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Master's Thesis

**Default Forward Rate Models for the
Valuation of Loans including Behavioral
Aspects**

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1 Introduction

1.1 Motivation

1.2 Aim of the thesis

1.3 Preliminaries

The thesis is aimed at an audience that has a deep analytical background and a basic knowledge in probability theory and financial mathematics.

If one has knowledge in the following areas, it is a good start:

- Brownian-Motions and martingales,
- stochastic integration,
- Itô stochastic processes,
- definition of and theorems on arbitrage freeness.

Furthermore we assume a fundamental understanding of what these mathematical concepts imply on the real world and the other way around: How are the mathematical concepts motivated by the economical world?

2 Fundamentals

In this section we provide some fundamentals for the thesis. Many of the results mentioned here can also be found in different versions in other scientific papers. We will stick to source [\[Add source\]](#) for more theoretical and source [\[Add source\]](#) for more application-oriented results.

2.1 Probability Theory

In our whole thesis we will assume a filtered probability space

$$(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{Q})$$

where

- Ω is the set of all states,
- \mathcal{F} is a σ -algebra,
- $\mathbb{F} = (\mathcal{F}_t)_{t \in [0; \tilde{T}]}$ is a filtration with $\mathcal{F}_t \subset \mathcal{F} \quad \forall t \in [0; \tilde{T}]$, $\mathcal{F}_0 = \{\Omega, \emptyset\}$ and
- \mathbb{Q} is a probability measure on \mathcal{F} .

Let us cover some notations.

Notation 2.1. *Let X and Y be Itô stochastic processes and W be a Brownian-Motion with:*

$$\begin{aligned} X_t &= X_0 + \int_0^t \mu_s^X ds + \int_0^t \phi_s dW_s, \\ Y_t &= Y_0 + \int_0^t \mu_s^Y ds + \int_0^t \psi_s dW_s. \end{aligned}$$

The sharp bracket or quadratic variation of X is

$$\langle X \rangle_t = \int_0^t \phi_s^2 ds.$$

. The quadratic covariation of X and Y is

$$\langle X, Y \rangle_t = \int_0^t \phi_s \psi_s ds.$$

For a n -dimensional Brownian-Motion $W = (W^i)_{i \in \{1, \dots, n\}}$ and therefore n -dimensional diffusion processes $\phi = (\phi^i)_{i \in \{1, \dots, n\}}$, $\psi = (\psi^i)_{i \in \{1, \dots, n\}}$ the quadratic covariation is

$$\langle X, Y \rangle_t = \sum_{i=1}^n \int_0^t \phi_s^i \psi_s^i ds$$

For convenience we state a formula for stochastic integration by parts and a extended version of Itô's theorem:

Lemma 2.2. *Let X and Y be two Itô stochastic processes. Then*

$$X_t Y_t = X_0 Y_0 + \int_0^t X_s dY_s + \int_0^t Y_s dX_s + \langle X, Y \rangle_t$$

Proof. See [5]. □

Theorem 2.3. *Let X be an Itô stochastic process, $f : \mathbb{R}^n \times [0; \tilde{T}] \rightarrow \mathbb{R}$, $(x, t) \mapsto f(x, t)$ be two times differentiable in x and differentiable in t . Then*

$$\begin{aligned} f(X_t, t) &= f(X_0, 0) + \int_0^t (\partial_t f)(X_s, s) ds + \sum_{i=1}^n \int_0^t (\partial_{x^i} f)(X_s, s) dX_s^i \\ &\quad + \frac{1}{2} \sum_{i,j=1}^n \int_0^t (\partial_{x^i x^j}^2 f)(X_s, s) d\langle X^i, X^j \rangle_s \end{aligned}$$

Proof. See [5]. □

Through Itô's formula we can prove the following statement.

Lemma 2.4. *Let $W = (W^i)_{i \in \{1, \dots, d\}}$ be a d -dimensional Brownian Motion, μ be a 1- dimensional and $\sigma = (\sigma^i)_{i \in \{1, \dots, d\}}$ a d -dimensional stochastic process. Let following stochastic differential equation (SDE) be given:*

$$\begin{aligned} dY_t &= Y_t \mu_t dt + Y_t \sigma_t \cdot dW_t, \\ Y_0 &= y, \end{aligned} \tag{1}$$

where $y > 0$.

Then solving eq. (1) is equivalent to solving

$$\begin{aligned} Y_t &= \exp(X_t), \\ dX_t &= (\mu_t - \frac{1}{2} \sum_{i=1}^d (\sigma_t^i)^2) dt + \sigma_t \cdot dW_t, \\ X_0 &= \log(y). \end{aligned} \tag{2}$$

Proof. We use Itô's formula on eq. (2) with $f(x) = \exp(x)$, hence

$$(\partial_x f)(x) = \exp(x), \quad (\partial_{xx}^2 f)(x) = \exp(x).$$

We get (in SDE format):

$$\begin{aligned} dY_t &= d\exp(X_t) = \exp(X_t)dX_t + \frac{1}{2}\exp(X_t)d\langle X \rangle_t \\ &= Y_t\left((\mu_t - \frac{1}{2}\sum_{i=1}^d(\sigma_t^i)^2)dt + \sigma_t \cdot dW_t\right) + \frac{1}{2}Y_t\sum_{i=1}^d(\sigma_t^i)^2dt \\ &= Y_t\mu_t dt + Y_t\sigma_t \cdot dW_t, \end{aligned}$$

which yields eq. (1). □

Remark 2.5. *It is easy to see, that because of the relation*

$$Y_t = \exp(X_t),$$

it holds that $Y_t > 0 \quad \forall t \in [0; \tilde{T}]$.

2.2 Financial Mathematics

While the reader should have a deep understanding of what arbitrage is and how to avoid it when pricing financial products, we will formulate some fundamental results as a reminder.

Theorem 2.6. *Following statements are equivalent:*

- *The market is arbitrage free and complete.*
- *There exists exactly one probability measure \mathbb{Q}^B w.r.t. a numeraire B , such that the price process of every traded asset discounted by the numeraire $\frac{X}{B}$ is a martingale w.r.t. the filtration \mathbb{F} .*

Proof. See [5]. □

This directly give us a notation for the price of any product in an arbitrage free and complete market.

Lemma 2.7. *Let X be the payoff of a T -claim. Then the arbitrage-free price of the claim at any time $t \in [0, T]$ is*

$$\Pi_t^X = B(t) \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X}{B(T)} \middle| \mathcal{F}_t \right].$$

Proof. See [5]. □

Elaborate!!!.

2.3 Factor Loadings

The problem we face in this section is that of correlated Brownian-Motions.

Assume we have two SDEs for stochastic processes X and Y :

$$\begin{aligned} dX_t &= \mu_t^X dt + \sigma_t^X dW_t^{\mathbb{Q},1}, \\ dY_t &= \mu_t^Y dt + \sigma_t^Y dW_t^{\mathbb{Q},2}, \end{aligned}$$

where $W^{\mathbb{Q},1}$ and $W^{\mathbb{Q},2}$ are instantaneously correlated Brownian-Motions under the same measure \mathbb{Q} . This correlation ρ is expressed by a quadratic covariation of the Brownian-Motions [1]:

$$\langle W^{\mathbb{Q},1}, W^{\mathbb{Q},2} \rangle_t = \int_0^t \rho_s ds$$

or as SDE:

$$d \langle W^{\mathbb{Q},1}, W^{\mathbb{Q},2} \rangle_t = \rho_t dt.$$

However implementation-wise we need to simulate SDEs using only independent Brownian-Motions.

For our computations we will stick to a constant instantaneous correlation $\rho = \rho_t \in \mathbb{R}$, so lets formulate this assumption first:

Assumption 2.1. *For all 1-dim. Brownian-Motions under the martingale measure \mathbb{Q}^B the instantaneous correlation is assumed to be constant. That is for any \mathbb{Q}^B -Brownian-Motions W^1 and W^2 the following holds for some $\rho \in \mathbb{R}$:*

$$d \langle W^1, W^2 \rangle_t = \rho dt$$

Let us now look at how to simulate correlated Brownian-Motions using only independent ones by taking advantage of its properties.

