

```

1  /*
2      Marshall Lindsay
3      Max Houck
4      Formula SAE Tire Temperature Visualization
5      ECE 3220 Final Project
6      main.cpp
7  */
8  #include<windows.h>
9  #include "tires.h"
10 #include "SerialClass.h"
11 #include "CarGraphics.h"
12
13 #define LOGGING_RATE .1
14 #define ACCEPTABLE_PERCENTAGE .05
15
16 void programStart(void);
17 void mainOptionsMenu(void);
18 void dataVisualization(void);
19 void dataVisualizationWelcomeMessage(void);
20 void simulation(Car* car, CarGraphics*);
21 void realTimeDemo(void);
22 Car* carSetup(void);
23 void graphicsSetup(CarGraphics*);
24 void graphicsSetupOptionsMenu(void);
25 void realTimeGraphicsSetup(RealTimeGraphics*);
26 void realTimeGraphicsSetupOptionsMenu(void);
27
28
29 int main() {
30     try{
31         programStart();
32     }
33     catch(...){
34         cout<<"\nProgram Failed. Catch all Main()"<<endl;
35         return(1);
36     }
37 }
38
39 void programStart(void){
40     string userInput;
41     for(int i = 0; i < 60; i++){
42         cout<<"#";
43     }
44     cout<<"\n\nFSAE TIRE TEMPERATURE DATA VISUALIZATION SOFTWARE\n"<<endl;
45     for(int i = 0; i < 60; i++){
46         cout<<"#";
47     }
48     cout<<"\n\nWelcome to version 1 of the FSAE Tire Temperature Visualization
Software!"<<endl;
49     while(1){
50         mainOptionsMenu();
51         getline(cin, userInput);
52
53         if(userInput == "1"){
54             realTimeDemo();
55         }else if(userInput == "2"){
56             dataVisualization();
57         }else if(userInput == "3"){
58             return;
59         }else{
60             cout<<"\n Invalid input!"<<endl;
61         }
62     }
63 }
64
65 void mainOptionsMenu(void){
66     cout<<"\n\nPlease select from the following options: "
67         <<"\n    1)Real time data sensor visualization"
68         <<"\n    2)Data visualization from file and video"

```

```

69         <<"\n    3)Quit"<<endl;
70     }
71
72     void realTimeDemo(void){
73         string userInput;
74         HWND myconsole = GetConsoleWindow();
75         HDC mydc = GetDC(myconsole);
76         RealTimeGraphics* realTime = new RealTimeGraphics();
77         realTimeGraphicsSetup(realTime);
78         cout<<"\n Real Time graphics setup complete... Press any key to begin"<<endl;
79         getline(cin, userInput);
80         Serial* SP;
81
82         while(1){
83             try{
84                 SP = new Serial("COM4"); //We may need to adjust this as necessary
85                 break;
86             }
87             catch(const int x){
88                 if(x == 1){
89                     cout<<"\n Please connect the arduino!"<<endl;
90                     Sleep(3000);
91                 }else if(x == 2){
92                     cout<<"\n Unknown error!"<<endl;
93                 }
94             }
95             catch(...){
96                 cout<<"\n Catch all realTimeDemo. Should not be here!"<<endl;
97             }
98         }
99
100         if (SP->IsConnected()){
101             cout<<"\n Ardiuno Connected!"<<endl;
102         }else{
103             cout<<"\n Arduino not connected?.. Terminating!"<<endl;
104         }
105         char* token;
106         string incomingDataString;
107         char incomingData[256] = "";
108         int dataLength = 255;
109         int readResult = 0;
110         int data1 = 0;
111         int data2 = 0;
112         int data3 = 0;
113         int bufferSize = 5;
114         int bufferHold1,bufferHold2;
