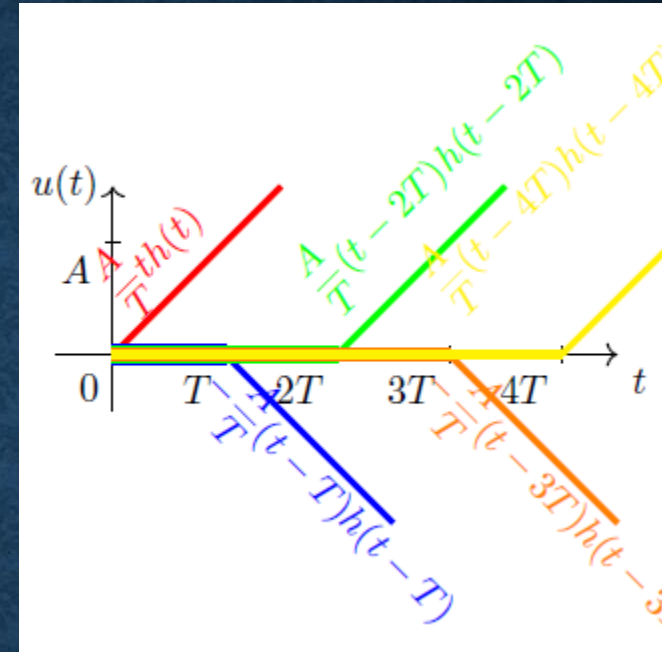
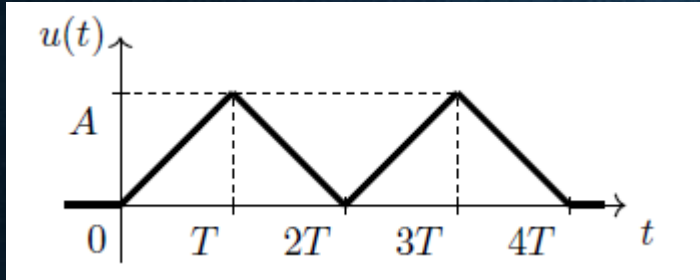
- Za signal sa slike odrediti $u(t)$ i $U(s)$.



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- $u(t) = \frac{A}{T} th(t)$

PRIMER 5

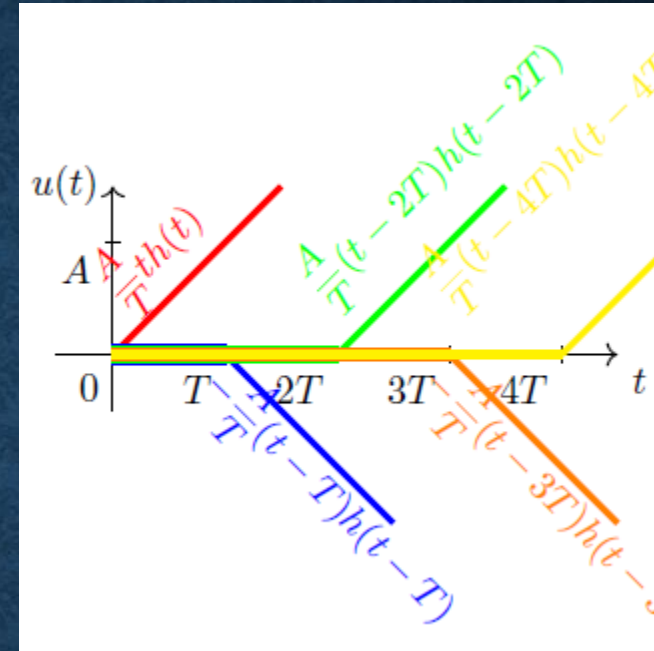
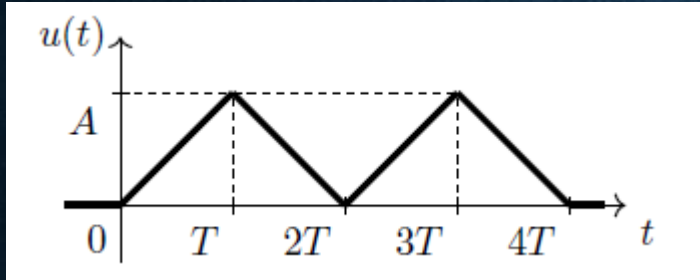
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- $u(t) = \frac{A}{T}th(t) - 2\frac{A}{T}(t-T)h(t-T) + \frac{A}{T}(t-2T)h(t-2T) - \frac{A}{T}(t-3T)h(t-3T) + \frac{A}{T}(t-4T)h(t-4T)$

