

# BLTouch : Auto Bed Leveling Sensor for 3D Printers

## Smart V3.0 Highlights

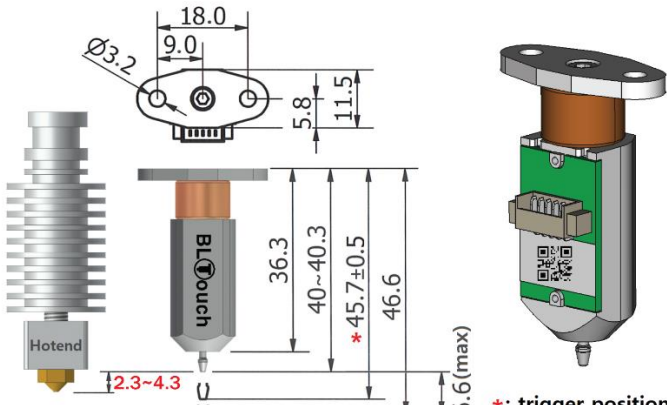
**Logic Voltage Free** : 3.3V / 5V logic voltage free(default)  
**Long Stroke**: The stroke is up to 1.6mm longer than before

## Smart V2.0 and later versions highlights

**Blue & Red LED**: Blue and Red LED for checking wiring defects.  
**Engineering plastic Push-pin**: Engineering plastic push-pin can be bent more easily than aluminum pins so that engineering plastic push-pin can be recovered well and the device can be protected.

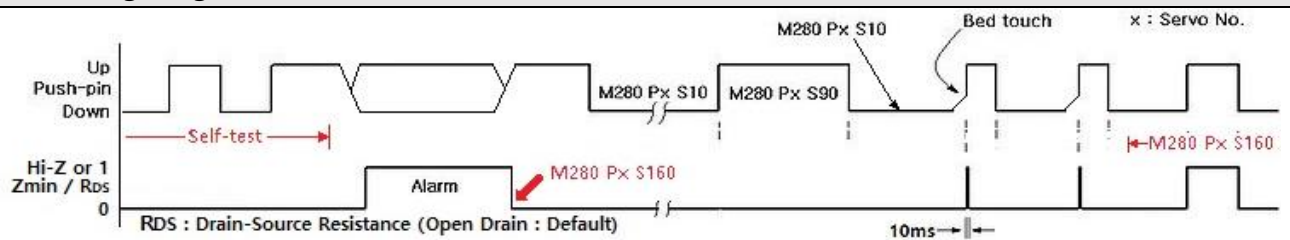
BLTouch – Smart V3.0 (Smart V3.0 produced by April 4th, 2019)				
BLTouch Instruction	Center Of PWM (Available PWM Range $\pm 20$ )	G-code x: Servo Pin or No.		
		Marlin / Duet	Repetier	Smoothieware
Push-pin Down(deploy)	650 us (10°)	M280 Px S10	M340 Px S650	M280 S3.3
Alarm Release & Touch SW Mode(M119)	1165 us (60°)	M280 Px S60	M340 Px S1165	M280 S5.88
Push-pin Up (Stow)	1475 us (90°)	M280 Px S90	M340 Px S1475	M280 S7.43
Self-test	1780 us (120°)	M280 Px S120	M340 Px S1780	M280 S8.99
5V Logic Zmin (Do not activate on 3.3V logic system)	1985 us (140°)	M280 Px S140	M340 Px S1985	M280 S10.01
Logic voltage Free Zmin (default: open drain)	2090 us (150°)	M280 Px S150	M340 Px S2090	M280 S10.53
Alarm Release & Push-pin UP	2190 us (160°)	M280 Px S160	M340 Px S2190	M280 S11.05

※ Depending on your board, you can need to adjust the PWM range or Duty cycle.  
 ※ 5V Logic Zmin(140°) for unusual board : High Signal is very weak( Not recommended for general board)  
 ⚠ **Do not activate 5V logic on 3.3V logic system without 3.3V logic conversion.**  
 ※ The first one mode declaration will last until power OFF or a new mode transition. ← (Only if the firmware does not support it yet)

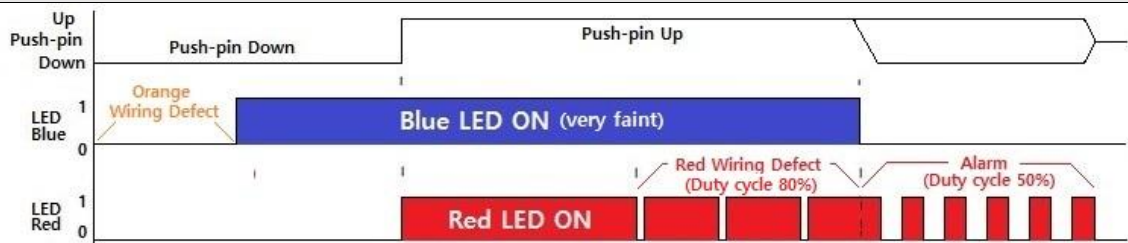
Specification		BLTouch CAD Dimension	
Voltage / Current	4.8 ~ 5.1 V		
Current	15mA		
Maximum (Peak)	300mA		
Z Probe Output	Logic Free (Open Drain: default) or 5V		
Open Drain VDS / ID	Max VDS = 5V / Max ID = 300mA		
PCB / Soldering	OSP / Lead Free		
Cable Length	150±5 mm (for retail)		
Weight	0.35oz (10g)		
Wiring	3Pin: Brown (GND), Red (+5V) Orange (control signal) 2Pin: Black (GND) White (Zmin)	*: trigger position	
Case & Push-pin	Polycarbonate (PC)		
Push-pin stroke	5.6 ~ 6.6 mm (If the stroke is large, push-pin may not deploy)		

※ Additional power supply may be needed in case which your board does not supply enough amperage.  
 ※ Electronic devices can be damaged or even destroyed if connected to the wrong side polarity.  
 ※ **Set Zmin pull-up on your firmware when using Logic Free (In most cases, it is already set up)**  
 ※ If push-pin down error occurs, turn core 180 degrees with Allen-key so that the core is further inside the casing.  
 ※ Depending on your type of 3D printer, you may need to remove or add some parts of the board.  
 ※ In principle, Board with large capacitor on end stop input circuit is not supported.(You may need to remove the capacitor from your board.)  
 ※ If noise, etc. interference is expected, you should use a anti-interference extension cable (Shielded or Twisted Cable).  
 ※ Selling price and specifications are subject to change without prior notice.

## ■ Signal Timing Diagram



## ■ Blue & Red LED (Please check wiring defects with Blue and Red LED(Smart V2.0 and later).)



※ Red wiring defect : When the BLTouch was disconnected and reconnected during normal operation. Unlike previous versions, it does not perform self-test even if wiring defects occur during printing.

## ■ Wiring : Soldering and firmware update might be needed in rare case

	<a href="#">I can find a servo pin on my board.</a> click here RAMPS1.3/1.4, MKS-Gen V1.3, MKS-Base V1.4, etc.	
	<a href="#">I can not find any Servo pin on my board.</a> click here MKS-Base V1.2, mini-Rambo, etc.	
	<a href="#">I can not find Servo Pin on my board and</a> click here <a href="#">#define SERVO0_PIN is not included in pins_YourMotherboard.h.</a> (Sanguinololu1.3a, Melzi , Ender-3, Anet, FlashForge, Azteeg X3, etc.) ※ Depending on your type of 3D printer, you may need to remove or add some parts of the board.	
	<a href="#">32bit board</a> click here Smoothieboard, MKS-Sbase, BBP1S, Alligator, AZSMZ, STEVAL-3DP001V1, Duet, etc.	

## ■ Insert the following G-code into Slic3r or Cura

Depending on your board, you can choose between the following two.

### 1. Logic voltage free(default) mode (Recommended) ← Both 3.3V /5V Logic are available

M280 P0 S160 ; BLTouch alarm release  
 G4 P100 ; delay for BLTouch  
 G28 ; home  
 G29 ; auto bed leveling

### 2. 5V Logic Zmin(140°) for unusual board : High Signal is very weak( Not recommended for general board)

M280 P0 S140 ← Only 5V Logic mode(Do not activate 5V logic on 3.3V logic system without 3.3V logic conversion)  
 G4 P2000 ; delay for BLTouch  
 M280 P0 S160 ; BLTouch alarm release  
 G4 P100 ; delay for BLTouch  
 G28 ; home  
 G29 ; auto bed leveling

## ■ Setting (e.g. Marlin firmware)

Please refer to other auto bed leveling setting documents ( Youtube etc. ).

### Marlin-bugfix-2.0.x Setting

<https://github.com/MarlinFirmware/Marlin/archive/bugfix-2.0.x.zip>

Step 1 : Copy the file below and overwrite at the Marlin folder. <== e.g. default

Marlin-bugfix-2.0.x\config\default\Configuration.h

Marlin-bugfix-2.0.x\config\default\Configuration\_adv.h

Step 2 : Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin.

Step 3 : Check your 3D printer works well.

Step 4 : Please install your BLTouch.

Step 5 : Edit Configuration.h and Configuration\_adv.h like below.

#### ■ Configuration.h

```
//===== Endstop Settings =====
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE

//===== Z Probe Options =====
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN

#define BLTOUCH
#if ENABLED(BLTOUCH)
  // #define BLTOUCH_DELAY 500 // *option : Minimum Command delay (ms). Enable and increase if needed
  // #define BLTOUCH_FORCE_5V_MODE // only for 5V logic mode of Smart V3.0 : Do not remove // on 3.3V logic system
#endif

#define PROBING_HEATERS_OFF // *option
#define PROBING_FANS_OFF // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0 // Depend on your BLTouch installation value
#define Y_PROBE_OFFSET_FROM_EXTRUDER -22 // Depend on your BLTouch installation value
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 // Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
#define Z_CLEARANCE_DEPLOY_PROBE 15 // set up at least 15
#define Z_CLEARANCE_BETWEEN_PROBES 10 // set up at least 10

//===== Bed Leveling =====
// Choose a line of below lines and remove // at the start of the line
// #define AUTO_BED_LEVELING_3POINT
// #define AUTO_BED_LEVELING_LINEAR
#define AUTO_BED_LEVELING_BILINEAR
// #define AUTO_BED_LEVELING_UBL
// #define MESH_BED_LEVELING

//===== Extra Featurest =====
#define NUM_SERVOS 3 // set up at least 1
#define SERVO_DELAY { 300, 300, 300 }
```

## Marlin 1.1.x(1.1.9) Setting

<https://github.com/MarlinFirmware/Marlin/archive/1.1.x.zip>

- Step 1 : Copy the file below and overwrite at the Marlin folder. <== e.g. Delta  
Marlin\example\_configurations\delta\generic\configuration.h  
Marlin\example\_configurations\delta\generic\configuration\_adv.h
- Step 2 : Look at the Configuration.h at your previous firmware and edit Configuration.h at Marlin 1.1.x
- Step 3 : Check your 3D printer works well.
- Step 4 : Please install your BLTouch.
- Step 5 : Edit Configuration.h and Configuration\_adv.h like below.

### ■ Configuration.h

```
//===== Endstop Settings =====
#define USE_ZMIN_PLUG // a Z probe
#define ENDSTOPPULLUPS // BLTouch Smart V3.0 and Later
#define ENDSTOP_INTERRUPTS_FEATURE

//===== Z Probe Options =====
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN
// #define Z_MIN_PROBE_ENDSTOP
// #define FIX_MOUNTED_PROBE
#define BLTOUCH
#if ENABLED(BLTOUCH)
  #define BLTOUCH_DELAY 100 // *option
#endif
#define PROBING_HEATERS_OFF // *option
#define PROBING_FANS_OFF // *option
#define X_PROBE_OFFSET_FROM_EXTRUDER 0 // Depend on your BLTouch installation value
#define Y_PROBE_OFFSET_FROM_EXTRUDER -22 // Depend on your BLTouch installation value
#define Z_PROBE_OFFSET_FROM_EXTRUDER -2.35 // Depend on your BLTouch installation value
#define MIN_PROBE_EDGE 20
// #define Z_PROBE_ALLEN_KEY
#define Z_CLEARANCE_DEPLOY_PROBE 15 // set up at least 15
#define Z_CLEARANCE_BETWEEN_PROBES 10 // set up at least 10

//===== Bed Leveling =====
// Choose a line of below lines and remove // at the start of the line
// #define AUTO_BED_LEVELING_3POINT
// #define AUTO_BED_LEVELING_LINEAR
#define AUTO_BED_LEVELING_BILINEAR
// #define AUTO_BED_LEVELING_UBL
// #define MESH_BED_LEVELING

//===== Additional Features =====
#define EEPROM_SETTINGS // Enable for M500 and M501 command

//===== Extra Featurest =====
#define NUM_SERVOS 3 // set up at least 1
#define SERVO_DELAY { 300, 300, 300 }
```

## Previous Versions before Marlin RC7

### ■ Configuration.h

```
//===== Mechanical Settings =====
const bool Z_MIN_ENDSTOP_INVERTING = false;

//===== Z Probe Options =====
// #define Z_MIN_PROBE_ENDSTOP // *RC4 ~ RC6
#define Z_MIN_PROBE_USES_Z_MIN_ENDSTOP_PIN // *RC4 ~ RC6

//===== Bed Auto Leveling =====
#define AUTO_BED_LEVELING_FEATURE
#define X_PROBE_OFFSET_FROM_EXTRUDER 20 //Your BLTouch X_PROBE_OFFSET_FROM_EXTRUDE
#define Y_PROBE_OFFSET_FROM_EXTRUDER -20 //Your BLTouch Y_PROBE_OFFSET_FROM_EXTRUDE
#define Z_PROBE_OFFSET_FROM_EXTRUDER -1.0 //Your BLTouch Z_PROBE_OFFSET_FROM_EXTRUDE
#define Z_SAFE_HOMING

//===== R/C SERVO support =====
#define NUM_SERVOS 3
#define SERVO_ENDSTOP_ANGLES {{0,0}, {0,0}, {10,90}} // 10=deploy, 90=retract
// #define DEACTIVATE_SERVOS_AFTER_MOVE
```

If you want more additional information about the other versions, please visit our website, [www.antclabs.com](http://www.antclabs.com)