Timestamp fast defence

December 2, 2021

1 Define the libraries

```
[12]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from matplotlib.backends.backend_pdf import PdfPages
from datetime import timedelta
from scipy import signal
```

2 Define Function

```
[13]: def_
       →PlotData(Begin, Duration, Mistake, OncourtFrame, OncourtVideo, Time, Data1, Data2, Figuur, player, df
          #Define starting en stopping positions for the CSV data
          Start = int((((OncourtFrame - OncourtVideo)*100) + Begin/10) - Mistake*100)
          Stop = int(Start + Duration*100)
          WheelRotationspeed = Data1[Start:Stop]
          FrameRotationspeed = Data2[Start:Stop]
          Timestamp = Time[Start:Stop]
          \#Lowpass filter design for rotation and wheelspeed to improve accuracy of
       →code (Butterworth filter)
          Order = 5
          cutoff_freq = 1.5
          sampling_freq = 100
          sampling_duration = Duration
          normalized_cutoff_freq = 2 * cutoff_freq / sampling_freq
          numerator_coeffs, denominator_coeffs = signal.butter(Order,_
       →normalized cutoff freq)
          filtered_WheelRotationspeed = signal.lfilter(numerator_coeffs,_
       →denominator_coeffs, WheelRotationspeed)
```

```
filtered_FrameRotationspeed = signal.lfilter(numerator_coeffs,_
→denominator_coeffs, FrameRotationspeed)
   #Play with different operations to see clearer patterns
   Sub = filtered WheelRotationspeed + filtered FrameRotationspeed
   Conv1 = filtered FrameRotationspeed / filtered WheelRotationspeed
   Conv2 = (abs(filtered_FrameRotationspeed)+abs(filtered_WheelRotationspeed))/
→filtered_WheelRotationspeed
   DiffFrame = np.diff(filtered_FrameRotationspeed,n=1)
   DiffFrame = np.insert(DiffFrame,0,0) #Add a 0 to beginning of array to fix_
⇒size error
   DiffWheel = np.diff(filtered_WheelRotationspeed,n=1)
   DiffWheel = np.insert(DiffWheel,0,0)
   Multi = filtered_WheelRotationspeed + filtered_FrameRotationspeed
   #Visualize operations done
   fig, ax = plt.subplots(2,2)
   ax[1,1].plot(Timestamp,Conv1,'r')
   ax[1,0].plot(Timestamp,abs(DiffFrame),'b')
   #Set all data into a datafram
   Data = pd.DataFrame({'Time':Timestamp,'WheelRotationspeed':
→filtered_WheelRotationspeed,
                        'FrameRotationspeed':filtered_FrameRotationspeed,
                        'Sub':Sub ,'Conv':Conv1, 'DiffFrame':DiffFrame, __
→ 'DiffWheel':DiffWheel},
                       columns=['Time', |
→ 'WheelRotationspeed', 'FrameRotationspeed', 'Sub', 'Conv', 'DiffFrame', 'DiffWheel'])
   #Convert data into chunks of n/100 of a second
   n = 50 #chunk row size
   Data_chunks = [Data[i:i+n] for i in range(0,Data.shape[0],n)]
   #Search for the sprints
   Startsprint = []
   Stopsprint = []
   Sprinting = False
   Stop = True
   #Use Sub en Conv to detect sprints
```

```
for chunks in Data_chunks:
       if abs(chunks['Conv'].max()) < 3 and chunks['Sub'].mean() > 300 and

→Sprinting == False:
           Startsprint.append(chunks['Time'].min())
           Sprinting = True
           Stop = False
       elif abs(chunks['Conv'].max() < 3) and chunks['Sub'].mean() > 300:
           Sprinting = True
           Stop = False
       elif Stop == False:
           Stopsprint.append(chunks['Time'].min())
           Sprinting = False
           Stop = True
   #Use wheelrotation, framerotation and conv to detect rotations
   Startrotate = []
   Stoprotate = []
   Rotate = False
   Stop = True
   for chunks in Data chunks:
       if abs(chunks['FrameRotationspeed'].max()) > 75 and
→abs(chunks['DiffFrame'].max()) > 4 and Rotate == False:
           Startrotate.append(chunks['Time'].min())
           Rotate = True
           Stop = False
       elif abs(chunks['FrameRotationspeed'].max()) > 75 and___
⇒abs(chunks['DiffFrame'].max()) > 4:
           Rotate = True
           Stop = False
       elif Stop == False:
           Stoprotate.append(chunks['Time'].min())
           Rotate = False
           Stop = True
   print(Startrotate, Stoprotate)
   #Filter Sprints by length, if length is below 2 delete sprint
   Deleted = 0
   if len(Startsprint) > len(Stopsprint):
       Startsprint.pop(-1)
   if len(Startsprint) == len(Stopsprint):
       for i in range(0,len(Startsprint)-1):
           if (Stopsprint[i-Deleted] - Startsprint[i-Deleted]) < 2:</pre>
               Startsprint.pop(i-Deleted)
```

```
Stopsprint.pop(i-Deleted)
               Deleted = Deleted + 1
   #Plot graph
   ax[0,0].
→plot(Timestamp, WheelRotationspeed, 'r', Timestamp, FrameRotationspeed, 'b')
→plot(Timestamp, WheelRotationspeed, 'r', Timestamp, FrameRotationspeed, 'b')
   #Plot the vertical lines in plot 1
   for Start in Startsprint:
       ax[0,0].axvline(x=Start, color = 'g')
   for Stop in Stopsprint:
       ax[0,0].axvline(x=Stop, color = 'm')
   #ax[0,0].legend(['Wheel Rotation Speed', 'Frame Rotation Speed'])
   ax[0,0].set_xlabel('Time (sec)')
   ax[0,0].set_title("Fast Defence " + str(Figuur) + ", " + str(player) + ", "
→Video Time = "
                     + str(timedelta(seconds=(int(Begin/1000)-Mistake))))
   #Plot the vertical lines in plot 2
   for Start in Startrotate:
       ax[0,1].axvline(x=Start, color = 'g')
   for Stop in Stoprotate:
       ax[0,1].axvline(x=Stop, color = 'm')
```

