

Numbers and Points

Overview

Julian Pfeifle

Dept. Matemàtica Aplicada II
Universitat Politècnica de Catalunya



Computational Geometry 2018

Computational Geometry is about ... Computing

... and *computing* means: Algorithms work on numbers.

What is a number?

\mathbb{N}, \mathbb{Z}	int, long int, long long int or work with arbitrary precision (slower)	$-9.2 \cdot 10^{18} \dots 9.2 \cdot 10^{18}$ gmp <code>lib.org</code>
\mathbb{Q}	$\{(n, d) : n \in \mathbb{Z}, d \in \mathbb{N}_{>0}\} / \sim$, where $(n, d) \sim (n', d')$ iff $nd' = n'd$	gmp <code>lib.org</code>
\mathbb{R}	algebraic numbers ok ($\sqrt{2}$, $\sqrt[4]{3}$), transcendental ones not (π , e)	cgal <code>.org</code> , mpfr <code>.org</code>
\mathbb{C}, \mathbb{H}	pairs or quadruples of reals	<code>#include <complex></code>

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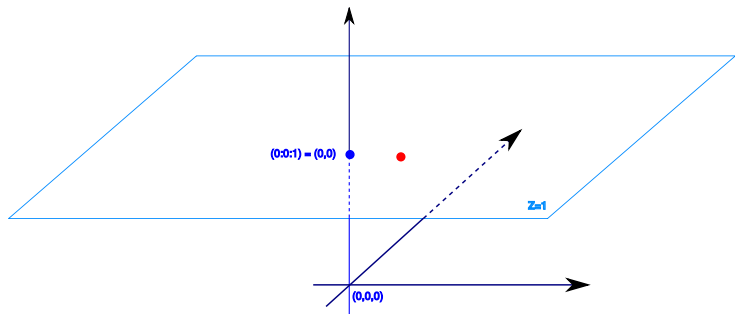
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How much space does a number occupy on your hard disk?

Roughly $\log_2 n$ bits.

$(5 \cdot 10^{12})$ digits of π occupy 8.32 TB as .txt, 3.8 TB compressed)

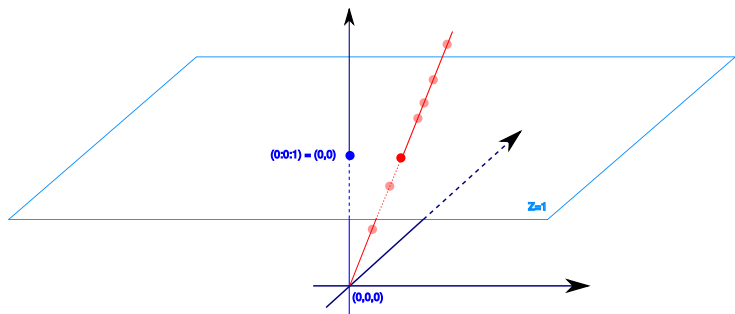
Computational Geometry is about ... Geometry



Homogeneous coordinates for points in the plane

- Embed \mathbb{R}^2 at height 1 into \mathbb{R}^3 : $(x, y) \mapsto (x : y : 1)$

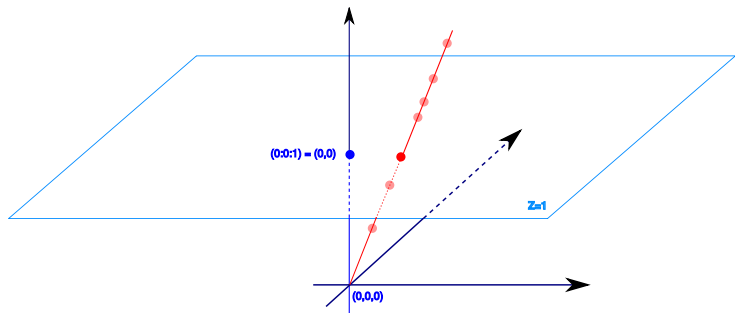
Computational Geometry is about ... Geometry



