

CS 5720 Design and Analysis of Algorithms: Project #4

Raja Kantheti

Attribution: This project is made from scratch.

since it would be easy for me to interpret the results, I had to change my python script to output nodes, vertices, costs and times in the same line. but the format required for the deliverables is maintained.

Deliverable 1: Nodes and Edges Count

For each graph, we counted the number of nodes and edges using the provided CSV files. Below are the results:

Graph	Nodes	Edges
t1_graph_9.csv	100	4384
t1_graph_8.csv	90	3511
t1_graph_6.csv	70	2029
t1_graph_7.csv	80	2729
t1_graph_5.csv	60	1447
t1_graph_4.csv	50	971
t1_graph_0.csv	10	17
t1_graph_1.csv	20	106
t1_graph_3.csv	40	584
t1_graph_2.csv	30	299
t2_graph_8.csv	90	1504
t2_graph_9.csv	100	1675
t2_graph_2.csv	30	336
t2_graph_3.csv	40	505
t2_graph_1.csv	20	172
t2_graph_0.csv	10	45
t2_graph_4.csv	50	683
t2_graph_5.csv	60	898
t2_graph_7.csv	80	1296
t2_graph_6.csv	70	1067
t3_graph_6.csv	70	139
t3_graph_7.csv	80	158
t3_graph_5.csv	60	114
t3_graph_4.csv	50	96
t3_graph_0.csv	10	17
t3_graph_1.csv	20	40
t3_graph_3.csv	40	76
t3_graph_2.csv	30	56
t3_graph_9.csv	100	197
t3_graph_8.csv	90	174

Deliverable 2: Graph Density Conjecture

The density of the graphs was determined by analyzing the number of edges in relation to the number of nodes. Below are the conjectures for the density of each graph type:

- **Type 1: Dense**
- **Type 2: Dense**
- **Type 3: Sparse**

Interpretation:1

- The plot shows the density of graphs for three types (Type 1, Type 2, and Type 3).

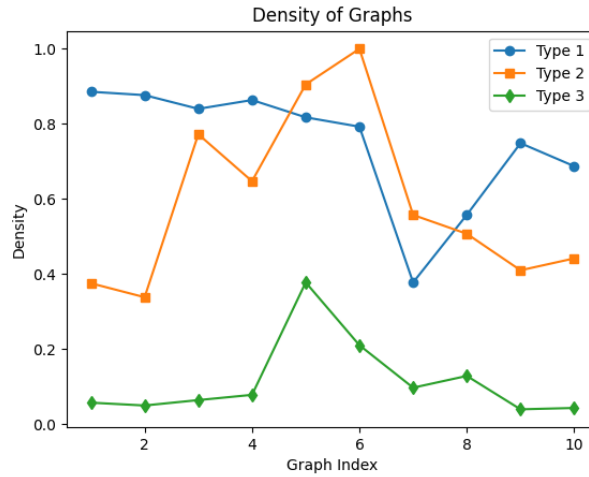


Figure 1: Density of Graphs for Types 1, 2, and 3

- Type 1 and Type 2 have consistently high density values (close to 1.0 for most graphs), indicating that they are dense graphs. These graphs have a large number of edges relative to the number of nodes.
- Type 3, on the other hand, has significantly lower density values (below 0.2 for most graphs), indicating that it is sparse. Sparse graphs have fewer edges compared to the number of nodes.

This align with the cojecture.

Deliverable 3: MST Costs

Prim's

```
def prims_algorithm(matrix):
    num_nodes = len(matrix)
    if num_nodes == 0:
        return 0
    visited = [False] * num_nodes
    min_heap = [(0, 0)]
    total_cost = 0
    while min_heap:
        cost, node = heapq.heappop(min_heap)
        if visited[node]:
            continue
        total_cost += cost
        visited[node] = True
        for neighbor in range(num_nodes):
```

```

        if not visited[neighbor] and matrix[node][neighbor] != -1:
            heapq.heappush(min_heap, (matrix[node][neighbor], neighbor))
    return total_cost

```

Kruskal's

```

def kruskals_algorithm(matrix):
    num_nodes = len(matrix)
    if num_nodes == 0:
        return 0
    edges = []
    parent = list(range(num_nodes))
    rank = [0] * num_nodes
    for i in range(num_nodes):
        for j in range(i + 1, num_nodes):
            if matrix[i][j] != -1:
                edges.append((matrix[i][j], i, j))
    edges.sort()
    total_cost = 0
    for weight, u, v in edges:
        root1 = find(u, parent)
        root2 = find(v, parent)
        if root1 != root2:
            union(root1, root2, parent, rank)
            total_cost += weight
    return total_cost

