

# Induced Drag and High-Speed Aerodynamics

Robert Stengel, Aircraft Flight Dynamics, MAE 331, 2014

## Learning Objectives

- Understand drag-due-to-lift and effects of wing planform
- Recognize effect of angle of attack on lift and drag coefficients
- How to estimate Mach number (i.e., air compressibility) effects on aerodynamics
- Be able to use Newtonian approximation to estimate lift and drag

**Reading:**  
*Flight Dynamics*  
Aerodynamic Coefficients, 85–96  
*Airplane Stability and Control*  
Chapter 1



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<http://www.princeton.edu/~stengel/MAE331.html>  
<http://www.princeton.edu/~stengel/FlightDynamics.html>

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## Early Developments in Stability and Control

### Chapter 1, *Airplane Stability and Control*, Abzug and Larrabee

- What are the principal subject and scope of the chapter?
- What technical ideas are needed to understand the chapter?
- During what time period did the events covered in the chapter take place?
- What are the three main "takeaway" points or conclusions from the reading?
- What are the three most surprising or remarkable facts that you found in the reading?

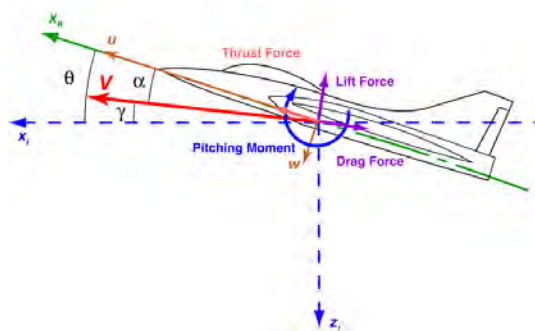
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## *Induced Drag*

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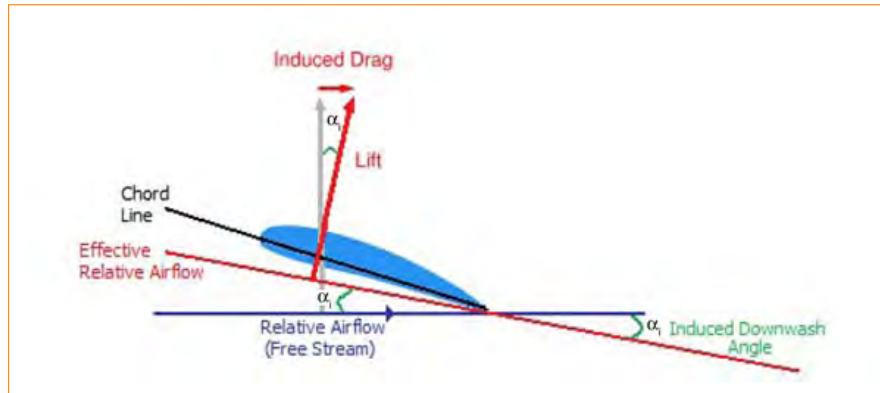
## Aerodynamic Drag

$$\begin{aligned} \text{Drag} &= C_D \frac{1}{2} \rho V^2 S \approx \left( C_{D_0} + \epsilon C_L^2 \right) \frac{1}{2} \rho V^2 S \\ &\approx \left[ C_{D_0} + \epsilon \left( C_{L_0} + C_{L_\alpha} \alpha \right)^2 \right] \frac{1}{2} \rho V^2 S \end{aligned}$$



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# Induced Drag of a Wing, $\epsilon C_L^2$



- Lift produces **downwash** (angle proportional to lift)
  - Downwash rotates local velocity vector CW in figure
  - Lift is perpendicular to velocity vector
  - **Axial component of rotated lift induces drag**

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## Three Expressions for Induced Drag of a Wing

$$C_{D_i} = C_{L_i} \sin \alpha_i \approx (C_{L_0} + C_{L_\alpha} \alpha) \sin \alpha_i$$

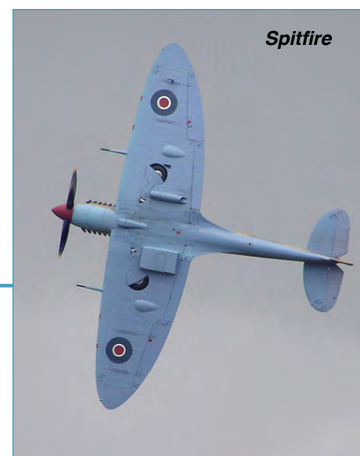
$$\approx (C_{L_0} + C_{L_\alpha} \alpha) \alpha_i \equiv \epsilon C_L^2$$

$$\equiv \frac{C_L^2}{\pi e AR} = \frac{C_L^2 (1 + \delta)}{\pi AR}$$

where

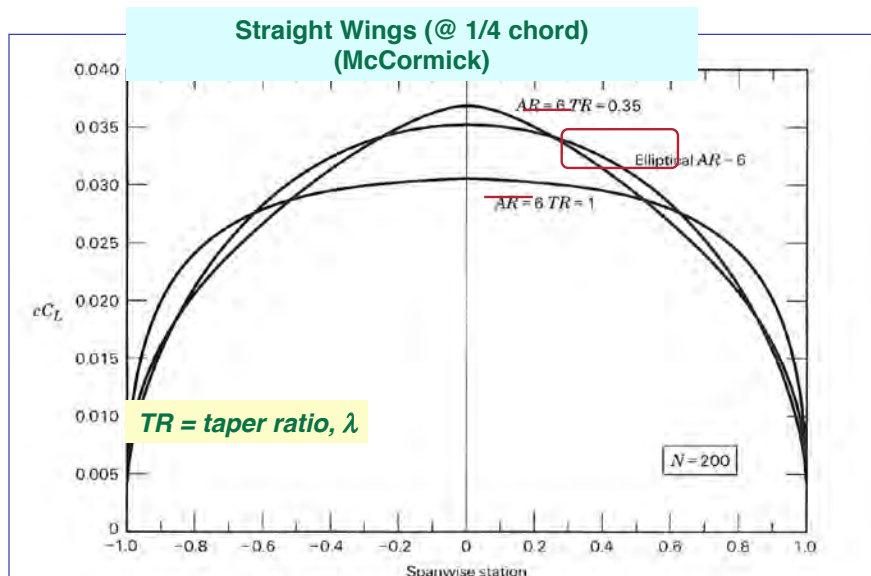
$e$  = Oswald efficiency factor = 1 for elliptical distribution

$\delta$  = departure from ideal elliptical lift distribution



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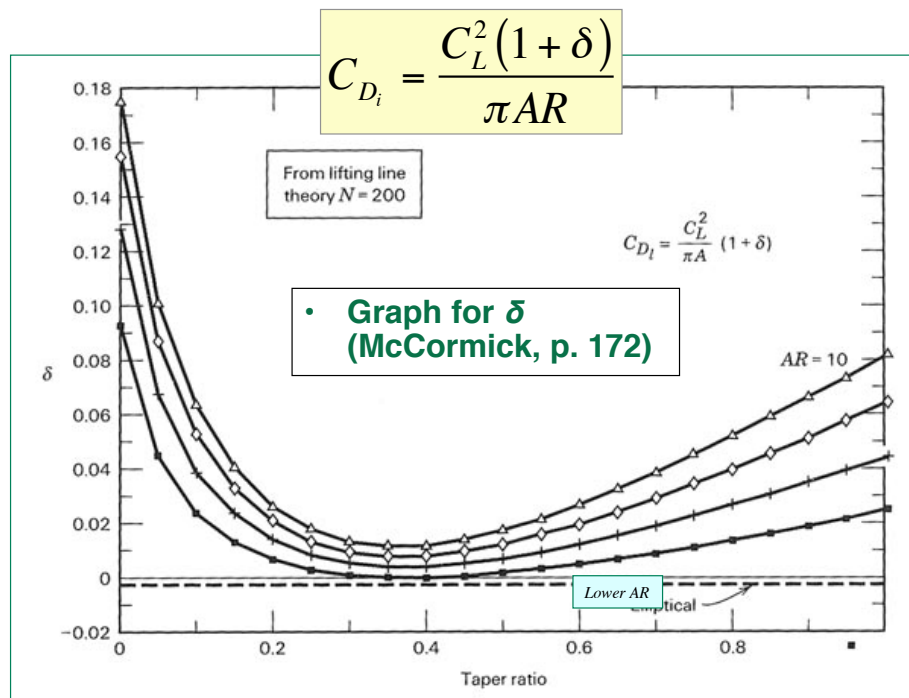
# Spanwise Lift Distribution of 3-D (Trapezoidal) Wings



