

OperationalState::suspend

RealTimeLoopOuterState
::suspend

SuspendedState::getInstance

```
graph LR; A[OperationalState::suspend] --> C[SuspendedState::getInstance]; B[RealTimeLoopOuterState::suspend] --> C;
```

The diagram illustrates a state management pattern. On the left, two white rectangular boxes represent different states: 'OperationalState::suspend' and 'RealTimeLoopOuterState::suspend'. On the right, a gray rectangular box represents 'SuspendedState::getInstance'. Two blue arrows point from the right side of each white box to the left side of the gray box, indicating that both states share or reference the same instance of the suspended state.