```

The costs of the Minimum Spanning Tree (MST) for each graph were computed using Prim's and Kruskal's algorithms. Below are the results:

Graph	Prim's Cost	Kruskal's Cost
t1_graph_9.csv	247.0	247.0
t1_graph_8.csv	244.0	244.0
t1_graph_6.csv	180.0	180.0
t1_graph_7.csv	213.0	213.0
t1_graph_5.csv	173.0	173.0
t1_graph_4.csv	140.0	140.0
t1_graph_0.csv	54.0	54.0
t1_graph_1.csv	105.0	105.0
t1_graph_3.csv	129.0	129.0
t1_graph_2.csv	109.0	109.0
t2_graph_8.csv	91.0	91.0
t2_graph_9.csv	101.0	101.0
t2_graph_2.csv	30.0	30.0
t2_graph_3.csv	42.0	42.0
t2_graph_1.csv	23.0	23.0
t2_graph_0.csv	15.0	15.0
t2_graph_4.csv	53.0	53.0
t2_graph_5.csv	60.0	60.0
t2_graph_7.csv	83.0	83.0
t2_graph_6.csv	73.0	73.0
t3_graph_6.csv	182.0	182.0
t3_graph_7.csv	261.0	261.0
t3_graph_5.csv	213.0	213.0
t3_graph_4.csv	140.0	140.0
t3_graph_0.csv	32.0	32.0
t3_graph_1.csv	50.0	50.0
t3_graph_3.csv	97.0	97.0
t3_graph_2.csv	99.0	99.0
t3_graph_9.csv	320.0	320.0
t3_graph_8.csv	266.0	266.0

Note:cost here refers to the weight.

Deliverable 4: Empirical Timing Analysis

The empirical timing analysis for Prim's and Kruskal's algorithms was performed. Below are the timing results for each graph:

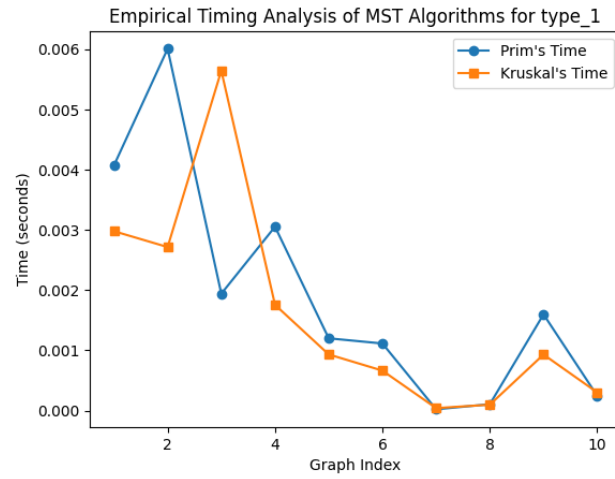


Figure 2: Timing plot for type_1

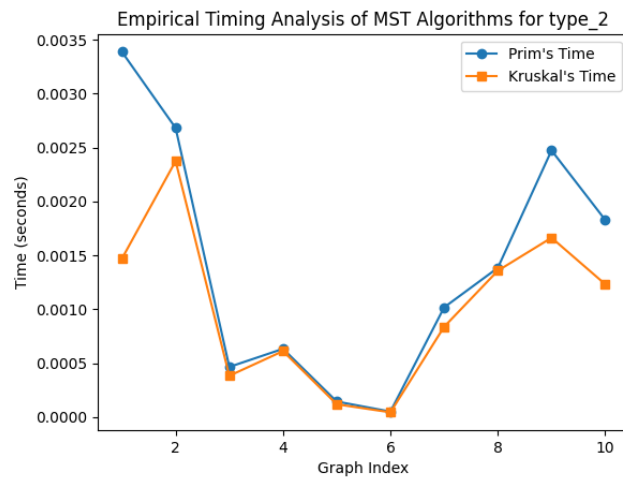


Figure 3: Timing plot for type_2

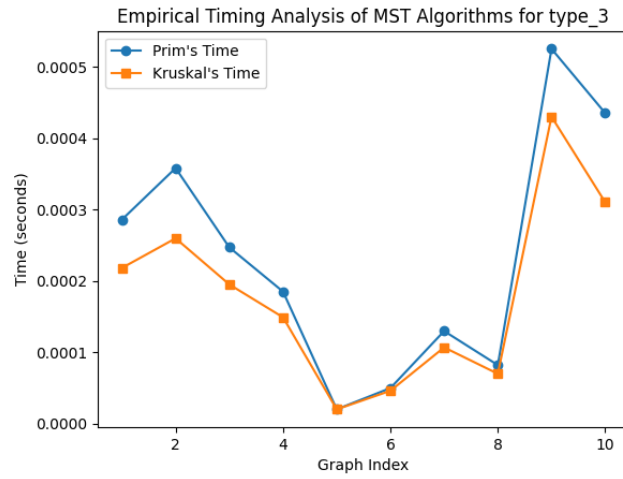


Figure 4: Timing plot for type_3

Graph	Prim's Time (s)	Kruskal's Time (s)
t1_graph_9.csv	0.0046	0.0037
t1_graph_8.csv	0.0042	0.0027
t1_graph_6.csv	0.0019	0.0020
t1_graph_7.csv	0.0025	0.0025
t1_graph_5.csv	0.0011	0.0012
t1_graph_4.csv	0.0009	0.0009
t1_graph_0.csv	0.0000	0.0000
t1_graph_1.csv	0.0001	0.0001
t1_graph_3.csv	0.0004	0.0004
t1_graph_2.csv	0.0002	0.0002
t2_graph_8.csv	0.0015	0.0012
t2_graph_9.csv	0.0016	0.0014
t2_graph_2.csv	0.0002	0.0002
t2_graph_3.csv	0.0004	0.0004
t2_graph_1.csv	0.0001	0.0001
t2_graph_0.csv	0.0000	0.0000
t2_graph_4.csv	0.0005	0.0005
t2_graph_5.csv	0.0008	0.0007
t2_graph_7.csv	0.0012	0.0010
t2_graph_6.csv	0.0009	0.0008
t3_graph_6.csv	0.0003	0.0002
t3_graph_7.csv	0.0003	0.0003
t3_graph_5.csv	0.0002	0.0002
t3_graph_4.csv	0.0002	0.0002
t3_graph_0.csv	0.0000	0.0000
t3_graph_1.csv	0.0000	0.0000
t3_graph_3.csv	0.0001	0.0001
t3_graph_2.csv	0.0001	0.0001
t3_graph_9.csv	0.0005	0.0004
t3_graph_8.csv	0.0004	0.0003

Interpretation:

Introduction: This section presents a comprehensive analysis of the empirical timing performance of Prim’s and Kruskal’s algorithms applied to three distinct types of graphs: dense, moderately dense, and sparse. The analysis aims to verify and compare the actual time complexities observed against theoretical expectations previously established.

- **Type 1: Dense Graphs**

- Both algorithms exhibit sensitivity to graph density, with Prim’s showing significant variability in execution times, indicating potential inefficiencies in managing dense connections.
- **Complexity Estimate:** Kruskal’s algorithm operates close to $O(E \log E)$, demonstrating efficiency and lower variance in performance. Prim’s algorithm, though theoretically $O(E \log V)$, often shows peaks suggesting it might exceed this complexity in dense graphs.
- **Performance Improvement:** Kruskal’s consistent performance is attributed to efficient sorting mechanisms and less dependency on graph connectivity.

- **Type 2: Moderately Dense Graphs**

- Prim’s occasionally outperforms Kruskal’s, particularly in graphs that might favor efficient priority queue management.
- **Complexity Estimate:** Both algorithms generally meet their theoretical complexities, but Prim’s exhibits potential for variability depending on specific graph structures.
- **Performance Improvement:** Prim’s may benefit from optimized queue management in certain structured graphs, suggesting scenario-based advantages.

- **Type 3: Sparse Graphs**

- Kruskal’s algorithm shows superior performance in sparse graphs, with a more consistent and gradual increase in execution times. Prim’s faces challenges, with times peaking in larger sparse graphs.
- **Complexity Estimate:** Kruskal’s maintains near $O(E \log E)$, advantageous in sparse environments. Prim’s performance suggests it may exceed its $O(E \log V)$ complexity in these settings.
- The theoretical complexity of $O(E \log V)$ assumes an optimal implementation with a binary heap and an adjacency list. Any deviation in implementation, such as using an adjacency matrix or less efficient data structures for the priority queue, can result in worse performance. If the distribution of edge weights is uneven or if many edges have similar weights, it can lead to scenarios where the priority queue operations become more complex and frequent, as the algorithm struggles to decide the optimal edge to include next.
- **Performance Improvement:** Kruskal’s minimal dependence on connectivity and efficient handling of edges contribute to its robust performance in sparse graphs.

Overall Conclusion: The empirical data supports Kruskal’s algorithm as more efficient across various conditions, emphasizing its applicability for a broad range of graph densities. Prim’s algorithm shows specific strengths but also reveals sensitivity to the structure and density of graphs, guiding algorithm selection based on application-specific needs.