Recall following Lemmatas:

Lemma 2.8. $W = (W^i)_{i \in \{1, \dots, d\}}$ is a d -dimensional Brownian-Motion if and only if W^1, \dots, W^d are independent 1-dimensional Brownian-Motions

Proof. See [5]. □

Lemma 2.9. For any d -dimensional standard Brownian-Motion $U = (U^i)_{i \in \{1, \dots, d\}}$ and weights $(a_i)_{i \in \{1, \dots, d\}}$ with $a_1^2 + \dots + a_d^2 = 1$ it holds, that the process W given by:

$$W_t = \sum_{i=1}^d a_i U_t^i$$

is a 1-dimensional standard Brownian-Motion.

Proof. We proof that W fulfills the properties of a Brownian-Motion:

Property $W_0 = 0$ a.s.:

$$W_0 = \sum_{i=1}^d a_i U_0^i = 0 \text{ a.s.}$$

Property $(W_t - W_s) \sim \mathcal{N}(0, t - s)$ for $s < t$:

$$\begin{aligned} W_t - W_s &= \sum_{i=1}^d a_i U_t^i - \sum_{i=1}^d a_i U_s^i \sim \mathcal{N}\left(0, \sum_{i=1}^d a_i^2 (t - s)\right) \\ &\sim \mathcal{N}\left(0, (t - s) \sum_{i=1}^d a_i^2\right) \\ &\sim \mathcal{N}(0, (t - s)) \end{aligned}$$

Property W has stationary independent increments: **Elaborate!!!**.

Property W has continuous sample paths a.s.:

Let $U^i(\omega)$ be continuous for $\omega \in A_i \subset \Omega$ where A_i^c is a null set. Then $W(\omega) = \sum_{i=1}^d a_i U^i(\omega)$ is continuous for $\omega \in \bigcap_{i=1}^d A_i$. Because $\left(\bigcap_{i=1}^d A_i\right)^c = \bigcup_{i=1}^d A_i^c$ is still a null set, we have that also W has continuous sample paths almost surely. □

We can now create different linear combinations of the same d -dimensional Brownian-Motion U and look at their correlation:

Lemma 2.10. *Let $U = (U^i)_{i \in \{1, \dots, d\}}$ be a d -dimensional Brownian-Motion, let $(a_i)_{i \in \{1, \dots, d\}}$ and $(b_i)_{i \in \{1, \dots, d\}}$ be weights with $\sum_{i=1}^d a_i^2 = 1$, $\sum_{i=1}^d b_i^2 = 1$ respectively. Then W^1 and W^2 given by*

$$W_t^1 = \sum_{i=1}^d a_i U^i$$

$$W_t^2 = \sum_{i=1}^d b_i U^i$$

are 1-dimensional Brownian-Motions with:

$$d \langle W^1, W^2 \rangle_t = \left(\sum_{i=1}^d a_i b_i \right) dt \quad (3)$$

Proof. By Lemma 2.9 we have that W^1 and W^2 are Brownian-Motions. Taking the quadratic covariation directly yields eq. (3). \square

With this lemma we now have a way to construct correlated Brownian-Motions W^1, \dots, W^d . We still need to find the linear combinations, given a certain correlation matrix $R = (\rho_{i,j})_{i,j \in \{1, \dots, d\}}$, however. A way to do that is to use principal component analysis (PCA). It is beyond the scope of this thesis to give a detailed description of PCA, but the key idea is to take the eigenvectors of R and use them as linear combination. PCA also gives a way to reduce the number of factors, by only considering the Eigenvectors with the highest Eigenvalues [1]. Let us summarize this procedure in a lemma:

Lemma 2.11. *Let $U = (U^i)_{i \in \{1, \dots, d\}}$ be a d -dim. Brownian-Motion, let $R = (\rho_{i,j})_{i,j \in \{1, \dots, d\}}$ be a $\mathbb{R}^{d \times d}$ correlation matrix (positive-definite, symmetric, entries in $[-1; 1]$ and 1 on the diagonal). Let $(\lambda^{i,j})_{i,j \in \{1, \dots, d\}}$ be a matrix constructed by PCA from R .*

For $i = 1, \dots, d$ let W^i be the 1-dim. Brownian-Motion given by:

$$W_t^i = \sum_{j=1}^d \lambda^{i,j} U_t^j.$$

Then $\forall i, k \in \{1, \dots, d\}$

$$\sum_{j=1}^d \lambda^{i,j} \lambda^{k,j} = \rho_{i,k}$$

$$d \langle W^i, W^k \rangle_t = \rho_{i,k} dt$$

Proof. This is a direct implication from the previous results together with the definition of PCA and the proof that it works in [\[Add source\]](#). \square

We now have a way of constructing correlated Brownian Motions. As mentioned we can perform a factor reduction with PCA, meaning we can construct d correlated Brownian-Motions with $m < d$. This comes at the cost of "losing" a bit of the independence of some factors. But because in most cases the advantages of a factor reduction (less computational cost) outweigh the disadvantages, we will from here on assume, that the correlation- and factor loading matrix are not of the same size.

3 LIBOR Market Model

While the actual LIBOR, short for "London Inter-Bank Offered Rate" [\[Add source\]](#) lost most of its influence after the banking crash of 2008 [\[Add source\]](#) the LIBOR market model - or discrete forward rate model - is still a very popular mathematical model for simulation and valuation of financial products on fixed income markets.

The idea of the model [Elaborate!!!](#).

The basic assumption of the LIBOR Market Model is that we are in an arbitrage free and complete market.

3.1 Fixed Income Markets Terminology

We start with the definition of some fixed income market terms:

Definition 3.1. *A zero coupon bond with maturity $T \in [0; \tilde{T}]$ (short: T -bond) is a product that pays 1 at maturity. Its price process is denoted:*

$$P(t; T) := P(\omega, t; T)$$

Note: by construction $P(T; T) = 1$ and $P(\cdot, T)$ discounted with the numeraire must be a martingale under the corresponding martingale-measure \mathbb{Q}^B .

While the zero coupon bond does not yield any payoff (or coupons) between buying- and maturity time - hence the name - one can also find coupon paying bonds:

Definition 3.2. *Let $T_1 < \dots < T_M$ be a tenor with $T_1, T_M \in [0; \tilde{T}]$.*

A (fixed) coupon bond with nominal $N \in \mathbb{R}$ and coupons $c_i \in \mathbb{R}$ for $i = 1, \dots, M$ on the given tenor is a product that pays c_i at each time point T_i and additionally the nominal N at maturity T_M .

Remark 3.3. *A variation of this definition is that c_i are defined as coupon rates and the actual coupon payment is then $c_i N$ at each time step T_i . Another popular definition includes the terminal payment of the nominal N in the last coupon c_M . Additionally to this "normal" coupon bond one can also find amortizing coupon*

bonds in the market that distribute the nominal N in the coupons over all periods instead of paying it all at once at the maturity time.

Lemma 3.4. *Let T_i and c_i be as in the definition above. The price of a fixed coupon paying bond is:*

$$\Pi(t) = \sum_{i=1}^M c_i P(t; T_i) + NP(t; T_M) \quad (4)$$

for $t \in [0; T_1[$.

Proof. The coupon bond can be replicated by buying c_i T_i -zero-coupon-bonds for each $i = 1, \dots, M$ and N T_M -bonds.