115         int buf1[bufferSize], buf2[bufferSize], buf3[bufferSize];
116         int data1Hold, data2Hold, data3Hold;
117         int average1,average2,average3, i;
118
119         int slope1, slope2, slope3;
120         int estimatedPoint1, estimatedPoint2, estimatedPoint3;
121         double percentDiff1, percentDiff2, percentDiff3;
122         double averageDelta;
123         while(1){
124
125             data1Hold = data1;
126             data2Hold = data2;
127             data3Hold = data3;
128             readResult = SP->ReadData(incomingData,dataLength);
129
130             token = strtok(incomingData,","); //parsing serial output from arduino
131             data1 = atoi(token);
132             token = strtok(NULL, ",");
133             data2 = atoi(token);
134             token = strtok(NULL, ",");
135             data3 = atoi(token);
136
137             if(buf1[0] == 0) { //if buffers are empty

```

```

138         for(i=0;i<bufferSize;i++) {
139             buf1[i] = data1; //fill them completely with first value
140             buf2[i] = data2;
141             buf3[i] = data3;
142         }
143     }
144     int sum = 0; //calculate averages of buffers and error check
145     /*
146     for(int i=0;i<bufferSize;i++){
147         sum+=buf1[i];
148     }
149     averagel = sum / bufferSize;
150     sum = 0;
151     for(int i = 0; i < bufferSize; i++){
152         sum += buf1[i] - averagel;
153     }
154     averageDelta = sum / buffersize;
155     percentDiff1 = (data1 - averagel) / averageDelta;
156     if(percentDiff1 > ACCEPTABLE_PERCENTAGE && percentDiff1 <
157        (ACCEPTABLE_PERCENTAGE + .01)
158        || percentDiff1 < ACCEPTABLE_PERCENTAGE && percentDiff1 >
159        (ACCEPTABLE_PERCENTAGE - .01)){
160         data1 *= .9;
161     }
162     if(percentDiff1 > (ACCEPTABLE_PERCENTAGE + .01) && percentDiff1 <
163        (ACCEPTABLE_PERCENTAGE + .05)
164        || percentDiff1 < (ACCEPTABLE_PERCENTAGE - .01) && percentDiff1 >
165        (ACCEPTABLE_PERCENTAGE - .05)){
166         data1 *= .8;
167     }
168     if(percentDiff1 > (ACCEPTABLE_PERCENTAGE + .05) && percentDiff1 <
169        (ACCEPTABLE_PERCENTAGE + .1)
170        || percentDiff1 < (ACCEPTABLE_PERCENTAGE - .05) && percentDiff1 >
171        (ACCEPTABLE_PERCENTAGE - .1)){
172         data1 *= .6;
173     }
174     if(percentDiff1 > (ACCEPTABLE_PERCENTAGE + .1) && percentDiff1 <
175        (ACCEPTABLE_PERCENTAGE + .2)
176        || percentDiff1 < (ACCEPTABLE_PERCENTAGE - .1) && percentDiff1 >
177        (ACCEPTABLE_PERCENTAGE - .2)){
178         data1 *= .;
179     }
180     */
181     sum = 0;
182     for(int i=0;i<bufferSize;i++)
183         sum+=buf1[i];
184     averagel = sum / bufferSize;
185     if (data1 > averagel + 10 | data1 < averagel - 10)
186         data1 = averagel;
187     sum = 0;
188     for(int i=0;i<bufferSize;i++)
189         sum+=buf2[i];
190     average2 = sum / bufferSize;
191     if (data2 > average2 + 10 | data2 < average2 - 10)
192         data2 = average2;
193     sum = 0;
194     for(int i=0;i<bufferSize;i++)
195         sum+=buf3[i];
196     average3 = sum / bufferSize;
197     if (data3 > average3 + 10 | data3 < average3 - 10)
198         data3 = average3;
199
200     //rotate it in the new values to each buffer
201     bufferHold1 = buf1[0];
202     buf1[0] = data1;
203     for(int i=1;i<bufferSize;i++) {
204         bufferHold2 = buf1[i];
205         buf1[i] = bufferHold1;

```

```