For some taper ratio between 0.35 and 1, lift distribution is nearly elliptical

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## Induced Drag Factor, $\delta$



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## Oswald Efficiency Factor, $e$

$$C_{D_i} = \frac{C_L^2}{\pi e AR}$$

### Approximations for $e$

**Pamadi**

$$\kappa = \frac{AR \lambda}{\cos \Lambda_{LE}}$$

$$R = 0.0004\kappa^3 - 0.008\kappa^2 + 0.05\kappa + 0.86$$

$$e \approx \frac{1.1C_{L_\alpha}}{RC_{L_\alpha} + (1-R)\pi AR}$$

**Raymer**

$$e \approx 1.78(1 - 0.045AR^{0.68}) - 0.64 \quad [\text{Straight wing}]$$

$$e \approx 4.61(1 - 0.045AR^{0.68})(\cos \Lambda_{LE})^{0.15} - 3.1 \quad [\text{Swept wing}]$$

## Maximum Lift-to-Drag Ratio

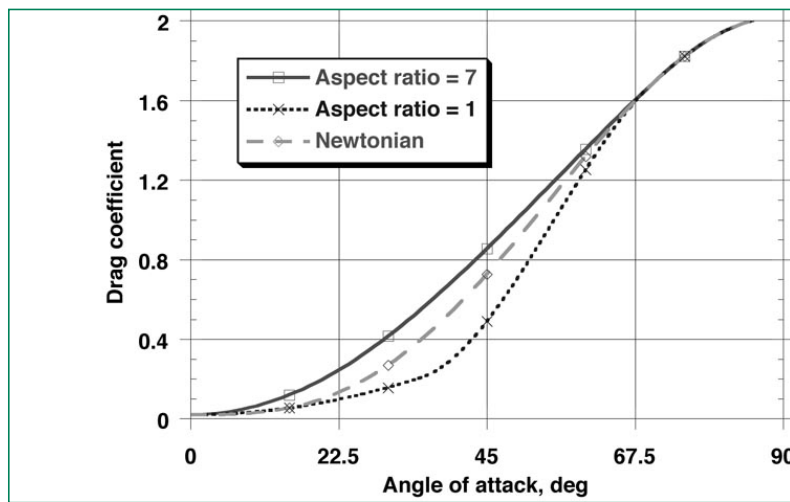
- Maximize  $L/D$  by proper choice of  $C_L$

$$\frac{L}{D} = \frac{C_L}{C_D} = \frac{C_L}{C_{D_o} + \epsilon C_L^2} \quad \frac{\partial(L/D)}{\partial C_L} = 0$$

$$\frac{\partial(L/D)}{\partial C_L} = 0 = \frac{(C_{D_o} + \epsilon C_L^2) - C_L(2\epsilon C_L)}{(C_{D_o} + \epsilon C_L^2)^2} = \frac{(C_{D_o} - \epsilon C_L^2)}{(C_{D_o} + \epsilon C_L^2)^2}$$

$$(C_L)_{(L/D)_{\max}} = \sqrt{\frac{C_{D_o}}{\epsilon}}$$

## Large Angle Variations in Subsonic Drag Coefficient ( $0^\circ < \alpha < 90^\circ$ )

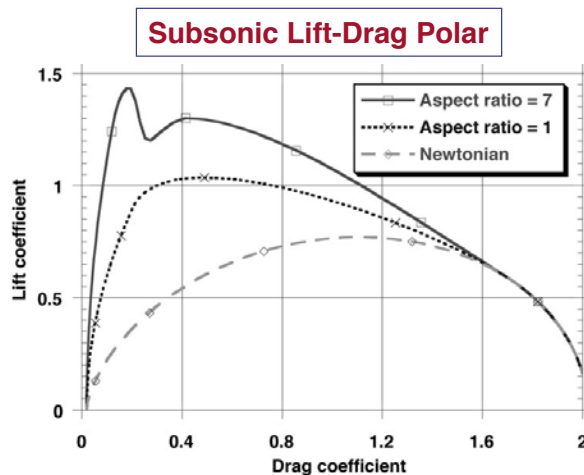


All wing drag coefficients converge to Newtonian-like values at high angle of attack

Low-AR wing has less drag than high-AR wing at given  $\alpha$

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## Lift vs. Drag for Large Variation in Angle-of-Attack ( $0^\circ < \alpha < 90^\circ$ )



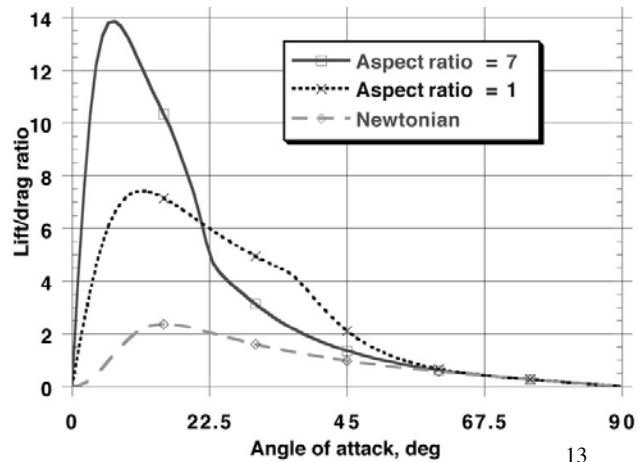
- Low-AR wing has less drag than high-AR wing, but less lift as well
- High-AR wing has the best overall  $L/D$

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# Lift-to-Drag Ratio vs. Angle of Attack

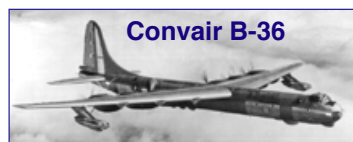
- L/D is an important performance metric for aircraft
- High-AR wing has best overall L/D
- Low-AR wing has best L/D at intermediate angle of attack

$$\frac{L}{D} = \frac{C_L \bar{q} S}{C_D \bar{q} S} = \frac{C_L}{C_D}$$



## Historical Factoid

### Conversions from Propellers to Jets



# Historical Factoid

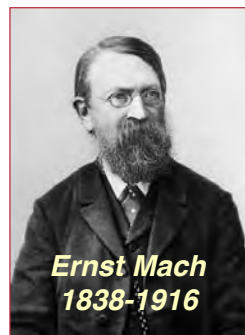
## Jets at an Awkward Age

- **Performance** of the first jet aircraft **outstripped stability and control technology**
  - Lacked satisfactory actuators, sensors, and control electronics
  - Transistor: 1947, integrated circuit: 1958
- **Dramatic dynamic variations** over larger flight envelope
  - Control mechanisms designed to lighten pilot loads were subject to instability
- **Reluctance of designers to embrace change**, fearing decreased reliability, increased cost, and higher weight



