

Design and Analysis of Algorithms

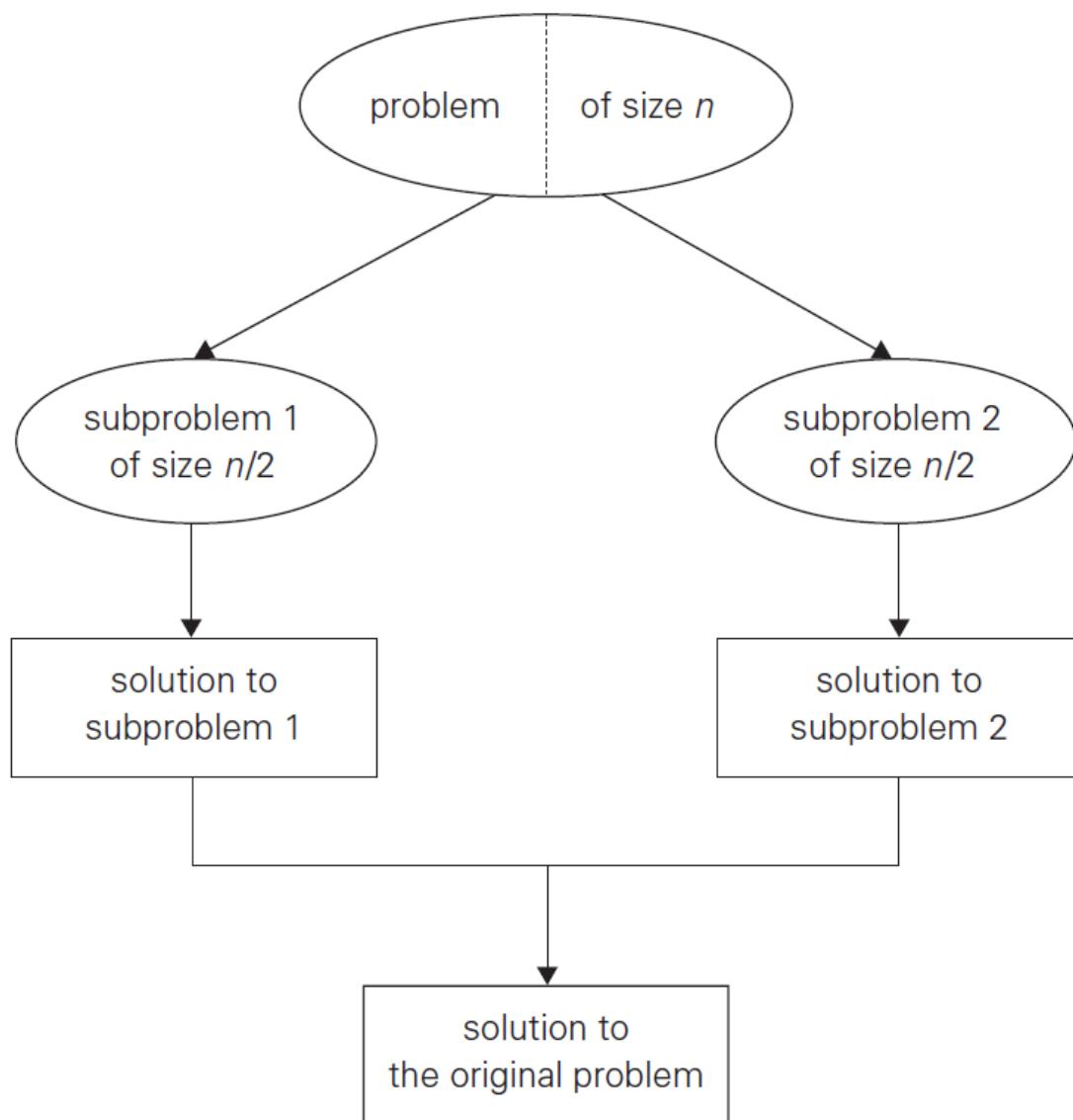
Algorithm Design Techniques

- **Brute Force and Exhaustive Search**
- **Divide-and-Conquer**
- **Decrease-and-Conquer**
- Transform-and-Conquer
- Space and Time Trade-Offs
- Dynamic Programming
- Greedy Technique
- Iterative Improvement
- Backtracking
- Branch-and-Bound

Divide-and-Conquer

- Divide-and-conquer algorithms work according to the following general plan:
 1. A problem is divided into several subproblems of the **same type**, ideally of about equal size.
 2. The **subproblems** are solved recursively.
 3. The **solutions** to the subproblems are **combined** to get a **solution** to the original problem.