199         bufferHold1 = bufferHold2;
200     }
201     bufferHold1 = buf2[0];
202     buf2[0] = data2;
203     for(int i=1;i<bufferSize;i++) {
204         bufferHold2 = buf2[i];
205         buf2[i] = bufferHold1;
206         bufferHold1 = bufferHold2;
207     }
208     bufferHold1 = buf3[0];
209     buf3[0] = data3;
210     for(int i =1;i<bufferSize;i++) {
211         bufferHold2 = buf3[i];
212         buf3[i] = bufferHold1;
213         bufferHold1 = bufferHold2;
214     }
215
216     realTime->setData(data1, data2, data3); //output to graphics
217     realTime->draw(&mydc);
218     Sleep(150);
219 }
220 delete realTime;
221 }
222
223
224
225 void realTimeGraphicsSetup(RealTimeGraphics* graphics){
226     string userInput;
227     HWND myconsole = GetConsoleWindow();
228     HDC mydc = GetDC(myconsole);
229     int value;
230     while(1){
231
232         realTimeGraphicsSetupOptionsMenu();
233         getline(cin,userInput);
234         if(userInput == "1"){
235             graphics->draw(&mydc);
236             getline(cin, userInput);
237         }else if(userInput == "2"){
238             int value2;
239             cout<<"\n Please enter the new X value: "<<endl;
240             cin>>value;
241             cout<<"\n Please enter the new Y value: "<<endl;
242             cin>>value2;
243             graphics->move(value, value2);
244         }else if(userInput == "3"){
245             cout<<"\n Please enter the value you wish to vertically shift the graph
246             by:"<<endl;
247             cin>>value;
248             graphics->verticalShift(value);
249         }else if(userInput == "4"){
250             cout<<"\n Please enter the value you wish to horizontally shift the graph
251             by:"<<endl;
252             cin>>value;
253             graphics->horizontalShift(value);
254         }else if(userInput == "5"){
255             int value2;
256             cout<<"\n Please enter the new length:"<<endl;
257             cin>>value;
258             cout<<"\n Please enter the new width:"<<endl;
259             cin>>value2;
260             graphics->resize(value, value2);
261         }else if(userInput == "6"){
262             int value2;
263             cout<<"\n Please enter the lowest temperature:"<<endl;
264             cin>>value;
265             cout<<"\n Please enter the highest temperature:"<<endl;
266             cin>>value2;
267             graphics->setRange(value, value2);

```

```

266         }else if(userInput == "7"){
267             break;
268         }else{
269             cout<<"\n Invalid Input!"<<endl;
270         }
271
272         fflush(stdin);
273     }
274     return;
275 }
276
277 void realTimeGraphicsSetupOptionsMenu(void) {
278     cout<<"\n Graphics Setup Options:"
279         <<"\n 1)Print"
280         <<"\n 2)Move"
281         <<"\n 3)Vertical Shift"
282         <<"\n 4)Horizontal Shift"
283         <<"\n 5)Resize graph"
284         <<"\n 6)Set temperature range"
285         <<"\n 7)Finish"<<endl;
286 }
287
288 void dataVisualization(void) {
289     string userInput;
290     CarGraphics* graphicsCar = new CarGraphics();
291     graphicsSetup(graphicsCar);
292     Car* car = carSetup();
293
294     cout<<"\n\n\n\n Car creation and GUI setup complete.\nPress any key to
continue"<<endl;
295     getline(cin, userInput);
296     simulation(car, graphicsCar);
297     cout<<"\n Simulation complete!"<<endl;
298     while(1){
299
300         cout<<"\n What would you like to do?"