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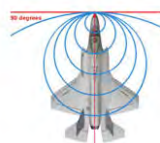
## Mach Number Effects



$$\text{Mach Number} = \frac{\text{True Airspeed}}{\text{Speed of Sound}}$$



No Speed



Mach 1

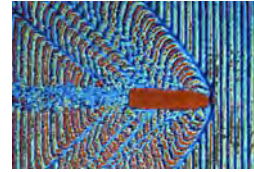


Mach 2

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# Drag Due to Pressure Differential



$$C_{D_{base}} = C_{pressure_{base}} \frac{S_{base}}{S} \approx \frac{0.029}{\sqrt{C_{friction} \frac{S_{wet}}{S_{base}}}} \frac{S_{base}}{S} \quad (M < 1) \quad [Hoerner]$$

**Blunt base pressure drag**

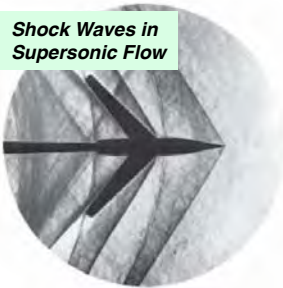
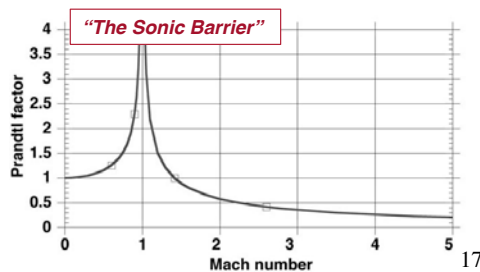
$$< \frac{2}{\gamma M^2} \left( \frac{S_{base}}{S} \right) \quad (M > 2, \quad \gamma = \text{specific heat ratio})$$

**Prandtl factor**

$$C_{D_{wave}} \approx \frac{C_{D_{incompressible}}}{\sqrt{1 - M^2}} \quad (M < 1)$$

$$\approx \frac{C_{D_{compressible}}}{\sqrt{M^2 - 1}} \quad (M > 1)$$

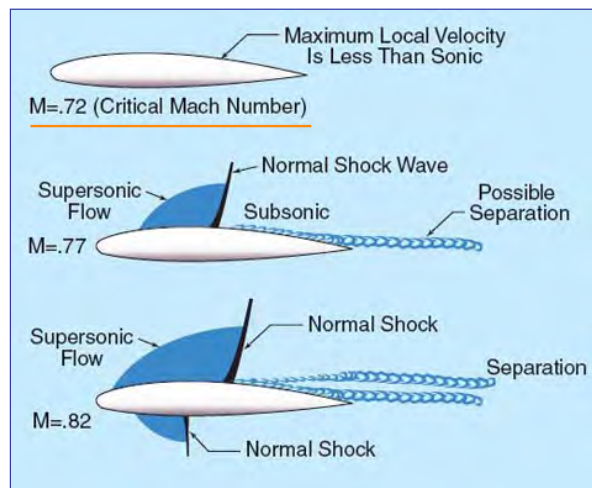
$$\approx \frac{C_{D_{M=\sqrt{2}}}}{\sqrt{M^2 - 1}} \quad (M > 1)$$



Shock Waves in Supersonic Flow

## Air Compressibility Effect

- **Drag rises due to pressure increase across a shock wave**
- **Subsonic flow**
  - Local airspeed is less than sonic (i.e., speed of sound) everywhere
- **Transonic flow**
  - Airspeed is less than sonic at some points, greater than sonic elsewhere
- **Supersonic flow**
  - Local airspeed is greater than sonic virtually everywhere



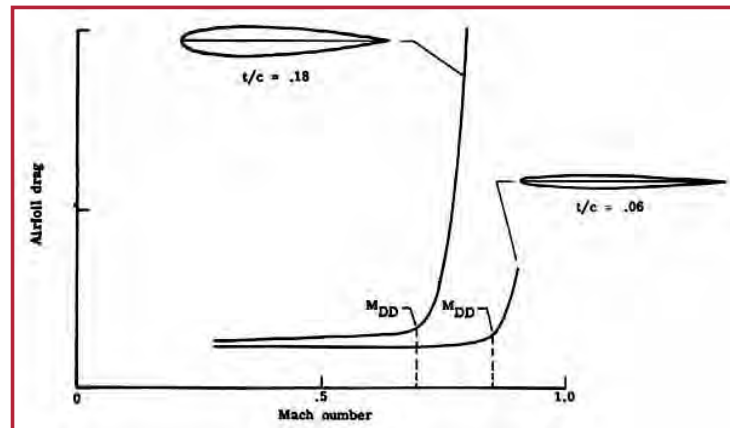
- **Critical Mach number**
  - Mach number at which local flow first becomes sonic
  - Onset of drag-divergence
  - $M_{crit} \sim 0.7$  to  $0.85$



## Effect of Chord Thickness on Wing Pressure Drag

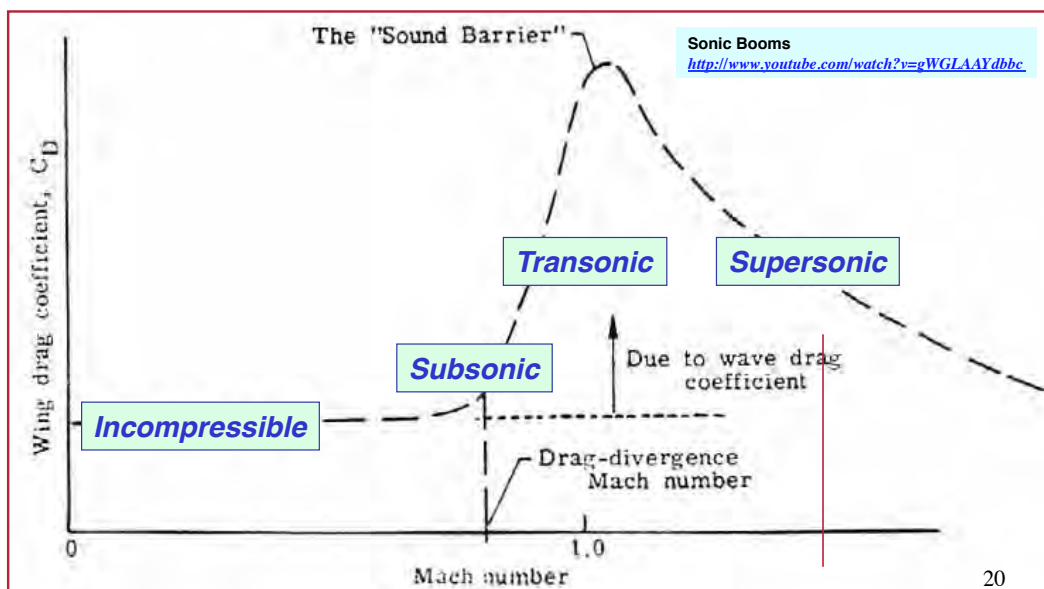
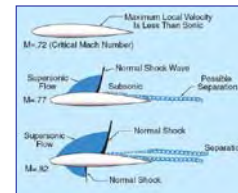


- Thinner chord sections lead to higher  $M_{crit}$  or drag-divergence Mach number