3 Visualize Data

3.1 Define player and match

```
[14]: Player = 15
Game = 2
```

3.2 Insert Data player

```
[15]: df_Player = pd.read_csv('matrix_Player_' + str(Player) + '_game_' + str(Game) + \_ \to '.csv')

df_Player.columns = \_ \to ['frAcc','frRoAcc','frDispl','frRoAng','frSpeed','timeLine','frameRotationalSpeedX','frameR

df_Action = pd.read_csv('Ned_DUI_Game_' + str(Game) + '.csv')

df_Player
```

```
[15]:
                          frRoAcc frDispl frRoAng
                                                         frSpeed
                                                                   timeLine
                  frAcc
      0
               0.000000
                              0.0
                                             0.00000
                                                        0.00000
                                                                       0.01
                                        0.0
                                                                       0.02
      1
               0.00000
                              0.0
                                        0.0
                                             0.00000
                                                        0.000000
      2
               0.000000
                              0.0
                                        0.0
                                             0.00000
                                                        0.00000
                                                                       0.03
      3
                              0.0
                                        0.0
                                             0.00000
                                                                       0.04
               0.000000
                                                        0.000000
      4
               0.00000
                              0.0
                                        0.0
                                              0.00000
                                                        0.000000
                                                                       0.05
      860405 -0.002098
                           6556.8
                                   -1946.6 -0.18538 -0.000787
                                                                    8604.10
                                    -1946.6 -0.18939 -0.000808
                                                                    8604.10
      860406 -0.026347
                           6556.8
      860407
               0.012933
                           6556.8
                                    -1946.6 -0.23979 -0.001071
                                                                    8604.10
      860408
                              {\tt NaN}
                                        NaN
                                                  NaN
                                                             NaN
                                                                        NaN
                    NaN
      860409
                    NaN
                              NaN
                                        NaN
                                                  NaN
                                                             {\tt NaN}
                                                                        NaN
               frameRotationalSpeedX
                                        frameRotationalSpeedY
                                                                  frameRotationalSpeedZ
      0
                                   NaN
                                                            NaN
                                                                                      NaN
      1
                                   NaN
                                                            NaN
                                                                                     NaN
      2
                                   NaN
                                                            NaN
                                                                                     NaN
      3
                                   NaN
                                                            NaN
                                                                                     NaN
      4
                                   NaN
                                                            NaN
                                                                                     NaN
      860405
                               1.0500
                                                        0.85556
                                                                                 -1.0500
                                                                                 -1.0710
      860406
                               1.0920
                                                        0.93100
      860407
                               1.1690
                                                        0.95900
                                                                                 -1.1200
      860408
                               1.1433
                                                        0.93333
                                                                                 -1.0967
      860409
                                1.1900
                                                        0.94500
                                                                                 -1.0850
                                        wheelRotationalSpeedY
               wheelRotationalSpeedX
                                                                  wheelRotationalSpeedZ
      0
                                   NaN
                                                            NaN
                                                                                     NaN
      1
                                   NaN
                                                            NaN
                                                                                     NaN
      2
                                   NaN
                                                            NaN
                                                                                     NaN
      3
                                   NaN
                                                            NaN
                                                                                     NaN
      4
                                   {\tt NaN}
                                                            NaN
                                                                                     NaN
      860405
                               1.4000
                                                                                 -1.5867
                                                        1.16670
      860406
                               1.4000
                                                        1.09200
                                                                                 -1.6240
      860407
                                1.4000
                                                        1.08110
                                                                                 -1.5089
      860408
                               1.4000
                                                        1.08500
                                                                                 -1.4700
      860409
                               1.4389
                                                        0.97222
                                                                                 -1.5089
               frRoSpeed
      0
                 0.00000
      1
                 0.00000
      2
                 0.00000
      3
                 0.00000
                 0.00000
      860405
                -0.40135
```

```
860406 -5.03910
860407 NaN
860408 NaN
860409 NaN
[860410 rows x 13 columns]
```