301         <<"\n 1)Run the simulation"
302         <<"\n 2)Change car data"
303         <<"\n 3)Change graphics settings"
304         <<"\n 4)Quit to main menu"<<endl;
305         getline(cin,userInput);
306
307         if(userInput == "1"){
308             simulation(car, graphicsCar);
309         }else if(userInput == "2"){
310             delete car;
311             car = carSetup();
312         }else if(userInput == "3"){
313             graphicsSetup(graphicsCar);
314         }else if(userInput == "4"){
315             break;
316         }
317     }
318     delete car;
319     delete graphicsCar;
320
321 }
322
323 void graphicsSetup(CarGraphics* car) {
324     string userInput;
325     HWND myconsole = GetConsoleWindow();
326     HDC mydc = GetDC(myconsole);
327     int value;
328     while(1){
329
330         graphicsSetupOptionsMenu();
331         getline(cin,userInput);
332         if(userInput == "1"){
333             car->drawGraphics(&mydc);

```

```

334         car->drawGraphics(&mydc);
335         getline(cin, userInput);
336     }else if(userInput == "2"){
337         int x, y;
338         cout<<"\n Please enter the new X value:"<<endl;
339         cin>>x;
340         cout<<"\n Please enter the new Y value:"<<endl;
341         cin>>y;
342         car->move(x, y);
343     }else if(userInput == "3"){
344         cout<<"\n Please enter the value you wish to shift the object vertically
        by:"<<endl;
345         cin>>value;
346         car->verticalShift(value);
347     }else if(userInput == "4"){
348         cout<<"\n Please enter the value you wish to shift the object horizontally
        by:"<<endl;
349         cin>>value;
350         car->horizontalShift(value);
351     }else if(userInput == "5"){
352         cout<<"\n Please enter the new size for the tires:"<<endl;
353         cin>>value;
354         car->resize(value);
355     }else if(userInput == "6"){
356         cout<<"\n Please enter the new size for the front left tire:"<<endl;
357         cin>>value;
358         car->flResize(value);
359     }else if(userInput == "7"){
360         cout<<"\n Please enter the new size for the front right tire:"<<endl;
361         cin>>value;
362         car->frResize(value);
363     }else if(userInput == "8"){
364         cout<<"\n Please enter the new size for the rear left tire:"<<endl;
365         cin>>value;
366         car->rlResize(value);
367     }else if(userInput == "9"){
368         cout<<"\n Please enter the new size for the rear right tire:"<<endl;
369         cin>>value;
370         car->rrResize(value);
371     }else if(userInput == "10"){
372         cout<<"\n Please enter the new offset value:"<<endl;
373         cin>>value;
374         car->updateOffset(value, value);
375     }else if(userInput == "11"){
376         int value2;
377         cout<<"\n Please enter the low temperature:"<<endl;
378         cin>>value;
379         cout<<"\n Please enter the high temperature:"<<endl;
380         cin>>value2;
381         car->setRange(value, value2);
382     }else if(userInput == "12"){
383         break;
384     }else{
385         cout<<"\nInvalid Input!"<<endl;
386     }
387     fflush(stdin);
388 }
389
390 return;
391 }
392
393 void graphicsSetupOptionsMenu(void){
394     cout<<"\n Graphics Setup Options:"
395         <<"\n 1)Print"
396         <<"\n 2)Move"
397         <<"\n 3)Vertical Shift"
398         <<"\n 4)Horizontal Shift"
399         <<"\n 5)Resize Every Tire"
400         <<"\n 6)Resize Front Left Tire"

```

```

401         <<"\n 7)Resize Front Right Tire"
402         <<"\n 8)Resize Rear Left Tire"
403         <<"\n 9)Resize Rear Right Tire"
404         <<"\n 10)Increase Offset From MidPoint"
405         <<"\n 11)Set temperature range"
406         <<"\n 12)Finish"<<endl;
407     }
408
409
410 void simulation(Car* car, CarGraphics* graphicsCar){
411     HWND myconsole = GetConsoleWindow();
412     HDC mydc = GetDC(myconsole);
413     graphicsCar->setRange(0, 110);
414     for(int i = 0; i < car->numDataPoints(); i++){
415         graphicsCar->setDataFrontLeft(car->getTemperature(frontLeft, outer, i),