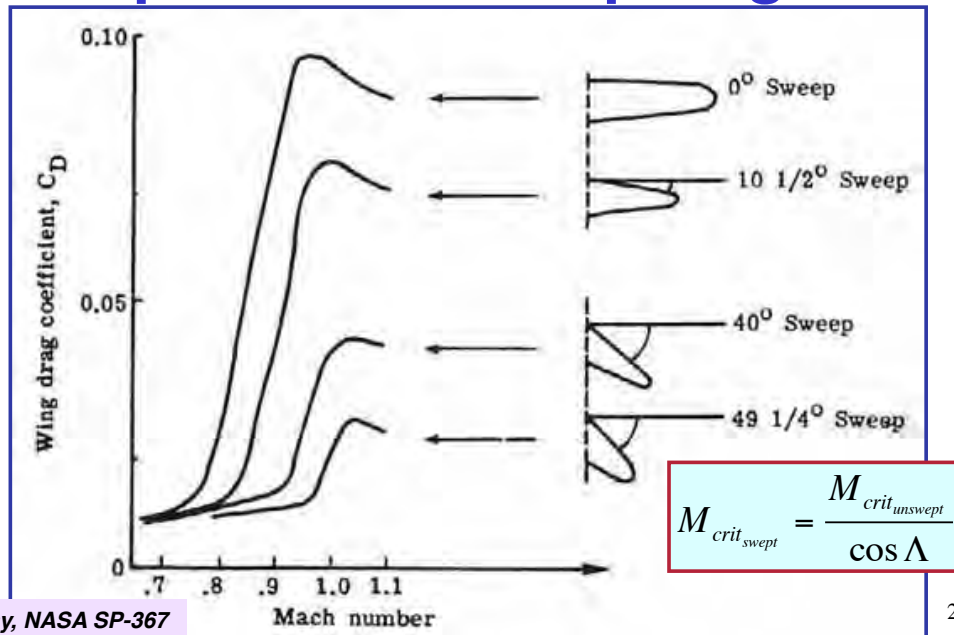
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## Air Compressibility Effect on Wing Drag



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# Pressure Drag on Wing Depends on Sweep Angle



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## Historical Factoid From Straight to Swept Wings

- Straight-wing models were redesigned with swept wings to reduce compressibility effects on drag and increase speed
- Dramatic change in stability, control, and flying qualities
- North American FJ-1 and FJ-4 Fury
- Republic F-84B Thunderbird and F-84F Thunderstreak
- Grumman F9F-2 Panther and F9F-6 Cougar



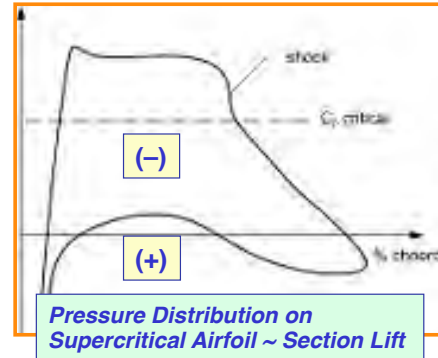
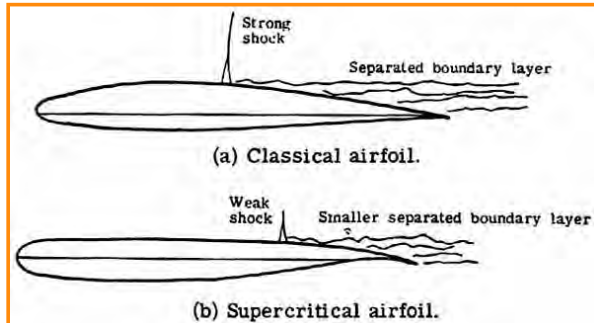
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# Supercritical Wing



- Richard Whitcomb's supercritical airfoil
  - Wing upper surface flattened to increase  $M_{crit}$
  - Wing thickness can be restored
    - Important for structural efficiency, fuel storage, etc.

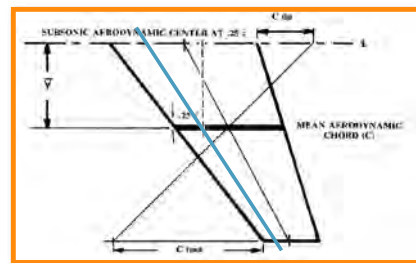


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## Subsonic Air Compressibility and Sweep Effects on 3-D Wing Lift Slope

- Subsonic 3-D wing, with sweep effect

$$C_{L_\alpha} = \frac{\pi AR}{1 + \sqrt{1 + \left( \frac{AR}{2 \cos \Lambda_{1/4}} \right)^2 (1 - M^2 \cos \Lambda_{1/4})}}$$



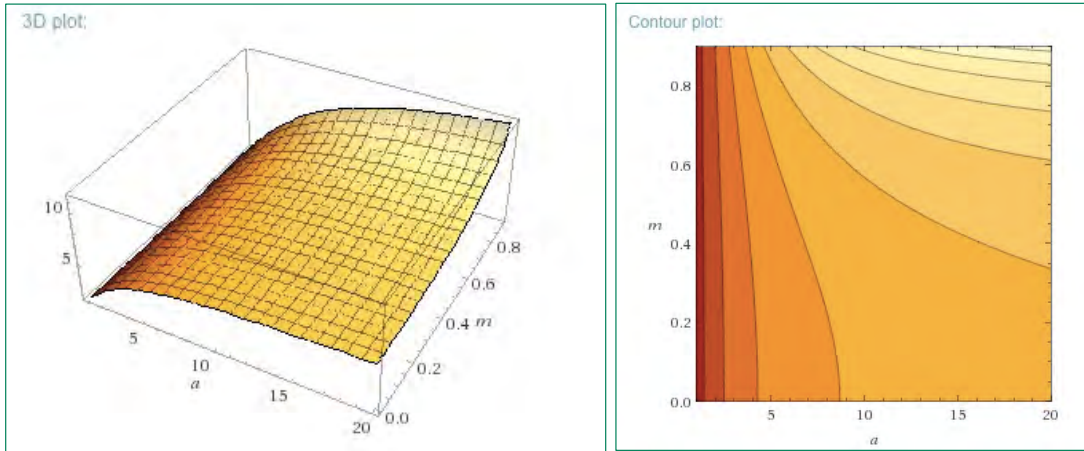
$$\Lambda_{1/4} = \text{sweep angle of quarter chord}$$

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## Subsonic Air Compressibility Effects on 3-D Wing Lift Slope

- Subsonic 3-D wing, sweep = 0

`plot(pi A / (1+sqrt(1 + ((A / 2)^2) (1 - M^2))), A=1 to 20, M = 0 to 0.9)`

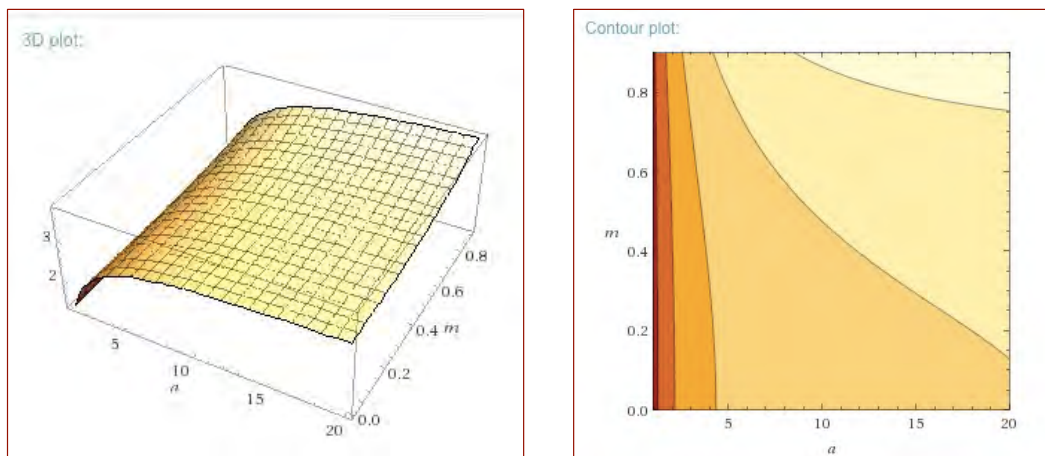


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## Subsonic Air Compressibility Effects on 3-D Wing Lift Slope

