Lecture 10:

Convolutional Neural Networks (CNN) – Part II



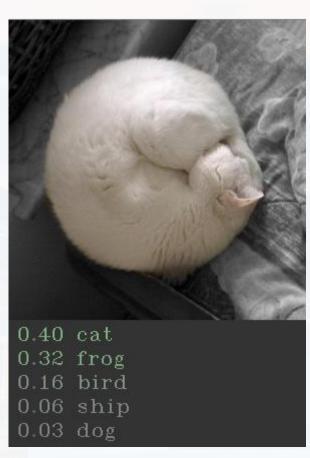
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Machine Learning Algorithms
MSSE 277B, 3 Units
Fall 2024



Berkeley Machine Learning Algorithms:





Outline

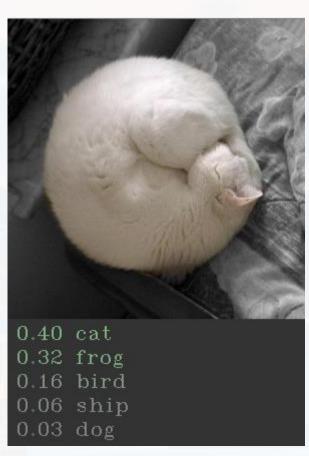
- Labeling Tools

- Calling a Pretrained CNN



Berkeley Machine Learning Algorithms:





Outline

- Labeling Tools

- Calling a Pretrained CNN



<u>"labelme"</u>

Description

Labelme is a graphical image annotation tool inspired by http://labelme.csail.mit.edu. It is written in Python and uses Qt for its graphical interface.



VOC dataset example of instance segmentation.

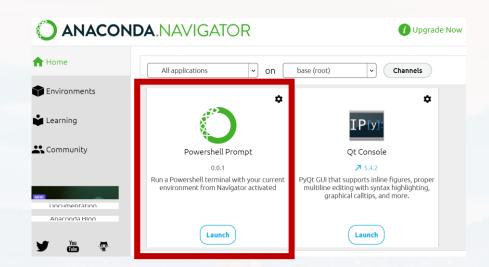


Other examples (semantic segmentation, bbox detection, and classification).



Various primitives (polygon, rectangle, circle, line, and point).



