## RNN Overlap Dataloader

December 6, 2021

#### 1 Libraries

 $Import\ your\ libraries\ https://towards datascience.com/how-to-use-convolutional-neural-networks-for-time-series-classification-56b1b0a07a57$ 

```
[1]: import torch
     import os
     import math
     import numpy as np
     import pandas as pd
     from tqdm import tqdm
     import seaborn as sns
     from pylab import rcParams
     import matplotlib.pyplot as plt
     from torch.utils.data import DataLoader, TensorDataset
     from matplotlib import rc
     from sklearn.utils import resample
     from sklearn.model_selection import train_test_split
     from sklearn.metrics import confusion_matrix, classification_report
     from torch import nn, optim
     import torch.nn.functional as F
```

using gpu 4

## 2 Importing Data

Import the CSV file with Actions, Sum and Div as a Dataframe called df. Fill the empty values of Action with 0. Replace NaN values with 0. Delete first 100 rows.

```
[2]: #load in df
Player = 15
Game = 2
Quarter = 2

df = pd.read_csv('Split_RNN_player15game2.csv')
df_Results = pd.read_csv('Player_15_Game2_Sprints_Q1234.csv')
```

```
#Clean and expand dataset
     df = df.drop(columns = ['Unnamed: 0'])
     df.head()
[2]:
           frAcc frRoAcc frDispl frRoAng frSpeed timeLine \
      17.91200
                   2828.7
                            3394.9
                                     81.515 0.23278
                                                         3581.0
                   2828.7
                                     81.397 0.41190
       7.14760
                            3395.7
                                                         3581.0
     1
     2 -0.89061
                   2828.8
                            3396.5
                                     82.233 0.48338
                                                         3581.0
                   2828.8
     3
       4.17050
                            3397.3
                                     74.342 0.47447
                                                         3581.0
         1.15710
                   2828.8
                            3398.0
                                     74.332 0.51618
                                                         3581.0
        \verb|frameRotationalSpeedX| frameRotationalSpeedY| frameRotationalSpeedZ|
     0
                       7.3500
                                              -8.9367
                                                                       80.033
                       4.0600
                                              -8.1200
     1
                                                                       80.010
     2
                     -17.5700
                                              -0.4200
                                                                       81.340
     3
                      -1.6940
                                             -10.5000
                                                                       72.576
     4
                      -2.0922
                                                                       73.111
                                              -6.1600
        wheelRotationalSpeedY wheelRotationalSpeedY
                                                       wheelRotationalSpeedZ
     0
                      -32.737
                                              -39.114
                                                                       45.033
                       -1.050
                                              -15.960
                                                                       38.570
     1
     2
                       10.780
                                              -32.340
                                                                       45.640
     3
                       16.485
                                              -41.601
                                                                       51.163
                       23.847
                                              -34.619
                                                                       54.281
        frRoSpeed Filt_WheelX Filt_FrameZ Action Quarter
         -11.8030
     0
                     67.674366
                                   8.849375
                                                 0.0
     1
          83.6110
                     65.140780
                                   8.214781
                                                 0.0
                                                            1
       -789.0700
                     62.446959
                                   7.721630
                                                 0.0
     2
                                                            1
     3
         -1.0099
                     59.592743
                                   7.380241
                                                 0.0
                                                            1
          94.2010
                     56.579696
                                   7.199759
                                                 0.0
                                                            1
        wheelRotationalSpeedX_Diff
     0
                             0.000
     1
                            31.687
     2
                            11.830
     3
                             5.705
                             7.362
```

# 3 Pre Preprocessing

```
[3]: #Split data set into train en test with the quarters of the game train = pd.

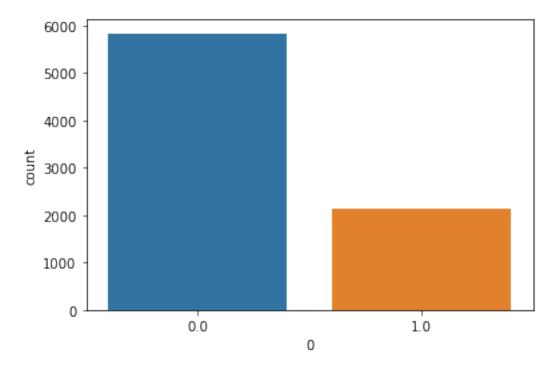
→read_csv('Split_Xtrain_balanced_RNN_player15game2_Quartor'+str(Quarter)+'.

→csv')
```

/opt/jupyterhub/anaconda/lib/python3.9/site-packages/seaborn/\_decorators.py:36: FutureWarning: Pass the following variable as a keyword arg: x. From version 0.12, the only valid positional argument will be `data`, and passing other arguments without an explicit keyword will result in an error or misinterpretation.