- Subsonic 3-D wing, sweep = 60°

`plot(pi A / (1+sqrt(1 + (A ^2) (1 - 0.5 M^2))), A=1 to 20, M = 0 to 0.9)`



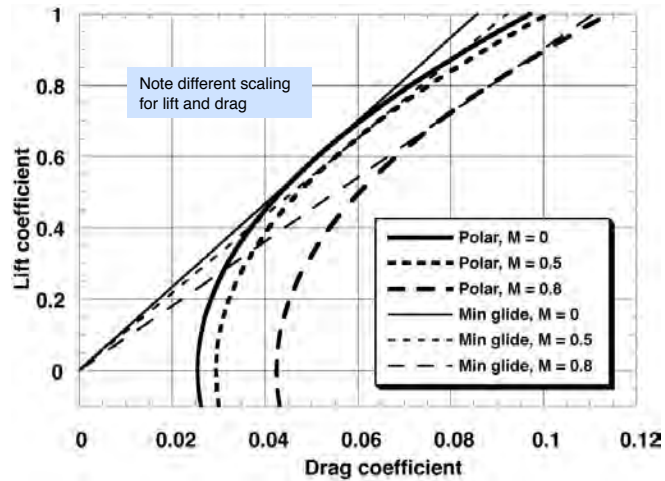
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## Lift-Drag Polar for a Typical Bizjet

- Lift-Drag Polar: Cross-plot of  $C_L(\alpha)$  vs.  $C_D(\alpha)$

- L/D equals slope of line drawn from the origin
  - Single maximum for a given polar
  - Two solutions for lower L/D (high and low airspeed)



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## Wing Lift Slope at $M = 1$

Approximation for all wing planforms

$$C_{L_\alpha} = \frac{\pi AR}{2} = 2\pi \left( \frac{AR}{4} \right)$$

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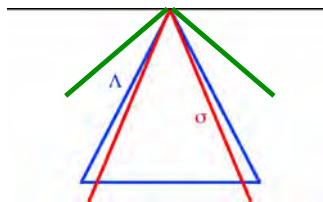


# Supersonic Compressibility Effects on Triangular Wing Lift Slope

- Supersonic delta (triangular) wing

Supersonic leading edge

$$C_{L_\alpha} = \frac{4}{\sqrt{M^2 - 1}}$$



Subsonic leading edge

$$C_{L_\alpha} = \frac{2\pi^2 \cot \Lambda}{(\pi + \lambda)}$$

$$\text{where } \lambda = m(0.38 + 2.26m - 0.86m^2)$$

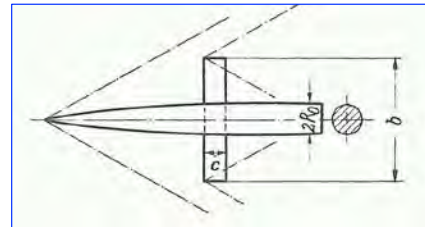
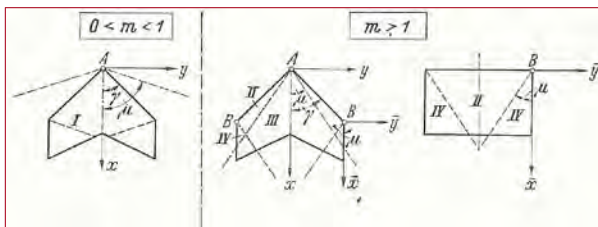
$$m = \cot \Lambda_{LE} / \cot \sigma$$

$\Lambda_{LE}$  = sweep angle of leading edge

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## Supersonic Effects on Arbitrary Wing and Wing-Body Lift Slope

- Impinging shock waves
- Discrete areas with differing  $M$  and local pressure coefficients,  $c_p$
- Areas change with  $\alpha$
- No simple equations for lift slope



Schlichting & Truckenbrodt, 1979

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# *Historical Factoid*

## Fighter Jets of the 1950s: “Century Series”

- Emphasis on supersonic speed



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# *Historical Factoid*

## What Happened to the F-103?

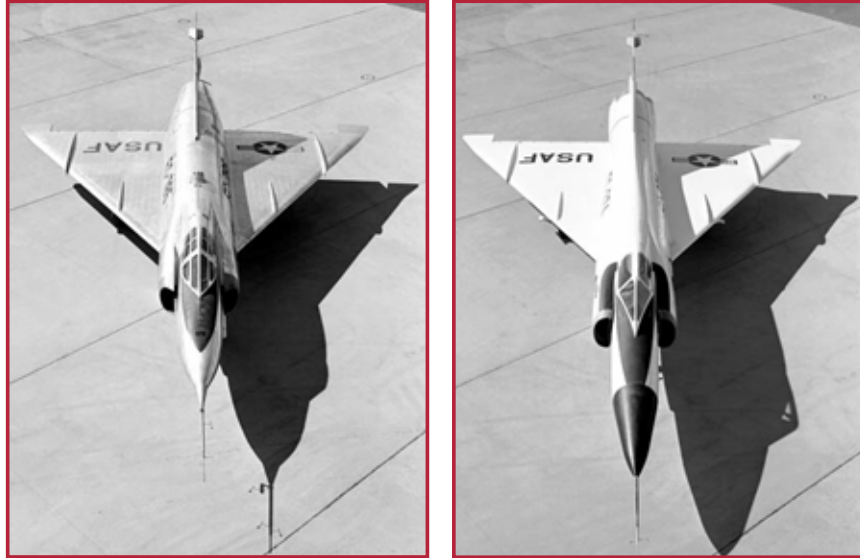


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# Transonic Drag Rise and the Area Rule

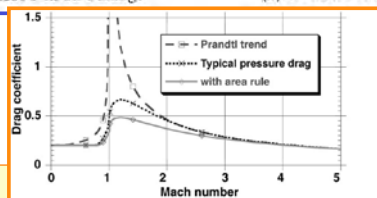
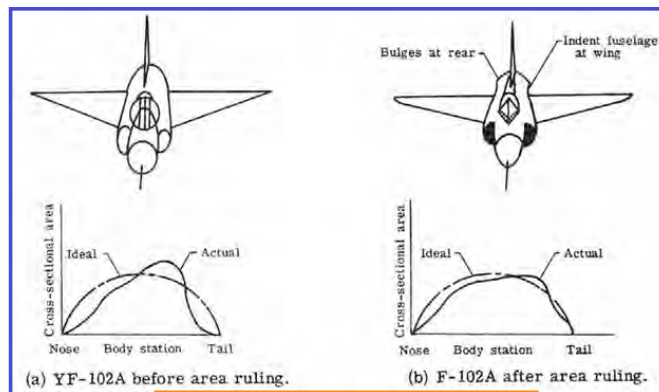
- **Richard Whitcomb** (NASA Langley) and **Wallace Hayes** (Princeton)
- **YF-102A** (left) could not break the speed of sound in level flight;  
**F-102A** (right) could



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# Transonic Drag Rise and the Area Rule

- Cross-sectional area of the total configuration should gradually increase and decrease to minimize transonic drag



Talay, NASA SP-367

**Sears-Haack Body**

[http://en.wikipedia.org/wiki/Sears-Haack\\_body](http://en.wikipedia.org/wiki/Sears-Haack_body)