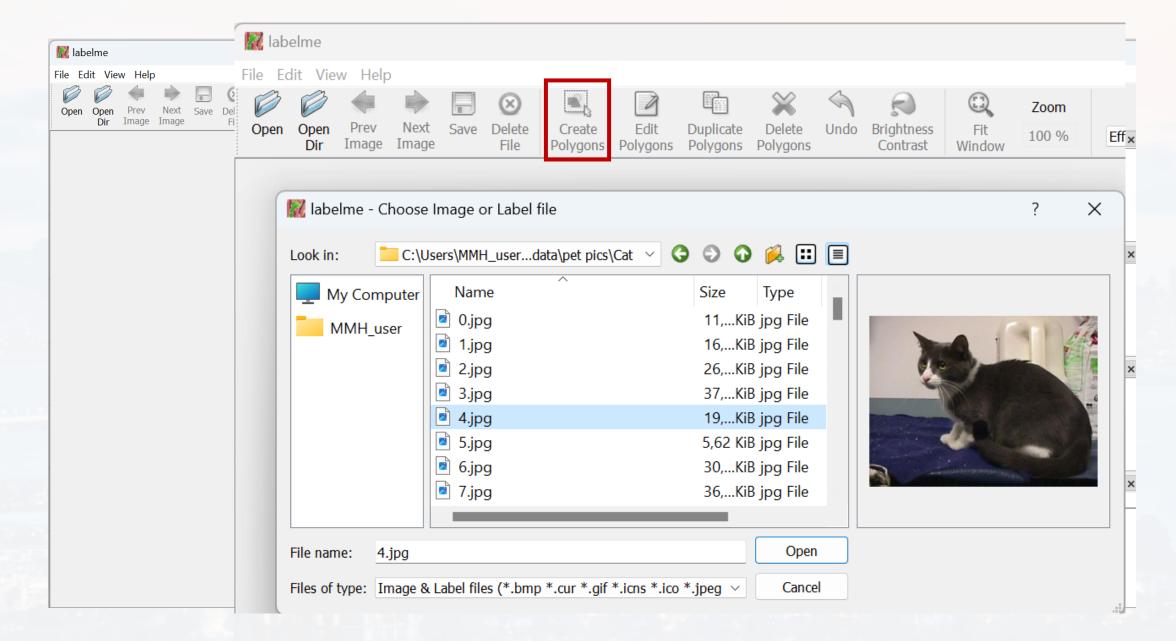


conda install labelme

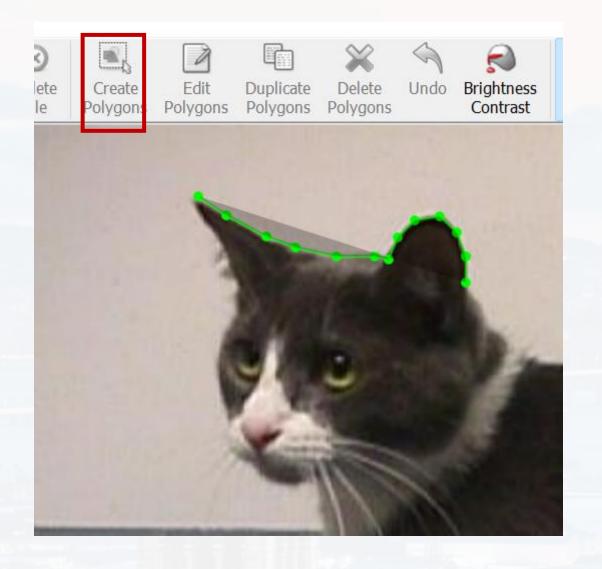
(base) PS C:\Users\MMH_user> conda activate labelme

(labelme) PS C:\Users\MMH_user> labelme

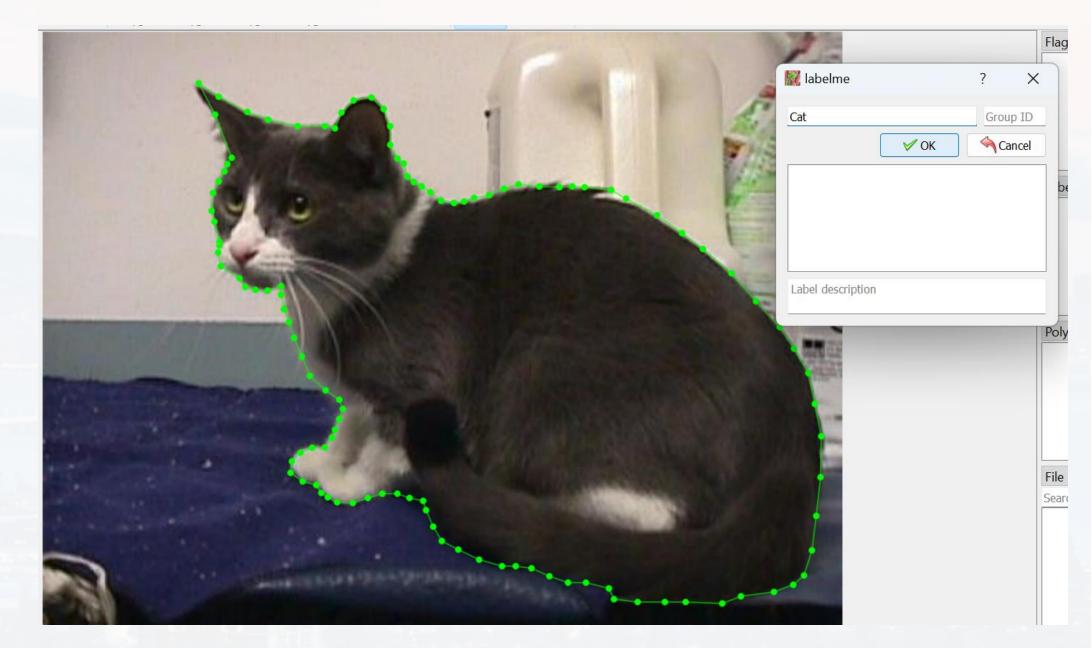














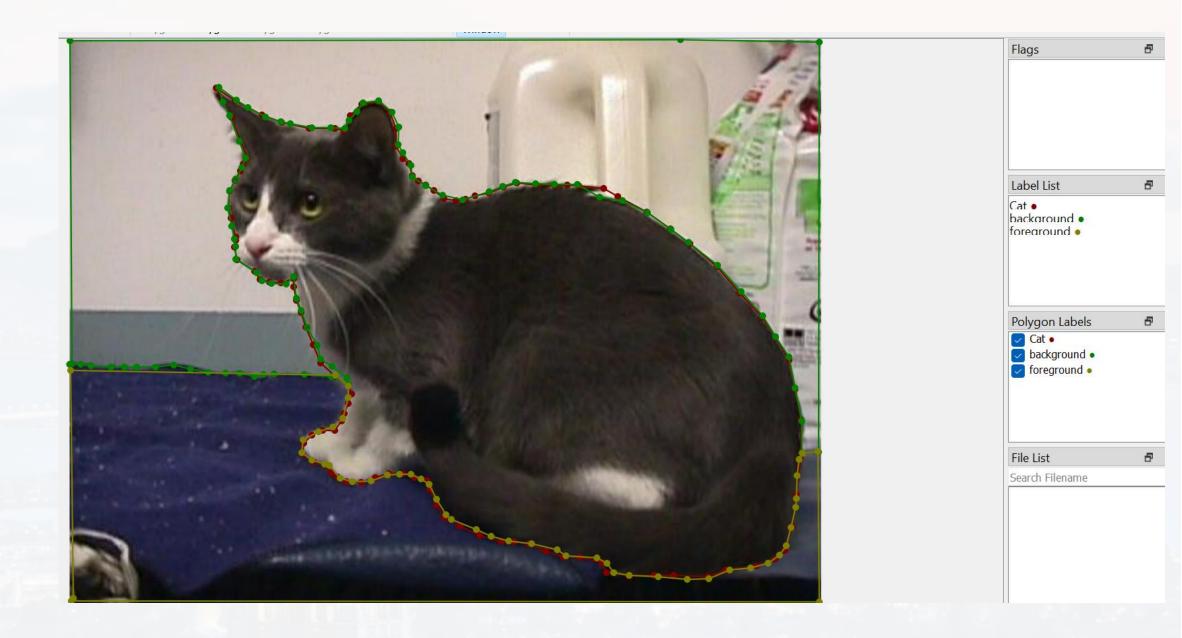




image is saved as .json

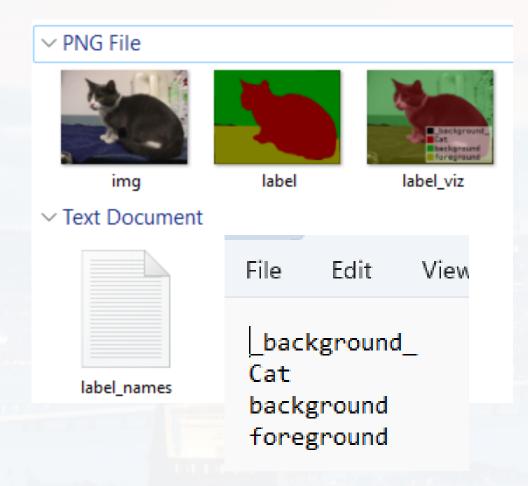


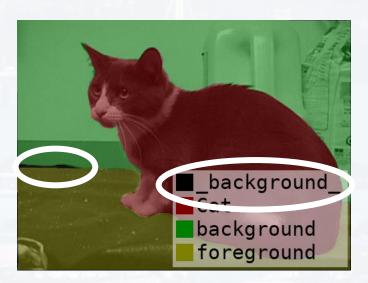
run within the labelme prompt:

labelme_export_json .\Cat4label.json -o Cat4label_json

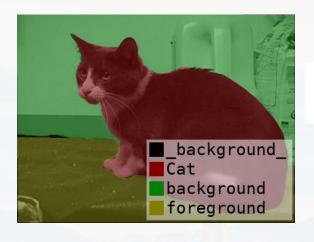




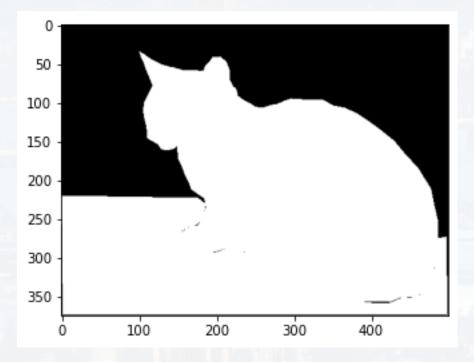


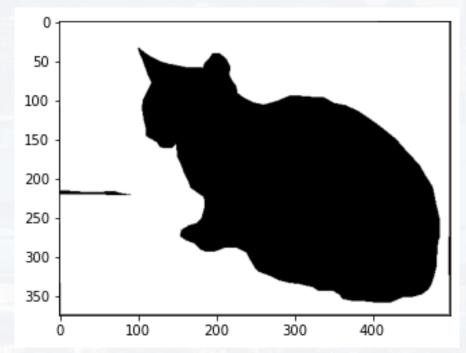




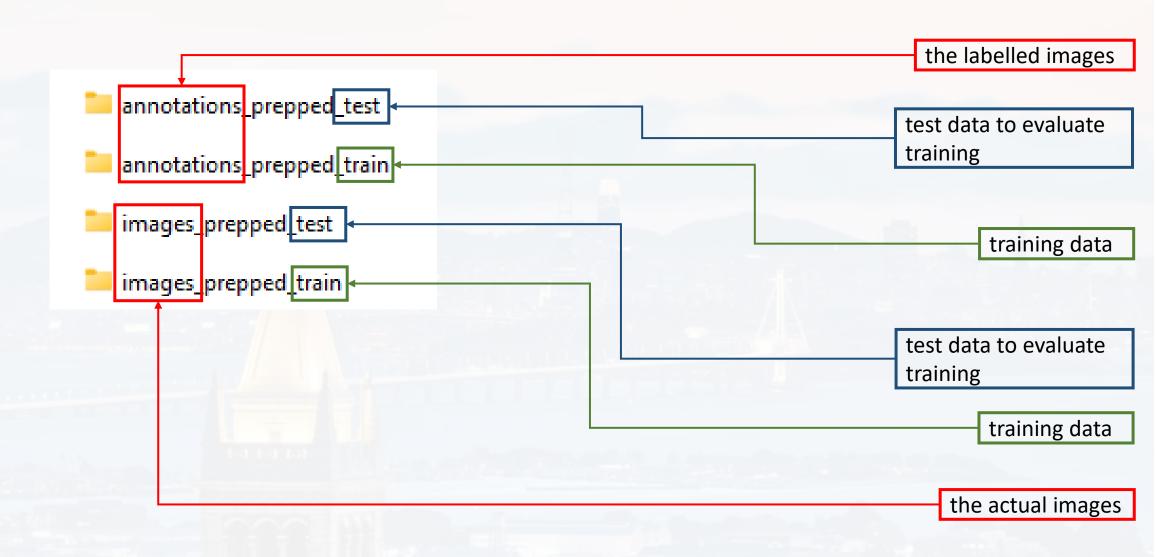


I = plt.imread('Cat/Cat4label_json/label.png')
I.shape
(375, 500, 4)







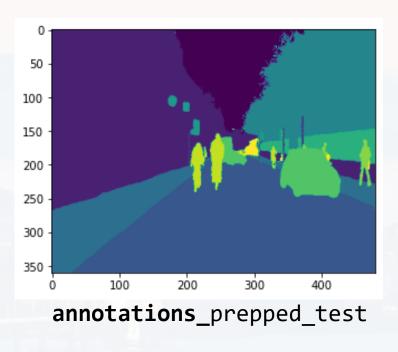




nice dataset



images_prepped_test

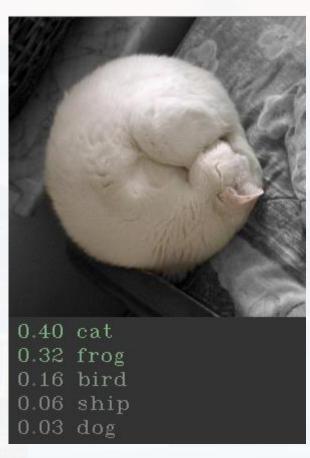


I = plt.imread('segmentation/pics/annotations prepped test/0016E5_07959.png')

I.shape (360, 480)

Berkeley Machine Learning Algorithms:





Outline

- Labeling Tools

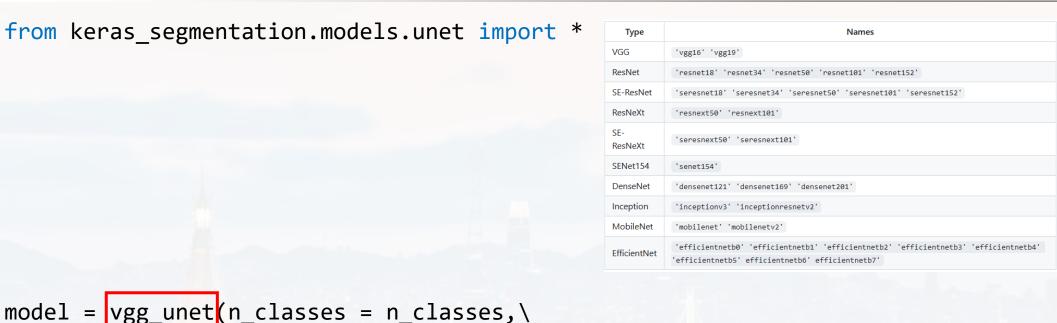
- Calling a Pretrained CNN



demonstrating realistic segmentation with reasonable results will take a few hours

→ check out my code on GitHub

Segmentation



```
model = vgg_unet(n_classes = n_classes,\
                          input height = 416, input width = 608)
                                                                calling the specific net-
model.train(
                                                                work
       train images
                          = my path + r"images prepped train//",
       train_annotations = my_path + r"annotations_prepped_train//",
       checkpoints path = my path + r"checkpoints/
                                                                saves current
       do augment
                                = True,
                                                                weights
       gen_use_multiprocessing = True,
       auto resume checkpoint = True,
                                                                Keras provides an
       epochs = 5)
                                                                augmentation routine
```



```
run:
S = SegmentMyImages()
S.Training()
```

S = SegmentMyImages()

S.Training()

```
Dataset verified!
Epoch 1/5
saved ../data/segmentation
pics/checkpoints//.0
Epoch 2/5
saved ../data/segmentation
pics/checkpoints//.1
Epoch 3/5
saved ../data/segmentation
pics/checkpoints//.2
Epoch 4/5
saved ../data/segmentation
pics/checkpoints//.3
Epoch 5/5
pics/checkpoints//.4
```

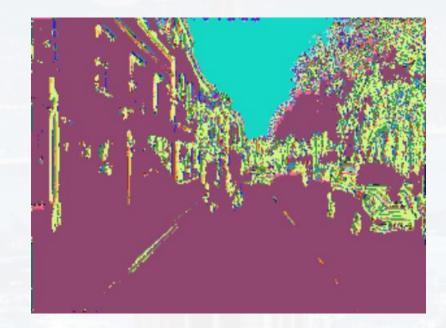
MyModel = S.TrainedModel

MyModel.summary()

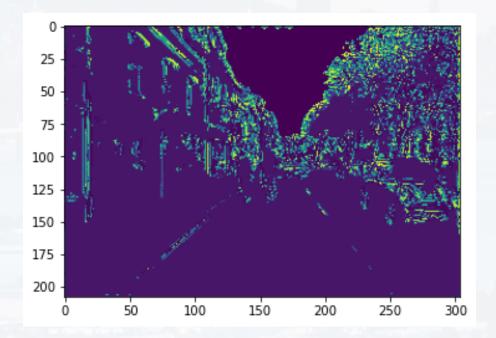
→ returns the structure of the CNN

applying the trained CNN to an image:

out = S.ApplyTrainedNetwork()



plt.imshow(out)





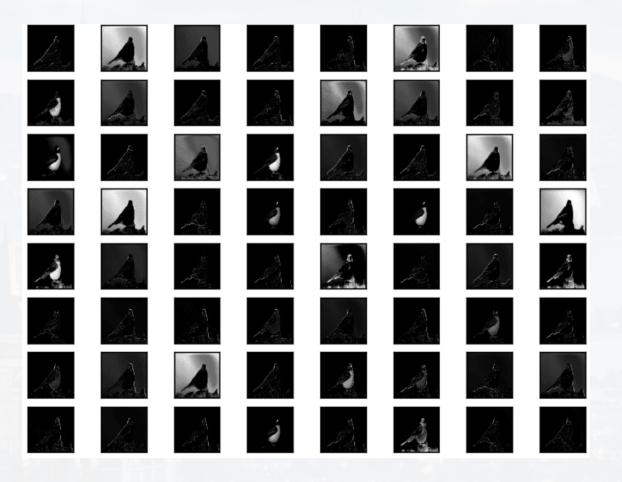
```
recovering model from checkpoints:
MyModel = S.TrainedModel
out
         = S.ApplyTrainedNetwork()
                                                applying the trained CNN to an image:
S.RecoverFromCheckpoint()
                                                                            untrained
                                                                           model (just
                                                                            CNN itself)
·#loading·untrained·CNN
 model = self.model
                                                       transfer the saved weights to untrained
 if not image_name:
                                                       network → now it starts from latest
     image_name = '0016E5_07965.png'
                                                       training state
#calling input from checkpoints
 latest = tf.train.<u>latest c</u>heckpoint(self.checkpoint_path)
 model.load_weights(latest)
```



visualizing weights:

→ see model.layers

nice example





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Thank you very much for your attention!