Divide-and-Conquer



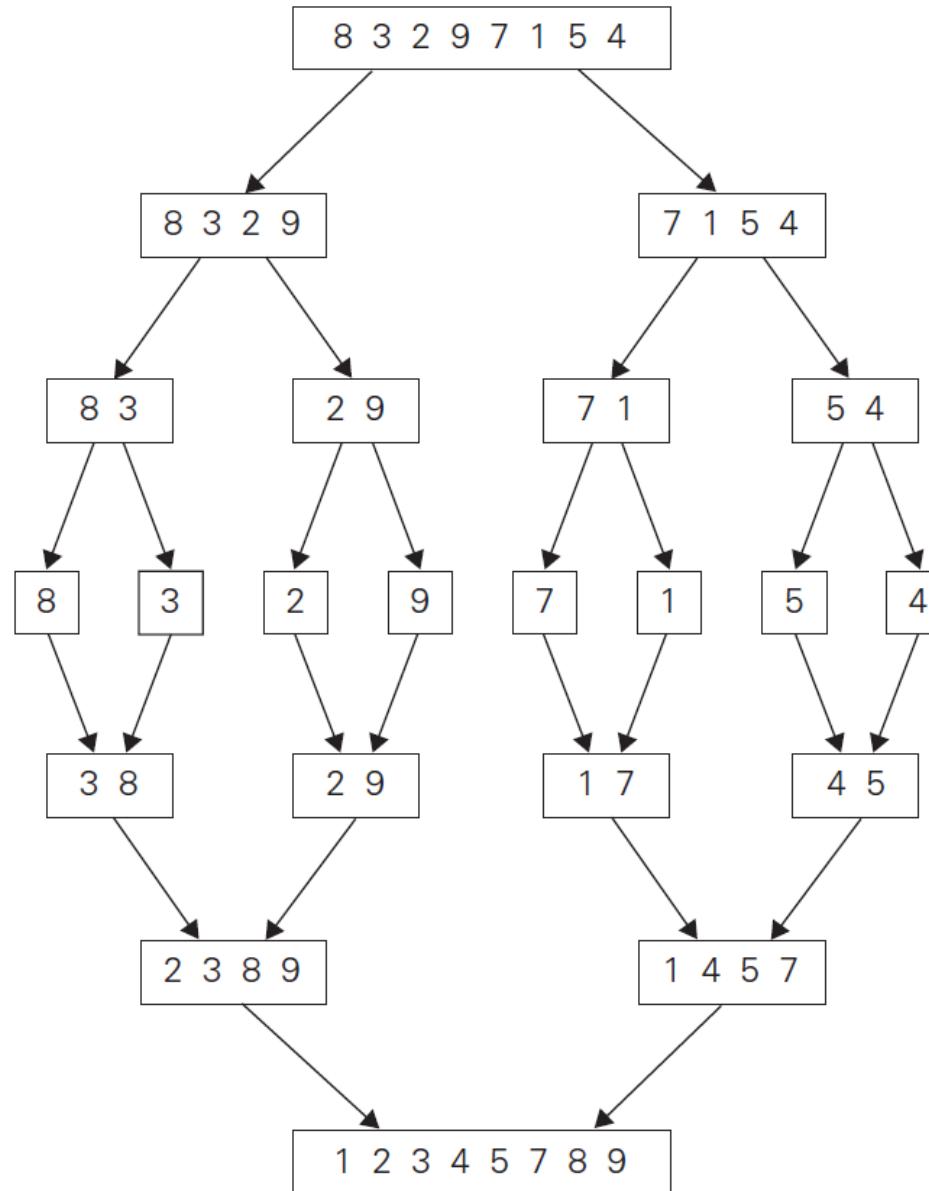
Divide-and-Conquer

- Divide-and-conquer is probably the **best-known general algorithm design technique**.
- Thus, not every divide-and-conquer algorithm is necessarily more efficient than even a brute-force solution.
- In fact, the divide-and-conquer approach yields some of the most important and efficient algorithms in **computer science**.
- The divide-and-conquer technique is ideally suited for **parallel computations**, in which each subproblem can be solved at the same time by its own processor.

