

```
> restart; with(LinearAlgebra) :
```

```
> n := 10;
```

$n := 10$

(1)

```
> Theta := Matrix(n, symbol = theta)
```

$$\Theta := \begin{bmatrix} \theta_{1,1} & \theta_{1,2} & \theta_{1,3} & \theta_{1,4} & \theta_{1,5} & \theta_{1,6} & \theta_{1,7} & \theta_{1,8} & \theta_{1,9} & \theta_{1,10} \\ \theta_{2,1} & \theta_{2,2} & \theta_{2,3} & \theta_{2,4} & \theta_{2,5} & \theta_{2,6} & \theta_{2,7} & \theta_{2,8} & \theta_{2,9} & \theta_{2,10} \\ \theta_{3,1} & \theta_{3,2} & \theta_{3,3} & \theta_{3,4} & \theta_{3,5} & \theta_{3,6} & \theta_{3,7} & \theta_{3,8} & \theta_{3,9} & \theta_{3,10} \\ \theta_{4,1} & \theta_{4,2} & \theta_{4,3} & \theta_{4,4} & \theta_{4,5} & \theta_{4,6} & \theta_{4,7} & \theta_{4,8} & \theta_{4,9} & \theta_{4,10} \\ \theta_{5,1} & \theta_{5,2} & \theta_{5,3} & \theta_{5,4} & \theta_{5,5} & \theta_{5,6} & \theta_{5,7} & \theta_{5,8} & \theta_{5,9} & \theta_{5,10} \\ \theta_{6,1} & \theta_{6,2} & \theta_{6,3} & \theta_{6,4} & \theta_{6,5} & \theta_{6,6} & \theta_{6,7} & \theta_{6,8} & \theta_{6,9} & \theta_{6,10} \\ \theta_{7,1} & \theta_{7,2} & \theta_{7,3} & \theta_{7,4} & \theta_{7,5} & \theta_{7,6} & \theta_{7,7} & \theta_{7,8} & \theta_{7,9} & \theta_{7,10} \\ \theta_{8,1} & \theta_{8,2} & \theta_{8,3} & \theta_{8,4} & \theta_{8,5} & \theta_{8,6} & \theta_{8,7} & \theta_{8,8} & \theta_{8,9} & \theta_{8,10} \\ \theta_{9,1} & \theta_{9,2} & \theta_{9,3} & \theta_{9,4} & \theta_{9,5} & \theta_{9,6} & \theta_{9,7} & \theta_{9,8} & \theta_{9,9} & \theta_{9,10} \\ \theta_{10,1} & \theta_{10,2} & \theta_{10,3} & \theta_{10,4} & \theta_{10,5} & \theta_{10,6} & \theta_{10,7} & \theta_{10,8} & \theta_{10,9} & \theta_{10,10} \end{bmatrix}$$

(2)

```
> LinearAlgebra:-Map[ (i,j) → evalb(i ≤ j) ](x→0, Theta);
```

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{2,1} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{3,1} & \theta_{3,2} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{4,1} & \theta_{4,2} & \theta_{4,3} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{5,1} & \theta_{5,2} & \theta_{5,3} & \theta_{5,4} & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{6,1} & \theta_{6,2} & \theta_{6,3} & \theta_{6,4} & \theta_{6,5} & 0 & 0 & 0 & 0 & 0 \\ \theta_{7,1} & \theta_{7,2} & \theta_{7,3} & \theta_{7,4} & \theta_{7,5} & \theta_{7,6} & 0 & 0 & 0 & 0 \\ \theta_{8,1} & \theta_{8,2} & \theta_{8,3} & \theta_{8,4} & \theta_{8,5} & \theta_{8,6} & \theta_{8,7} & 0 & 0 & 0 \\ \theta_{9,1} & \theta_{9,2} & \theta_{9,3} & \theta_{9,4} & \theta_{9,5} & \theta_{9,6} & \theta_{9,7} & \theta_{9,8} & 0 & 0 \\ \theta_{10,1} & \theta_{10,2} & \theta_{10,3} & \theta_{10,4} & \theta_{10,5} & \theta_{10,6} & \theta_{10,7} & \theta_{10,8} & \theta_{10,9} & 0 \end{bmatrix}$$

(3)

```
> A :=
```

```
ImportMatrix("/Users/polisank/Professionnel/Travaux/Recherche/Graphical models/graph-  
generation/marthyna/chordal_adj.txt", delimiter = " ");
```

$$A := \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 1 & 1 & 0 & 0 & 1 & 1 & 0 \end{bmatrix} \quad (4)$$

