

CS 5720 Design and Analysis of Algorithms  
Homework #8

**Submission requirements:**

- Submit your work in PDF format to the appropriate assignment on Canvas.
- **5% extra credit** if your writeup is *typed*.

**Assignment:**

1. *Comparing Minimum Spanning Tree Algorithms:* In class we went over two algorithms which find the minimum spanning tree of a weighted, connected graph. In this exercise, you will compare the worst-case time efficiencies of these algorithms using various graph and data structure representations.
  - (a) **Show that Prim's Algorithm has  $\Theta(|V|^2)$  time complexity** when the graph is represented by a weight matrix and the priority queue is implemented as an un-ordered array (that is, if the queue has  $n$  items, inserting **and updating** are  $\Theta(1)$  but deleting is  $\Theta(n)$ ). (Hint: you might find it useful to refer to the book's pseudocode for Dijkstra's algorithm; this pseudocode shows the priority queue operations explicitly)
  - (b) **Show that Prim's Algorithm has  $\Theta(|E| \log |V|)$  time complexity** when the graph is represented by adjacency lists and the priority queue is implemented as a min-heap (that is, if the queue has  $n$  items, inserting, updating, and deleting are all  $\Theta(\log n)$ ). (Hint: you might find it useful to refer to the book's pseudocode for Dijkstra's algorithm; this pseudocode shows the priority queue operations explicitly)

Now, Kruskal's algorithm can be as fast as  $\Theta(|E| \log |E|)$  when the graph is represented by adjacency lists and a fast sorting algorithm is used to sort the edge weights (to be precise, this also requires another optimization which the book explains in the section "Disjoint Subsets and Union-Find Algorithms; read that section if you're interested). So we have this list:

- $\Theta(|V|^2)$ : Prim with weight matrix and un-ordered array.
  - $\Theta(|E| \log |V|)$ : Prim with adjacency lists and min-heap.
  - $\Theta(|E| \log |E|)$ : Kruskal with adjacency lists and fast sort.
- (c) A graph that has few edges is called *sparse*, and has  $|E| \in \Theta(|V|)$ . **Which of the above combinations of algorithms and data structures is asymptotically fastest for finding a MST in a sparse graph?**
  - (d) What about a graph that has a moderate number of edges with  $|E| \in \Theta(|V| \log |V|)$ ? **Which of the above combinations of algorithms and data structures is asymptotically fastest for finding a MST in this type of graph?**
  - (e) A graph that has many edges is called *dense*, and has  $|E| \in \Theta(|V|^2)$ . **Which of the above combinations of algorithms and data structures is asymptotically fastest for finding a MST in a dense graph?**