PRIMER 5

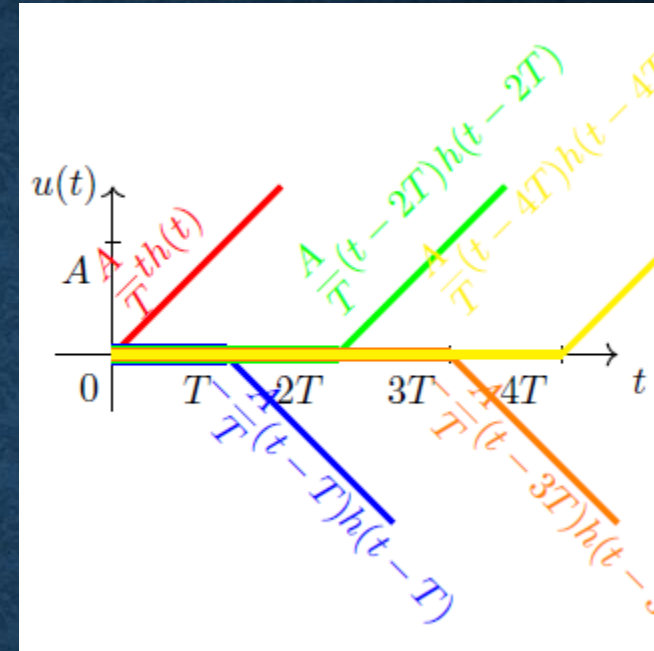
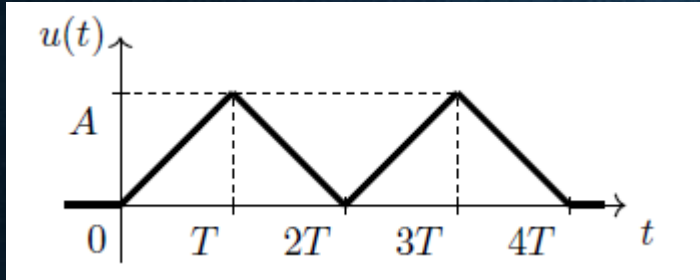
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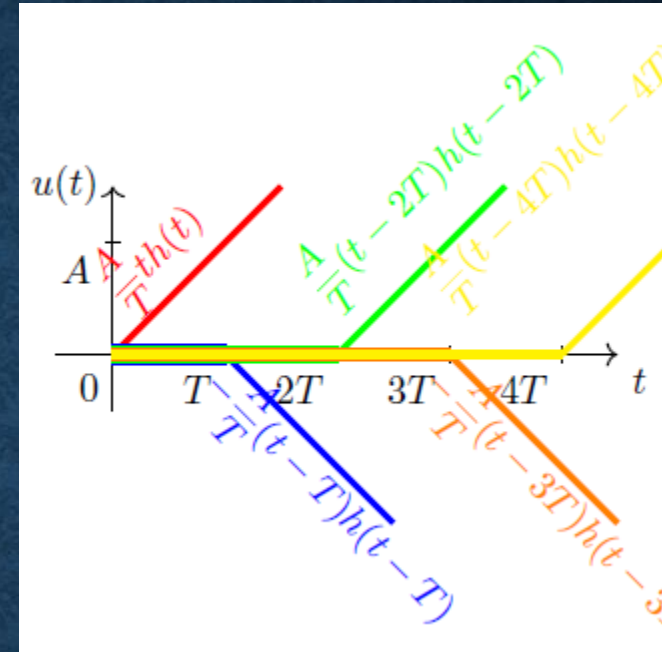
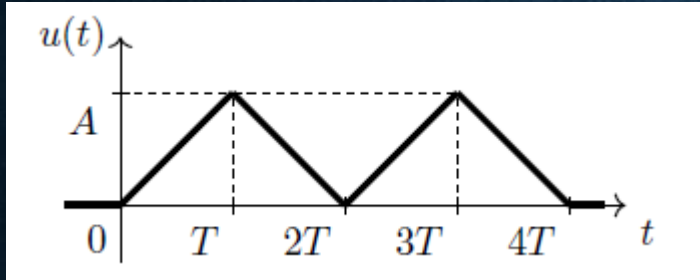
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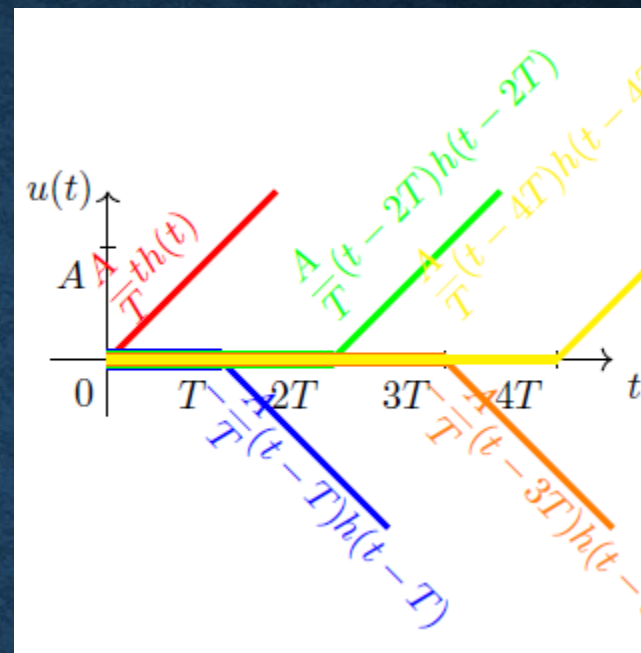
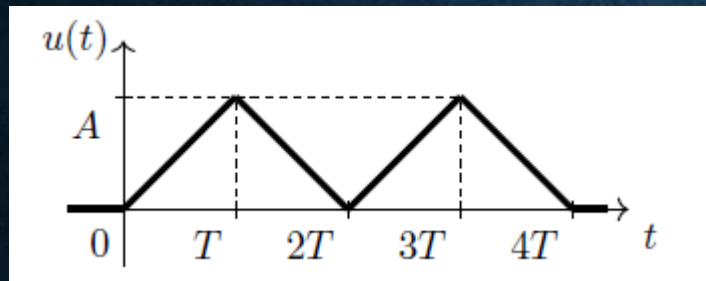
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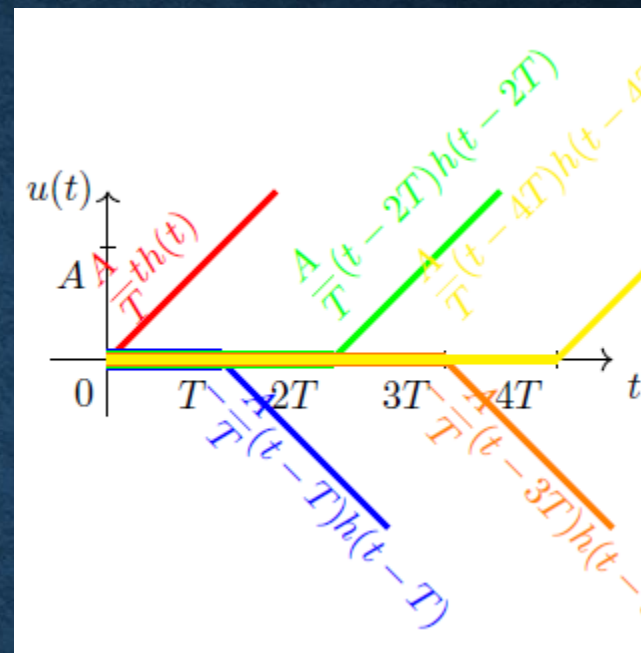
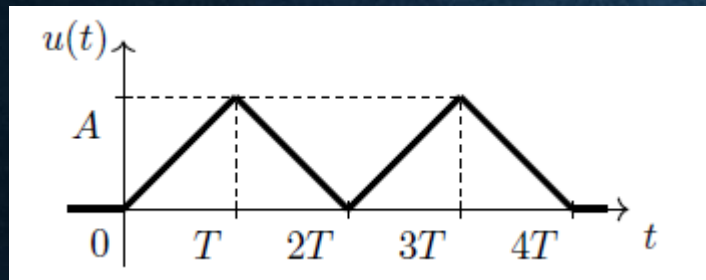
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- $$U(s) = \frac{A}{T} \frac{1}{s^2} (1 - 2e^{-sT} + 2e^{-s*2T} - 2e^{-s*3T} + e^{-s*4T})$$