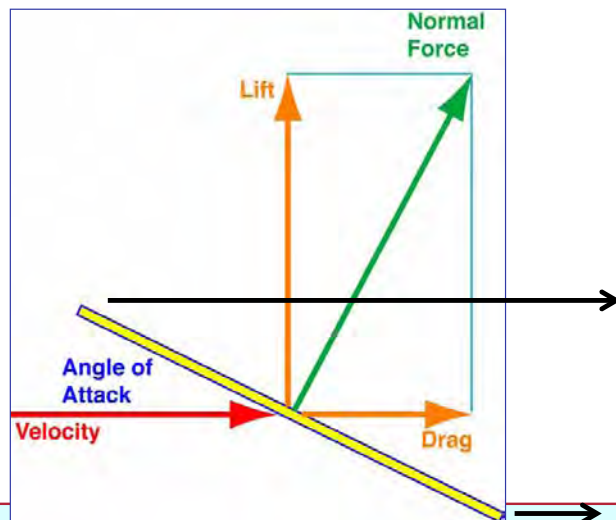
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# Newtonian Flow and High-Angle-of-Attack Lift and Drag

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## Newtonian Flow

- No circulation
- “Cookie-cutter” flow
- Equal pressure across bottom of the flat plate

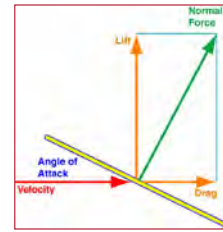


*Normal Force =*

$$\left( \frac{\text{Mass flow rate}}{\text{Unit area}} \right) (\text{Change in velocity}) (\text{Projected Area}) (\text{Angle between plate and velocity})$$

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# Newtonian Flow



$$\begin{aligned}
 N &= (\rho V)(V)(S \sin \alpha)(\sin \alpha) \\
 &= (\rho V^2)(S \sin^2 \alpha) \\
 &= (2 \sin^2 \alpha) \left( \frac{1}{2} \rho V^2 \right) S \\
 &\equiv C_N \left( \frac{1}{2} \rho V^2 \right) S = C_N \bar{q} S
 \end{aligned}$$

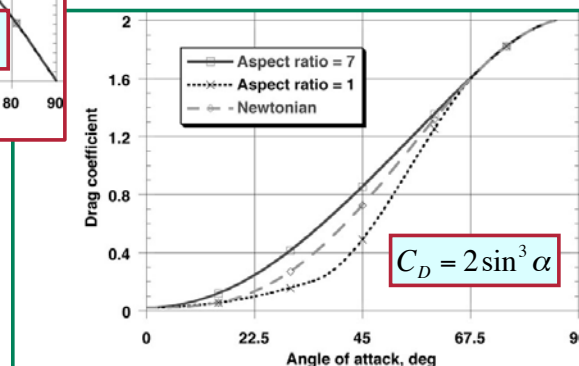
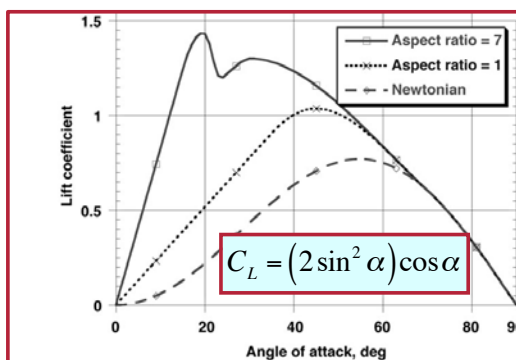
## Lift and drag coefficients

$$\begin{aligned}
 \text{Lift} &= N \cos \alpha \\
 C_L &= (2 \sin^2 \alpha) \cos \alpha
 \end{aligned}$$

$$\begin{aligned}
 \text{Drag} &= N \sin \alpha \\
 C_D &= 2 \sin^3 \alpha
 \end{aligned}$$

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## Newtonian Lift and Drag Coefficients



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# Application of Newtonian Flow

- Hypersonic flow ( $M \sim > 5$ )
  - Shock wave close to surface (thin shock layer), merging with the boundary layer
  - Flow is  $\sim$  parallel to the surface
  - Separated upper surface flow
- All Mach numbers at high angle of attack
  - Separated flow on upper (leeward) surfaces



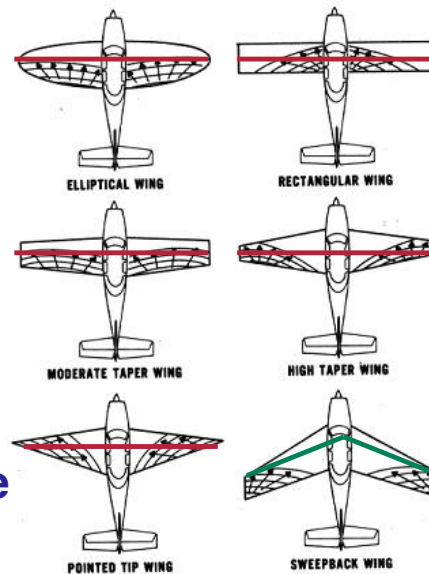
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*Next Time:  
Aerodynamic Moments  
(i.e., Torques)*

**Reading:**  
*Flight Dynamics*  
Aerodynamic Coefficients, 96-118  
*Airplane Dynamics and Control*  
Chapter 6

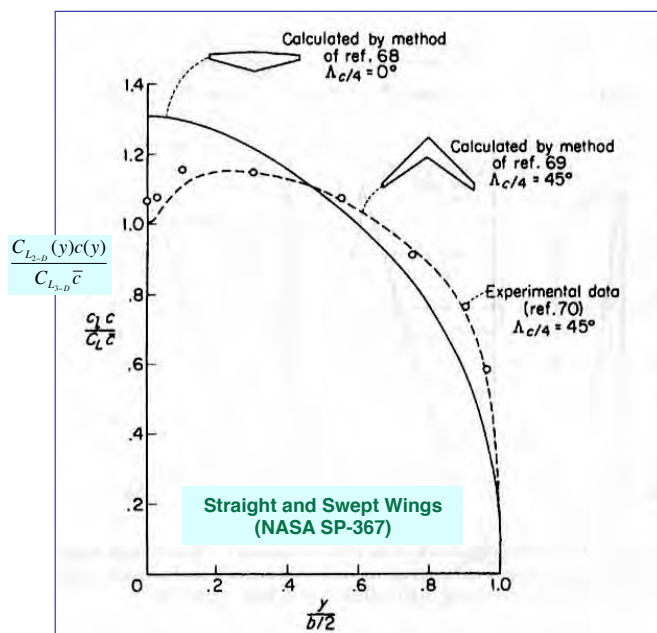
# Straight, Swept, and Tapered Wings

- **Straight at the quarter chord**
- **Swept at the quarter chord**
- **Progression of separated flow from trailing edge with increasing angle of attack**



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## Spanwise Lift Distribution of 3-D Wings



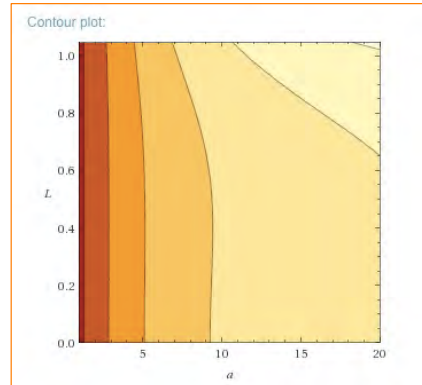
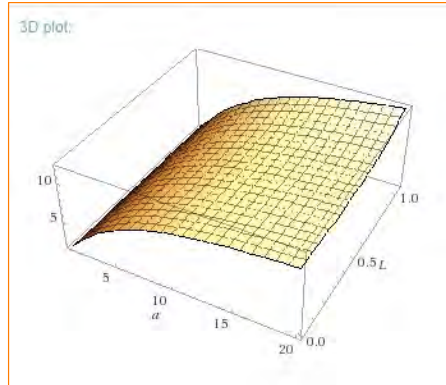
- **Wing does not have to have a geometrically elliptical planform to have a nearly elliptical lift distribution**
- **Sweep moves lift distribution toward tips**

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# Transonic Sweep Effects on 3-D Wing Lift Slope

- Subsonic 3-D wing,  $M = 0.85$

plot( $\pi A / (1 + \sqrt{1 + ((A / 2 \cos(L))^2 (1 - \cos(L) 0.85^2))})$ ),  $A=1$  to  $20$ ,  
 $L = 0$  to  $(\pi / 3)$ )



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## Sweep Reduces Subsonic Lift Slope

### Swept Wing

$$C_{L_\alpha} = \frac{\pi AR}{1 + \sqrt{1 + \left( \frac{AR}{2 \cos \Lambda_{1/4}} \right)^2 (1 - M^2 \cos \Lambda_{1/4})}}$$

$$= \frac{\pi AR}{1 + \sqrt{1 + \left( \frac{AR}{2 \cos \Lambda_{1/4}} \right)^2}} \quad [\text{Incompressible flow}]$$

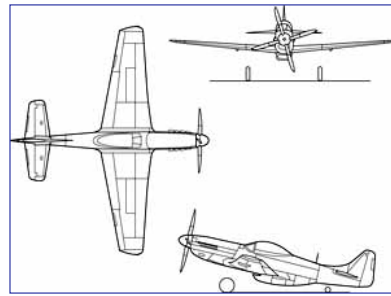
### Triangular Wing

$$C_{L_\alpha} = \frac{2\pi^2 \cot \Lambda_{LE}}{(\pi + \lambda)}$$

where  $\lambda = m(0.38 + 2.26m - 0.86m^2)$   
 $m = \cot \Lambda_{LE} / \cot \sigma$   
 $\Lambda_{LE}, \sigma$  : measured from y axis

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# P-51 Mustang

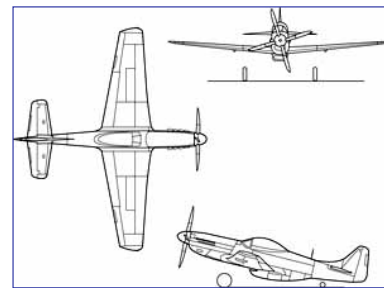


$Wing\ Span = 37\ ft\ (9.83\ m)$   
 $Wing\ Area = 235\ ft\ (21.83\ m^2)$   
 $Loaded\ Weight = 9,200\ lb\ (3,465\ kg)$   
 $Maximum\ Power = 1,720\ hp\ (1,282\ kW)$   
 $C_{D_0} = 0.0163$   
 $AR = 5.83$   
 $\lambda = 0.5$

[http://en.wikipedia.org/wiki/P-51\\_Mustang](http://en.wikipedia.org/wiki/P-51_Mustang)

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## P-51 Mustang Example



$$C_{L_\alpha} = \frac{\pi AR}{\left[1 + \sqrt{1 + \left(\frac{AR}{2}\right)^2}\right]} = 4.49\ per\ rad\ (wing\ only)$$

$$e = 0.947$$

$$\delta = 0.0557$$

$$\varepsilon = 0.0576$$

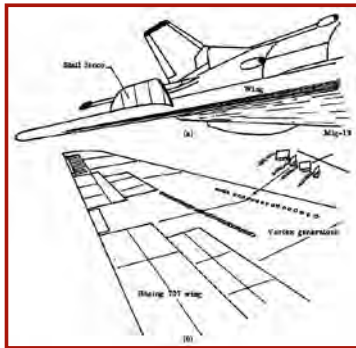
$$C_{D_i} = \varepsilon C_L^2 = \frac{C_L^2}{\pi e AR} = \frac{C_L^2 (1 + \delta)}{\pi AR}$$

<http://www.youtube.com/watch?v=WE0sr4vmZtU>

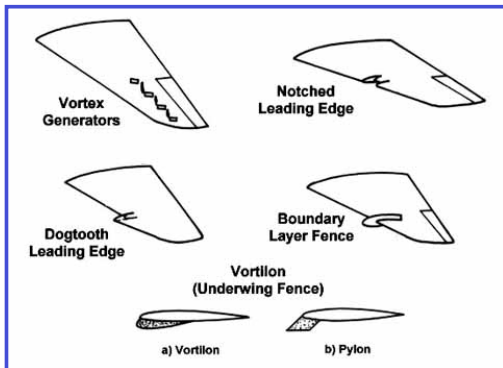
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# Secondary Wing Structures



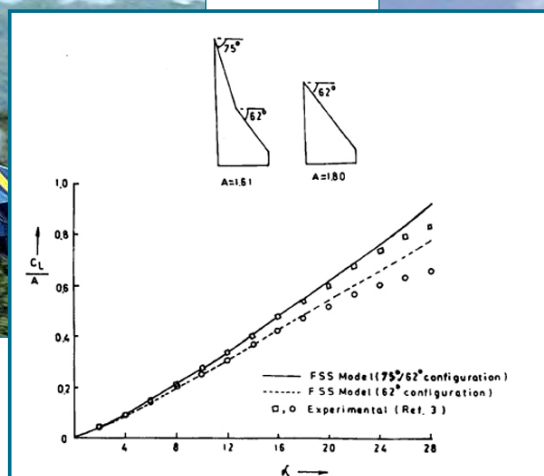
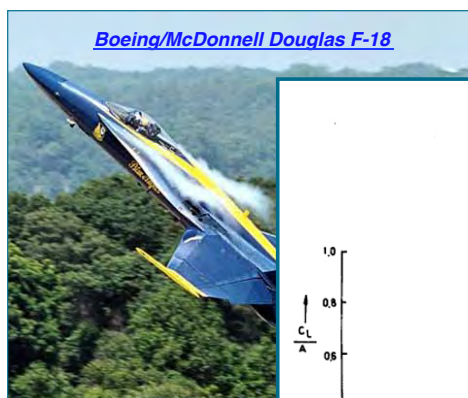
- Vortex generators, fences, vortilons, notched or dog-toothed wing leading edges
  - Boundary layer control
  - Maintain attached flow with increasing  $\alpha$
  - Avoid tip stall



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# Leading-Edge Extensions

- Strakes or leading edge extensions
  - Maintain lift at high  $\alpha$
  - Reduce c.p. shift at high Mach number

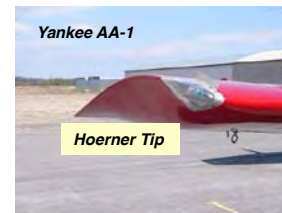


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# Wingtip Design

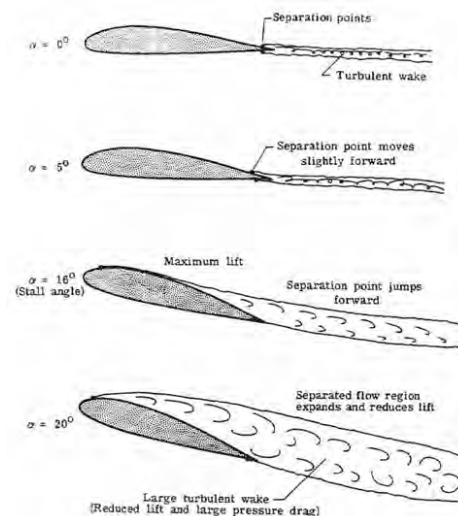
- **Winglets, rake, and Hoerner tip** reduce induced drag by controlling the tip vortices
- **End plate, wingtip fence** straightens flow, increasing apparent aspect ratio ( $L/D$ )
- **Chamfer** produces favorable roll w/ sideslip



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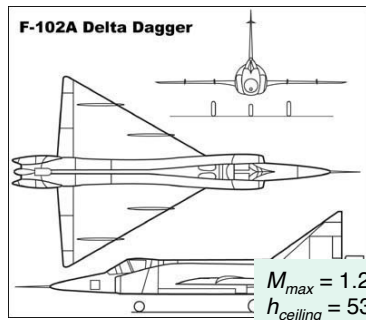
# Design for Satisfactory Stalls

- Marked by noticeable, uncommanded changes in pitch, yaw, or roll and/or by a marked increase in buffet
- Stall must be **detectable**
- Aircraft must pitch down when it occurs
- Up to the stall break, ailerons and rudder should operate properly
- Inboard **stall strips** to prevent tip stall and loss of roll control before the stall
- **Strakes** for improved high- $\alpha$  flight

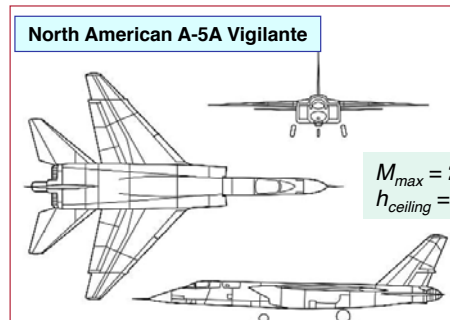


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# Low Aspect Ratio Configurations

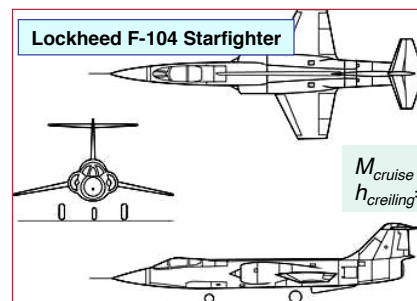


$M_{max} = 1.25$   
 $h_{ceiling} = 53 \text{ kft}$



$M_{max} = 2$   
 $h_{ceiling} = 52 \text{ kft}$

- Typical for supersonic aircraft

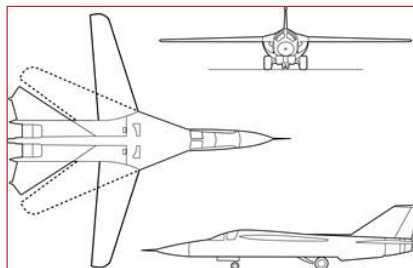


$M_{cruise} = 1.4$   
 $h_{ceiling} = 50 \text{ kft}$

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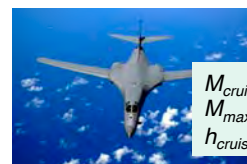
# Variable Aspect Ratio Configurations

**General Dynamics F-111**



$M_{max} = 2.5$   
 $h_{ceiling} = 65 \text{ kft}$

**North American B-1**

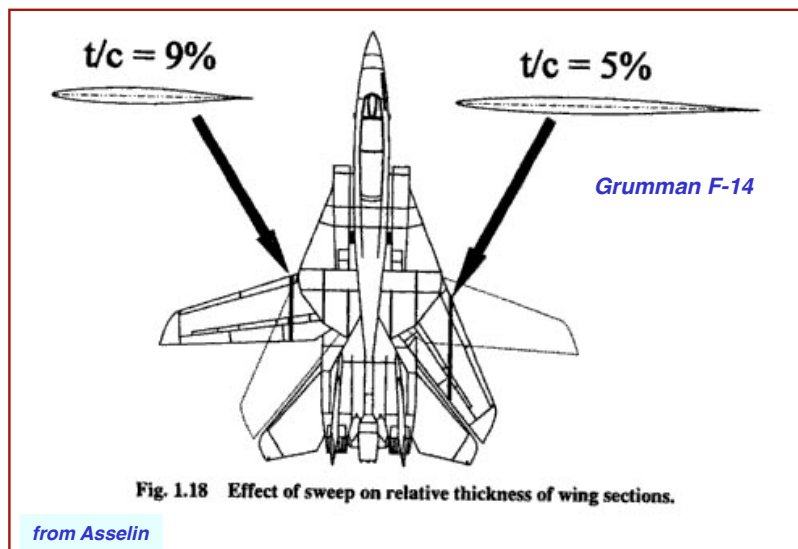


$M_{cruise} = 0.9$   
 $M_{max} = 1.25$   
 $h_{cruise} = 50 \text{ kft}$

- Aerodynamic efficiency at sub- and supersonic speeds

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## Sweep Effect on Thickness Ratio



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## Lifting Body Re-Entry Vehicles



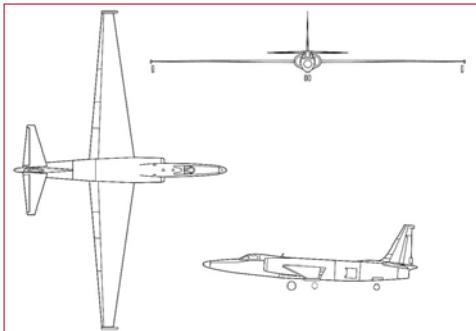
<http://www.youtube.com/watch?v=K13G1uxNYks>

<http://www.youtube.com/watch?v=YCZWNW4NrLVY>

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# Reconnaissance Aircraft

Lockheed U-2 (ER-2)

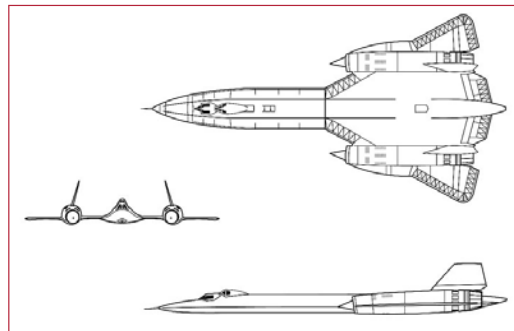


$V_{cruise} = 375 \text{ kt}$   
 $h_{cruise} = 70 \text{ kft}$



- Subsonic, high-altitude flight

Lockheed SR-71 Trainer

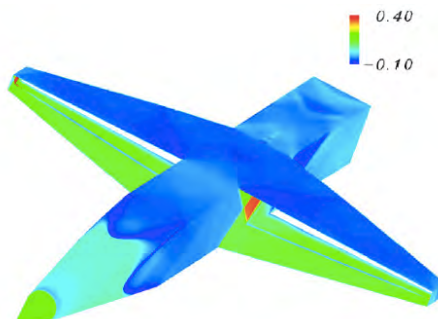
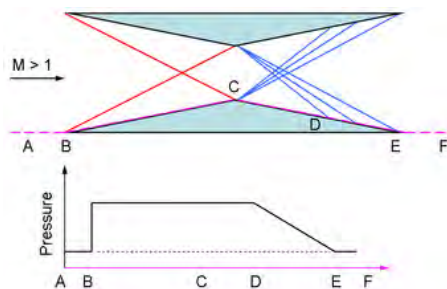


$M_{cruise} = 3$   
 $h_{cruise} = 85 \text{ kft}$

- Supersonic, high-altitude flight

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## Supersonic Biplane



- Concept of Adolf Busemann (1935)

- Shock wave cancellation at one specific Mach number
- 2-D wing

[http://en.wikipedia.org/wiki/Adolf\\_Busemann](http://en.wikipedia.org/wiki/Adolf_Busemann)

- Kazuhiro Kusunose *et al*, Tohoku U (PAS, 47, 2011, 53-87)

- Adjustable flaps
- Tapered, variably spaced 3-D wings
- Fuselage added

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# Supersonic Transport Concept



- **Rui Hu, Qiqi Wang (MIT), Antony Jameson (Stanford), AIAA-2011-1248**
  - Optimization of biplane aerodynamics
  - Sketch of possible configuration