Spring 2020 MAT303 Recitations

Week of 4/6/20: Sections 3.4 and 3.5

Problems in this section deal with second-order differential equations of type

$$mx''(t) + cx'(t) + kx(t) = F(t),$$

Problems in this section deal with second-order differential equations of type

$$mx''(t) + cx'(t) + kx(t) = F(t),$$

where m, c, k are constants $(m \neq 0)$.

Problems in this section deal with second-order differential equations of type

$$mx''(t) + cx'(t) + kx(t) = F(t),$$

where m, c, k are constants $(m \neq 0)$. In today's recitation, we will discuss a few examples of such equations.

The first few homework problems deal with homogeneous equations.

The first few homework problems deal with homogeneous equations. We learned how to express solutions as combinations of sines, cosines, and exponentials in the last section, but now we adopt a different convention regarding trigonometric representations.

The first few homework problems deal with homogeneous equations. We learned how to express solutions as combinations of sines, cosines, and exponentials in the last section, but now we adopt a different convention regarding trigonometric representations. We will write

$$A\cos(\omega_1 t) + B\sin(\omega_1 t) = C\cos(\omega_1 t - \alpha),$$

The first few homework problems deal with homogeneous equations. We learned how to express solutions as combinations of sines, cosines, and exponentials in the last section, but now we adopt a different convention regarding trigonometric representations. We will write

$$A\cos(\omega_1 t) + B\sin(\omega_1 t) = C\cos(\omega_1 t - \alpha),$$

where

• $C = \sqrt{A^2 + B^2}$ the amplitude;

The first few homework problems deal with homogeneous equations. We learned how to express solutions as combinations of sines, cosines, and exponentials in the last section, but now we adopt a different convention regarding trigonometric representations. We will write

$$A\cos(\omega_1 t) + B\sin(\omega_1 t) = C\cos(\omega_1 t - \alpha),$$

where

- $C = \sqrt{A^2 + B^2}$ the amplitude;
- $\omega_1 = \frac{\sqrt{4cm-k^2}}{2m}$ is the relative frequency;

The first few homework problems deal with homogeneous equations. We learned how to express solutions as combinations of sines, cosines, and exponentials in the last section, but now we adopt a different convention regarding trigonometric representations. We will write

$$A\cos(\omega_1 t) + B\sin(\omega_1 t) = C\cos(\omega_1 t - \alpha),$$

where

- $C = \sqrt{A^2 + B^2}$ the amplitude;
- $\omega_1 = \frac{\sqrt{4cm-k^2}}{2m}$ is the relative frequency;
- $\alpha \in [0, 2\pi)$ is the phase, so that $\cos(\alpha) = \frac{A}{C}$ and $\sin(\alpha) = \frac{B}{C}$.

Problem 3.4.4 concerns the movement of a mass-spring system, with:

Problem 3.4.4 concerns the movement of a mass-spring system, with:

- m = 250g = 0.25kg
- k = 9N/0.25m = 36N/m.
- at t = 0s, x(0) = 1m, x'(0) = -5m/s.

The movement of the system is described by the equation

$$0.25x'' + 36x = 0 \Leftrightarrow x'' + 144x = 0,$$

Problem 3.4.4 concerns the movement of a mass-spring system, with:

- m = 250g = 0.25kg
- k = 9N/0.25m = 36N/m.
- at t = 0s, x(0) = 1m, x'(0) = -5m/s.

The movement of the system is described by the equation

$$0.25x'' + 36x = 0 \Leftrightarrow x'' + 144x = 0,$$

thus the relative frequency is $\omega = 12$.

Problem 3.4.4 concerns the movement of a mass-spring system, with:

- m = 250g = 0.25kg
- k = 9N/0.25m = 36N/m.
- at t = 0s, x(0) = 1m, x'(0) = -5m/s.

The movement of the system is described by the equation

$$0.25x'' + 36x = 0 \Leftrightarrow x'' + 144x = 0,$$

thus the relative frequency is $\omega=\mbox{12}.$ A solution can be written in form

$$x(t) = C\cos(12t - \alpha),$$

for constants C > 0, $\alpha \in [0, 2\pi)$ to be determined.