PRIMER 5

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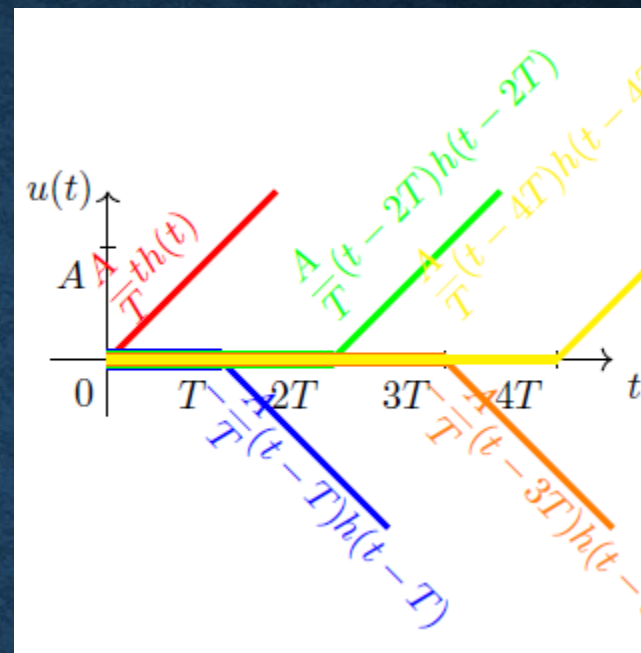
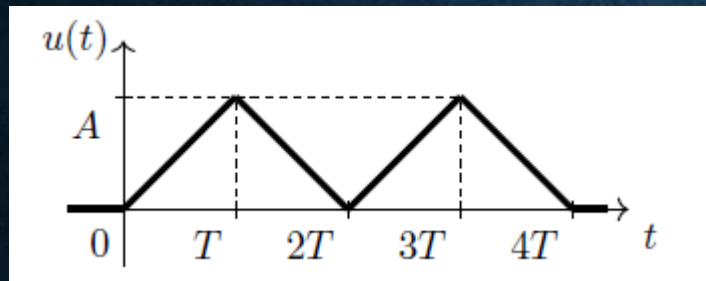


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- $$u(t) = \frac{A}{T} t h(t) - 2 \frac{A}{T} (t-T) h(t-T) + 2 \frac{A}{T} (t-2T) h(t-2T) - 2 \frac{A}{T} (t-3T) h(t-3T) + \frac{A}{T} (t-4T) h(t-4T)$$
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Veliko T!

FUNKCIJA PRENOSA

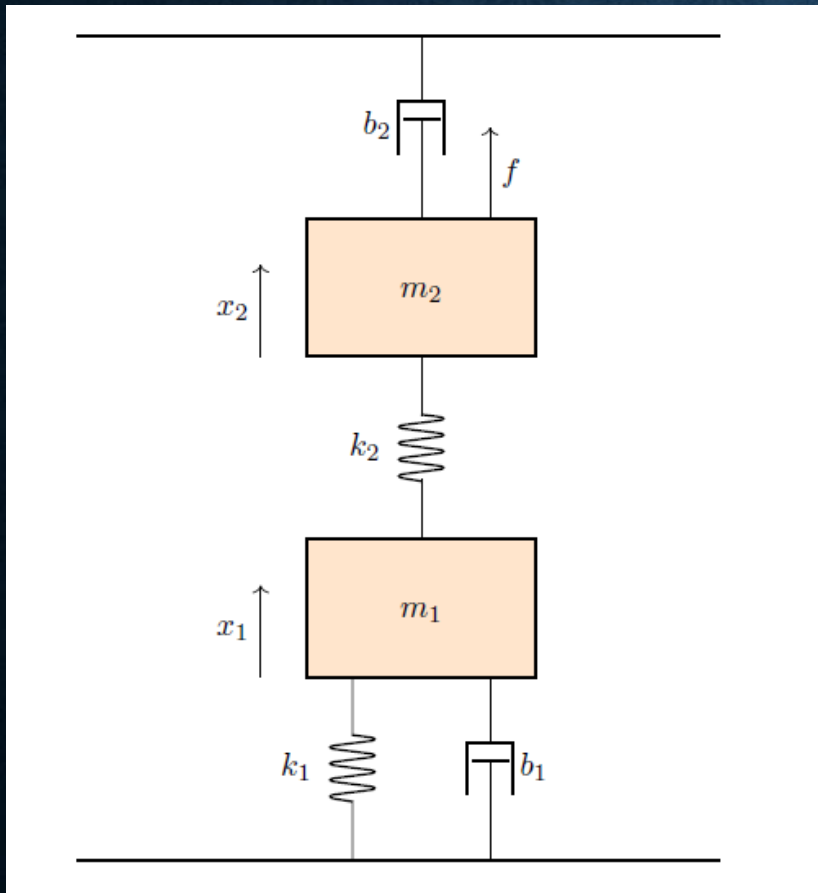
- Odnos kompleksnih likova izlaza i ulaza
- Osnovni izraz:

$$G(s) = \frac{Y(s)}{U(s)}$$

PRIMER 3

- Odrediti funkciju prenosa mehaničkog translatornog sistema sa slike ako je ulaz pobudna sila $f(t)$, a izlaz pozicija $x_2(t)$. Parametri modela su:

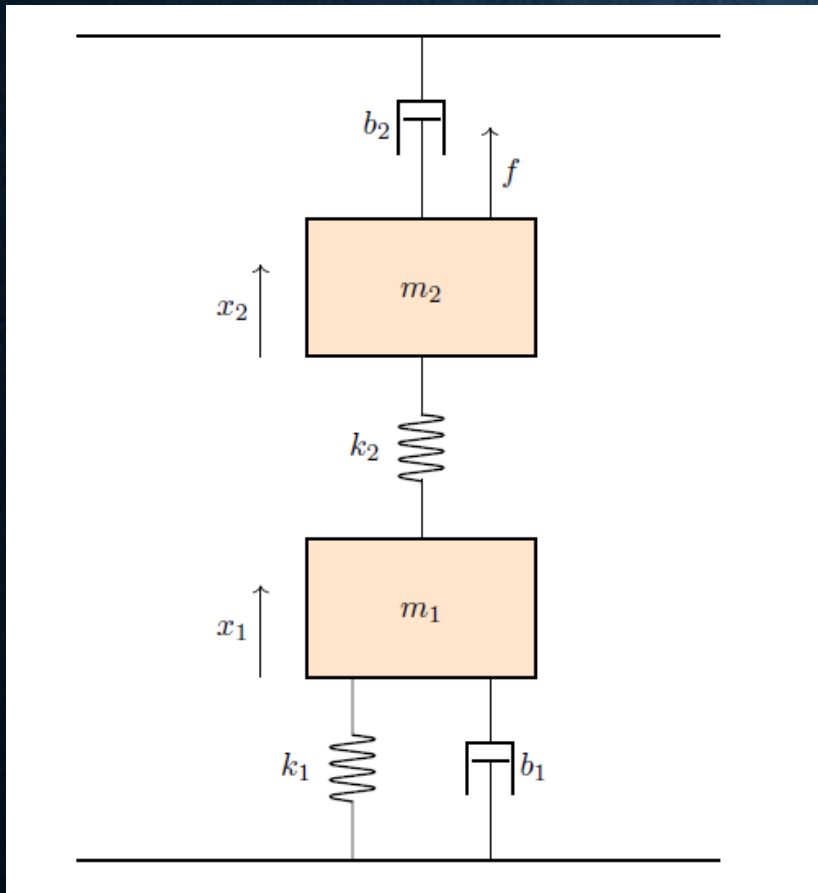
$m_1 = 1$, $m_2 = 1$, $b_1 = 10$, $b_2 = 8$, $k_1 = 9$, $k_2 = 16$. Zanemariti gravitaciju.



PRIMER 3

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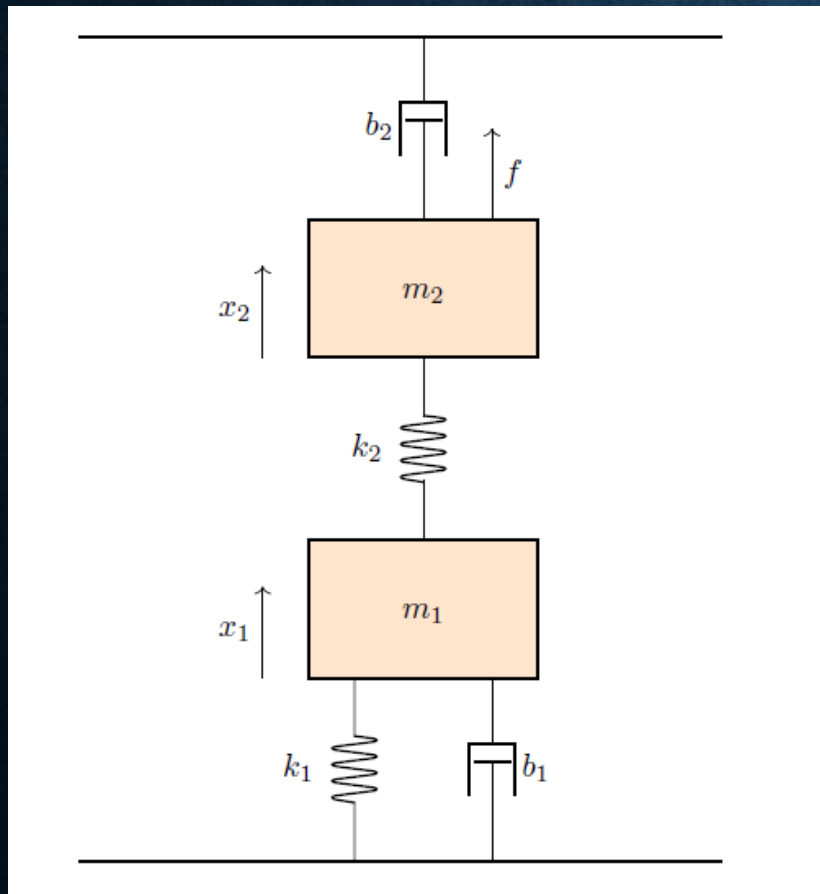


- IDEJA:

PRIMER 3

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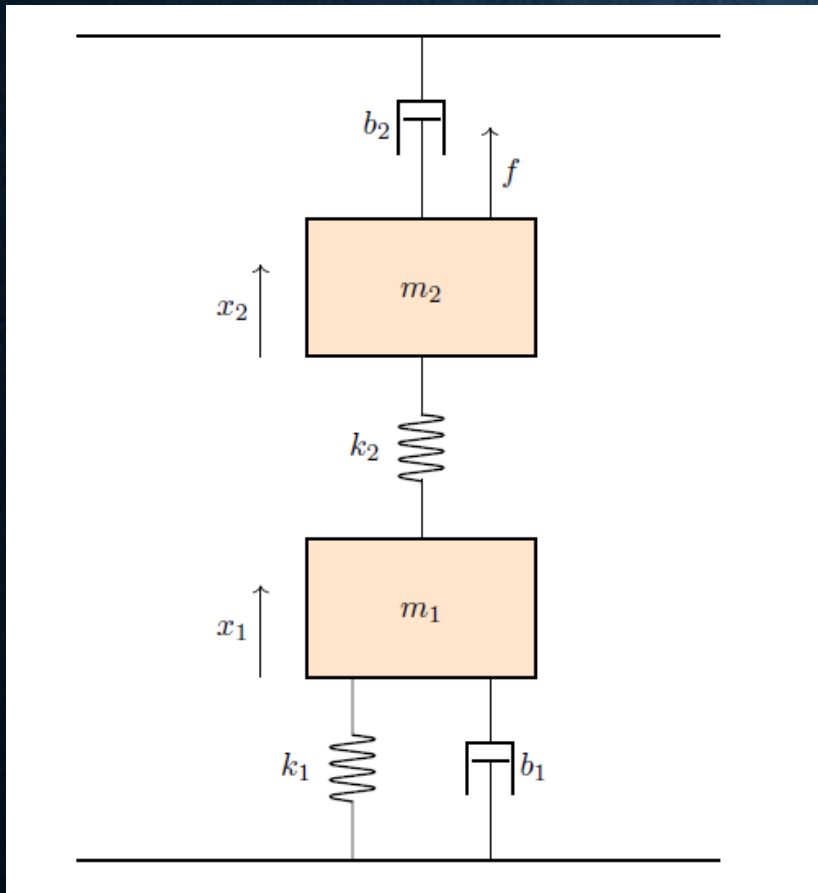
- IDEJA:

1. Formirati FBD i dif. jednačine

PRIMER 3

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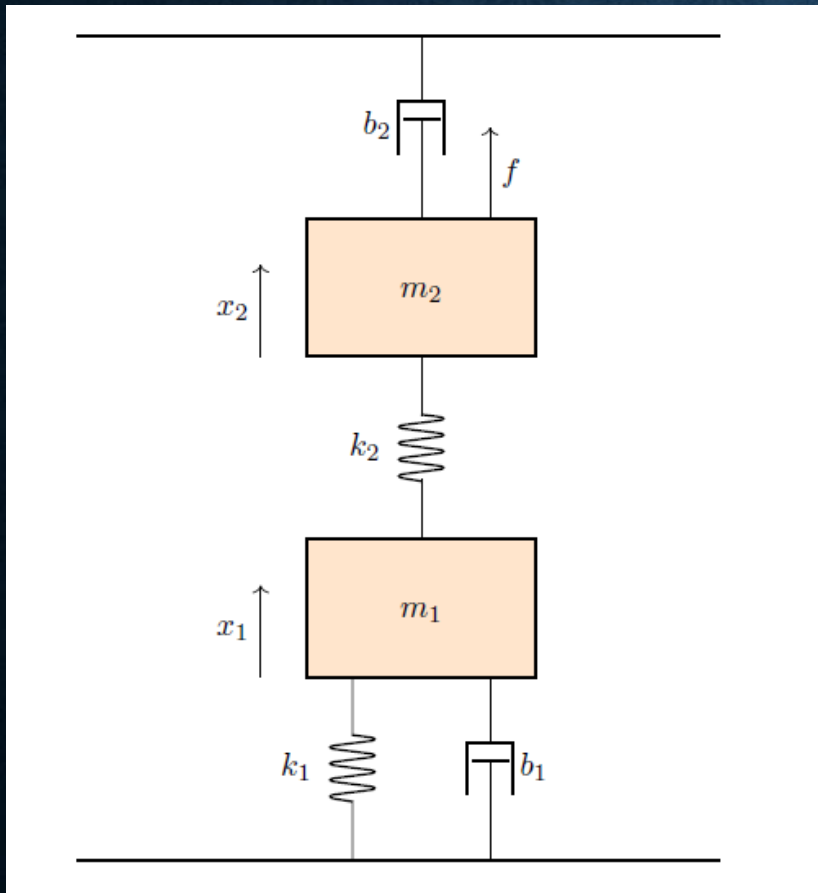
- IDEJA:

1. Formirati FBD i dif. jednačine
2. Primijeniti LT nad dobijenim jednačinama

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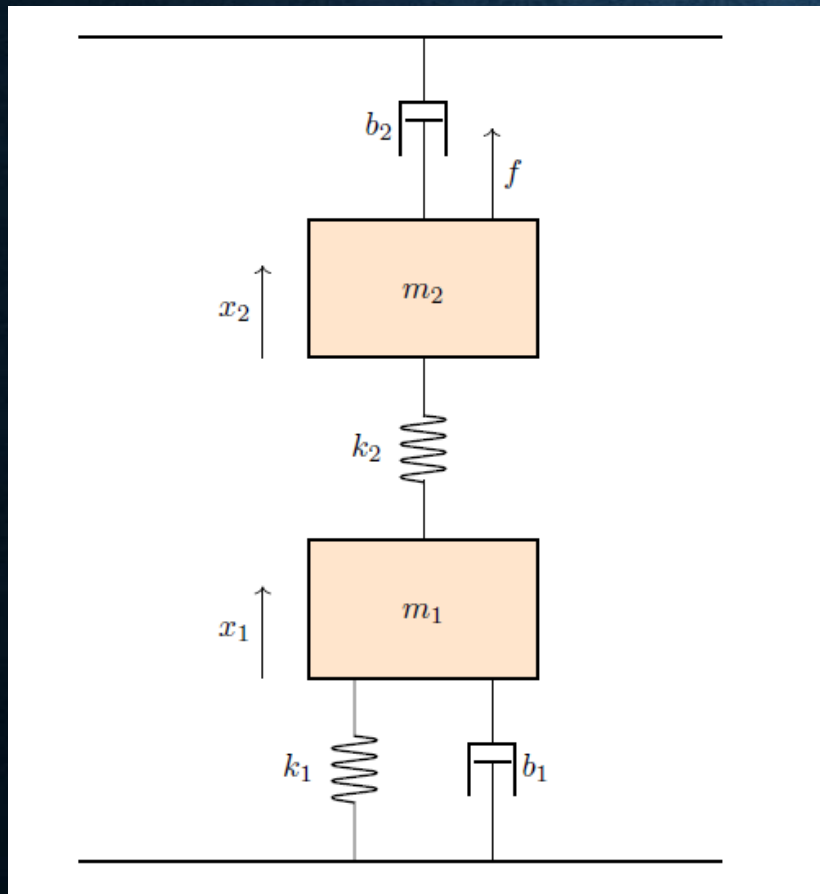
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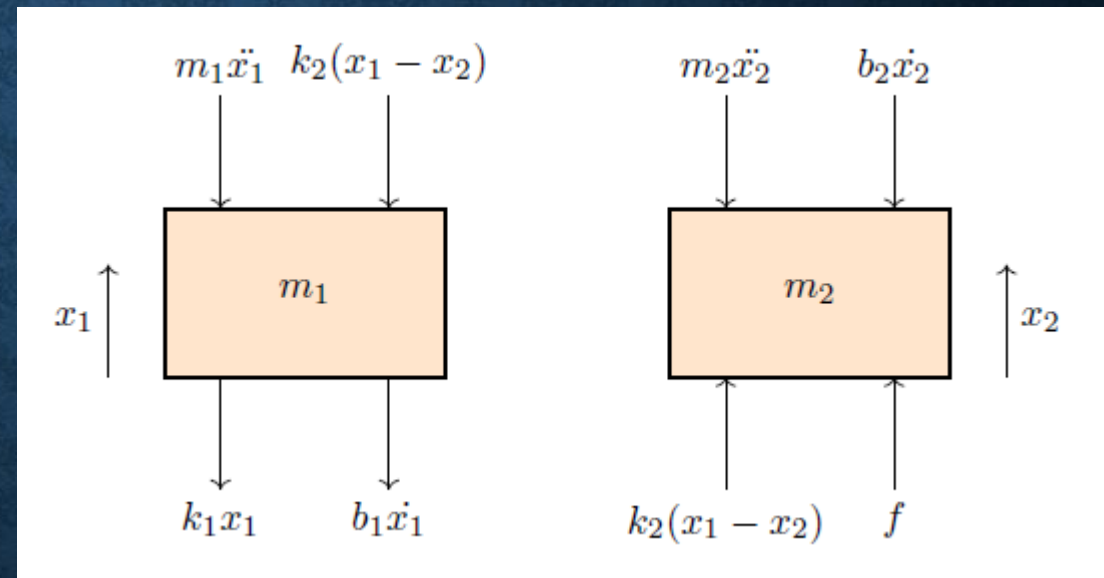
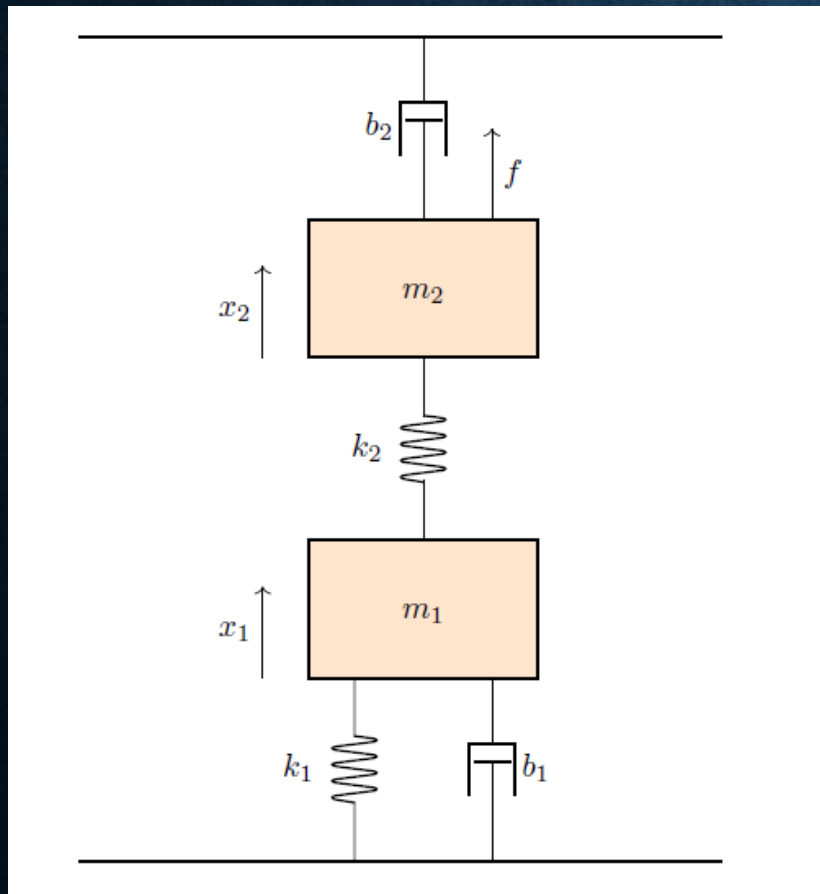
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4. Pronaći funkciju prenosa