Such a portfolio of zero coupon bonds has a price as given in eq. (4). As we are in a complete market, the two products must have the same value. \square

Definition 3.5. *We define the simple forward rate $L(t; S, T)$ with fixing time S and payment time T at evaluation time t to be a relation of S - and T -bonds:*

$$1 + L(t; S, T)(T - S) = \frac{P(t; S)}{P(t; T)} \quad (5)$$

We can define different products that are strictly positive as numeraires as alternatives to the money market account. We then use a change of measure which gives us a different martingale measure corresponding to the numeraire, i.e. under this new measure all price processes of traded assets discounted with the numeraire are martingales as well.

A simple example is the terminal measure:

Definition 3.6. *The terminal measure is the martingale measure \mathbb{Q}^B gained by using the terminal Bond as numeraire, i.e.*

$$B(t) = P(t; \tilde{T}) \quad (6)$$

A more complex example is the spot measure.

Definition 3.7. *Let $0 = T_0 < T_1 < \dots < T_N = \tilde{T}$ be a tenor on the time set $[0; \tilde{T}]$.*

The spot measure is the martingale measure \mathbb{Q}^B gained by using the numeraire:

$$B(t) = P(t; T_{m(t)+1}) \prod_{i=0}^{m(t)} \frac{1}{P(T_i; T_{i+1})}, \quad (7)$$

where $m(t) = \max\{i \in \{0, \dots, N-1\} \mid T_i \leq t\}$.

Remark 3.8. Equation (7) can be rewritten to:

$$B(t) = P(t; T_{m(t)+1}) \prod_{i=0}^{m(t)} (1 + L(T_{i-1}; T_{i-1}, T_i)(T_{i+1} - T_i)) \quad (8)$$

The numeraire in the spot measure can be explained as follows:

At $T_0 = 0$ we invest 1 into T_1 -bonds. Once these expire (at T_1) we reinvest the money gained from them into T_2 -bonds and so on. This product is generally known as *rolling bond*.

Elaborate!!!.

3.2 Model specification

Through the LIBOR model we construct the stochastic differential equations of simple forward rates for a consecutive set of time periods.

We start with a fixed time tenor of $N + 1$ ($N \in \mathbb{N}$) points, that splits our time horizon $[0; \tilde{T}]$:

$$0 = T_0 < T_1 < \dots < T_N = \tilde{T}.$$

The main objective is to simulate the one step simple forward rates for this tenor:

Assumption 3.1. The one step simple forward rate (called LIBOR rate)

$$L_i(t) := L(t; T_i, T_{i+1}) \quad \forall i \in \{0, \dots, N\}, t \in [0; T_i],$$

where $L(t; S, T)$ is defined as in definition 3.5, follows an Itô stochastic process satisfying

$$\begin{aligned} dL_i &= \mu_t^i dt + \sigma_t^i dW_t^{\mathbb{Q}^B, L_i}, \\ L_i(0)(T_{i+1} - T_i) &= \frac{P(0; T_i)}{P(0; T_{i+1})} - 1, \end{aligned}$$

where $(W^{\mathbb{Q}^B, L_i})_{i \in \{0, \dots, N\}}$ are possibly instantaneously correlated Brownian-Motions.

In the LIBOR model, all other variables are then derived from these interest rates, most importantly the T_i -Bond prices. The attentive reader will have noticed, however, that there is a hole in this derivation: the so-called short-period Bond $P(t; T_{m(t)+1})$ cannot be calculated by $(L_i(t))_{i \in \{0, \dots, N\}}$ alone, which is why we need the following assumption:

Assumption 3.2. *The short-period Bond*

$$P(t; T_{m(t)+1})$$

is $\mathcal{F}_{m(t)}$ -measurable. This means that all T_i -Bond prices are predictable in $[T_{i-1}; T_i]$. A specification that satisfies this assumption is:

$$P(t; T_{m(t)+1}) = (1 + L_{m(t)}(t)(T_{m(t)+1} - t))^{-1}$$

Given a variance-structure for the rates $(\sigma^i)_{i \in \{0, \dots, N\}}$, a correlation-structure $(\rho^{i,j})_{i,j \in \{0, \dots, N\}}$ for the Brownian-Motions and we can specify a drift for the SDEs of the LIBORs:

Lemma 3.9. *Let L_i satisfy assumption 3.1. Let $(\sigma^i)_{i \in \{0, \dots, N\}}$ and $(\rho^{i,j})_{i,j \in \{0, \dots, N\}}$ be given, where*

$$d \left\langle W^{\mathbb{Q}^B, L_i}, W^{\mathbb{Q}^B, L_j} \right\rangle_t = \rho_t^{i,j} dt.$$

Then *Elaborate!!!*.

4 Defaultable LIBOR Market Models

In this section we will introduce defaultable LIBOR market models that we can use to value credits and credit options.

Our main source for this section is the article "Defaultable Discrete Forward Rate Model with Covariance Structure guaranteeing Positive Credit Spreads" authored by Christian Fries [2].

4.1 The Defaultable Forward Rate

We remain in the same setting as in the non-defaultable model, where we have a LIBOR tenor discretization $(T_i)_{i \in \{0,1,\dots,N\}}$ and a set of (non-defaultable) zero coupon bonds $(P(t; T_i))_{i \in \{0,1,\dots,N\}}$. Hence we can define the same products and apply the same valuation formulas.

We extend the model by defining an additional set of zero coupon bonds which are defaultable: $(P^d(t; T_i))_{i \in \{0,\dots,N\}}$.

Note here, that by construction we must still use the riskless bonds for the calculation of the Numeraire, as one can not use a risky asset as numeraire. Furthermore we will - for now - not consider recovery rates, i.e. we assume that a party is either able to pay all or nothing. We will now introduce the concept of default and defaultable zero coupon bonds.

Definition 4.1. *The default time is a stopping time $\tau(\omega)$ on the Filtration $(\mathcal{F}_t)_{t \in \mathbb{R}^+}$.*

The default indicator $J(t)$ is the indicator process over the default time:

$$J(t) := \mathbf{1}_{\{\tau(\omega) \leq t\}}$$

Definition 4.2. *The Defaultable Zero Coupon Bond with price process*

$$P^d(t; T_i)$$

at time $t \in [0, T]$ is a traded asset that pays $1 - J(T_i)$ at maturity $T_i \in \{T_0, \dots, T_N\}$.

Hence it pays 1 if the default has not happened until maturity.

It is easy to see, that if default occurs, the price of a defaultable zero coupon bond jumps to zero. This means that the price process can be discontinuous at default events. This gives notion to the definition of a zero coupon bond conditional on pre-default.

Definition 4.3. *The Defaultable Zero Coupon Bond conditional pre-default is a continuous Itô-stochastic process $P^{d,*}(t; T_i)$ at time $t \in [0, T_i]$ with maturity T_i ($i \in \{0, \dots, N\}$) such that*

$$P^d(t; T_i) = P^{d,*}(t; T_i)(1 - J(t))$$

Definition 4.4. *The simple Defaultable Forward Rate is the rate gained from $P^{d,*}(t; T)$ by the same concept as in a non-defaultable model:*

$$L_i^d(t) := L^d(t; T_i, T_{i+1}) := \left(\frac{P^{d,*}(t; T_i)}{P^{d,*}(t; T_{i+1})} - 1 \right) \Delta T_i, \quad (9)$$

where $T_i \in \{T_0, \dots, T_N\}$.

The simple Defaultable Forward Rate is the rate at which one can lend money to a defaultable party (for the time period T_i to T_{i+1}) at the risk of default, if the defaultable party is not in default at the evaluation time t [\[Add source\]](#).

Assumption 4.1. *As in the non defaultable model we assume, that the defaultable short period bond conditional pre-default*

$$P^{d,*}(t; T_{m(t)+1})$$

has no diffusion. This means that the only stochasticity on the defaultable short rate bond is the default time.

I.e. we specify the defaultable short period bond as:

$$P^{d,*}(t; T_{m(t)+1}) = (1 + L_{m(t)}^d(t)(T_{m(t)+1} - t))^{-1}$$

Theorem 4.5. *Let L_i^d be defined as in eq. (9). Let $B(t)$ be the numeraire under the spot measure (i.e. $B(t)$ is given by eq. (7)) and $W^{\mathbb{Q}^B}$ a Brownian Motion*

w.r.t. the spot measure. Let $\sigma_t^{i,d} := \sigma^{i,d}(t, \omega)$ be a progressive stochastic process. Let

$$dL_i^d(t) = \mu_t^{i,d} dt + \sigma_t^{i,d} dW_t^{\mathbb{Q}^B, L_i^d} \quad (10)$$

be the stochastic differential of L_i^d .

Then

$$\mu_t^{i,d} = \sigma_t^{i,d} \sum_{j=m(t)+1}^i \frac{\rho_t^{ij,d} \sigma_t^{j,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)}, \quad (11)$$

where $\rho_t^{ij,d} = d \left\langle W_t^{\mathbb{Q}^B, L_i^d}, W_t^{\mathbb{Q}^B, L_j^d} \right\rangle$.

Proof. By construction the defaultable zero coupon bond $P^d(t; T_i)$ is a traded asset. We get

$$L_i^d(t) P^d(t; T_{i+1}) = (P^d(t; T_i) - P^d(t; T_{i+1})) \Delta T_i$$

is also a traded asset, because it is a portfolio of defaultable zero coupon bonds.

Hence both processes discounted with the numeraire $B(t)$ are martingales.

By Itô we have:

$$\begin{aligned} d \left(L_i^d(t) \frac{P^d(t; T_{i+1})}{B(t)} \right) &= L_i^d(t) d \left(\frac{P^d(t; T_{i+1})}{B(t)} \right) + \frac{P^d(t; T_{i+1})}{B(t)} dL_i^d(t) \\ &\quad + d \left\langle L_i^d(t), \frac{P^d(t; T_{i+1})}{B(t)} \right\rangle \end{aligned}$$

We analyze the drift terms on each diffusion:

$$d \left(L_i^d(t) \frac{P^d(t; T_{i+1})}{B(t)} \right) \quad \text{and} \quad d \left(\frac{P^d(t; T_{i+1})}{B(t)} \right)$$

are martingale diffusions and hence have no drift. Therefore the drift terms of the two remaining differentials must cancel each other out. I.e.:

$$\frac{P^d(t; T_{i+1})}{B(t)} \mu_t^{i,d} dt \stackrel{!}{=} -d \left\langle L_i^d(t), \frac{P^d(t; T_{i+1})}{B(t)} \right\rangle \quad (12)$$

To calculate the quadratic variation we need the diffusion of the discounted

defaultable zero coupon bond:

$$\begin{aligned}
d\left(\frac{P^d(t; T_{i+1})}{B(t)}\right) &= d\left(\frac{P^d(t; T_{m(t)+1})}{B(t)} \prod_{j=m(t)+1}^i (1 + \Delta T_j L_j^d(t))^{-1}\right) \\
&= (...)dt - \frac{P^d(t; T_{m(t)+1})}{B(t)} \sum_{j=m(t)+1}^i \frac{\sigma_t^{j,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} dW_t^{\mathbb{Q}^B, L_j^d} \\
&\quad + \prod_{j=m(t)+1}^i (1 + \Delta T_j L_j^d(t))^{-1} d\left(\frac{P^d(t; T_{m(t)+1})}{B(t)}\right) \\
&\quad + d\left\langle \frac{P^d(t; T_{m(t)+1})}{B(t)}, \prod_{j=m(t)+1}^i (1 + \Delta T_j L_j^d(t))^{-1} \right\rangle.
\end{aligned}$$

With Assumption 3.2 and 4.1 we get

$$d\left(\frac{P^d(t; T_{m(t)+1})}{P(t; T_{m(t)+1})}\right) = (...)dt - \frac{P^{d,*}(t; T_{m(t)+1})}{P(t; T_{m(t)+1})} dJ(t).$$

Furthermore we have

$$d\left(\frac{P^d(t; T_{m(t)+1})}{B(t)}\right) = \prod_{j=0}^{m(t)} (1 + \Delta T_j L_j(T_j))^{-1} d\left(\frac{P^d(t; T_{m(t)+1})}{P(t; T_{m(t)+1})}\right)$$

and for any Itô-process X : $d\langle X, J \rangle = 0$ [\[Add source\]](#).

This yields

$$\begin{aligned}
d\left(\frac{P^d(t; T_{i+1})}{B(t)}\right) &= (...)dt - \frac{P^d(t; T_{m(t)+1})}{B(t)} \sum_{j=m(t)+1}^i \frac{\sigma_t^{j,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} dW_t^{\mathbb{Q}^B, L_j^d} \\
&\quad - \frac{P^{d,*}(t; T_{i+1})}{P(t; T_{m(t)+1})} dJ(t).
\end{aligned}$$

We get

$$d\left\langle L_i^d(t), \frac{P^d(t; T_{i+1})}{B(t)} \right\rangle = \sigma_t^{i,d} \frac{P^d(t; T_{m(t)+1})}{B(t)} \sum_{j=m(t)+1}^i \frac{\sigma_t^{j,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} \rho_t^{ij,d} dt.$$

Inserting into (12) yields our statement (11). \square

We now move from the "covariance" process model to a "factor loading" model as described in Section 2.3.

Lemma 4.6. *There exist m^d -dimensional stochastic processes $\lambda^{i,d} = (\lambda^{ik,d})_{k \in \{1, \dots, m^d\}}$ and a $m^d 1$ -dimensional \mathbb{Q}^B -Brownian-Motion $U = (U^k)_{k \in \{1, \dots, m^d\}}$ such that*

$$dL_i^d(t) = \mu_t^{i,d} dt + \sigma_t^{i,d} dW_t^{\mathbb{Q}^B, L_i^d} \iff dL_i^d(t) = \mu_t^{i,d} dt + \lambda_t^{i,d} \cdot dU_t$$

Furthermore

$$\sum_{k=1}^{m^d} \lambda_t^{ik,d} \lambda_t^{ik,d} = (\sigma_t^i)^2$$

as well as

$$\sum_{k=1}^{m^d} \lambda_t^{ik,d} \lambda_t^{jk,d} = \sigma_t^i \sigma_t^j \rho_t^{i,j}$$

Proof. Follows directly from Section 2.3. □

Hence from here on we will use this computation friendly version:

$$dL_i^d(t) = \mu_t^{i,d} dt + \lambda_t^{i,d} \cdot dU_t. \quad (13)$$

Remark 4.7. *For the spot measure the drifts $\mu^{i,d}$ in eq. (13) can be rewritten in terms of λ^d :*

$$\mu_t^{i,d} = \sum_{k=1}^{m^d} \lambda_t^{ik,d} \sum_{j=m(t)}^i \frac{\lambda_t^{jk,d} \Delta T_j}{1 + L_j^d(t) \Delta T_j}$$

Proof. By Equation (11) and Lemma 4.6 we have:

$$\begin{aligned} \mu_t^{i,d} &= \sigma_t^{i,d} \sum_{j=m(t)+1}^i \frac{\rho_t^{ij,d} \sigma_t^{j,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} = \sum_{j=m(t)+1}^i \frac{\rho_t^{ij,d} \sigma_t^{j,d} \sigma_t^{i,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} \\ &= \sum_{j=m(t)+1}^i \frac{\left(\sum_{k=1}^{m^d} \lambda_t^{ik,d} \lambda_t^{jk,d} \right) \Delta T_j}{1 + \Delta T_j L_j^d(t)} = \sum_{k=1}^{m^d} \sum_{j=m(t)+1}^i \frac{\lambda_t^{ik,d} \lambda_t^{jk,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} \\ &= \sum_{k=1}^{m^d} \lambda_t^{ik,d} \sum_{j=m(t)+1}^i \frac{\lambda_t^{jk,d} \Delta T_j}{1 + \Delta T_j L_j^d(t)} \end{aligned}$$

□

4.2 Covariance Structures Guaranteeing positive spreads

We now investigate how we can generate positive spreads from the defaultable LIBOR market model.

For this purpose let us define a spread:

Definition 4.8. *Let L^d and L be defined as before. The spread S_i for the LIBOR period $[T_i; T_{i+1}]$, where $i \in \{0, \dots, N\}$ is defined as:*

$$S_i(t) := L_i^d(t) - L_i(t)$$

Remark 4.9. *A negative spread would mean $L_i^d(t) < L_i(t)$. This constitutes an arbitrage possibility, which is why the model needs to be specified, such that this case is "impossible" (i.e. has probability 0).*

The spreads dynamics are given by

$$dS_i(t) = \mu_t^{i,S} dt + \lambda_t^{i,S} \cdot dU_t$$

where

$$\mu_t^{i,S} = \mu_t^{i,d} - \mu_t^i, \quad \text{and} \quad \lambda_t^{i,S} = \lambda_t^{i,d} - \lambda_t^i.$$

Note that we "extended" the vectors $\lambda_t^i = (\lambda_t^{i1}, \dots, \lambda_t^{im}, 0, \dots, 0)^T$.

Given a numeraire and the factor loadings of the non-defaultable LIBOR rates λ^i , the goal is, to find a specification for the defaultable factor loadings $\lambda^{i,d}$ such that S_i is always positive.

The most common dynamics that guarantee positivity are log-normal dynamics as discussed in Lemma 2.4. So one idea is to find restrictions on $\lambda_t^{i,d}$ such that

$$\mu_t^{i,d} - \mu_t^i = S_i(t) \tilde{\mu}_t^{i,S}, \quad \text{and} \quad \lambda_t^{i,d} - \lambda_t^i = S_i(t) \tilde{\lambda}_t^{i,S}$$

for two processes $\tilde{\mu}^{i,S}$ and $\tilde{\lambda}^{i,S}$.

Lemma 4.10. *Let \mathbb{Q}^B be the spot measure (i.e. $B(t)$ is given by eq. (7)). Let L^d be defined as before with*

$$\begin{aligned} \lambda_t^{ik,d} &= \frac{1 + L_i^d \Delta T_i}{1 + L_i \Delta T_i} \lambda_t^{ik} & \text{for } k = 1, \dots, m \\ \lambda_t^{ik,d} &= (L_i^d(t) - L_i(t)) f_t^{ik} & \text{for } k = m+1, \dots, m^d \end{aligned} \tag{14}$$

where f_t^{ik} are (possibly stochastic) processes for $i = 1, \dots, N$ and $k = m+1, \dots, m^d$.
Then $S = (S_i)_{i \in \{0, \dots, N\}}$ satisfies

$$dS_i = S_i(t) \tilde{\mu}_t^{i,S} dt + S_i(t) \tilde{\lambda}_t^{i,S} \cdot dU_t.$$

for some process $\tilde{\mu}^{i,S}$ and $\tilde{\lambda}^{i,S}$.

Proof. By Remark 4.7 we have:

$$\begin{aligned} dS_i &= dL_i^d - dL_i \\ &= \sum_{k=1}^{m^d} \lambda_t^{ik,d} \sum_{j=m(t)+1}^i \frac{\lambda_t^{jk,d} \Delta T_j}{1 + L_j^d(t) \Delta T_j} dt + \sum_{k=1}^{m^d} \lambda_t^{ik,d} dU_t^k \end{aligned} \quad (\text{A})$$

$$\begin{aligned} &- \sum_{k=1}^m \lambda_t^{ik} \sum_{j=m(t)+1}^i \frac{\lambda_t^{jk} \Delta T_j}{1 + L_j(t) \Delta T_j} dt - \sum_{k=1}^m \lambda_t^{ik} dU_t^k \\ &= \sum_{k=1}^m \left(\lambda_t^{ik,d} - \lambda_t^{ik} \right) \left(\sum_{j=m(t)+1}^i \frac{\lambda_t^{jk} \Delta T_j}{1 + L_j(t) \Delta T_j} dt + dU_t^k \right) \end{aligned} \quad (\text{B})$$

$$\begin{aligned} &+ (L_i^d(t) - L_i(t)) \left(\sum_{k=m+1}^{m^d} f_t^{ik} \sum_{j=m(t)+1}^i \frac{\lambda_t^{jk,d} \Delta T_j}{1 + L_j^d(t) \Delta T_j} dt + dU_t^k \right) \\ &= S_i \sum_{k=1}^m \frac{\lambda_t^{ik} \Delta T_i}{1 + L_i(t) \Delta T_i} \left(\sum_{j=m(t)+1}^i \frac{\lambda_t^{jk} \Delta T_j}{1 + L_j(t) \Delta T_j} dt + dU_t^k \right) \quad (\text{C}) \\ &+ S_i \left(\sum_{k=m+1}^{m^d} f_t^{ik} \sum_{j=m(t)+1}^i \frac{\lambda_t^{jk,d} \Delta T_j}{1 + L_j^d(t) \Delta T_j} dt + dU_t^k \right) \end{aligned}$$

where (A) to (B) used the relation:

$$\frac{\lambda_t^{jk,d} \Delta T_j}{1 + L_j^d(t) \Delta T_j} = \frac{\lambda_t^{jk} \Delta T_j}{1 + L_j(t) \Delta T_j} \quad \text{for } k = 1, \dots, m$$

and (B) to (C) used:

$$\lambda_t^{ik,d} - \lambda_t^{ik} = \left(\frac{1 + L_i^d(t) \Delta T_i}{1 + L_i(t) \Delta T_i} - \frac{1 + L_i(t) \Delta T_i}{1 + L_i(t) \Delta T_i} \right) \lambda_t^{ik} = S_i \frac{\lambda_t^{ik} \Delta T_i}{1 + L_i(t) \Delta T_i}$$

for $k = 1, \dots, m$. □

Elaborate!!!.

4.3 The Survival Probability

Until now we assumed every stochastic process to be adapted to the filtration \mathbb{F} . This is what is commonly done in mathematical finance to find theoretical prices and it simulates the availability of information at each time t . This includes the indicator over the default time $J(t)$. However the products we are interested in, are rarely dependent on the (future) default state, but rather its' probability, as we will see in the next chapter. So it is more efficient (and less dependent on extra assumptions) to calculate the survival probability instead of simulating the default time.

It is important to note here, that for pricing we are only interested in the behavior of the rates under the martingale measure \mathbb{Q}^B and so we will also only focus on the survival probability under this measure. This means the probability we will derive, is not to be confused with the real world probability of survival.

Let us start by stating an assumption that is important for the derivation:

Assumption 4.2. *The default time $\tau(\omega)$ has a stochastic driver, that is not fully dependent on the Brownian-Motion U .*

Furthermore $\{\tau(\omega) > 0\} = \Omega$.

This statement seems to be a bit vague, but this is only a requirement to find σ -Algebras \mathcal{G}_t such that $L_i^d(t)$ and $L_i(t)$ are \mathcal{G}_t -measurable but $J(t) = \mathbf{1}_{\{\tau < t\}}$ is not $\forall t \in [0; \tilde{T}]$.

The second part of the assumption means that, independent of the filtration, the default has not happened at time $t = 0$.

Let us now define a new filtration with this property:

Definition 4.11. *The filtration $\mathbb{G} := (\mathcal{G}_t)_{t \in [0; \tilde{T}]}$ is given by*

$$\mathcal{G}_t := \sigma(U_t^k | k = 1, \dots, m^d) \subset \mathcal{F}_t \quad \forall t \in [0; \tilde{T}].$$

Remark 4.12. *It is worth to note that all processes that are dependent on $J(t)$*

are not \mathbb{G} -adapted. This includes $P^d(t; T_i)$ for $i = 1, \dots, N$ (remember $P(0; T_0) = 1$).

As we will work quite a lot with conditional expectation from here on, let us denote for a σ -algebra \mathcal{G} :

$$\mathbb{E}_{\mathcal{G}}^{\mathbb{Q}^B} [\cdot] = \mathbb{E}^{\mathbb{Q}^B} [\cdot \mid \mathcal{G}].$$

Lemma 4.13. *For $T_i < s < t < T_{i+1}$ it holds that*

- $P(s; T_{i+1}) = P(s; t)P(t; T_{i+1})$ or $P(s; t) = \frac{P(s; T_{i+1})}{P(t; T_{i+1})}$ and
- $P^{d,*}(s; T_{i+1}) = P^{d,*}(s; t)P^{d,*}(t; T_{i+1})$ or $P^{d,*}(s; t) = \frac{P^{d,*}(s; T_{i+1})}{P^{d,*}(t; T_{i+1})}$.

Proof. Let $T_i < s < t < T_{i+1}$. With Assumption 3.2 we have:

$$\begin{aligned} P(s; T_{i+1}) &= B(s) \mathbb{E}^{\mathbb{Q}^B} \left[\frac{P(t; T_{i+1})}{B(t)} \mid \mathcal{F}_s \right] = P(t; T_{i+1}) B(s) \mathbb{E}^{\mathbb{Q}^B} \left[\frac{P(t; t)}{B(t)} \mid \mathcal{F}_s \right] \\ &= P(t; T_{i+1}) P(s; t) \end{aligned}$$

Prove the same for $P^{d,*}$!!! □

Before we start to derive the survival probability we need the following assumption:

Assumption 4.3. *Following equality is assumed to hold for all $j > i$:*

$$\mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} [\mathbf{1}_{\{\tau > T_{i+1}\}}] = \mathbb{E}_{\mathcal{G}_{T_j}}^{\mathbb{Q}^B} [\mathbf{1}_{\{\tau > T_{i+1}\}}]$$

This assumption means that the filtration \mathbb{G} does not gain any more (probability) information about the default state at time T_{i+1} from the time point T_i forward.

Lemma 4.14. *Let B be the numeraire under the spot measure, $i = 0, \dots, N$. The one-step survival probability w.r.t. \mathcal{G}_{T_i} given pre-default is*

$$q(T_i, \omega) := \mathbb{Q}^B (\{\tau(\omega) > T_{i+1}\} \mid \{\tau(\omega) > T_i\} \mid \mathcal{G}_{T_i}) = \frac{P^{d,*}(T_i; T_{i+1})}{P(T_i; T_{i+1})}. \quad (15)$$

The total survival probability until T_{i+1} w.r.t. \mathcal{G}_{T_i} is

$$\mathbb{Q}^B (\{\tau(\omega) > T_{i+1}\} \mid \mathcal{G}_{T_i}) = \prod_{k=1}^i q(T_k, \omega). \quad (16)$$

Proof. Let us start with statement 15. We get:

$$q_i(T_i, \omega) = \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} [\mathbf{1}_{\{\tau > T_{i+1}\}} \mid \{\tau(\omega) > T_i\}] \quad (\text{A})$$

$$= \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\frac{B(T_i)B(T_{i+1})}{B(T_i)B(T_{i+1})} \mathbb{E}_{\mathcal{F}_{T_i}}^{\mathbb{Q}^B} [\mathbf{1}_{\{\tau > T_{i+1}\}} \mid \{\tau(\omega) > T_i\}] \right] \quad (\text{B})$$

$$= \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\left(\frac{B(T_i)}{B(T_{i+1})} \right)^{-1} B(T_i) \mathbb{E}_{\mathcal{F}_{T_i}}^{\mathbb{Q}^B} \left[\frac{\mathbf{1}_{\{\tau > T_{i+1}\}}}{B(T_{i+1})} \mid \{\tau(\omega) > T_i\} \right] \right] \quad (\text{C})$$

$$= \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\left(B(T_i) \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\frac{1}{B(T_{i+1})} \right] \right)^{-1} (P^d(T_i; T_{i+1}) \mid \{\tau(\omega) > T_i\}) \right] \quad (\text{D})$$

$$= \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\frac{P^{d,*}(T_i; T_{i+1})}{P(T_i; T_{i+1})} \right] = \frac{P^{d,*}(T_i; T_{i+1})}{P(T_i; T_{i+1})} \quad (\text{E})$$

where from (A) to (B) we use the tower property of conditional expectation. From (B) to (C) we use the \mathcal{G}_{T_i} - and therefore \mathcal{F}_{T_i} -measurability of $B(T_{i+1})$, which we again use from (C) to (D). From (C) to (D) and from (D) to (E) we use the martingale property of $\frac{P^d(t; T_{i+1})}{B(t)}$ and $\frac{P(t; T_{i+1})}{B(t)}$ respectively.

For Equation (16) we use Bayes-Rule and assumption 4.3 to get:

$$\begin{aligned} \mathbb{Q}^B(\{\tau(\omega) > T_{i+1}\} \mid \mathcal{G}_{T_i}) &= q(T_i, \omega) \mathbb{Q}^B(\{\tau(\omega) > T_i\} \mid \mathcal{G}_{T_i}) \\ &= q(T_i, \omega) \mathbb{Q}^B(\{\tau(\omega) > T_i\} \mid \mathcal{G}_{T_{i-1}}) \\ &= q(T_i, \omega) q(T_{i-1}, \omega) \mathbb{Q}^B(\{\tau(\omega) > T_{i-1}\} \mid \mathcal{G}_{T_{i-1}}) \\ &= \dots \\ &= \prod_{k=1}^i q(T_k, \omega) \end{aligned}$$

□

Note, that while we calculate a probability here, it is a *pathwise* probability. At first glance this seems counter-intuitive, but consider this: \mathbb{G} does not capture the default state. I.e. while we can calculate $P^{d,*}(t; T_i)$, the default might have already happened, which we would not know, even past t and T_i . This is why we can and need to calculate the survival probability even when given $P^{d,*}(t; T_i)$.

Figure 1 illustrates this concept in a very simplified and discretized example.

In this example \mathbb{G} captures only the path of $P^{d,*}(t; 4.0)$, which is equal for $\omega = \omega_1, \omega_2$ and ω_3 , while $P^d(t; 4.0)(\omega_1) \neq P^d(t; 4.0)(\omega_2) \neq P^d(t; 4.0)(\omega_3)$ for $t = 4.0$.

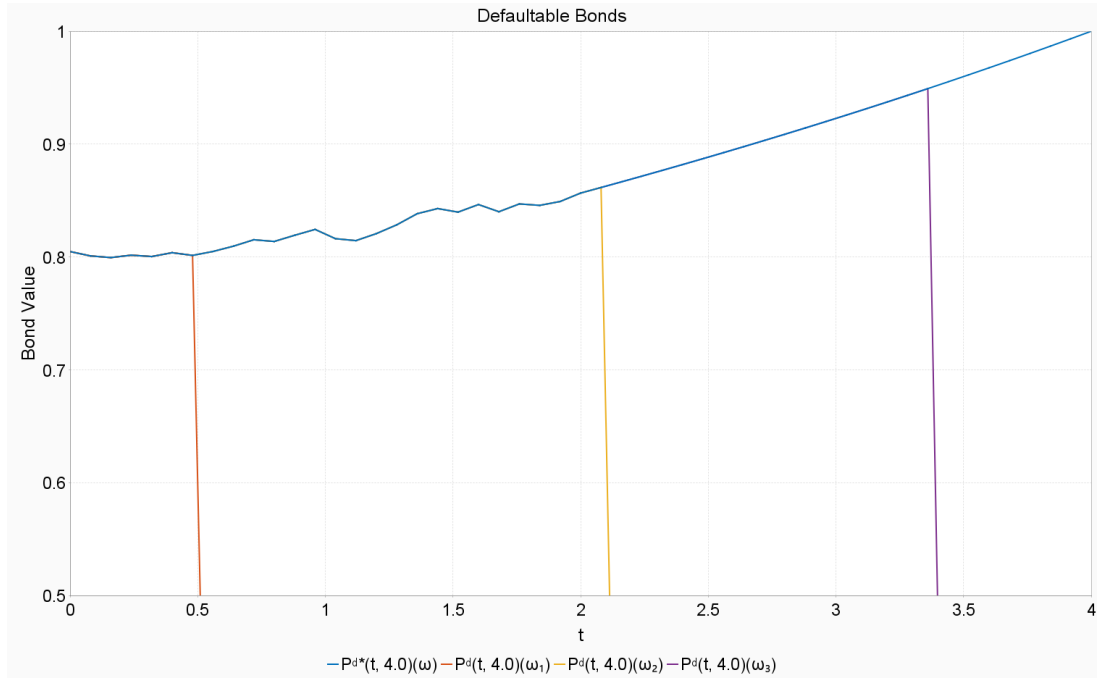


Figure 1: Paths of P^d

With this pathwise probability we will now be able to numerically price credits and credit derivatives.

5 Loans and Credit Option Pricing

A model is useless without a practical application for it. Therefore, we take a look at how to apply our results to pricing loans and credit options.

Note here, that the model is for use in numerical option pricing, so deriving prices in terms of an expectation over model primitives (directly simulated values or values that can be derived from these) is sufficient. We can then use Monte Carlo Methods to approximate the expectation.

Note that all model primitives are \mathbb{G} -adapted, as \mathbb{G} is the filtration over the only simulated stochastic processes (in our case the Brownian-Motion U). In this sense the default time/state is therefore not one of the model primitives.

5.1 General Application

In this short subsection, we will derive a general pricing methodology before moving to specific products.

Assume a T_i -claim X that has a payoff that is dependent on survival of the defaultable bonds. We can then use the pricing methodology described in the following lemma.

Lemma 5.1. *Let X be a payoff at $T_i \in \{T_1, \dots, T_N\}$, with*

$$X = X^S \mathbf{1}_{\{\tau(\omega) > T_i\}},$$

where X^S is the payoff conditional pre-default. Let X^S be \mathcal{G}_{T_i} -measurable.

Then the price at time $t = 0$ is

$$\Pi^X = \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbb{Q}^B (\{\tau(\omega) > T_i\} | \mathcal{G}_{T_i}) \right].$$

With this lemma and the pathwise survival probability derived in the last section, we can express the claim price in terms of model primitives. The proof for this statement is quite straightforward:

Proof. Note that X itself is not \mathcal{G}_{T_i} -measurable and $B(T_0) = 1$. We have:

$$\begin{aligned}
\Pi^X &= \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X}{B(T_i)} \right] = \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbf{1}_{\{\tau(\omega) > T_i\}} \right] \\
&= \mathbb{E}^{\mathbb{Q}^B} \left[\mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbf{1}_{\{\tau(\omega) > T_i\}} \right] \right] \\
&= \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbb{E}_{\mathcal{G}_{T_i}}^{\mathbb{Q}^B} [\mathbf{1}_{\{\tau(\omega) > T_i\}}] \right] \\
&= \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbb{Q}^B (\{\tau(\omega) > T_i\} | \mathcal{G}_{T_{i-1}}) \right],
\end{aligned}$$

where we used assumption 4.3 for the last equation. \square

This methodology can easily be extended to products where only parts of the payoff are dependent on survival and even where other parts are dependent on default:

Lemma 5.2. *Let X be a payoff at $T_i \in \{T_1, \dots, T_N\}$, with*

$$X = X^O + X^S \mathbf{1}_{\{\tau(\omega) > T_i\}} + X^D \mathbf{1}_{\{\tau(\omega) \leq T_i\}},$$

where the payoff X^O is unconditional, X^S is conditional pre-default and X^D is conditional past-default and all are \mathcal{G}_{T_i} -measurable.

Then the price at time $t = 0$ is

$$\begin{aligned}
\Pi^X &= \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^O}{B(T_i)} \right] + \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^S}{B(T_i)} \mathbb{Q}^B (\{\tau(\omega) > T_i\} | \mathcal{G}_{T_i}) \right] \\
&\quad + \mathbb{E}^{\mathbb{Q}^B} \left[\frac{X^D}{B(T_i)} (1 - \mathbb{Q}^B (\{\tau(\omega) > T_i\} | \mathcal{G}_{T_i})) \right].
\end{aligned}$$

Proof. The proof is similar to the proof above. \square

With these formulas we now have an expression for claim prices in terms of an expectation over model primitives. We can therefore move to more specific products now.

5.2 General Loan Pricing

Let us first take a look what a loan is in general. "A loan is a sum of money that one or more individuals or companies borrow from banks or other financial

institutions [...]. In doing so, the borrower incurs a debt, which he has to pay back with interest and within a given period of time.”[6].

In this sense a loan is nothing else than a fixed coupon bond, where the nominal N represents the debt and the coupons c_i represent the interest.

Elaborate!!!.

5.3 Credit Options

5.4 Introducing Behavioral Aspects

6 Implementation Details

The implementation of the described concepts are a crucial part of this thesis.

We use Java, which is a purely object oriented programming language, for having a good code readability while still performing very well. We assume a basic knowledge in Java. As build system we use Maven.

Before we can jump into any code, though, we need to describe ways to discretize a stochastic process.

6.1 Numerical Schemes for Stochastic Processes

In this chapter we introduce three ways to approach the simulation of stochastic processes described by SDEs. All of these numerical schemes can also be found in [4], which is also the main source of this section.

As basis for all our schemes we have a known SDE for a n -dimensional stochastic process $X = (X_t)_{t \in [0; \tilde{T}]}$ that we want to simulate:

$$\begin{aligned} dX_t &= \mu(t, X_t)dt + \sigma(t, X_t) \cdot dU_t, \\ X_0 &= x, \end{aligned} \tag{17}$$

where U is a d -dimensional standard Brownian Motion, $\mu : [0; \tilde{T}] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $\sigma : [0; \tilde{T}] \times \mathbb{R}^n \rightarrow \mathbb{R}^{n \times d}$ are functions and $x \in \mathbb{R}^n$.

Let us start with the well-known Euler or Euler-Maruyama scheme:

Definition 6.1. *Let $X = (X_t)_{t \in [0; \tilde{T}]}$ be as above in (17).*

Furthermore let $m \in \mathbb{N}$, $(t_i)_{i \in \{0, \dots, m\}}$, where $0 = t_0 < t_1 < \dots < t_m = \tilde{T}$.

Then we call the discrete process $\hat{X} = (\hat{X}_{t_i})_{i \in \{0, \dots, m\}}$, given by

$$\begin{aligned} \hat{X}_{t_0} &= x, \\ \hat{X}_{t_{i+1}} &= \hat{X}_{t_i} + \mu(t_i, \hat{X}_{t_i})\Delta t_i + \sigma(t_i, \hat{X}_{t_i}) \cdot \Delta U_{t_i}, \end{aligned}$$

where $i \in \{0, \dots, m-1\}$, an Euler-Maruyama scheme of X .

The Euler-Maruyama scheme takes the concept of approaching deterministic integrals and applies it on stochastic integrals. While this works quite well for

constant and deterministic factor loadings $\sigma(t_i, x) = \sigma(t_i)$ [Add source], it has a weakness for stochastic factor loadings.

An improvement is the Milstein scheme:

Definition 6.2. Let again $X = (X_t)_{t \in [0, \tilde{T}]}$ be as above in (17) and $m \in \mathbb{N}$, $(t_i)_{i \in \{0, \dots, m\}}$, where $0 = t_0 < t_1 < \dots < t_m = \tilde{T}$.

Then we call the discrete process $\hat{X} = (\hat{X}_{t_i})_{i \in \{0, \dots, m\}}$, given by

$$\begin{aligned} \hat{X}_{t_0} &= x, \\ \hat{X}_{t_{i+1}}^l &= \hat{X}_{t_i}^l + \mu(t_i, \hat{X}_{t_i}) \Delta t_i + \sigma(t_i, \hat{X}_{t_i}) \cdot \Delta U_{t_i} \\ &\quad + \frac{1}{2} \sum_{k=1}^d \sigma_k(t_i, \hat{X}_{t_i}) (\partial_{x^i} \sigma_k)(t_i, \hat{X}_{t_i}) ((\Delta U_{t_i}^k)^2 - \Delta t_i), \end{aligned}$$

where $i \in \{0, \dots, m-1\}$ and $l \in \{1, \dots, n\}$, a Milstein scheme of X .

This gives an improvement due to the correction term at the end. We can also easily see, that if σ is independent of X_t the Milstein is equal to the Euler-Maruyama scheme.

Another numerical scheme for the approximation of stochastic processes is the functional Euler Scheme:

Definition 6.3. Let $X = (X_t)_{t \in [0, \tilde{T}]}$ be as above in (17).

Let $Y = (Y_t)_{t \in [0, \tilde{T}]}$ have the property $Y_t = f(t, X_t) \quad \forall t \in [0, \tilde{T}]$ for a 2-times differentiable function $f : [0, \tilde{T}] \times \mathbb{R}^n \rightarrow \mathbb{R}^k$ and $k \in \mathbb{N}$.

Let $m \in \mathbb{N}$, $(t_i)_{i \in \{0, \dots, m\}}$, where $0 = t_0 < t_1 < \dots < t_m = \tilde{T}$. Let $\hat{X} = (\hat{X}_{t_i})_{i \in \{0, \dots, m\}}$ be an Euler-Maruyama scheme of X .

Then we call the discrete process $\hat{Y} = (\hat{Y}_{t_i})_{i \in \{0, \dots, m\}}$, given by

$$\hat{Y}_{t_i} = f(t, \hat{X}_{t_i}),$$

where $i \in \{0, \dots, m\}$, a functional Euler scheme of Y .

This scheme performs well in situations, where the factor loadings of X are less dependent on X , than the factor loadings of Y are on Y .

It is also very useful, if f preserves a property of Y which otherwise might be lost

through the numerical error of the other schemes (such as staying in a certain domain).

Considering this, the functional Euler scheme is great for the approximation of log-normal processes, as it cancels a part of the numerical error due to the dependency of the factor loadings on the approximated process and at the same time it preserves its' positivity.

Elaborate (i.e. error estimates and reference for proofs that these work)!!!.

6.2 The finMath Library

We can now start to look at the actual implementation.

As a starting point for the code base we use the finMath Library of Prof. Christian Fries.

The finMath library is written in Java and provides interfaces and classes for the use in stochastics and financial mathematics.

In this section we take a look at the ones that are most frequently used by our code. For a more thorough description one can use the website of the finMath library [3], which will also be our main source for this section.

RandomVariable

ProcessModel

The `ProcessModel` interface is the finMath equivalent of an SDE. It specifies that any implementation has methods for getting the drift and the factor loadings, which can then be used in other implementations e.g. for simulating the specified model.

LIBORCovarianceModel

MonteCarloProcess

6.3 Implementation of the Defaultable LIBOR Model

To use the full flexibility of the finMath Library, the implementation of our models is structured in the same way: we have an Interface for the defaultable LIBOR market model which extends the ProcessModel:

```
12 public interface DefaultableLIBORMarketModel extends LIBORMarketModel, ProcessModel {
```

Listing 1: Declaration of DefaultableLIBORMarketModel

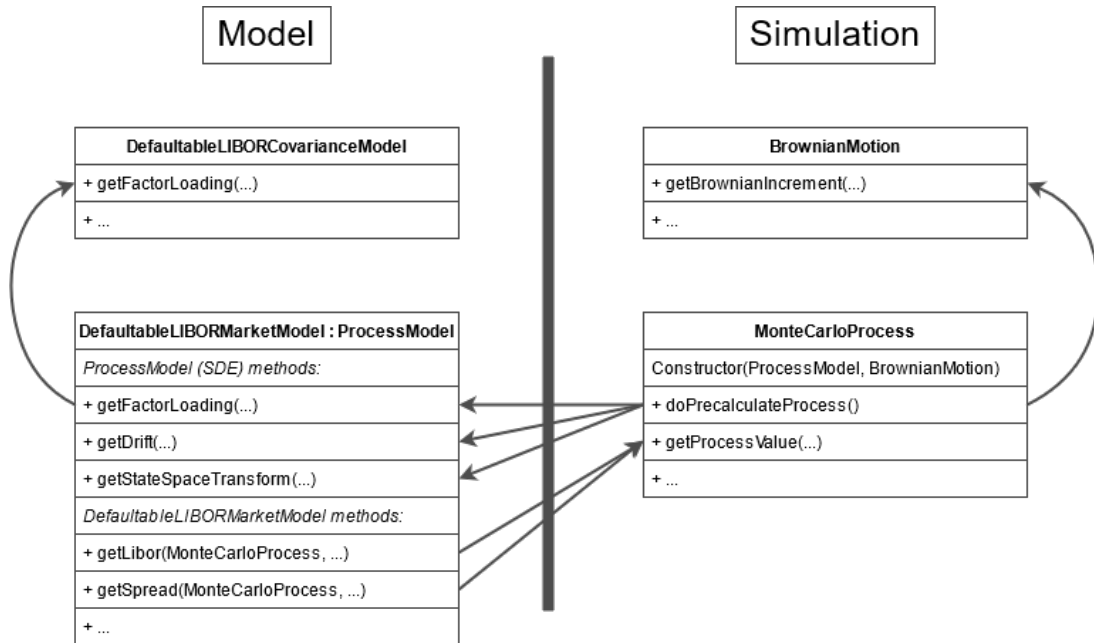


Figure 2: Using DefaultableLIBORMarketModel as Plug-In for MonteCarloProcess

Figure 2 shows how we can use classes implementing this interface: The DefaultableLIBORMarketModel can be used as a plug in for a class implementing the MonteCarloProcess interface, which calls SDE-methods of the ProcessModel to pre-calculate the process. Calls to getFactorLoading(...) should be delegated to the DefaultableLIBORCovarianceModel as we can then reuse the code of DefaultableLIBORMarketModel, even though creating different kinds of covariance (factor-loading-) models. When needed the process values are accessed by the DefaultableLIBORMarketModel through an

input parameter. We therefore have a clean separation of model specifications and simulation.

6.4 Valuation of Financial Products

7 List of Symbols

Annotation	Meaning
SDE	stochastic differential equation
w.r.t.	with respect to
\mathbb{Q}^B	martingale measure w.r.t. the numeraire $B(t)$
$m(t)$	For a tenor $T_0 < \dots < T_N$, $m(t) := \max\{i \in \{0, \dots, N-1\} \mid T_i \leq t\}$
$(\partial_x f)(x)$	Same as $\frac{\partial}{\partial x} f(x)$.
$(\partial_{xy} f)(x, y)$	Same as $\frac{\partial^2}{\partial x \partial y} f(x, y)$.
$\mathbb{E}_{\mathcal{G}}^{\mathbb{Q}^B} [\cdot]$	Same as $\mathbb{E}^{\mathbb{Q}^B} [\cdot \mid \mathcal{G}]$. for a σ -algebra \mathcal{G}

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Ehrenwörtliche Erklärung

Ich erkläre hiermit ehrenwörtlich, dass ich die vorliegende Arbeit selbständig angefertigt habe; die aus fremden Quellen direkt oder indirekt übernommenen Gedanken sind als solche kenntlich gemacht.

Die Arbeit wurde bisher keiner anderen Prüfungsbehörde vorgelegt und auch noch nicht veröffentlicht.

Ort, Datum

Unterschrift