

## Chapter 8: Functions on Euclidean Space

**Definition.**  $F_n \xrightarrow{\text{pw}} F$  if  $\forall \varepsilon > 0, \exists N = N(x)$  with  $\|F_n(x) - F(x)\| < \varepsilon$  for  $n \geq N$ .

**Definition.**  $F_n \xrightarrow{u} F$  if  $\forall \varepsilon > 0, \exists N$  w/  $\|F_n(x) - F(x)\| < \varepsilon \forall n \geq N$  and  $\forall x \in D$ .

**Theorem.** Let  $F_n, F : D \rightarrow \mathbb{R}^q, D \subseteq \mathbb{R}^p$ . If  $\|F_n(x) - F(x)\| \leq b_n \forall x \in D$  and  $b_n \rightarrow 0$  and  $\{b_n\} \subseteq \mathbb{R}$ , then  $F_n \xrightarrow{u} F$ .

**Theorem.** If  $F_n \xrightarrow{u} F$  and  $F_n$  is continuous, then  $F$  is continuous.

**Theorem (W.M. Test).** If  $\|F_k(x)\| \leq M_k$  for some  $M_k > 0 \forall x \in D$  with  $\sum_{k=1}^{\infty} M_k$  convergent  $< \infty$ . Then  $\sum_{k=1}^{\infty} F_k$  is uniformly convergent.

**Definition.**  $L : \mathbb{R}^p \rightarrow \mathbb{R}^q$  is linear if  $L(x + y) = L(x) + L(y)$  and  $L(cx) = cL(x) \forall x, y \in \mathbb{R}^p$  and  $\forall c \in \mathbb{R}$ .

## Chapter 9: Differentiation in Several Variables

**Definition.**  $\frac{\partial f}{\partial y} = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h}$ .

**Definition.** We say  $F$  is differentiable at  $a$  iff  $\exists$  linear function such that  $\lim_{h \rightarrow 0} \frac{F(a+h) - F(a) - L(h)}{\|h\|} = 0$ .

**Theorem (Chain Rule).**  $d(F \circ G)(a) = dF(G(a))dG(a)$ .

**Definition.** Level surfaces are surfaces where  $f(x, y, z) = c$ , e.g.  $S = f(x, y, z) = 1$  for function  $f(x, y, z) = x^2 + y^2 - z^2$ . To find tangent plane to  $S$  at  $(a, b, c)$ , calculate  $\nabla f(a, b, c) = (a', b', c')$ . Then tangent plane to  $S$  is  $a'(x - a) + b'(y - b) + c'(z - c) = 0$ .

**Theorem (Taylor Formula).**  $f(a) + df(a)h + \frac{1}{2!} d^2 f(a)h^2 + \dots + \frac{1}{n!} d^n f(a)h^n$ .

**Theorem.** A critical point is a point  $a$  in the domain such that  $df(a) = 0$ . Plug in these CPs to  $\Delta = f_{x^2}f_{y^2} - f_{xy}^2$ . If  $\Delta < 0$ , saddle point. If  $\Delta > 0$ , take  $f_{x^2}$  at those CPs. If  $f_{x^2} > 0$ , local min. If  $f_{x^2} < 0$ , local max.

**Theorem (Inverse Function Theorem).**  $dF^{-1}(F(a)) = dF(a)^{-1}$ .

**Theorem.**  $dG(a) = -\left(\frac{\partial F}{\partial y}(a, b)\right)^{-1} \frac{\partial F}{\partial x}(a, b)$ .