Homogeneous coordinates for points in the plane

- ▶ **Embed** \mathbb{R}^2 at height 1 into \mathbb{R}^3 : $(x, y) \mapsto (x : y : 1)$
- ▶ **Identify** points on a ray through the origin:
 $(x : y : 1) \sim (\lambda x : \lambda y : \lambda)$, for any $\lambda > 0$

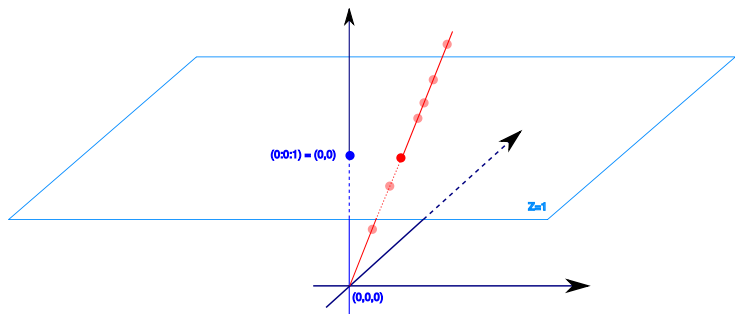
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- ▶ **Subtlety**: $\lambda > 0$ makes **oriented projective geometry** (we use this)

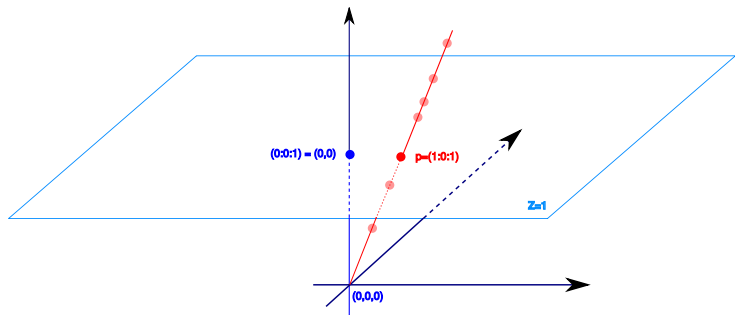
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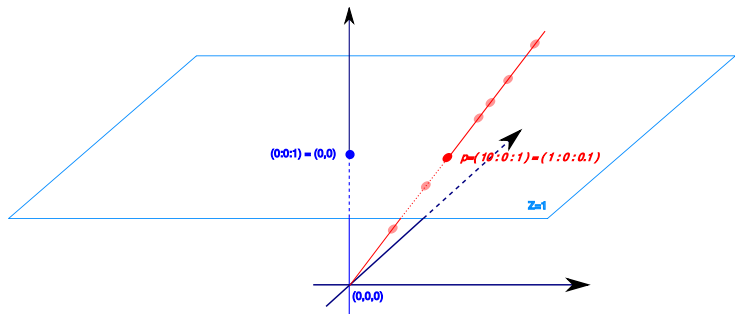
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- ▶ **Identify** points on a ray through the origin:
 $(x : y : 1) \sim (\lambda x : \lambda y : \lambda)$, for any $\lambda > 0$
- ▶ **Subtlety**: $\lambda \neq 0$ makes **projective geometry**

Computational Geometry is about ... Geometry



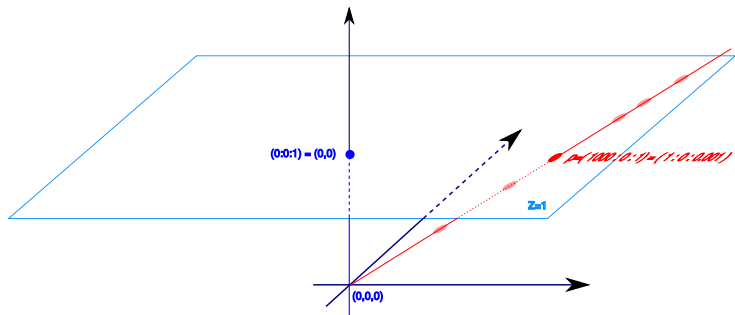
What happens if the last coordinate is zero?

