# Project2: Optimizing the Performance of a Pipelined Processor

CS 359, COMPUTER ARCHITECTURE, Yanyan Shen, Spring 2017

# 1 Preknowledge

I have read the CSAPP book and concluded several basic points which are essential to solving the problems in Part A, B, and C.

• There are 8 registers in the Y86 system

Each of these registers stores a word. Among then register %esp is used as a stack pointer by the push, pop, call, and return instructions.

- There are three single-bit condition codes, ZF, SF, and OF, storing information about the effect of the most recent arithmetic or logical instruction.
- The Y86 instruction set is largely a subset of the IA32 instruction set but it still have some differences. The picture below shows the Y86 instruction set.

Byte	0		1		2	3	4	5
halt	0	0						
nop	1	0						
rrmovl rA, rB	2	0	rA	rB				
irmovl V, rB	3	0	F	rB			V	
rmmovl rA, D(rB)	4	0	rA	rB			D	
mrmovl D(rB), rA	5	0	rA	rB			D	
OP1 rA, rB	6	fn	rA	rB				
jXX <b>Dest</b>	7	fn				Dest		
cmovXX rA, rB	2	fn	rA	rB				
call <b>Dest</b>	8	0				Dest		
ret	9	0						
pushl <b>rA</b>	A	0	rA	F				
popl rA	В	0	rA	F				

• In the Y86 system, the stack starts at a certain address and grows toward lower addresses, which prevents space conflict.

# 2 Part A

## 2.1 Description

- The program **sum.ys** was used to sum linked list elements iteratively. We are supposed to add the sum of a list from head to tail using the Y86 codeing rules.
- The program **rsum.ys** is similar to the **sum.ys**, except it sums linked list elements recursively . We are supposed to add the sum of a list from head to tail using the Y86 codeing rules.
- The program **copy.ys** is used for two purposes. First it copies a block of words from one part of memory to another area of memory. Second it computes the checksum (Xor) of all the words copied.

### 2.2 Solution

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17 18

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```
sum.ys
irmovl Stack, % esp
rrmovl %esp,%ebp
irmovl ele1, %edx
pushl %edx
call sum_list
halt
align 4
ele1:
.long 0x00a
.long ele2
ele2:
.long 0x0b0
.long ele3
ele3:
.\log 0xc00
.long 0
sum_list:
pushl %ebp
xorl %eax, %eax
```

rrmovl %esp,%ebp

andl %edx,%edx

addl %esi,%eax

andl %edx,%edx

rrmovl %ebp,%esp

je L4

jne L5 L4:

popl %ebp

L5:

mrmovl 8(%ebp),%edx

mrmovl (%edx),% esi

mrmovl 4(% edx), % edx