Finding these constants amounts to using the initial conditions.

Finding these constants amounts to using the initial conditions.

From
$$x(0) = 1$$
, $x'(0) = -5$, we obtain

$$C\cos(\alpha) = 1$$
, $C\sin(\alpha) = -\frac{5}{12}$,

Finding these constants amounts to using the initial conditions.

From
$$x(0) = 1$$
, $x'(0) = -5$, we obtain

$$C\cos(\alpha) = 1$$
, $C\sin(\alpha) = -\frac{5}{12}$,

thus
$$C = \sqrt{1 + \left(\frac{5}{12}\right)^2} = \frac{13}{12}$$
.

Finding these constants amounts to using the initial conditions. From x(0) = 1, x'(0) = -5, we obtain

$$C\cos(\alpha) = 1$$
, $C\sin(\alpha) = -\frac{5}{12}$,

thus $C=\sqrt{1+\left(\frac{5}{12}\right)^2}=\frac{13}{12}.$ The value of α (in radians) that satisfies the constraints above is found by calculator:

$$\alpha \approx$$
 5.89.

Thus

$$x(t) \approx \frac{13}{12}\cos(12t - 5.89).$$

Finding these constants amounts to using the initial conditions. From x(0) = 1, x'(0) = -5, we obtain

$$C\cos(\alpha) = 1$$
, $C\sin(\alpha) = -\frac{5}{12}$,

thus $C=\sqrt{1+\left(\frac{5}{12}\right)^2}=\frac{13}{12}.$ The value of α (in radians) that satisfies the constraints above is found by calculator:

$$\alpha \approx$$
 5.89.

Thus

$$x(t) \approx \frac{13}{12}\cos(12t - 5.89).$$

Amplitude: $A = \frac{13}{12}$ meters. Period: $T = \frac{2\pi}{12} = \frac{\pi}{6}$ seconds.



In problem 3.4.14, we have a mass-spring-dashpot system with constants

$$m = 25, c = 10, k = 226,$$

and initial data x(0) = 20, x'(0) = 41.

In problem 3.4.14, we have a mass-spring-dashpot system with constants

$$m = 25, c = 10, k = 226,$$

and initial data x(0) = 20, x'(0) = 41. Its characteristic polynomial is

$$25r^2 + 10r + 226 = (5r + 1)^2 + 15^2$$

whose roots are

$$r=-\frac{1}{5}\pm 3i.$$

In problem 3.4.14, we have a mass-spring-dashpot system with constants

$$m = 25, c = 10, k = 226,$$

and initial data x(0) = 20, x'(0) = 41. Its characteristic polynomial is

$$25r^2 + 10r + 226 = (5r + 1)^2 + 15^2$$

whose roots are

$$r=-\frac{1}{5}\pm 3i.$$

Solutions to the differential equation take the form

$$x(t) = Ce^{-\frac{t}{5}}\cos(3t - \alpha).$$

To use the initial data, we compute the first derivative,

$$x'(t) = -Ce^{-\frac{t}{5}} \left[\frac{\cos(3t - \alpha)}{5} + 3\sin(3t - \alpha) \right],$$

To use the initial data, we compute the first derivative,

$$x'(t) = -Ce^{-\frac{t}{5}} \left[\frac{\cos(3t - \alpha)}{5} + 3\sin(3t - \alpha) \right],$$

hence

$$C\cos(\alpha) = 20$$

$$C\left[-\frac{\cos(\alpha)}{5} + 3\sin(\alpha)\right] = 41,$$

To use the initial data, we compute the first derivative,

$$x'(t) = -Ce^{-\frac{t}{5}}\left[\frac{\cos(3t-\alpha)}{5} + 3\sin(3t-\alpha)\right],$$

hence

$$C\cos(\alpha) = 20$$

$$C\left[-\frac{\cos(\alpha)}{5} + 3\sin(\alpha)\right] = 41,$$

from which we infer C=25, $lpha\approx 0.64$, so

$$x(t) \approx 25e^{-\frac{t}{5}}\cos(3t - 0.64).$$

In problem 3.4.17, we are meant to contrast the damped motion of a spring-mass-dashpot system with its undamped counterpart.