PRIMER 3

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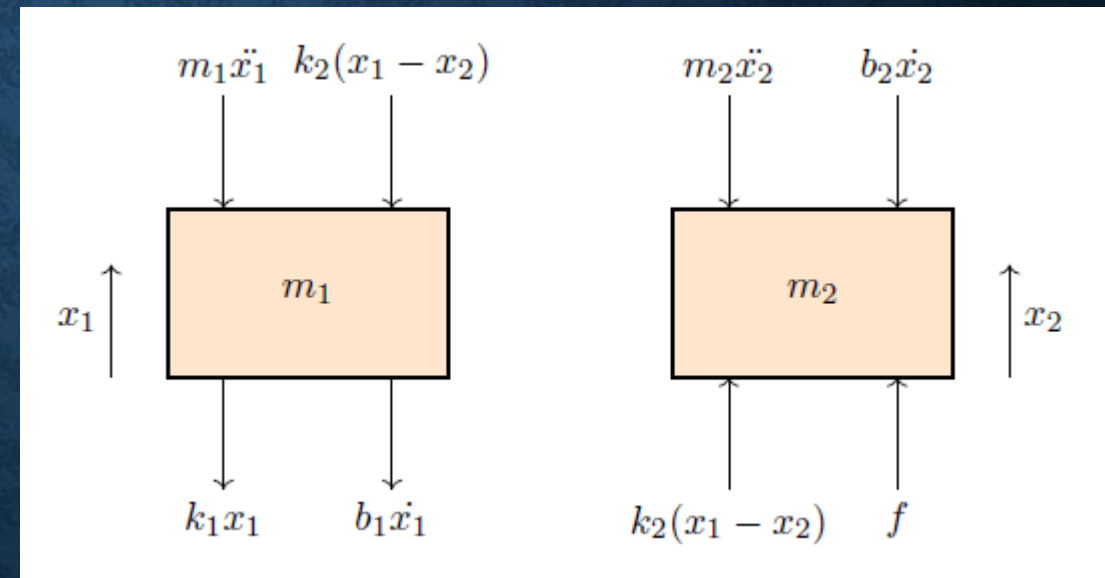
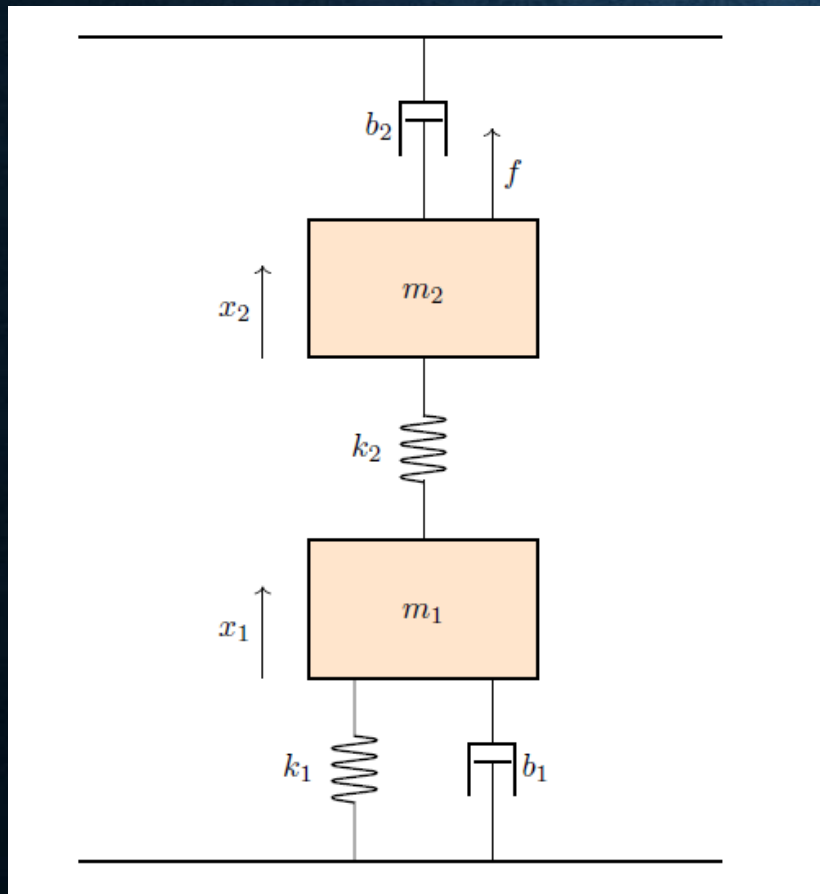
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PRIMER 3

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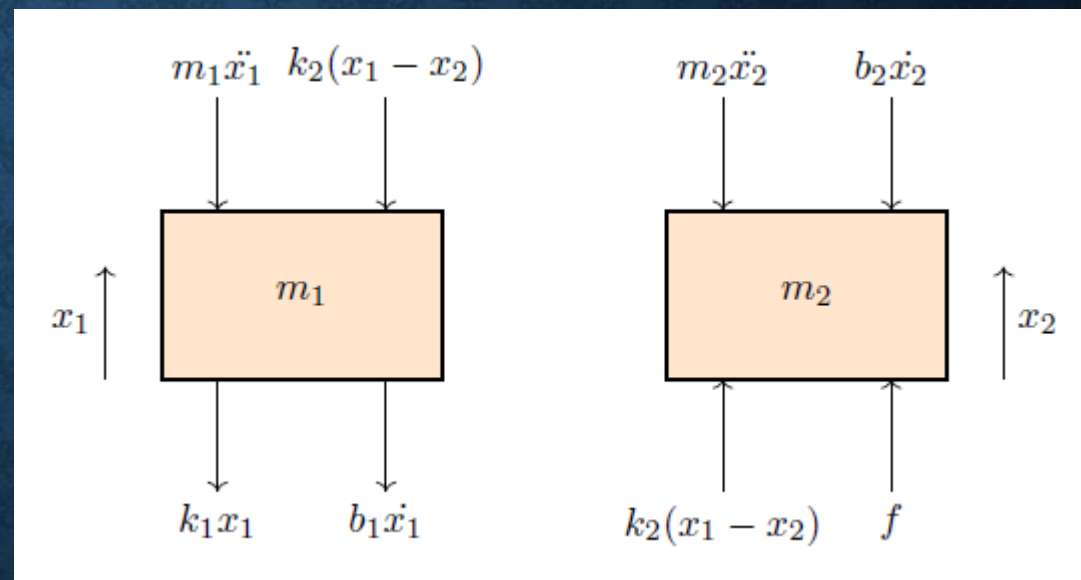
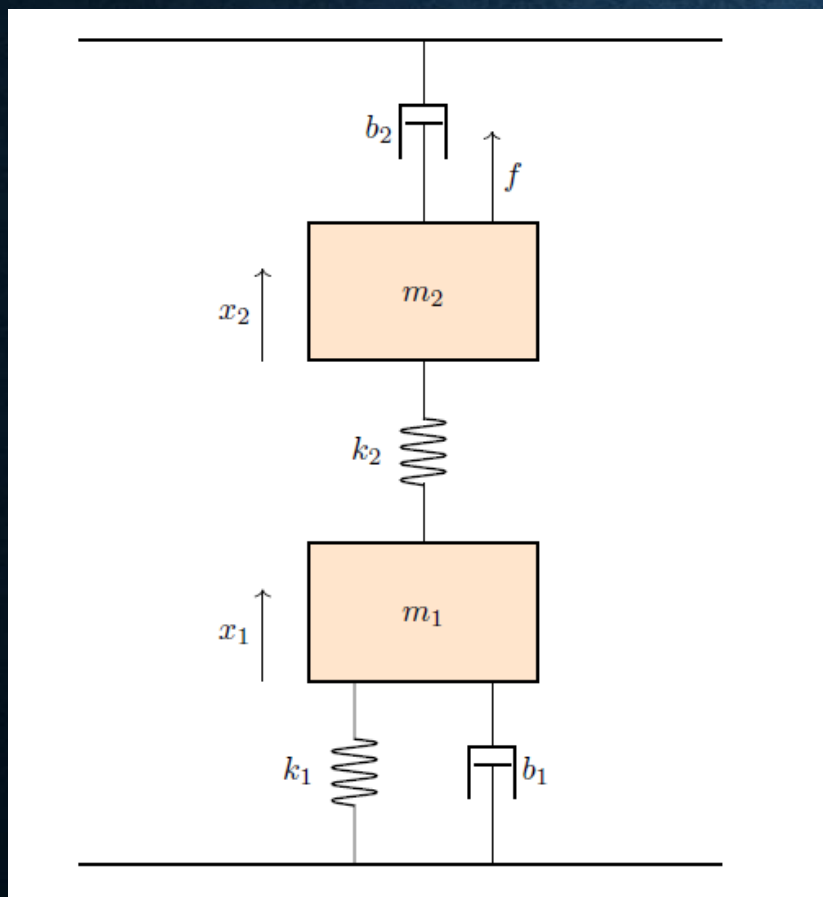
$$m_1 \ddot{x}_1 + b_1 \dot{x}_1 + k_1 x_1 + k_2 (x_1 - x_2) = 0$$

