Spring 2020 MAT303 Recitations

Week of 4/20/20: Sections 4.1 and 4.2

A system of differential equation consists of a finite collection of differential equations in indeterminates $x_1(t), x_2(t), \dots, x_n(t)$, depending on a parameter t. In this chapter, we will deal with linear systems.

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One's first encounter wiht systems of differential equations arises from higher-order scalar equations. One way of solving them is by reducing such equations to systems of first-order problems, as we shall see next. .

This example is extracted from problem 4.1.3 in our textbook. Consider the third-order equation

$$tx^{(3)} - 2t^2x'' + 3tx' + 5x = \ln(t)$$

By using the substitutions $x_1 = x$, $x_2 = x^{'}$, $x_3 = x^{''}$, we can rewrite this equation as a system in three variables

$$tx_{3}^{'} - 2t^{2}x_{3} + 3tx_{2} + 5x_{1} = \ln(t)$$

 $x_{2}^{'} = x_{3}$
 $x_{1}^{'} = x_{2}$

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To solve for y, we use the first equation in our system,

$$y(t) = x'(t)$$

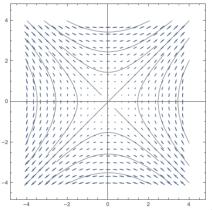
= $-A\sin(t) + B\cos(t)$.

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Below is a plot of the slope field for this equation, with several solution curves outlined.



In this example, extracted from problem 4.1.23, we have the system

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The characteristic polynomail of this equation is $r^2 + r - 6r = (r - 2)(r + 3)$, with roots r = 2, r = -3. The general solution takes the form

$$x(t) = Ae^{2t} + Be^{-3t}$$

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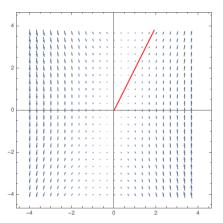
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whose solutions are A = 1, B = 0. As a result, $x(t) = e^{2t}$, and

$$y(t) = x'(t) = 2e^{2t}$$

Below is a plot of the direction field, as well as the solution curve corresponding to the given initial condition (in red).



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By adding the two equations we find

$$(D-1)(D+3)x + 8x = 0,$$

which in usual notation for derivatives is

$$(D-1)(D+3)x + 8x = 0$$

$$(D-1)(x'+3x) + 8x = 0$$

$$(x'+3x)' - (x'+3x) + 8x = 0$$

$$x'' + 3x' - x' - 3x + 8x = 0$$

$$x'' + 2x' + 5x = 0$$

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To find the solution y(t) we may use the first equation of the system,

$$y(t) = -\frac{x' + 3x}{4}$$

$$= -\frac{e^{-t}[(2B - A)\cos(2t) - (2A + B)\sin(2t)] + 3e^{-t}(A\cos(2t) + B)}{4}$$

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