In problem 3.4.17, we are meant to contrast the damped motion of a spring-mass-dashpot system with its undamped counterpart. The differential equation modelling this problem is

$$x'' + 8x' + 16x = 0,$$

In problem 3.4.17, we are meant to contrast the damped motion of a spring-mass-dashpot system with its undamped counterpart. The differential equation modelling this problem is

$$x'' + 8x' + 16x = 0,$$

with initial data x(0) = 5, x'(0) = -10.

The characteristic polynomial of the problem is

$$r^2 + 8r + 16 = (r+4)^2$$
.

Its root is -4, with multiplicity 2, thus this motion is critically damped.

A solution takes the form

$$x(t)=e^{-4t}(At+B),$$

A solution takes the form

$$x(t)=e^{-4t}(At+B),$$

and has derivative

$$x'(t) = e^{-4t}(-4At + A - 4B).$$

A solution takes the form

$$x(t) = e^{-4t}(At + B),$$

and has derivative

$$x'(t) = e^{-4t}(-4At + A - 4B).$$

Subject to initial conditions x(0) = 5, x'(0) = -10, we find

$$x(t) = e^{-4t}(2t+1).$$

The equation that models undamped motion is

$$u^{''}(t) + 16u(t) = 0.$$

The equation that models undamped motion is

$$u^{''}(t) + 16u(t) = 0.$$

Its solutions take the form

$$u(t) = C\cos(4t - \alpha).$$

The equation that models undamped motion is

$$u^{''}(t) + 16u(t) = 0.$$

Its solutions take the form

$$u(t) = C\cos(4t - \alpha).$$

Assuming the same initial conditions u(0) = 5, u'(0) = -10, we have

$$u(t) \approx \frac{5\sqrt{5}}{2}\cos(4t - 5.82)$$

In problem 3.4.31, we have a mass-spring-dashpot system with constants m=1, c=10 and k=125, subject to initial conditions x(0)=6, x'(0)=50. The characteristic polynomial of the system is

$$r^2 + 10r + 125 = (r+5)^2 + 10^2$$
,

whose roots are $r=-5\pm 10i$, characterizing underdamped motion. The corresponding solution to the differential equation is

$$x(t) = Ce^{-5t}\cos(10t - \alpha),$$

for constants C > 0, $\alpha \in [0, 2\pi)$ to be determined in what follows.

The first derivative of the solution takes the form

$$x^{'}(t) = Ce^{-5t}[-5\cos(10t - \alpha) - 10\sin(10t - \alpha)].$$

The first derivative of the solution takes the form

$$x^{'}(t) = Ce^{-5t}[-5\cos(10t - \alpha) - 10\sin(10t - \alpha)].$$

The initial conditions amount to

$$C\cos(\alpha) = 6,$$

$$C[-10\cos(\alpha) - 5\sin(\alpha)] = 50,$$

The first derivative of the solution takes the form

$$x^{'}(t) = Ce^{-5t}[-5\cos(10t - \alpha) - 10\sin(10t - \alpha)].$$

The initial conditions amount to

$$C\cos(\alpha) = 6,$$

$$C[-10\cos(\alpha) - 5\sin(\alpha)] = 50,$$

from which we infer $C=10,~\alpha\approx0.93.$ The solution is thus approximated by

$$x(t) \approx 10e^{-5t}\cos(10t - 0.93).$$

We will constrast this to solutions of the undamped motion, modelled by the equation

$$u''+125u=0.$$

We will constrast this to solutions of the undamped motion, modelled by the equation

$$u'' + 125u = 0.$$

The characteristic polynomial is $p(r) = r^2 + 125$, with roots $r = \pm 5\sqrt{5}i$. Solutions to this equation can be expressed as

$$u(t) = C_* \cos(5\sqrt{5}t - \alpha_*),$$

We will constrast this to solutions of the undamped motion, modelled by the equation

$$u'' + 125u = 0.$$

The characteristic polynomial is $p(r) = r^2 + 125$, with roots $r = \pm 5\sqrt{5}i$. Solutions to this equation can be expressed as

$$u(t) = C_* \cos(5\sqrt{5}t - \alpha_*),$$

where the constants $C_* > 0$ and $\alpha_* \in [0, 2\pi)$ are determined by the initial conditions u(0) = 6, u'(0) = 50.

