Lecture 11:

Convolution and Image Classification & Segmentation



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Bayesian Data Analysis and Machine Learning for Physical Sciences

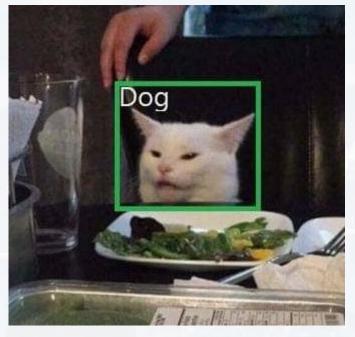


Berkeley Bayesian Data Analysis and Machine Learning for Physical Sciences

Course Map	Module 1	Maximum Entropy and Information, Bayes Theorem
	Module 2	Naive Bayes, Bayesian Parameter Estimation, MAP
	Module 3	MLE, Lin Regression
	Module 4	Model selection I: Comparing Distributions
	Module 5	Model Selection II: Bayesian Signal Detection
	Module 6	Variational Bayes, Expectation Maximization
	Module 7	Hidden Markov Models, Stochastic Processes
	Module 8	Monte Carlo Methods
	Module 9	Machine Learning Overview, Supervised Methods & Unsupervised Methods
	Module 10	ANN: Perceptron, Backpropagation, SGD
	Module 11	Convolution and Image Classification and Segmentation
	Module 12	RNNs and LSTMs
	Module 13	RNNs and LSTMs + CNNs
	Module 14	Transformer and LLMs
	Module 15	Graphs & GNNs



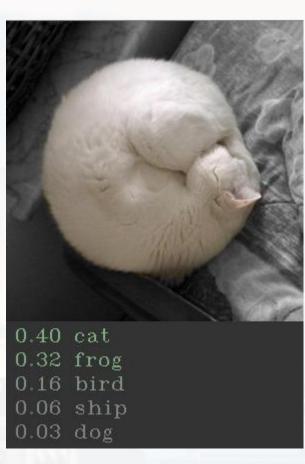
Part III











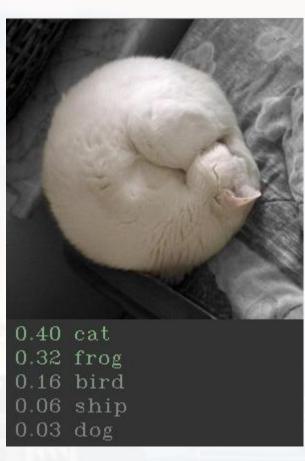
Outline

PyTorch & Cuda

Generative Adversarial Network (GAN)







<u>Outline</u>

PyTorch & Cuda

Generative Adversarial Network (GAN)



problem: even for moderate setups, computational time becomes the limiting factor

self made ANN

keras/tensor flow

pytorch

pytorch on GPU (Cuda)

speed

Lenovo T14, NVIDIA GeForce MX450: (simple LSTM)

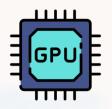
Keras (CPU):	300 sec
PyTorch (CPU):	11 sec
PyTorch (GPU):	3 sec





training Al

- → mainly matrix operations
- → GPUs are a lot better at it!

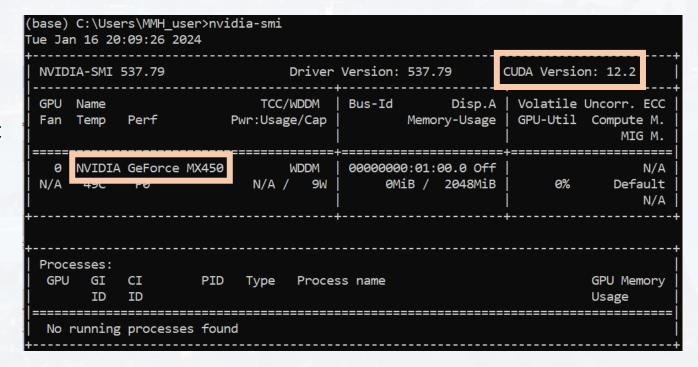




CUDA is the link of your GPU to Python (PyTorch) check, if graphic card is on list

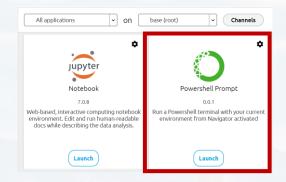
check your graphics device:

- → Windows command shell prompt
- → type nvidia-smi
- → press Enter



Installing CUDA

conda environment





```
C:\WINDOWS\System32\Winc × + \v

(base) PS C:\Users\MMH_user> conda activate CUDAenv
```



Installing CUDA

cuda toolkit

(CUDAenv) PS C:\Users\MMH_user> conda install -c anaconda cudatoolkit

check libraries

→ type: conda list

```
(CUDAenv) PS C:\Users\MMH_user> conda list
 packages in environment at C:\Users\MMH_user\anaconda3\envs\CUDAenv:
 Name
                           Version
                                                      Build
                                                             Channel
blas
                           1.0
                                                        mkl
                                                 h2bbff1b_6
bzip2
                           1.0.8
ca-certificates
                           2024.7.2
                                                 haa95532 0
cudatoolkit
                                                 hd77b12b_0
                           11.8.0
expat
                           2.6.2
                                                 hd77b12b_0
filelock
                           3.13.1
                                           py312haa95532_0
intel-openmp
                           2023.1.0
                                            h59b6b97_46320
```



Installing CUDA

usually, a few libraries are missing

check again graphics card: type in anaconda nvidia-smi

check libraries: type in anaconda conda list cudnn

conda list cudatoolkit

conda list torch

if not: conda install cond

check Python: type in anaconda **python**

import torch

torch.cuda.is_available()

open Spyder run in Spyder **pip install**

(see the commented line in CheckMyCuda.py)

```
Installing CUDA
```

usually, a few libraries are missing

CheckMyCuda.py

```
import torch

def test_cuda():
    print("PyTorch version: ", torch.__version__)
    print("CUDA version: ", torch.version.cuda)
    print("CUDA Available: ", torch.cuda.is_available())
    if torch.cuda.is_available():
        print("Number of GPUs: ", torch.cuda.device_count())
        print("GPU Name: ", torch.cuda.get_device_name(0))

if __name__ == "__main__":
    test_cuda()
```

PyTorch version: 2.3.1+cu118

CUDA version: 11.8 CUDA Available: True

Number of GPUs: 1

GPU Name: NVIDIA GeForce MX450

The key part in PyTorch is to set all matrices and the model to the device (CPU or GPU)

```
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
print("Using device:", device)
```

```
In [13]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
    ...: print("Using device:", device)
Using device: cuda
```

Congratulation! If you see this, you are ready to go!

The key part in PyTorch is to set all matrices and the model to the device (CPU or GPU)

```
In [13]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
    ...: print("Using device:", device)
Using device: cuda
```

Torch objects like model or torch.tensor have the property .to

```
TrainX = torch.tensor(TrainX, dtype = torch.float32)
TrainY = torch.tensor(TrainY, dtype = torch.float32)

TrainX = TrainX.to(device)
TrainY = TrainY.to(device)

turning numpy array into torch.tensor

model = model.to(device)

allocating objects to the device
```

The key part in PyTorch is to set all matrices and the model to the device (CPU or GPU)

When running the training, we need to **synchronize** between GPU (for training the model) and CPU (for everything else)...

```
torch.cuda.synchronize()
```

The key part in PyTorch is to set all matrices and the model to the device (CPU or GPU)

When running the training, we need to **synchronize** between GPU (for training the model) and CPU (for everything else)...

...and later detach the model from the GPU

```
PredY = model(TestX).detach().to('cpu').numpy()
```





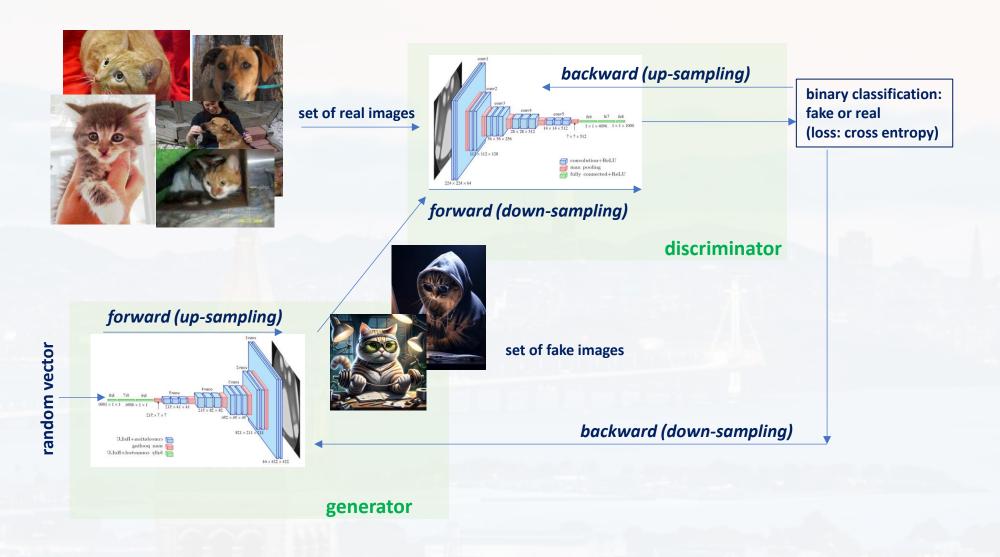


<u>Outline</u>

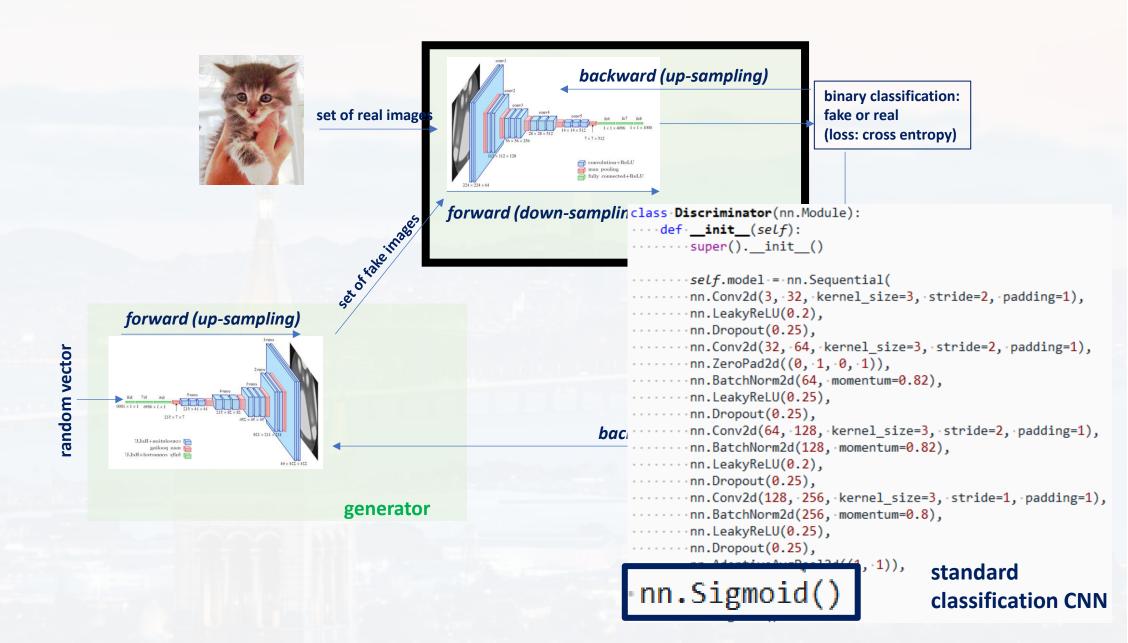
PyTorch & Cuda

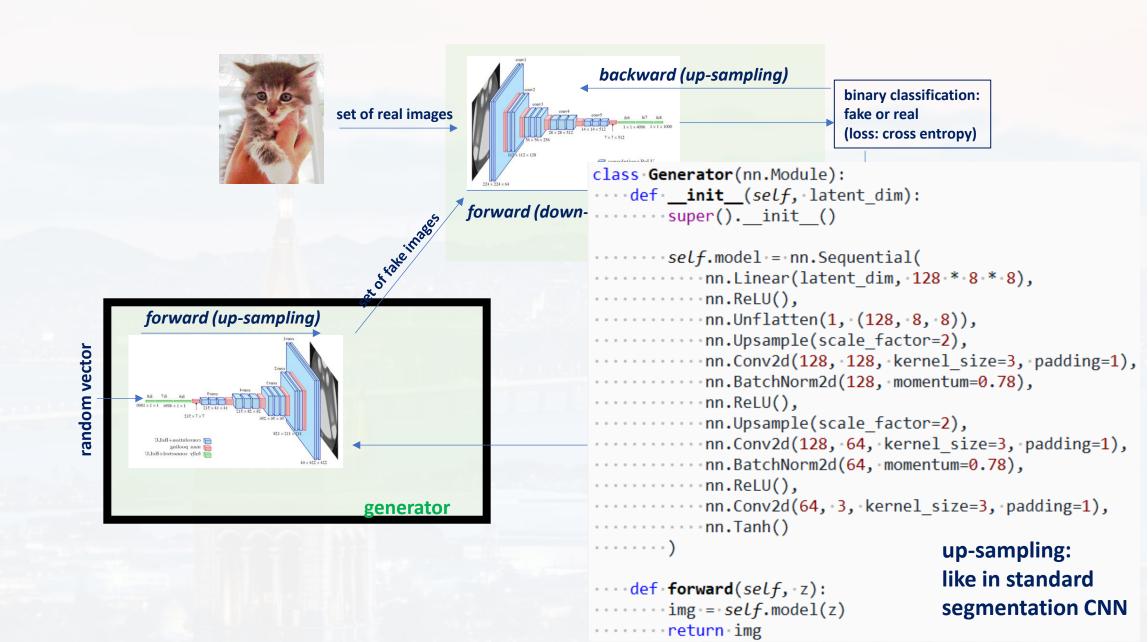
Generative Adversarial Network (GAN)













x: real image

z: latent vector (random numbers)

 $p_D(x)$: probability that discriminator D classifies x as real image

G(z): fake image generated from generator G

 \mathcal{L}_D : loss function of discriminator D

 \mathcal{L}_G : loss function of generator G

(mean) binary cross entropy (BCE): $\mathcal{L}_D = -\frac{1}{N} \sum_{i=1}^N \log[p_D(x_i)] + \log[1 - p_D(G(z_i))]$

over all N images $\mathcal{L}_G = -\frac{1}{N} \sum_{i=1}^N \log[1 - p_D(G(z_i))]$

ideal case for *D*: $\mathcal{L}_D = -\log[1] - \log[1 - 0] = 0$

worst case for *D*: $\mathcal{L}_D = -\log[1] - \log[1 - 0.5] = 0.69$

ideal case for G: $\mathcal{L}_D = \log[1 - 0.5] = -0.69$

worst case for G: $\mathcal{L}_D = \log[1 - 0] = 0$



check out

GAN architecture.ipynb

after 1 epoch(s)

after 10 epoch(s)





check out

GAN architecture.ipynb

after 30 epoch(s) after 55 epoch(s)



Thank you very much for your attention!