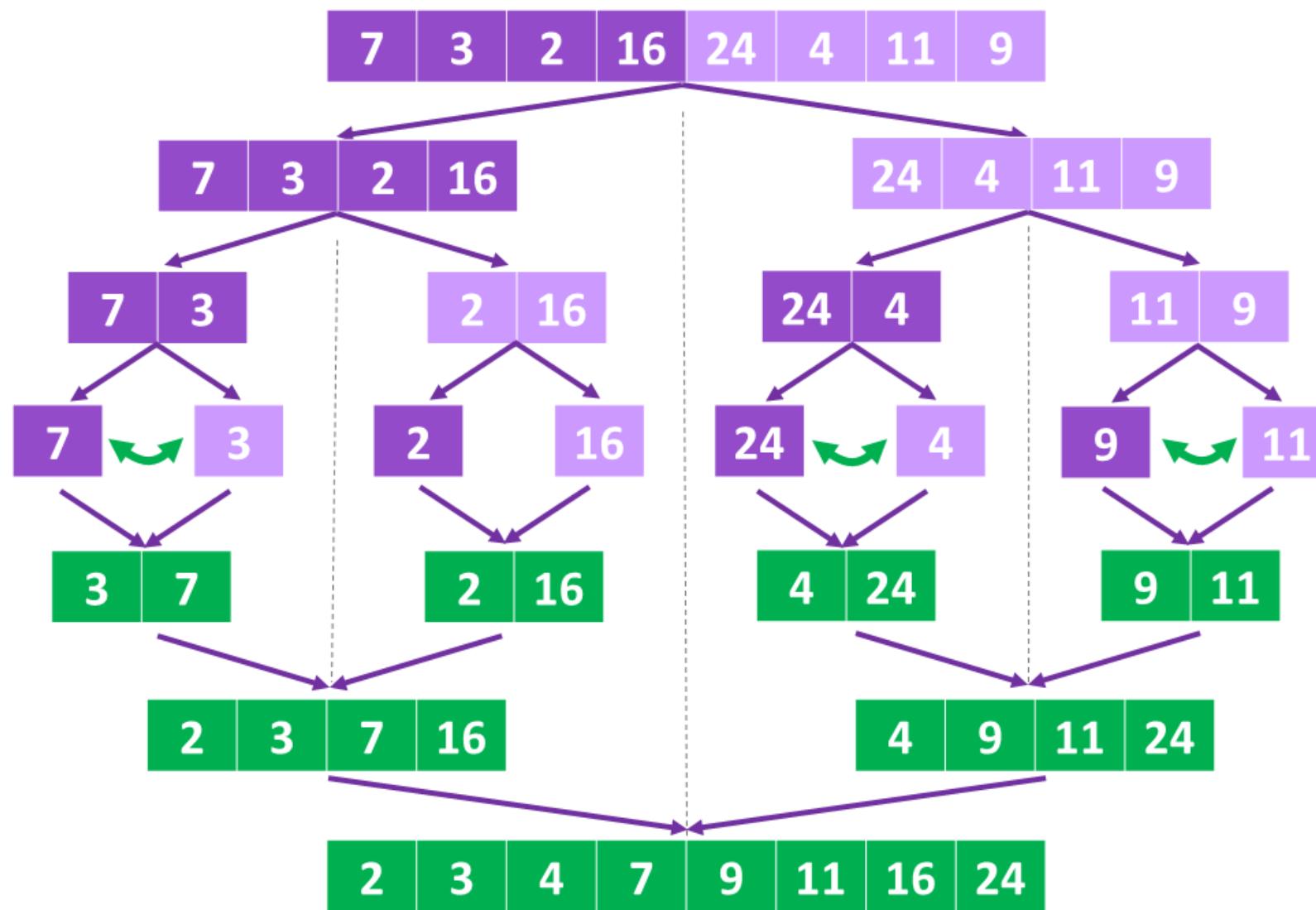
Mergesort

- Mergesort is a perfect example of a successful application of the **divide-and-conquer technique**.
- It sorts a given array $A[0 .. n - 1]$ by dividing it into two halves $A[0 .. n/2-1]$ and $A[n/2 .. n-1]$, sorting each of them recursively, and then **merging** the two smaller sorted arrays into a single sorted one.
- The **trick** is taking advantage of the two partial solutions to construct a solution of the full problem, as we did with the merge operation.

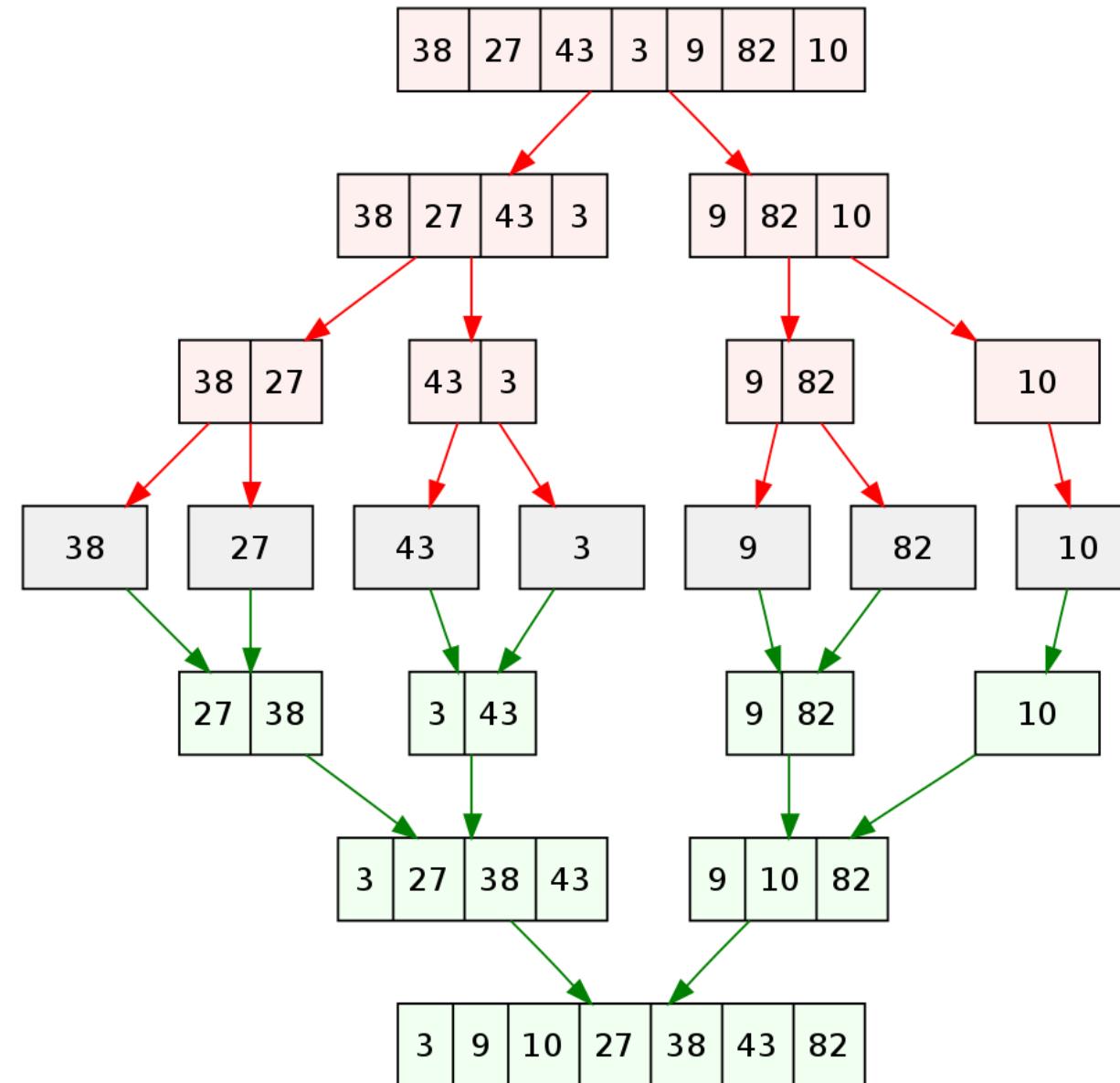
Mergesort: Example 1



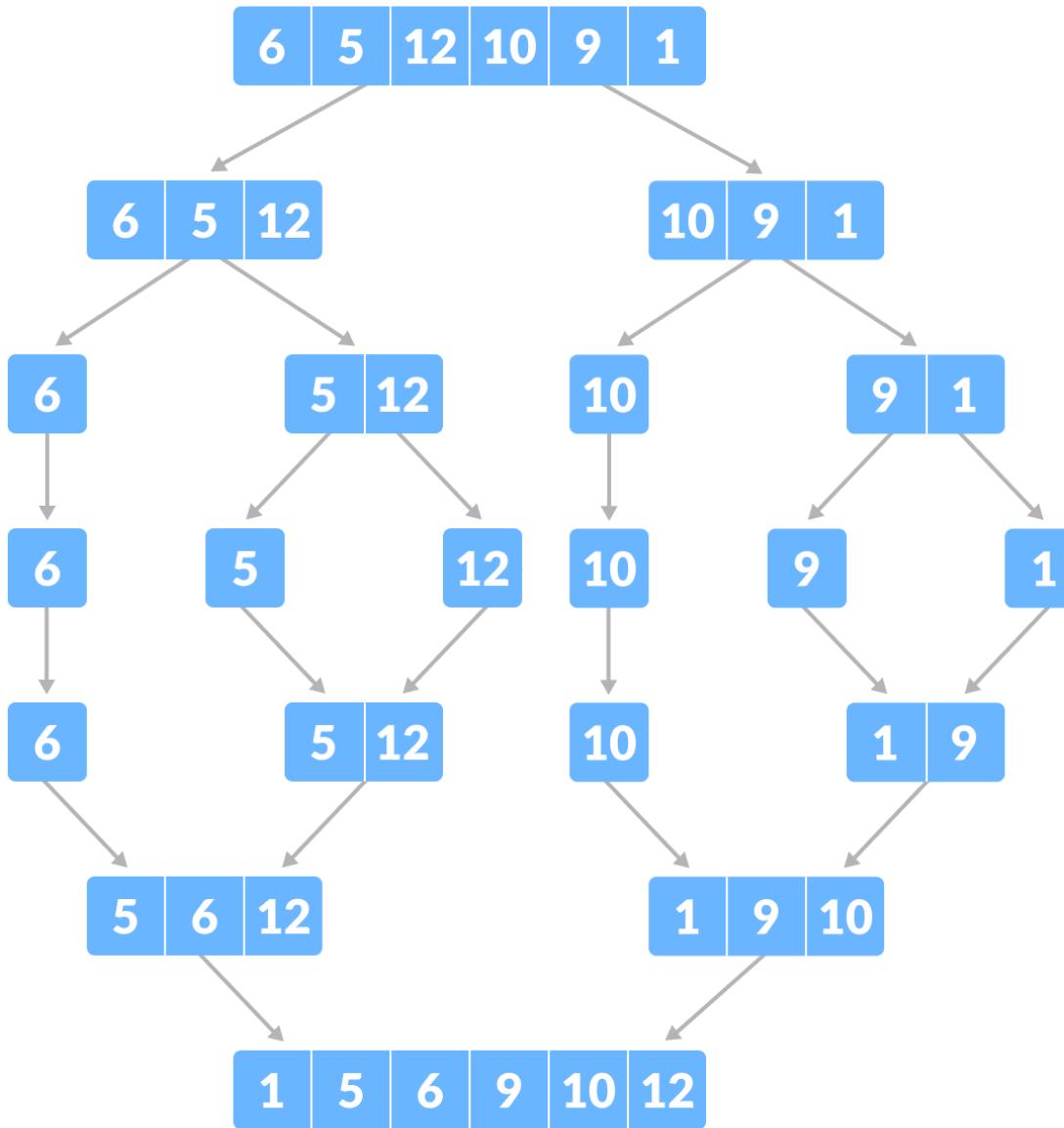
Mergesort: Example 2



Mergesort: Example 3



Mergesort: Example 4



Mergesort: Pseudocode

```
ALGORITHM Mergesort(A, low, high)
  //Sorts array A[low .. high] by recursive mergesort
  //Input: An array A[low .. high] of orderable elements
  //Output: Array A[low .. high] sorted in nondecreasing order
  if low < high
    mid = (low + high) / 2
    Mergesort(A, low, mid)
    Mergesort(A, mid + 1, high)
    Merge(A, low, mid, high)
```

Mergesort: Merge

i

2	3	8	9
---	---	---	---

j

1	4	5	7
---	---	---	---

k

--	--	--	--	--	--	--	--

Mergesort: Merge

i

2	3	8	9
---	---	---	---

j

1	4	5	7
---	---	---	---

k

1							
---	--	--	--	--	--	--	--

Mergesort: Merge

i

2	3	8	9
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1	4	5	7
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k

1							
---	--	--	--	--	--	--	--

Mergesort: Merge

i

2	3	8	9
---	---	---	---

j

1	4	5	7
---	---	---	---

k

1	2						
---	---	--	--	--	--	--	--

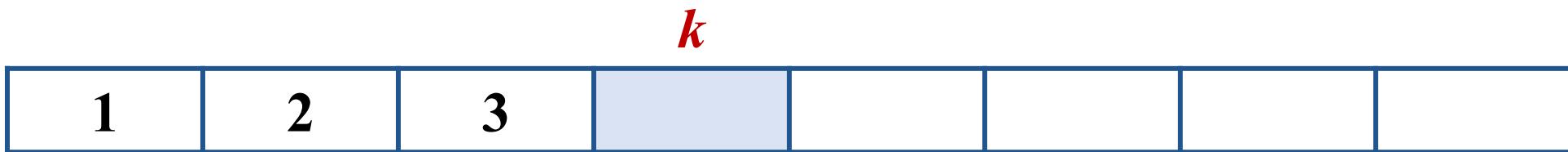
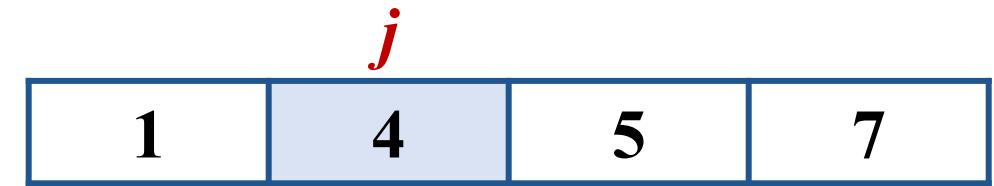
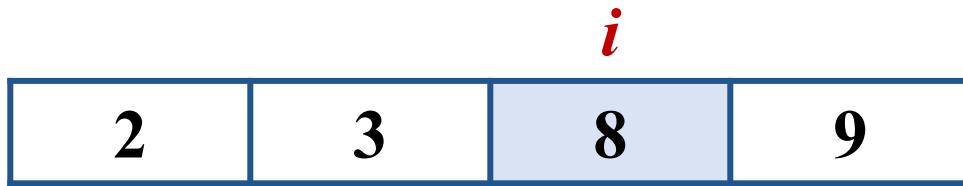
Mergesort: Merge

$$\begin{matrix} & i \\ \boxed{2} & | & \boxed{3} & | & 8 & | & 9 \end{matrix}$$
$$\begin{matrix} & j \\ \boxed{1} & | & \boxed{4} & | & 5 & | & 7 \end{matrix}$$
$$\begin{matrix} & k \\ \boxed{1} & | & \boxed{2} & | & \boxed{} & | & \boxed{} & | & \boxed{} & | & \boxed{} \end{matrix}$$

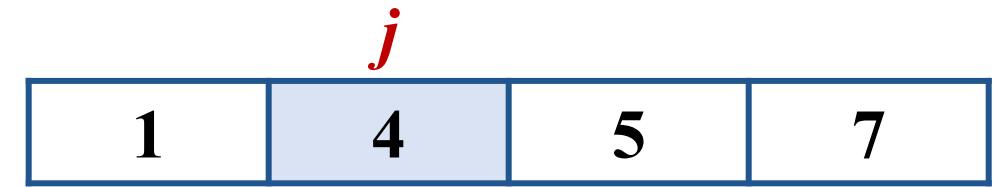
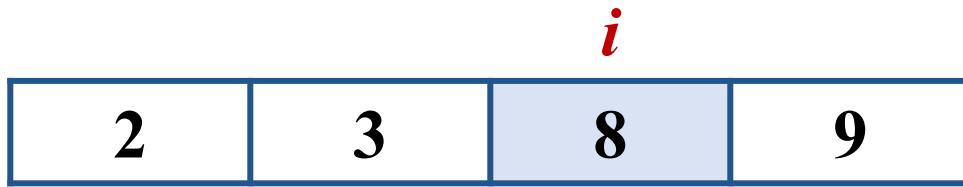
Mergesort: Merge

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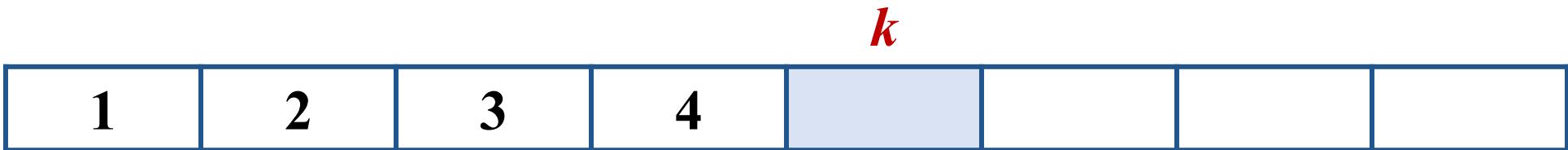
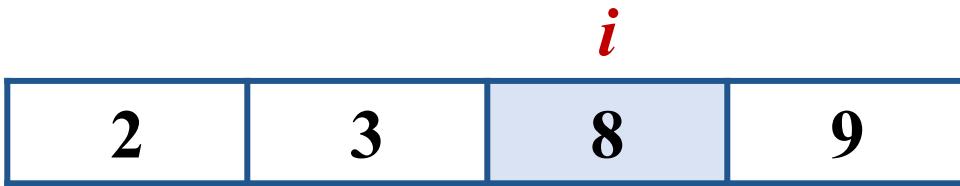
Mergesort: Merge