416                                     car->getTemperature(frontLeft, middle, i),
417                                     car->getTemperature(frontLeft, inner, i));
418
419         graphicsCar->setDataFrontRight(car->getTemperature(frontRight, outer, i),
420                                     car->getTemperature(frontRight, middle, i),
421                                     car->getTemperature(frontRight, inner, i));
422
423         graphicsCar->setDataRearLeft(car->getTemperature(rearLeft, outer, i),
424                                    car->getTemperature(rearLeft, middle, i),
425                                    car->getTemperature(rearLeft, inner, i));
426
427         graphicsCar->setDataRearRight(car->getTemperature(rearRight, outer, i),
428                                    car->getTemperature(rearRight, middle, i),
429                                    car->getTemperature(rearRight, inner, i));
430         graphicsCar->drawGraphics(&mydc);
431         Sleep(20);
432     }
433 }
434
435
436
437 void dataVisualizationWelcomeMessage(void){
438     string input;
439     for(int i = 0; i < 60; i++){
440         cout<<"-";
441     }
442     cout<<"\n Setup Wizard"<<endl;
443     cout<<"\n This wizard will guide you through the steps to set up your data for"
444         <<"\n visualization. Please follow the steps carefully."
445         <<"\n Press any key to continue"<<endl;
446
447     getline(cin,input);
448 }
449
450 Car* carSetup(void){
451     string userInput;
452     dataVisualizationWelcomeMessage();
453     ifstream dataFile1, dataFile2, dataFile3, dataFile4;
454
455     cout<<"\n Please enter the name of the car : "<<endl;
456     getline(cin, userInput);
457
458     Car* car = new Car(userInput);
459     try{
460
461         while(1){
462             cout<<"\n Please enter the name of the data file for the Front Left Tire:
463             "<<endl;
464             getline(cin, userInput);
465             if(userInput == "quit"){
466                 throw(1);
467             }
468             dataFile1.open((userInput.c_str()), ios::in);
469             if(!dataFile1.is_open()){

```

```

469         cout<<"\n Could not open the file! Please try again or enter 'quit' to
            exit"<<endl;
470     }else{
471         break;
472     }
473 }
474
475 while(1){
476     cout<<"\n Please enter the name of the data file for the Front Right Tire:
        "<<endl;
477     getline(cin, userInput);
478     if(userInput == "quit"){
479         dataFile1.close();
480         throw(1);
481     }
482     dataFile2.open((userInput.c_str()), ios::in);
483     if(!dataFile2.is_open()){
484         cout<<"\n Could not open the file! Please try again or enter 'quit' to
            exit"<<endl;
485     }else{
486         break;
487     }
488 }
489
490 while(1){
491     cout<<"\n Please enter the name of the data file for the Rear Left Tire:
        "<<endl;
492     getline(cin, userInput);
493     if(userInput == "quit"){
494         dataFile1.close();
495         dataFile2.close();
496         throw(1);
497     }
498     dataFile3.open((userInput.c_str()), ios::in);
499     if(!dataFile3.is_open()){
500         cout<<"\n Could not open the file! Please try again or enter 'quit' to
            exit"<<endl;
501     }else{
502         break;
503     }
504 }
505
506 while(1){
507     cout<<"\n Please enter the name of the data file for the Rear Right Tire:
        "<<endl;
508     getline(cin, userInput);
509     if(userInput == "quit"){
510         dataFile3.close();
511         throw(1);
512     }
513     dataFile4.open((userInput.c_str()), ios::in);
514     if(!dataFile4.is_open()){
515         cout<<"\n Could not open the file! Please try again or enter 'quit' to
            exit"<<endl;
516     }else{
517         break;
518     }
519 }
520 cout<<"\n Please wait while the Car is created and the data imported..."<<endl;
521 string line;
522 char* token;
523
524 //Front left tire creation
525 Tire FL(frontLeft, "FrontLeft");
526 Sensor FL_Outer("FL_Outer", outer, 0x5A);
527 Sensor FL_Middle("FL_Middle", middle, 0x5A);
528 Sensor FL_Inner("FL_Inner", inner, 0x5A);
529 //Data for the sensor objects.