3.3 Define boundaries

3.3.1 Get Timestamps from CSV

7

```
[21]: array([ 268440, 304760, 788800, 1617800, 3143280, 3750200, 3789200])
```

3.3.2 Synchronize

Times consist of the oncourt times in the video and the oncourt frames in Matlab

```
[22]: df_Sync = pd.read_csv('Sync_match_' + str(Game) + '.csv')
df_Sync_Player = df_Sync.loc[df_Sync["Player"] == Player]
Times = df_Sync_Player[["Video","Matlab"]].to_numpy()
Times[0][1]
```

[22]: 3580.0

```
[23]: Error = [6,6,6,4,6,6,6,6,8,8]
print(len(Error))
```

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3.3.3 Visualize

```
[24]: Quator = 0;
for i in range(0,len(Timestamp)):
    if Quator < (len(Times)-1):</pre>
```

```
[3804.6, 3809.6] [3805.1]

[3832.4] [3832.9]

[4325.9] [4326.4]

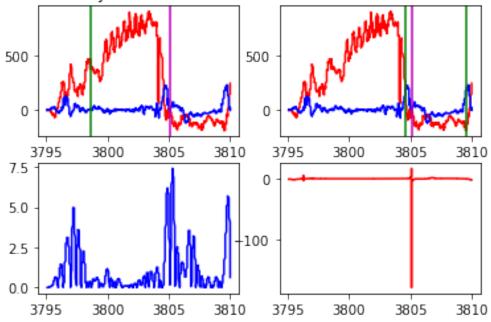
[5145.5] [5146.0]

[7157.5, 7165.0] [7158.5, 7165.5]

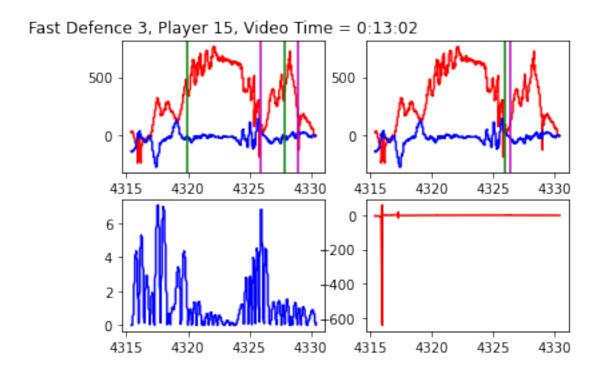
[7774.8] [7775.8]

[] []
```

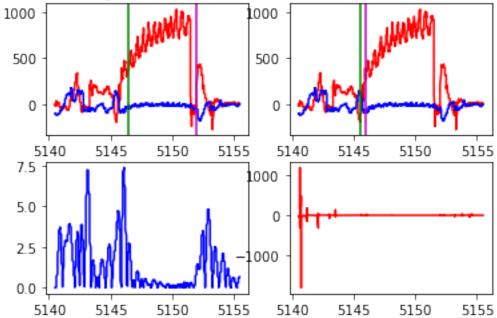
Fast Defence 1, Player 15, Video Time = 0:04:22

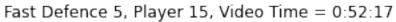


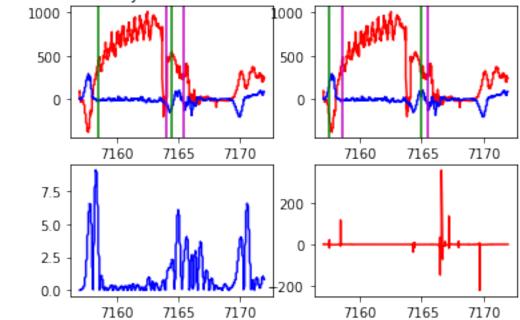
Fast Defence 2, Player 15, Video Time = 0:04:58 -1000 0 -

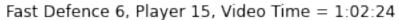


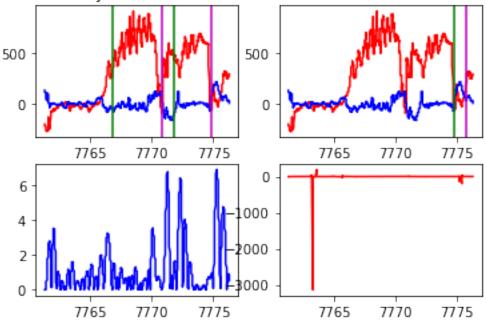
Fast Defence 4, Player 15, Video Time = 0:26:53



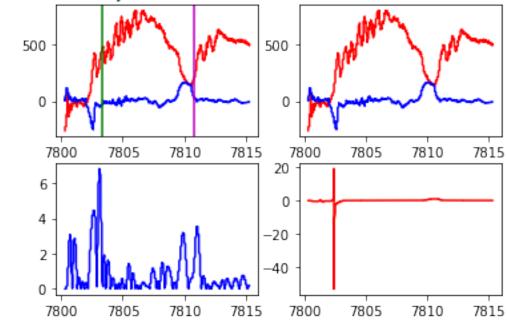








Fast Defence 7, Player 15, Video Time = 1:03:03



[]: