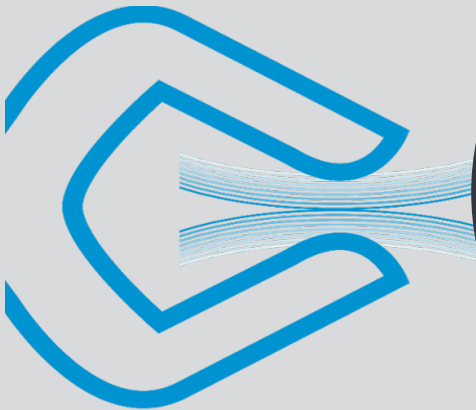




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THE UNIVERSITY OF
AUCKLAND
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NEW ZEALAND



DFG IRTG GRK2198/1

Soft Tissue Robotics

Design and implementation of a teleoperated drawing robot

26 March 2019

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Setup description

Concept and realization

Results

Conclusion

- Say why our task is important
- ...



Figure: Robotic teleoperation in an everyday scenario. Picture taken from the SitCom “The Big Bang Theory”

- Define goal set for the demonstrator week here
- ...

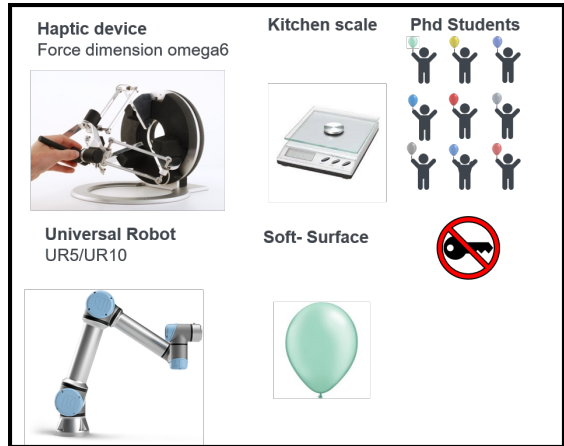


Figure: Original concept for the 2019 summer school demonstrator

- Here goes the description of the involved problems
- Force feedback from soft tissue
- control for the system
- sensor
- communication and interfaces
- ...

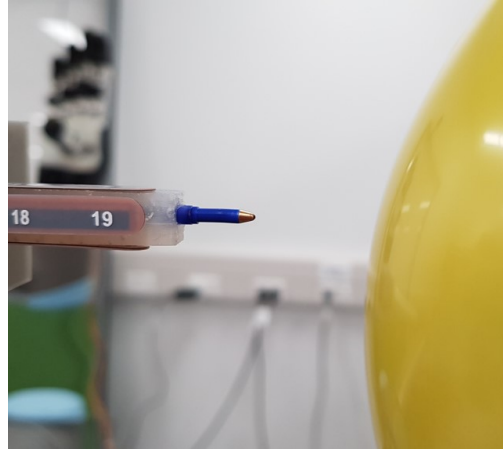


Figure: Balloon and pen during a drawing task. The pointy tip of the pen threatens to burst the balloon.

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Figure of the overall concept ...



Explain how the sensors were developed and their working principle



Explain the communication with MQTT Broker - IoT Style



Explain the control logic and how the robot is teleoperated

Setup description

Concept and realization

Results

Conclusion



Show video of the teleoperated robot motion here ...



Show video of the force feedback to the haptic device here ...



Show video/results of teleoperated drawig ...

Setup description

Concept and realization

Results

Conclusion



Come up with some conclusions here ...

Thank you!



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Say thanks to the PIs here ...