Computational Geometry is about ... Geometry



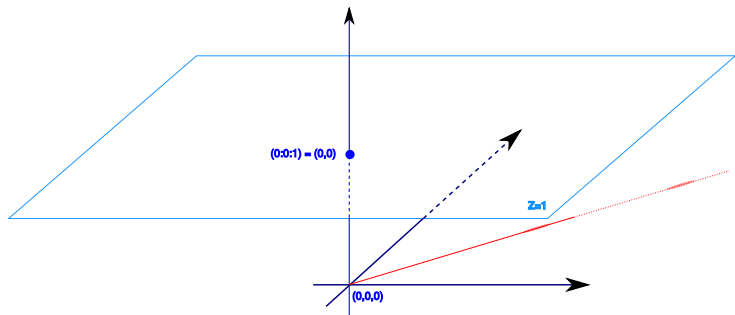
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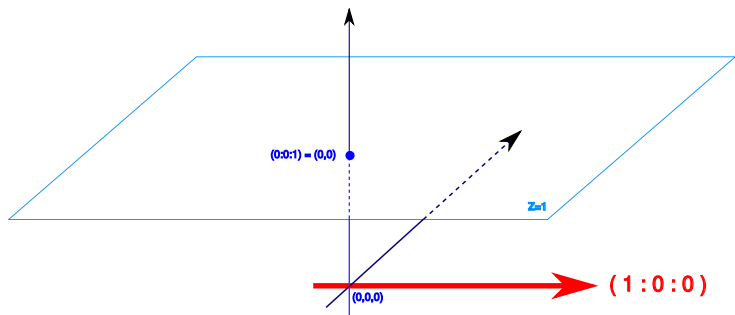
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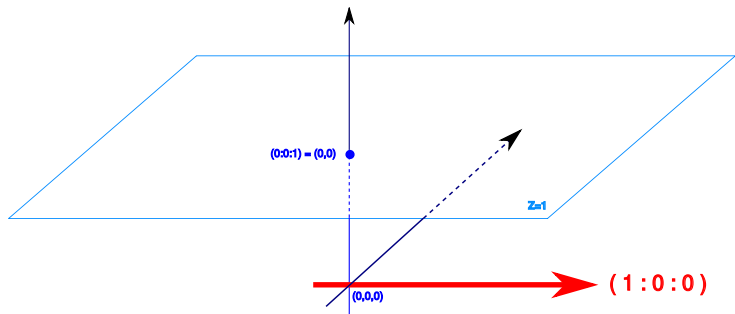
Computational Geometry is about ... Geometry



What happens if the last coordinate is zero?

These vectors correspond to **points at infinity**.

Computational Geometry is about ... Geometry



What happens if the last coordinate is zero?

These vectors correspond to **points at infinity**.
The only meaningless vector is $(0, 0, 0)$.

Operating with homogeneous coordinates

Homogeneous coordinates for **points**:

$$(x, y) \longleftrightarrow (x : y : 1)$$

Homogeneous coordinates for **lines**:

$$ax + by + c = 0 \longleftrightarrow (a : b : c)$$

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Incidence relationships

When does $p = (x : y : 1)$ lie on $\ell = (a : b : c)$?

Answer: When $ax + by + c = \langle (a, b, c), (x, y, 1) \rangle = 0$.

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Incidence relationships

When does $p = (x : y : 1)$ lie on $\ell = (a : b : c)$?

Answer: When $ax + by + c = \langle (a, b, c), (x, y, 1) \rangle = 0$. $p \perp \ell$

Operating with homogeneous coordinates: lines

The line ℓ through points p_1 and p_2

- ▶ p_1 lies on ℓ : $p_1 \perp \ell$
- ▶ p_2 lies on ℓ : $p_2 \perp \ell$

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Example (The line ℓ through $(1, 2) = (1 : 2 : 1)$ and $(3, -4) = (3 : -4 : 1)$)

$$\ell = (1, 2, 1) \times (3, -4, 1) = (6 : 2 : -10) \sim (3 : 1 : -5).$$

This is correct, because both points satisfy $3x + y - 5 = 0$.