530 while(getline(dataFile1, line)){

```



```

531         token = strtok((char*)line.c_str(), ",");
532         FL_Outer.addTemperature(atoi(token));
533         token = strtok(NULL, ",");
534         FL_Middle.addTemperature(atoi(token));
535         token = strtok(NULL, ",");
536         FL_Inner.addTemperature(atoi(token));
537     }
538     dataFile1.close();
539     //Add the sensors to the tire
540     FL.addSensor(FL_Outer);
541     FL.addSensor(FL_Middle);
542     FL.addSensor(FL_Inner);
543
544     //Front right tire creation
545     Tire FR(frontRight, "FrontRight");
546     Sensor FR_Outer("FR_Outer", outer, 0x5A);
547     Sensor FR_Middle("FR_Middle", middle, 0x5A);
548     Sensor FR_Inner("FR_Inner", inner, 0x5A);
549     while(getline(dataFile2, line)){
550         token = strtok((char*)line.c_str(), ",");
551         FR_Outer.addTemperature(atoi(token));
552         token = strtok(NULL, ",");
553         FR_Middle.addTemperature(atoi(token));
554         token = strtok(NULL, ",");
555         FR_Inner.addTemperature(atoi(token));
556     }
557     dataFile2.close();
558
559     //Add the sensors to the tire
560     FR.addSensor(FR_Outer);
561     FR.addSensor(FR_Middle);
562     FR.addSensor(FR_Inner);
563
564     //Rear left tire creation
565     Tire RL(rearLeft, "RearLeft");
566     Sensor RL_Outer("RL_Outer", outer, 0x5A);
567     Sensor RL_Middle("RL_Middle", middle, 0x5A);
568     Sensor RL_Inner("RL_Inner", inner, 0x5A);
569     while(getline(dataFile3, line)){
570         token = strtok((char*)line.c_str(), ",");
571         RL_Outer.addTemperature(atoi(token));
572         token = strtok(NULL, ",");
573         RL_Middle.addTemperature(atoi(token));
574         token = strtok(NULL, ",");
575         RL_Inner.addTemperature(atoi(token));
576     }
577     dataFile3.close();
578
579     //Add the sensors to the tire
580     RL.addSensor(RL_Outer);
581     RL.addSensor(RL_Middle);
582     RL.addSensor(RL_Inner);
583
584     //Rear right tire creation
585     Tire RR(rearRight, "RearRight");
586     Sensor RR_Outer("RR_Outer", outer, 0x5A);
587     Sensor RR_Middle("RR_Middle", middle, 0x5A);
588     Sensor RR_Inner("RR_Inner", inner, 0x5A);
589     while(getline(dataFile4, line)){
590         token = strtok((char*)line.c_str(), ",");
591         RR_Outer.addTemperature(atoi(token));
592         token = strtok(NULL, ",");
593         RR_Middle.addTemperature(atoi(token));
594         token = strtok(NULL, ",");
595         RR_Inner.addTemperature(atoi(token));
596     }
597     dataFile4.close();
598     //Add the sensors to the tire
599     RR.addSensor(RR_Outer);

```

```
600         RR.addSensor(RR_Middle);
601         RR.addSensor(RR_Inner);
602
603         //Add all of the tires to the car
604         car->addTire(FL);
605         car->addTire(FR);
606         car->addTire(RL);
607         car->addTire(RR);
608
609         return(car);
610     }
611     catch(...){
612         return(NULL);
613     }
614 }
615
```