> Theta := LinearAlgebra:-Map[(i,j) → evalb(A[i,j] = 0 and j < i)](x → $\frac{\mathbf{Pi}}{2}$, Theta);

$$\Theta := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_{2,1} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \frac{\pi}{2} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \theta_{4,2} & \theta_{4,3} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \theta_{5,2} & \theta_{5,3} & \theta_{5,4} & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \frac{\pi}{2} & \frac{\pi}{2} & \theta_{6,4} & \frac{\pi}{2} & 0 & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \theta_{7,2} & \frac{\pi}{2} & \theta_{7,4} & \frac{\pi}{2} & \frac{\pi}{2} & 0 & 0 & 0 & 0 \\ \frac{\pi}{2} & \theta_{8,2} & \theta_{8,3} & \theta_{8,4} & \theta_{8,5} & \theta_{8,6} & \frac{\pi}{2} & 0 & 0 & 0 \\ \frac{\pi}{2} & \frac{\pi}{2} & \frac{\pi}{2} & \theta_{9,4} & \theta_{9,5} & \frac{\pi}{2} & \frac{\pi}{2} & \theta_{9,8} & 0 & 0 \\ \frac{\pi}{2} & \theta_{10,2} & \theta_{10,3} & \theta_{10,4} & \theta_{10,5} & \frac{\pi}{2} & \frac{\pi}{2} & \theta_{10,8} & \theta_{10,9} & 0 \end{bmatrix} \quad (5)$$

> b := (i,j) → cos(Theta[i,j]) · product(sin('Theta[i,k]'), k = 1..j - 1)

$$b := (i,j) \mapsto \cos(\Theta_{i,j}) \cdot \left(\prod_{k=1}^{j-1} \sin(\Theta_{i,k}) \right) \quad (6)$$

> B := Matrix(n, b)

$$\begin{aligned}
B := & \left[\left[1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0 \right], \right. \\
& \left[\cos(\theta_{2,1}), \sin(\theta_{2,1}), 0, 0, 0, 0, 0, 0, 0, 0, 0 \right], \\
& \left[0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0 \right], \\
& \left[0, \cos(\theta_{4,2}), \cos(\theta_{4,3}) \sin(\theta_{4,2}), \sin(\theta_{4,2}) \sin(\theta_{4,3}), 0, 0, 0, 0, 0, 0, 0 \right], \\
& \left[0, \cos(\theta_{5,2}), \cos(\theta_{5,3}) \sin(\theta_{5,2}), \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}), \right. \\
& \left. \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}), 0, 0, 0, 0, 0 \right], \\
& \left[0, 0, 0, \cos(\theta_{6,4}), 0, \sin(\theta_{6,4}), 0, 0, 0, 0, 0 \right], \\
& \left[0, \cos(\theta_{7,2}), 0, \cos(\theta_{7,4}) \sin(\theta_{7,2}), 0, 0, \sin(\theta_{7,2}) \sin(\theta_{7,4}), 0, 0, 0, 0 \right], \\
& \left[0, \cos(\theta_{8,2}), \cos(\theta_{8,3}) \sin(\theta_{8,2}), \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}), \right. \\
& \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}), \cos(\theta_{8,6}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}), \\
& 0, \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}) \sin(\theta_{8,6}), 0, 0 \right], \\
& \left[0, 0, 0, \cos(\theta_{9,4}), \cos(\theta_{9,5}) \sin(\theta_{9,4}), 0, 0, \cos(\theta_{9,8}) \sin(\theta_{9,4}) \sin(\theta_{9,5}), \right. \\
& \left. \sin(\theta_{9,4}) \sin(\theta_{9,5}) \sin(\theta_{9,8}), 0 \right], \\
& \left[0, \cos(\theta_{10,2}), \cos(\theta_{10,3}) \sin(\theta_{10,2}), \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}), \right. \\
& \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}), 0, 0, \\
& \cos(\theta_{10,8}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}), \\
& \cos(\theta_{10,9}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}) \sin(\theta_{10,8}), \\
& \left. \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}) \sin(\theta_{10,8}) \sin(\theta_{10,9}) \right] \left. \right]
\end{aligned} \tag{7}$$