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Example (The x -axis)

$$y = 0 \quad \longleftrightarrow \quad 0 \cdot x + 1 \cdot y + 0 = 0 \quad \longleftrightarrow \quad (0 : 1 : 0)$$

Operating with homogeneous coordinates: points

The point q on lines ℓ_1 and ℓ_2

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$$q = (3, 1, -5) \times (0, 1, 0) = (5 : 0 : 3) \sim \left(\frac{5}{3} : 0 : 1\right).$$

This is correct, because this point lies on both lines.

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Watch out: Choose the order of the factors in $p \times q$ so that the last coordinate is **nonnegative**.

Operating with homogeneous coordinates: special cases

Where do parallel lines intersect?

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$l_1 \times l_2 = l_1 \times l_1 = (0, 0, 0)$, the only vector that has no meaning.

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*The **only** way to get $(0, 0, 0)$ is to intersect two equal lines,
or to calculate the line through two equal points.*

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What is the line through two points at infinity?

$(x_1 : y_1 : 0) \times (x_2 : y_2 : 0) = (0 : 0 : x_1 y_2 - x_2 y_1) \sim (0 : 0 : 1)$,
the line at infinity.

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$(x_1 : y_1 : 0) \times (x_2 : y_2 : 0) = (0 : 0 : x_1 y_2 - x_2 y_1) \sim (0 : 0 : 1)$,
the line at infinity.
(Unless the points coincide (are proportional); then you get $(0, 0, 0)$.)

Computational Geometry is about ... algorithms & coding

Let's intersect lines and join points, first in **homogeneous coordinates**.

```
void intersect_lines(const vec_t& l1, const vec_t& l2, vec_t& p)
{
    cross_product(l1, l2, p);
}
void join_points(const vec_t& p1, const vec_t& p2, vec_t& l)
{
    cross_product(p1, p2, l);
}
void cross_product(const vec_t& l1, const vec_t& l2, vec_t& p)
{
    p[0] =  l1[1]*l2[2] - l1[2]*l2[1];
    p[1] = -l1[0]*l2[2] + l1[2]*l2[0];
    p[2] =  l1[0]*l2[1] - l1[1]*l2[0];
}
```

- This code is **correct, efficient, and robust**.

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{
    p[0] =  l1[1]*l2[2] - l1[2]*l2[1];
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- This code is **correct**, **efficient**, and **robust**.
It calculates exactly what it should.

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No extraneous copying (&); reuse of code

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No influence of rounding errors

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}
```

- This code is **correct**, **efficient**, and **robust**.
It handles all cases, even degenerate ones.

Computational Geometry is about ... algorithms & coding

Now let's intersect lines in **Cartesian coordinates**.

A line is now $y = kx + d$, stored as a vector (k, d) .

```
bool intersect_lines(const vec_t& l1, const vec_t& l2, vec_t& p) {  
    if (l1[0]==l2[0]) {  
        if (l1[1]==l2[1]) {  
            return COINCIDENT_LINES;  
        }  
        return PARALLEL_LINES;  
    }  
    p[0] = (l2[1]-l1[1])/(l1[0]-l2[0]);  
    p[1] = l1[0]*p[0] + l1[1];  
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```

- This code is **somewhat efficient**, **not robust**, and *not even correct*.

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- This code is **somewhat efficient**, **not robust**, and *not even correct*.
Again, no copying; **BUT**: no reuse of code for `join_points`

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    p[1] = l1[0]*p[0] + l1[1];  
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- This code is **somewhat efficient**, **not robust**, and *not even correct*.
It's unstable numerically (`==`, `/`)—say `if (fabs(l1[0]-l2[0]) < EPS)`

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```

- This code is **somewhat efficient**, **not robust**, and *not even correct*.
It doesn't handle parallel lines, but that's Euclidean geometry's fault.

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}
```

- This code is **somewhat efficient**, **not robust**, and **not even correct**. But it **IS the code's fault** that it doesn't handle vertical lines! Need:

```
class line {
    bool is_vertical;
    vec_t k_and_d;
};
```

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}
```

- ▶ This code is **somewhat efficient**, **not robust**, and **not even correct**. But it **IS the code's fault** that it doesn't handle vertical lines! Need:
- ▶ It's much harder to get right, because of **more special cases**.
- ▶ It needs an **extra variable**, the boolean return value.