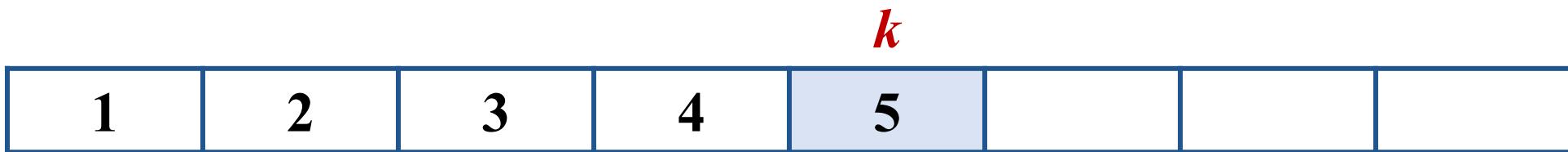
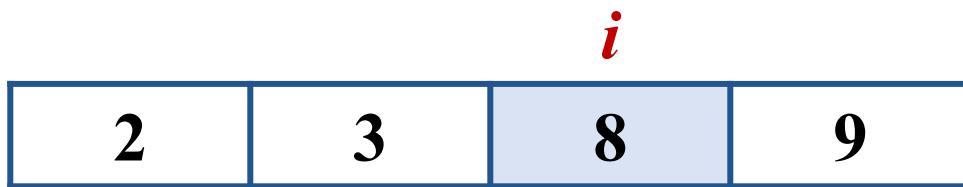
Mergesort: Merge



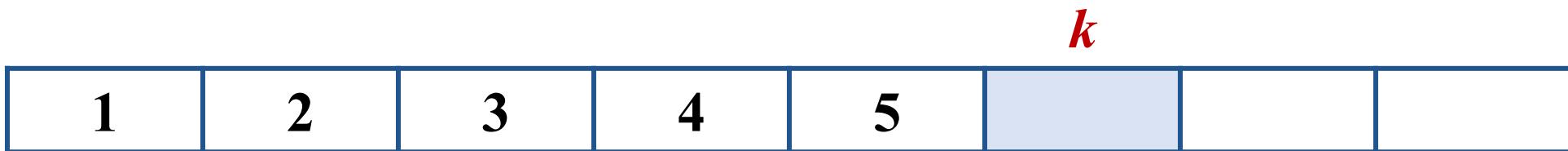
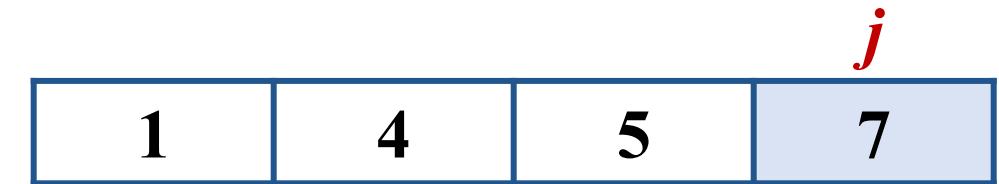
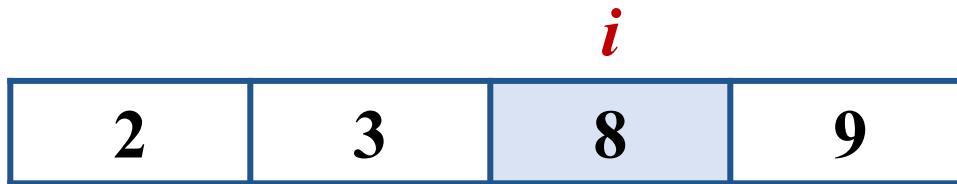
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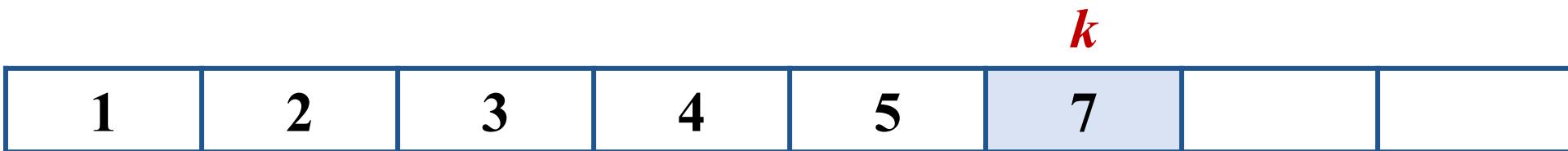
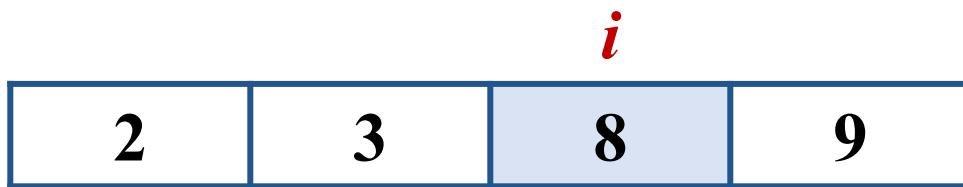
Mergesort: Merge



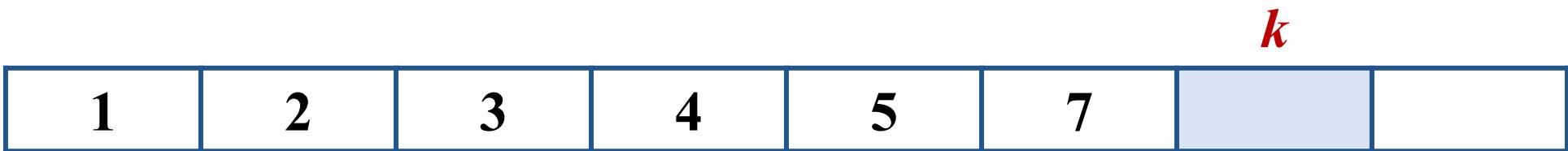
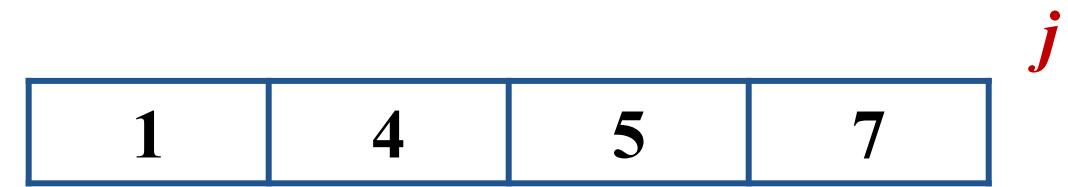
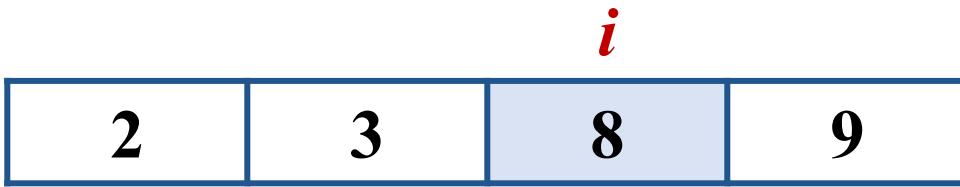
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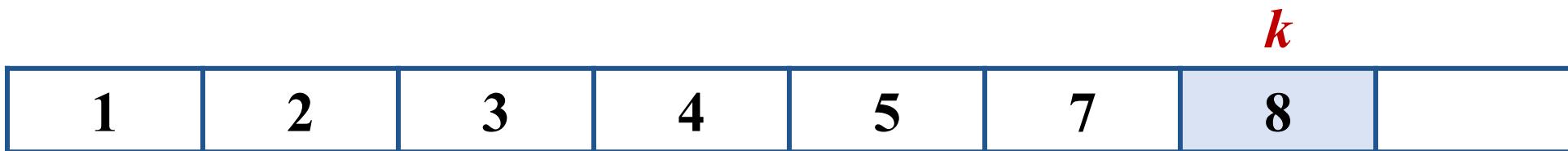
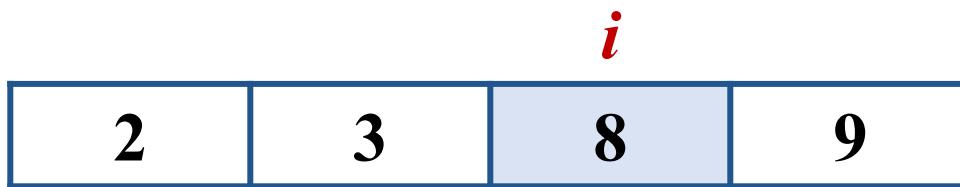
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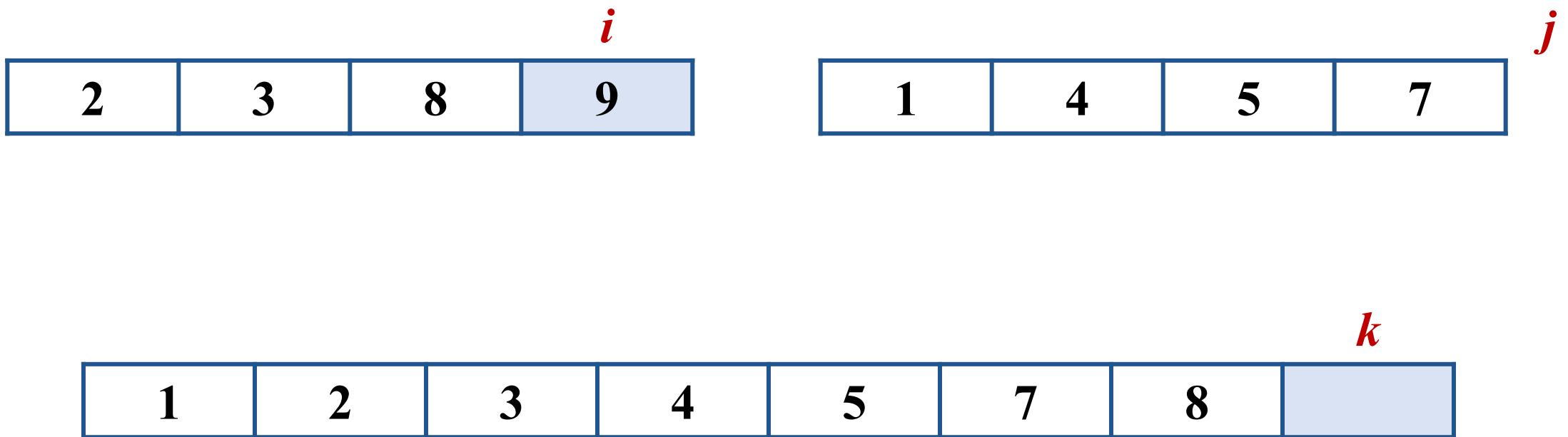
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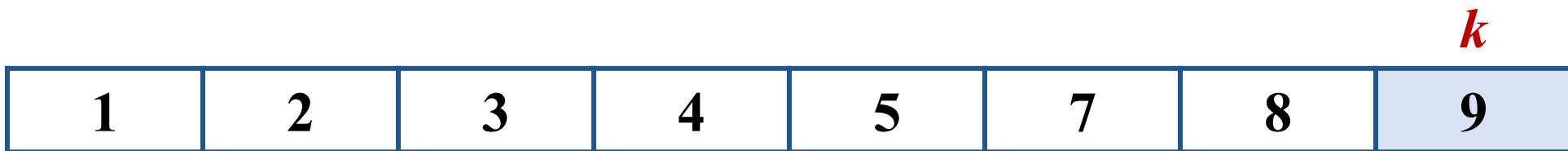
Mergesort: Merge



Mergesort: Merge



Mergesort: Merge



Analysis of Mergesort

- **Dividing** takes **constant time**, because it amounts to just computing the index mid .
- **Conquering** consists of the **two recursive calls** on subarrays, each with $n/2$ elements.

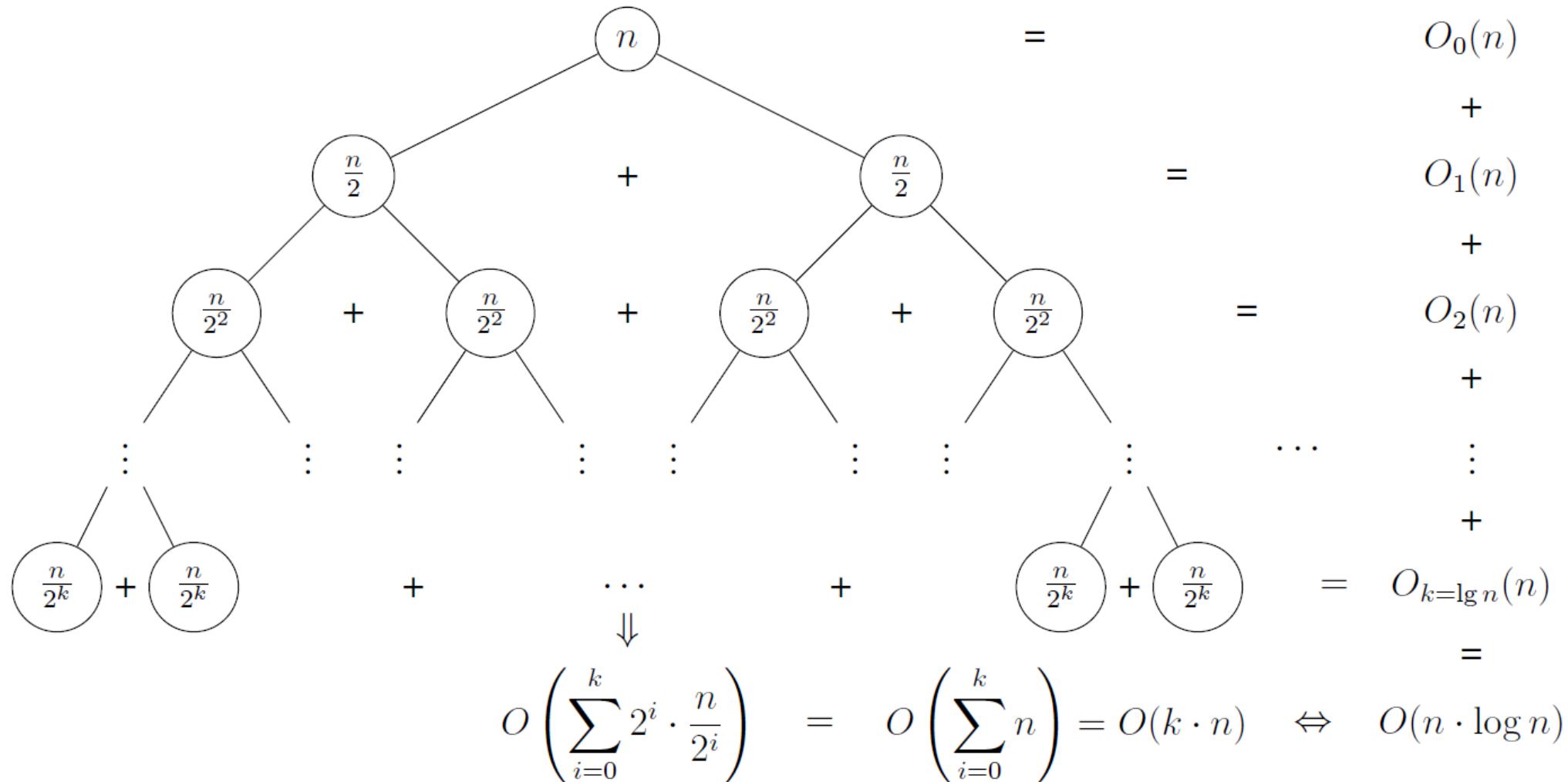
Each of the two recursive calls takes time $T(n/2)$.

- **Combining** the results of the two recursive calls by **merging** the sorted subarrays takes $O(n)$ time.
- The function $T(n)$ describes the **running time** of merge sort

$$T(n) = 2T(n / 2) + O(n)$$

Analysis of Mergesort: Recursion Tree

$$T(n) = 2T(n/2) + O(n)$$



Analysis of Mergesort

- The merge sort has a running time of only $O(n \log_2 n)$ in **all cases**.
- When we compare its running time with the $O(n^2)$ worst-case running times of **selection sort** and **insertion sort**, we are trading a factor of n for a factor of only $\log_2(n)$.
- Merge sort **does not work in place**.
- It has to make complete **copies** of the entire input array.

Analysis of Mergesort

Time Complexity	
Best	$O(n \log n)$
Worst	$O(n \log n)$
Average	$O(n \log n)$
Space Complexity	
	$O(n)$
Stability	
	Yes

Sorting Algorithms

Algorithm	Worst-case running time	Best-case running time	Worst-case swaps	In-place?
Selection sort	$\Theta(n^2)$	$\Theta(n^2)$	$\Theta(n)$	yes
Insertion sort	$\Theta(n^2)$	$\Theta(n)$	$\Theta(n^2)$	yes
Merge sort	$\Theta(n \lg n)$	$\Theta(n \lg n)$	$\Theta(n \lg n)$	no
Quicksort	$\Theta(n^2)$	$\Theta(n \lg n)$	$\Theta(n^2)$	yes