$$m_2 \ddot{x}_2 + b_2 \dot{x}_2 - k_2 (x_1 - x_2) = f(t)$$

PRIMER 3

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$$m_1 \ddot{x}_1 + b_1 \dot{x}_1 + k_1 x_1 + k_2 (x_1 - x_2) = 0$$

$$m_2 \ddot{x}_2 + b_2 \dot{x}_2 - k_2 (x_1 - x_2) = f(t)$$

/ \mathcal{L}

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

$$m_2 s^2 X_2(s) + b_2 s X_2(s) - k_2 X_1(s) + k_2 X_2(s) = F(s)$$

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Na osnovu prve jednačine, izrazimo X_1 u zavisnosti od X_2 (izlaza) i dobijeni izraz uvrstimo u drugu jednačinu

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$$(m_1 s^2 + b_1 s + k_1 + k_2) * X_1(s) = k_2 X_2(s)$$

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

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$$(m_1 s^2 + b_1 s + k_1 + k_2) * X_1(s) = k_2 X_2(s) \quad \Rightarrow \quad X_1(s) = \frac{k_2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s)$$

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

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$$m_2 s^2 X_2(s) + b_2 s X_2(s) - k_2 X_1(s) + k_2 X_2(s) = F(s)$$

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Uvrstimo zadate vrednosti

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$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - k_2 X_1(s) = F(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - \frac{k_2^2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s) = F(s)$$

Uvrstimo zadate vrednosti

$$(s^2 + 8s + 16 - \frac{256}{s^2 + 10s + 25}) * X_2(s) = F(s)$$

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

$$m_2 s^2 X_2(s) + b_2 s X_2(s) - k_2 X_1(s) + k_2 X_2(s) = F(s)$$

Na osnovu prve jednačine, izrazimo X_1 u zavisnosti od X_2 (izlaza) i dobijeni izraz uvrstimo u drugu jednačinu

$$(m_1 s^2 + b_1 s + k_1 + k_2) * X_1(s) = k_2 X_2(s) \quad \Rightarrow \quad X_1(s) = \frac{k_2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - k_2 X_1(s) = F(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - \frac{k_2^2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s) = F(s)$$

Uvrstimo zadate vrednosti

$$(s^2 + 8s + 16 - \frac{256}{s^2 + 10s + 25}) * X_2(s) = F(s)$$

$$\frac{s^4 + 18s^3 + 121s^2 + 360s + 144}{s^2 + 10s + 25} * X_2(s) = F(s)$$

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

$$m_2 s^2 X_2(s) + b_2 s X_2(s) - k_2 X_1(s) + k_2 X_2(s) = F(s)$$

Na osnovu prve jednačine, izrazimo X_1 u zavisnosti od X_2 (izlaza) i dobijeni izraz uvrstimo u drugu jednačinu

$$(m_1 s^2 + b_1 s + k_1 + k_2) * X_1(s) = k_2 X_2(s) \Rightarrow X_1(s) = \frac{k_2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - k_2 X_1(s) = F(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - \frac{k_2^2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s) = F(s)$$

Uvrstimo zadate vrednosti

$$(s^2 + 8s + 16 - \frac{256}{s^2 + 10s + 25}) * X_2(s) = F(s)$$

$$\frac{s^4 + 18s^3 + 121s^2 + 360s + 144}{s^2 + 10s + 25} * X_2(s) = F(s) \Rightarrow G(s) = \frac{X_2(s)}{F(s)} = \frac{s^2 + 10s + 25}{s^4 + 18s^3 + 121s^2 + 360s + 144}$$

$$m_1 s^2 X_1(s) + b_1 s X_1(s) + k_1 X_1(s) + k_2 X_1(s) - k_2 X_2(s) = 0$$

$$m_2 s^2 X_2(s) + b_2 s X_2(s) - k_2 X_1(s) + k_2 X_2(s) = F(s)$$

Na osnovu prve jednačine, izrazimo X_1 u zavisnosti od X_2 (izlaza) i dobijeni izraz uvrstimo u drugu jednačinu

$$(m_1 s^2 + b_1 s + k_1 + k_2) * X_1(s) = k_2 X_2(s) \Rightarrow X_1(s) = \frac{k_2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - k_2 X_1(s) = F(s)$$

$$(m_2 s^2 + b_2 s + k_2) * X_2(s) - \frac{k_2^2}{m_1 s^2 + b_1 s + k_1 + k_2} X_2(s) = F(s)$$

Uvrstimo zadate vrednosti

$$(s^2 + 8s + 16 - \frac{256}{s^2 + 10s + 25}) * X_2(s) = F(s)$$

$$\frac{s^4 + 18s^3 + 121s^2 + 360s + 144}{s^2 + 10s + 25} * X_2(s) = F(s)$$

\Rightarrow

$$G(s) = \frac{X_2(s)}{F(s)} = \frac{s^2 + 10s + 25}{s^4 + 18s^3 + 121s^2 + 360s + 144}$$