$$\triangleright R := B \cdot B^{\wedge \% T}$$

$$\begin{aligned}
R := & \left[\left[1, \cos(\theta_{2,1}), 0, 0, 0, 0, 0, 0, 0, 0, 0 \right], \right. \\
& \left[\cos(\theta_{2,1}), \cos(\theta_{2,1})^2 + \sin(\theta_{2,1})^2, 0, \sin(\theta_{2,1}) \cos(\theta_{4,2}), \sin(\theta_{2,1}) \cos(\theta_{5,2}), 0, \right. \\
& \left. \sin(\theta_{2,1}) \cos(\theta_{7,2}), \sin(\theta_{2,1}) \cos(\theta_{8,2}), 0, \sin(\theta_{2,1}) \cos(\theta_{10,2}) \right], \\
& \left[0, 0, 1, \cos(\theta_{4,3}) \sin(\theta_{4,2}), \cos(\theta_{5,3}) \sin(\theta_{5,2}), 0, 0, \cos(\theta_{8,3}) \sin(\theta_{8,2}), 0, \right. \\
& \left. \cos(\theta_{10,3}) \sin(\theta_{10,2}) \right], \\
& \left[0, \sin(\theta_{2,1}) \cos(\theta_{4,2}), \cos(\theta_{4,3}) \sin(\theta_{4,2}), \cos(\theta_{4,2})^2 + \cos(\theta_{4,3})^2 \sin(\theta_{4,2})^2 \right. \\
& + \sin(\theta_{4,2})^2 \sin(\theta_{4,3})^2, \cos(\theta_{4,2}) \cos(\theta_{5,2}) + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{5,3}) \sin(\theta_{5,2}) \\
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}), \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{6,4}), \\
& \cos(\theta_{4,2}) \cos(\theta_{7,2}) + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \cos(\theta_{4,2}) \cos(\theta_{8,2}) \\
& \left. + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{8,3}) \sin(\theta_{8,2}) \right]
\end{aligned} \tag{8}$$

$$\begin{aligned}
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}), \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{9,4}), \\
& \cos(\theta_{4,2}) \cos(\theta_{10,2}) + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3})], \\
& [0, \sin(\theta_{2,1}) \cos(\theta_{5,2}), \cos(\theta_{5,3}) \sin(\theta_{5,2}), \cos(\theta_{4,2}) \cos(\theta_{5,2}) \\
& + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{5,3}) \sin(\theta_{5,2}) \\
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}), \cos(\theta_{5,2})^2 + \cos(\theta_{5,3})^2 \sin(\theta_{5,2})^2 \\
& + \cos(\theta_{5,4})^2 \sin(\theta_{5,2})^2 \sin(\theta_{5,3})^2 + \sin(\theta_{5,2})^2 \sin(\theta_{5,3})^2 \sin(\theta_{5,4})^2, \\
& \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{6,4}), \cos(\theta_{5,2}) \cos(\theta_{7,2}) \\
& + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \cos(\theta_{5,2}) \cos(\theta_{8,2}) \\
& + \cos(\theta_{5,3}) \sin(\theta_{5,2}) \cos(\theta_{8,3}) \sin(\theta_{8,2}) \\
& + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}), \\
& \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{9,4}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{9,5}) \sin(\theta_{9,4}), \cos(\theta_{5,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{5,3}) \sin(\theta_{5,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4})], \\
& [0, 0, 0, \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{6,4}), \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{6,4}), \cos(\theta_{6,4})^2 \\
& + \sin(\theta_{6,4})^2, \cos(\theta_{6,4}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \cos(\theta_{6,4}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \\
& + \sin(\theta_{6,4}) \cos(\theta_{8,6}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}), \cos(\theta_{6,4}) \cos(\theta_{9,4}), \\
& \cos(\theta_{6,4}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3})], \\
& [0, \sin(\theta_{2,1}) \cos(\theta_{7,2}), 0, \cos(\theta_{4,2}) \cos(\theta_{7,2}) + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \\
& \cos(\theta_{5,2}) \cos(\theta_{7,2}) + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \\
& \cos(\theta_{6,4}) \cos(\theta_{7,4}) \sin(\theta_{7,2}), \cos(\theta_{7,2})^2 + \cos(\theta_{7,4})^2 \sin(\theta_{7,2})^2 + \sin(\theta_{7,2})^2 \sin(\theta_{7,4})^2, \\
& \cos(\theta_{7,2}) \cos(\theta_{8,2}) + \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}), \\
& \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{9,4}), \cos(\theta_{7,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3})], \\
& [0, \sin(\theta_{2,1}) \cos(\theta_{8,2}), \cos(\theta_{8,3}) \sin(\theta_{8,2}), \cos(\theta_{4,2}) \cos(\theta_{8,2})
\end{aligned}$$

$$\begin{aligned}
& + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{8,3}) \sin(\theta_{8,2}) \\
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}), \cos(\theta_{5,2}) \cos(\theta_{8,2}) \\
& + \cos(\theta_{5,3}) \sin(\theta_{5,2}) \cos(\theta_{8,3}) \sin(\theta_{8,2}) \\
& + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}), \\
& \cos(\theta_{6,4}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \\
& + \sin(\theta_{6,4}) \cos(\theta_{8,6}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}), \cos(\theta_{7,2}) \cos(\theta_{8,2}) \\
& + \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}), \cos(\theta_{8,2})^2 + \cos(\theta_{8,3})^2 \sin(\theta_{8,2})^2 \\
& + \cos(\theta_{8,4})^2 \sin(\theta_{8,2})^2 \sin(\theta_{8,3})^2 + \cos(\theta_{8,5})^2 \sin(\theta_{8,2})^2 \sin(\theta_{8,3})^2 \sin(\theta_{8,4})^2 \\
& + \cos(\theta_{8,6})^2 \sin(\theta_{8,2})^2 \sin(\theta_{8,3})^2 \sin(\theta_{8,4})^2 \sin(\theta_{8,5})^2 \\
& + \sin(\theta_{8,2})^2 \sin(\theta_{8,3})^2 \sin(\theta_{8,4})^2 \sin(\theta_{8,5})^2 \sin(\theta_{8,6})^2, \\
& \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \cos(\theta_{9,4}) \\
& + \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \cos(\theta_{9,5}) \sin(\theta_{9,4}) \\
& + \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}) \sin(\theta_{8,6}) \cos(\theta_{9,8}) \sin(\theta_{9,4}) \sin(\theta_{9,5}), \\
& \cos(\theta_{8,2}) \cos(\theta_{10,2}) + \cos(\theta_{8,3}) \sin(\theta_{8,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \\
& + \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}) \sin(\theta_{8,6}) \cos(\theta_{10,8}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& \sin(\theta_{10,4}) \sin(\theta_{10,5})], \\
& [0, 0, 0, \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{9,4}), \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{9,4}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{9,5}) \sin(\theta_{9,4}), \cos(\theta_{6,4}) \cos(\theta_{9,4}), \\
& \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{9,4}), \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \cos(\theta_{9,4}) \\
& + \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \cos(\theta_{9,5}) \sin(\theta_{9,4}) \\
& + \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}) \sin(\theta_{8,6}) \cos(\theta_{9,8}) \sin(\theta_{9,4}) \sin(\theta_{9,5}), \\
& \cos(\theta_{9,4})^2 + \cos(\theta_{9,5})^2 \sin(\theta_{9,4})^2 + \cos(\theta_{9,8})^2 \sin(\theta_{9,4})^2 \sin(\theta_{9,5})^2 \\
& + \sin(\theta_{9,4})^2 \sin(\theta_{9,5})^2 \sin(\theta_{9,8})^2, \cos(\theta_{9,4}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \cos(\theta_{9,5}) \sin(\theta_{9,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \\
& + \cos(\theta_{9,8}) \sin(\theta_{9,4}) \sin(\theta_{9,5}) \cos(\theta_{10,8}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5})
\end{aligned}$$

