Marthinus Johannes Nel

➤ marthinusnel2023@u.northwestern.edu

773-739-1853

in www.linkedin.com/in/mj-nel

EDUCATION

Northwestern University

Evanston, IL, USA

M.S. in Robotics Expected Graduation: December 2023 Significant courses: Embedded systems for Robotics (ROS2), Robotic Manipulation, Machine Learning,

Machine Dynamics, Sensing, Future: Navigation, and Machine Learning for Robotics (SLAM)

Stellenbosch University

Stellenbosch, South Africa

B.S. in Mechatronic Engineering

Class of 2021

Significant courses: Mechatronics, Electrical drive systems, Electronic design, Computer systems

PROJECTS

7-DOF Robot Arm for Autonomous Air-hockey opponent

Fall 2022

- Developing Python software for a Franka 7-DOF robot arm to autonomously play air-hockey
- Created a Python ROS2 API to plan and execute trajectories with the robot arm through MoveIt

Computer Vision Pen grab challenge

Fall 2022

- Performed background subtraction and color thresholding with a RGBD camera to determine the 3D location of pen
- Coded a Pincher X100 4-DOF robot arm in Python to grab the pen through inverse kinematics

Thrust vector controlled scaled rocket

Jan - Dec 2021

- Invented, built, and tested a thrust vector controlled scaled rocket
- Implemented a PID controller and a state machine in C++ for autonomous active orientation control in-flight and recovery
- Formulated and constructed a custom flight controller PCB
- Designed the rocket body, thrust vector control mount and parachute deploy system in Inventor/Fusion360
 - M.J. Nel, "Design of a Thrust Vector Controlled Model Rocket", 2021.

Unmanned Aerial Vehicle

Winter 2019

- Designed, and built a UAV with a pixhawk cube orange flight computer
- Planned flight paths and preformed autonomous flight tests through the utilization of Ardupilot

Autonomous beverage cooler

Summer 2019

- Programmed a Raspberry Pi for autonomous control and user interface in Python
- Accomplished optimal pump times for keeping beverages at desired temperatures
- Utilized peltier modules, a peristaltic pump and food grade tubing to design a drink cooler
- Developed a touchscreen user interface in Kivy for user control

PROFESSIONAL EXPERIENCE

CranioTech, Inc. Stellenbosch, South Africa

Biomedical Engineering Intern

Dec 2020

- Executed viability tests on a 3D orthodontic surgery software for implant design
- Created 3D patient specific implants and preformed titanium 3D printing

(DOT) Seedmaster, Inc., (OMNiPOWER), Raven, Inc.

Regina, Canada

Test Engineering Intern

Engineering consultant

Jun~2019

- Collaborated with the assembly team to assemble an autonomous robotic farming platform
- Coordinated a team of 3 to conduct uphill seeding field testing on the autonomous platform for data collection
- Resolved problems with regards to power loss to the wheels by locating faulty pressure relieve valves

Bronberg Dynamics (Pty), Ltd.

Pretoria, South Africa

Mechatronics Engineering Intern

Dec 2018

- Programmed a PID controller in C++ for turbine blade orientation at different wind speeds for rotation speed control
- Devised, constructed, and tested a low cost functional prototype single blade wind turbine for remote environments to improve electricity security
- Oversaw wind-tunnel experiments to ensure correct PID controller response

Vryburg Abbatoir Vryburg, South Africa Dec 2017

• Improved efficiency of process line by 13% by implementing a conveyor belt system

SKILLS

- Programming: Python, C++, Bash, R, Assembly Language
- Robotics: ROS2/(ROS), Gazebo, MoveIt, Machine Learning, OpenCV, SLAM, Computer Vision, Control systems design
- Manufacturing: Inventor, Fusion360, SolidWorks, Rapid Manufacturing, Machining, EAGLE, PCB Design
- Software: Linux, Git, CMake, Unit Testing, Ardupilot, MATLAB