```
ret

ret

pos 0x100

Stack:
```

#### rsum.ys

```
.pos 0
                      init:
2
                      irmovl Stack, %esp
3
                      irmovl Stack, %ebp
4
                      jmp Main
5
6
                      .align 4
                      ele1:
                      .long 0x00a
9
                      .long ele2
10
                      ele2:
11
                      .long 0x0b0
12
                      .long ele3
13
                      ele3:
14
                      .long 0xc00
15
                      .long 0
16
17
                      Main:
18
                      irmovl ele1, %edx
19
                      pushl %edx
                      call rsum_list
                      halt
22
23
                      rsum_list:
24
                      pushl %ebp
25
                      rrmovl %esp,%ebp
26
                      mrmovl 0x8(\%ebp),\%edx
27
                      xorl %eax,%eax
                      pushl %ebx
                      andl %edx,%edx
30
                      je End
31
                      mrmovl (%edx),%ebx
32
                      mrmovl 0x4(\%edx),\%ecx
33
                      pushl %ecx
                      call rsum_list
35
                      addl %ebx, %eax
36
37
                      End:
38
                               0 x fffffffc (%ebp), %ebx
                      mrmovl
39
                               %ebp, %esp
                      rrmovl
40
                      popl %ebp
                      r\,e\,t
42
43
                                0x100
                      . pos
44
```

# copy.ys

	copy.yb
1	. pos 0
2	init:
3	irmovl Stack, %esp
4	irmovl Stack, %ebp
5	jmp Main
6	
7	.align 4
8	src:
9	$\log 0 \times 00$ a
10	$\log 0 \times 0 = 0$
11	$\log 0 \times 000$
12	# Destination block
13	dest:
14	.long 0x111
15	$\log 0$ 0x222
16	$\log 0$ 0x333
17	
18	Main:
19	irmovl \$3,%eax
20	pushl %eax
21	irmovl dest, %edx
22	pushl %edx
23	irmovl src,%ecx
24	pushl %ecx
25	call Copy
26	halt
27	
28	Copy:
29	pushl %ebp
30	rrmovl %esp,%ebp
31	mrmovl $8(\%ebp),\%ecx$
32	mrmovl $12(\%ebp),\%ebx$
33	mrmovl $16(\%ebp),\%edx$
34	irmovl \$0,%eax
35	andl %edx,%edx
36	je End
37	
38	Loop:
39	$\operatorname{mrmovl} (\%\operatorname{ecx}), \%\operatorname{esi}$
40	rmmovl %esi,(%ebx)
41	xorl %esi,%eax
42	irmovl \$4,% edi
43	addl %edi,%ecx
44	addl %edi,%ebx
45	irmovl \$-1,%edi
46	addl %edi,%edx
47	jne Loop

### 2.3 Analysis

### 2.3.1 sum.ys

- For the program **sum.ys**, the line  $1 \sim 19$  and line  $37 \sim 38$  are the preparatory work and do not need further explanation. For the main part, which is the sum.ys, first we store the %ebp part to stack, then we set %eax to zero as the inital sum value, %edx as the inital list position, then if the list has reached its end, we jump to state L4, which restore the value. If not, we goto the LOOP L5 part.
- In the L5 part, first %eax + = %esi to add to the sum, then (%edx) + 4 to goto the list's next elements. After doing that, again we judge whether the list has reached its end and the condition is exactly the same.
- Based the outcome of this program, %eax stores the overall sum value, which is 0xcba, %ebp get popped and get its inital value, which is the 0x100, %esi stores the last elements of the list, which is %0xc00, which proves that our program is correct.

#### 2.3.2 rsum.ys

- For the program **rsum.ys**, the line  $1 \sim 17$  and line  $46 \sim 45$  are the preparatory work and do not need further explanation. For the main part, first we let %edx stores the elel, which is the beginning, then we save %edx and call  $rsum\_list$ .
- For the  $rsum\_list$  part(line24 ~ 42),which is the recursive version of the  $sum\_list$ , first we use %edx to get starting adddress, %eax to get the inital result which is 0, then we save %ebx and compare whether %edx is zero or not. If so, goto end, else, goto the next part, which is the recursive part. It is worth noting that in line 39 the constant number 0xfffffffc is -4 and we use this operation to restore %ebx, and in line 25, we push %ebp, in line 41, we pop %ebp, with these two operations we can get the old version of %ebp which is key to our recursive part.
- Based the outcome of this program, %ebp pop out and its inital value is 0x100, %eax stores the overall sum value 0xcba, which proves that our program is correct.

#### 2.3.3 copy.ys

- For the program **copy.ys**, the line  $1 \sim 17$  and line  $53 \sim 54$  are the preparatory work and do not need further explanation. For the main part(line  $18 \sim 26$ ), first we change %eax to 3, %edx to the dest, %ecx to the src and store the value to the stack, then we call Copy function and halt.
- For the Copy function(line  $28 \sim 47$ ), first we let %ebp store %esp, %ecx store src, %ebx store dest, %edx store the length, %eax stores the inital value of the result which is 0, then we

compare whether the copy function has reached its end, is so, goto the End part, else, goto the Loop part.

- For the Loop part, first we get the address of the scr, then we begin the copy process, while we add the src and dest by 4 to move to the next address, in the meantime we let len 1 to serve as flag to decide when to stop.
- Based the outcome of this program, register %eax do the xorl instruction with each value and then add to %eax, so the last value of %eax is 0xcba, also the address 0x0020 value is changed from 0x111 to 0xa, the address 0x0024 value is changed from 0x222 to 0xb0, the address 0x0028 value is changed from 0x333 to 0xc00, which proves that our program is correct.

### 2.4 Outcome

```
🕒 🗊 marshallee@ubuntu: ~/Documents/computer_architecture/project2/Project2/project2-l
marshallee@ubuntu:~/Documents/computer_architecture/project2/Project2/project2-h
andout/sim/sim/misc$ ./yis sum.yo
Stopped in 30 steps at PC = 0x15.
Changes to registers:
                                          Status 'HLT', CC Z=1 S=0 0=0
                             0x00000cba
         0x00000000
%eax:
         0x00000000
                             0x000000fc
%esp:
         0x00000000
                             0x00000100
         0x00000000
                             0x00000c00
Changes to memory:
0x00f4: 0x00000000
                             0x00000100
0x00f8: 0x00000000
                             0x00000015
0x00fc: 0x00000000 0x00000018
marshallee@ubuntu:~/Documents/computer_architecture/project2/Project2/project2-h
andout/sim/sim/misc$
```

```
🕽 🗇 📵 marshallee@ubuntu: ~/Documents/computer_architecture/project2/Project2/project2-l
marshallee@ubuntu:~/Documents/computer_architecture/project2/Project2/project2-h
andout/sim/sim/misc$ ./yis rsum.yo
Stopped in 72 steps at PC = 0x39. Status 'HLT', CC Z=0 S=0 0=0
Changes to registers:
%eax: 0x00000000
%eax:
                           0x00000cba
%esp:
         0x00000000
                           0x000000fc
%ebp:
         0x00000000
                           0x00000100
%esi:
        0x00000000
                           0x0000000c
Changes to memory:
        0x00000000
                           0x00000c00
0x00a0: 0x00000000
                           0x000000bc
0x00a4: 0x00000000
                           0x0000006a
0x00b8: 0x00000000
                           0x000000b0
0x00bc: 0x00000000
                           0x000000d8
0x00c0: 0x00000000
                           0x0000006a
                           0x00000024
        0x00000000
0x00d4: 0x00000000
                           0x0000000a
0x00d8: 0x00000000
                           0x000000f4
0x00dc: 0x00000000
                           0x0000006a
0x00e0: 0x00000000
                           0x0000001c
0x00f4: 0x00000000
                           0x00000100
0x00f8: 0x00000000
                           0x00000039
0x00fc: 0x00000000
                           0x00000014
```

```
marshallee@ubuntu: ~/Documents/computer_architecture/project2/Project2/project2-h
marshallee@ubuntu:~/Documents/computer_architecture/project2/Project2/project2-h
andout/sim/sim/misc$ ./yis copy.yo
Stopped in 48 steps at PC = 0x49. Status 'HLT', CC Z=1 S=0 0=0
Changes to registers:
%eax:
         0x00000000
ecx:
         0x00000000
                              0x00000020
         0x00000000
                              0x0000002c
éebx:
          0x00000000
                              0x000000f4
          0x00000000
                              0x00000100
          0x00000000
          0x00000000
         to memory:
0x00000111
Changes
                              0x0000000a
0x0024:
         0x00000222
                              0x000000b0
         0x00000333
0x0028:
                              0x00000c00
0x00ec: 0x00000000
                              0x00000100
x00f0: 0x00000000
                              0x00000049
x00f4: 0x00000000
                              0x00000014
```

#### 2.5 Review

## 3 Part B

### 3.1 Description

In this part, we are asked to add a new instruction iaddl to the SEQ processor, this instruction is meant to add a constant to a register.

#### 3.2 Solution

Since the code in seq-full.hcl is quite long, I only list the part where we have made changes.

### Fetch Stage

#### Decode Stage

```
int srcB = [
icode in { IOPL, IRMMOVL, IMRMOVL, IIADDL } : rB;
icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
1 : RNONE;
];

int dstE = [
icode in { IRRMOVL } && Cnd : rB;
icode in { IIRMOVL, IOPL, IIADDL} : rB;
icode in { IPUSHL, IPOPL, ICALL, IRET } : RESP;
```

```
1 : RNONE;
12 ];
```

### Execute Stage

```
int aluA = [
         icode in { IRRMOVL, IOPL } : valA;
2
                   { IIRMOVL, IRMMOVL, IMRMOVL, IIADDL } : valC;
         icode in
3
         icode in
                   \{ \text{ ICALL}, \text{ IPUSHL} \} : -4;
         icode in { IRET, IPOPL } : 4;
5
         |;
6
7
         int aluB = [
8
         icode in { IRMMOVL, IMRMOVL, IOPL, ICALL,
9
         IPUSHL, IRET, IPOPL, IIADDL \ : valB;
10
         icode in { IRRMOVL, IIRMOVL } : 0;
11
12
13
         bool set_cc = icode in { IOPL, IIADDL };
14
```

## 3.3 Analysis

It can be implemented by first using *irmovl* instruction to let the register contains the constant number, then we can use *addl* instruction to add the constant number to the destination register. Since there are roughly four stages in the Y86 instruction set, we will fully discuss this part reagarding each stages.

- For the Fetch Stage, first we should add the *IIADDL* instruction to the *instr\_valid*, then we should add the *IIADDL* instruction to the *need\_regids* set, indicating that we should register to do this operation. Finally since we need a constant for add, we need to add the *IIADDL* instruction to the *need\_valc* set.
- For the Decode Stage, first we need to add the IIADDL instruction to the srcB set, indicating that we put the register value in this part, then we need to add the IIADDL instruction to the dstE set, indicating that we store the value in the destination E.
- For the Execute Stage, first we should add the IIADDL instruction to the aluA part, indicating that the ALU operation need the valC, which is the constant value, then we should add the IIADDL instruction to the aluB part, indicating that the ALU operation need the valB, which is the destination register's value, finally we should add the IIADDL instruction to the  $set\_cc$  part, indicating that this instruction may lead the flag register to change.
- For the Memory Stage, since this instruction is to add a constant number to a register, so the Memory Stage don't have to change.

### 3.4 Outcome

#### 3.5 Review