The derivative of a solution takes the form

$$u'(t) = -5\sqrt{5}C_*\sin(5\sqrt{5}t - \alpha_*),$$

The derivative of a solution takes the form

$$u'(t) = -5\sqrt{5}C_*\sin(5\sqrt{5}t - \alpha_*),$$

so using the initial date we obtain

$$C\cos(\alpha_*) = 6$$
$$5\sqrt{5}C_*\sin(\alpha_*) = 50,$$

The derivative of a solution takes the form

$$u'(t) = -5\sqrt{5}C_*\sin(5\sqrt{5}t - \alpha_*),$$

so using the initial date we obtain

$$C\cos(\alpha_*) = 6$$
$$5\sqrt{5}C_*\sin(\alpha_*) = 50,$$

and infer $C_*=2\sqrt{14}$, $\alpha_*\approx$ 0.64. Finally, we motion of the undamped system is

$$u(t) \approx 2\sqrt{14}\cos(5\sqrt{5}t - 0.64).$$

In problem 3.5.3, we consider the equation

$$y'' - y' - 6y = 2\sin(3x).$$
 (1)

In problem 3.5.3, we consider the equation

$$y'' - y' - 6y = 2\sin(3x). (1)$$

The associated homogeneous equation has characteristic polynomial

$$r^2 - r - 6 = (r+2)(r-3),$$

In problem 3.5.3, we consider the equation

$$y'' - y' - 6y = 2\sin(3x). (1)$$

The associated homogeneous equation has characteristic polynomial

$$r^2 - r - 6 = (r+2)(r-3),$$

with roots $r_1 = -2$, $r_2 = 3$. The corresponding solutions to the complementary equation take the form

$$y_c = A_1 e^{-2x} + A_2 e^{3x}$$
.

As the solutions to the homogeneous problem and the inhomogeneous term of equation (1) are linearly independent (verify!), we can use the method of undetermined coefficients to guess a particular solution of the form

$$y_p = C_1 \sin(3x) + C_2 \cos(3x).$$

As the solutions to the homogeneous problem and the inhomogeneous term of equation (1) are linearly independent (verify!), we can use the method of undetermined coefficients to guess a particular solution of the form

$$y_p = C_1 \sin(3x) + C_2 \cos(3x).$$

To find the coefficients C_1 , C_2 , we need to compute the derivatives of the particular solution,

$$y_{p}^{'} = 3C_{1}\cos(3x) - 3C_{2}\sin(3x),$$

$$y_{p}^{''} = -9C_{1}\sin(3x) - 9C_{2}\cos(3x).$$

Combining all of this data into the equation we get

$$(-15C_1+3C_2)\sin(3x)+(-3C_1-15C_2)\cos(3x)=2\sin(3x),$$

Combining all of this data into the equation we get

$$(-15C_1 + 3C_2)\sin(3x) + (-3C_1 - 15C_2)\cos(3x) = 2\sin(3x),$$

from which we infer $C_1=-rac{5}{39}$, $C_2=rac{1}{39}$.

Combining all of this data into the equation we get

$$(-15C_1 + 3C_2)\sin(3x) + (-3C_1 - 15C_2)\cos(3x) = 2\sin(3x),$$

from which we infer $C_1=-\frac{5}{39}$, $C_2=\frac{1}{39}$. A general solution to the differential equation takes the form

$$y(x) = A_1 e^{-2x} + A_2 e^{3x} - \frac{5}{39} \sin(3x) + \frac{1}{39} \cos(3x),$$

Combining all of this data into the equation we get

$$(-15C_1 + 3C_2)\sin(3x) + (-3C_1 - 15C_2)\cos(3x) = 2\sin(3x),$$

from which we infer $C_1=-\frac{5}{39}$, $C_2=\frac{1}{39}$. A general solution to the differential equation takes the form

$$y(x) = A_1 e^{-2x} + A_2 e^{3x} - \frac{5}{39} \sin(3x) + \frac{1}{39} \cos(3x),$$

for constants A_1 and A_2 to be determined based upon initial conditions.