$$\begin{aligned}
& + \sin(\theta_{9,4}) \sin(\theta_{9,5}) \sin(\theta_{9,8}) \cos(\theta_{10,9}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}) \\
& \sin(\theta_{10,8}) \Big], \\
& \Big[0, \sin(\theta_{2,1}) \cos(\theta_{10,2}), \cos(\theta_{10,3}) \sin(\theta_{10,2}), \cos(\theta_{4,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{4,3}) \sin(\theta_{4,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \sin(\theta_{4,2}) \sin(\theta_{4,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}), \cos(\theta_{5,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{5,3}) \sin(\theta_{5,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \cos(\theta_{5,4}) \sin(\theta_{5,2}) \sin(\theta_{5,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \sin(\theta_{5,2}) \sin(\theta_{5,3}) \sin(\theta_{5,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}), \\
& \cos(\theta_{6,4}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}), \cos(\theta_{7,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{7,4}) \sin(\theta_{7,2}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}), \cos(\theta_{8,2}) \cos(\theta_{10,2}) \\
& + \cos(\theta_{8,3}) \sin(\theta_{8,2}) \cos(\theta_{10,3}) \sin(\theta_{10,2}) \\
& + \cos(\theta_{8,4}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \cos(\theta_{8,5}) \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \\
& + \sin(\theta_{8,2}) \sin(\theta_{8,3}) \sin(\theta_{8,4}) \sin(\theta_{8,5}) \sin(\theta_{8,6}) \cos(\theta_{10,8}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& \sin(\theta_{10,4}) \sin(\theta_{10,5}), \cos(\theta_{9,4}) \cos(\theta_{10,4}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \\
& + \cos(\theta_{9,5}) \sin(\theta_{9,4}) \cos(\theta_{10,5}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \\
& + \cos(\theta_{9,8}) \sin(\theta_{9,4}) \sin(\theta_{9,5}) \cos(\theta_{10,8}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}) \\
& + \sin(\theta_{9,4}) \sin(\theta_{9,5}) \sin(\theta_{9,8}) \cos(\theta_{10,9}) \sin(\theta_{10,2}) \sin(\theta_{10,3}) \sin(\theta_{10,4}) \sin(\theta_{10,5}) \\
& \sin(\theta_{10,8}), \cos(\theta_{10,2})^2 + \cos(\theta_{10,3})^2 \sin(\theta_{10,2})^2 + \cos(\theta_{10,4})^2 \sin(\theta_{10,2})^2 \sin(\theta_{10,3})^2 \\
& + \cos(\theta_{10,5})^2 \sin(\theta_{10,2})^2 \sin(\theta_{10,3})^2 \sin(\theta_{10,4})^2 \\
& + \cos(\theta_{10,8})^2 \sin(\theta_{10,2})^2 \sin(\theta_{10,3})^2 \sin(\theta_{10,4})^2 \sin(\theta_{10,5})^2 \\
& + \cos(\theta_{10,9})^2 \sin(\theta_{10,2})^2 \sin(\theta_{10,3})^2 \sin(\theta_{10,4})^2 \sin(\theta_{10,5})^2 \sin(\theta_{10,8})^2 \\
& + \sin(\theta_{10,2})^2 \sin(\theta_{10,3})^2 \sin(\theta_{10,4})^2 \sin(\theta_{10,5})^2 \sin(\theta_{10,8})^2 \sin(\theta_{10,9})^2 \Big] \Big]
\end{aligned}$$

```

> for i from 1 to n do
  for j from 1 to i - 1 do
    if A[i,j] = 0 then
      lprint(i,j, B[i,j], R[i,j])
    end if
  end do
end do

```

```

3, 1, 0, 0
3, 2, 0, 0
4, 1, 0, 0
5, 1, 0, 0
6, 1, 0, 0
6, 2, 0, 0
6, 3, 0, 0
6, 5, 0, cos(theta[5,4])*sin(theta[5,2])*sin(theta[5,3])*cos(theta[6,4]
)
7, 1, 0, 0
7, 3, 0, 0
7, 5, 0, cos(theta[5,2])*cos(theta[7,2])+cos(theta[5,4])*sin(theta[5,2]
)*sin(
theta[5,3])*cos(theta[7,4])*sin(theta[7,2])
7, 6, 0, cos(theta[6,4])*cos(theta[7,4])*sin(theta[7,2])
8, 1, 0, 0
8, 7, 0, cos(theta[7,2])*cos(theta[8,2])+cos(theta[7,4])*sin(theta[7,2]
)*cos(
theta[8,4])*sin(theta[8,2])*sin(theta[8,3])
9, 1, 0, 0
9, 2, 0, 0
9, 3, 0, 0
9, 6, 0, cos(theta[6,4])*cos(theta[9,4])
9, 7, 0, cos(theta[7,4])*sin(theta[7,2])*cos(theta[9,4])
10, 1, 0, 0
10, 6, 0, cos(theta[6,4])*cos(theta[10,4])*sin(theta[10,2])*sin(theta
[10,3])
10, 7, 0, cos(theta[7,2])*cos(theta[10,2])+cos(theta[7,4])*sin(theta[7,
2])*cos(
theta[10,4])*sin(theta[10,2])*sin(theta[10,3])

```