warnings.warn(

#### [3]: <AxesSubplot:xlabel='0', ylabel='count'>



### 4 Split Data

```
[4]: def rounddown(x):
    return (int(math.ceil(x / 100.0)) * 100) - 100

[5]: features = □
    →['wheelRotationalSpeedX','frameRotationalSpeedY','frAcc','wheelRotationalSpeedX_Diff']

X_train = train[features]
    X_train = X_train.iloc[0:rounddown(len(X_train))]

y_train = y_train_resample['0']

X_test = test[features]
    X_test = X_test.iloc[0:rounddown(len(X_test))]

y_test = y_test_resample
```

### 5 Convert the X\_train, X\_test, y\_train, y\_test to Tensors

```
[6]: X_train = torch.from_numpy(X_train.to_numpy()).float()
X_train = X_train.unsqueeze_(-1)
X_train = X_train.transpose(2, 0)
X_train = X_train.transpose(2,1)
X_train = torch.reshape(X_train, [-1,100,len(features)])

y_train = torch.squeeze(torch.from_numpy(y_train.to_numpy()).float())

X_test = torch.from_numpy(X_test.to_numpy()).float()
X_test = X_test.unsqueeze_(-1)
X_test = X_test.transpose(2,0)
X_test = X_test.transpose(2,1)
X_test = torch.reshape(X_test, [-1,100,len(features)])

y_test = torch.squeeze(torch.from_numpy(y_test.to_numpy()).float())
```

#### 6 Load Data into Dataloader

```
[7]: train_ds = TensorDataset(X_train, y_train)
train_dl = DataLoader(train_ds, batch_size=64, num_workers = 4, pin_memory = □
→True)
```

#### 7 CNN def

Define the Convolutional Neural Network

```
[8]: class LSTM(nn.Module):
         def __init__(self, hidden_state_size = 200, input_feature_size =_
      →len(features)):
             super().__init__()
             self.hidden_state_size = hidden_state_size
             self.feature_size = input_feature_size
             self.lstm1 = nn.LSTM(input_feature_size, self.hidden_state_size,__
      →batch first=True)
             self.12 = nn.Linear(self.hidden_state_size, 1)
         def forward(self, x):
             h, = self.lstm1(x)
             h = h[:,-1,:]
             y = self.12(h)
             y = y + x[:,-1,-1:]
             return torch.sigmoid(y)
         def post_forward(self, y):
             return torch.round(y)
     RNN = LSTM()
```

### 8 Training options

```
[9]: criterion = nn.BCELoss()
    optimizer = optim.Adam(RNN.parameters(), lr=0.001)
```

### 9 Training the RNN on the GPU

```
[10]: device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")

X_test = X_test.to(device)
y_test = y_test.to(device)

RNN = RNN.to(device)
criterion = criterion.to(device)
```

### 10 Define functions for calculating Accuracy of model

```
[11]: def calculate_accuracy(y_true, y_pred):
    return (y_true == y_pred).sum().float() / len(y_true)
```

### 11 For loop through different epochs

```
[12]: def round_tensor(t, decimal_places=3):
          return round(t.item(), decimal_places)
      Results_acc = pd.DataFrame(columns = ['Epoch', 'Acc_train', 'Acc_test'])
      Results_loss = pd.DataFrame(columns = ['Epoch', 'Loss_train', 'Loss_test'])
      Results recall = pd.DataFrame(columns = ['Epoch', 'Recall test'])
      Results_prec = pd.DataFrame(columns = ['Epoch', 'Prec_test'])
      for epoch in range (200):
          for x, y in train_dl:
              x, y = x.to(device), y.to(device)
              optimizer.zero_grad()
              y_pred = RNN(x)
              y_pred = y_pred.squeeze(axis = 1)
              train_loss = criterion(y_pred, y)
              train loss.backward()
              optimizer.step()
          if epoch % 1 == 0:
              train_acc = calculate_accuracy(y, RNN.post_forward(y_pred))
              train_loss = criterion(y_pred,y)
              y_test_pred = RNN(X_test)
              y_test_pred = torch.squeeze(y_test_pred)
              test_loss = criterion(y_test_pred, y_test)
              test_acc = calculate_accuracy(y_test, RNN.post_forward(y_test_pred))
              Confusion = confusion_matrix(y_test.cpu(),y_test_pred.ge(.5).view(-1).
       →cpu())
              test_recall = Confusion[1][1]/(Confusion[1][1] + Confusion[1][0])
              test_prec = Confusion[1][1]/(Confusion[0][1] + Confusion[1][1])
```

```
Acc = {'Epoch': epoch, 'Acc_train': round_tensor(train_acc), 'Acc_test':

round_tensor(test_acc)}

Loss = {'Epoch': epoch, 'Loss_train': round_tensor(train_loss),__

'Loss_test': round_tensor(test_loss)}

Recall = {'Epoch': epoch, 'Recall_test': round_tensor(test_recall)}

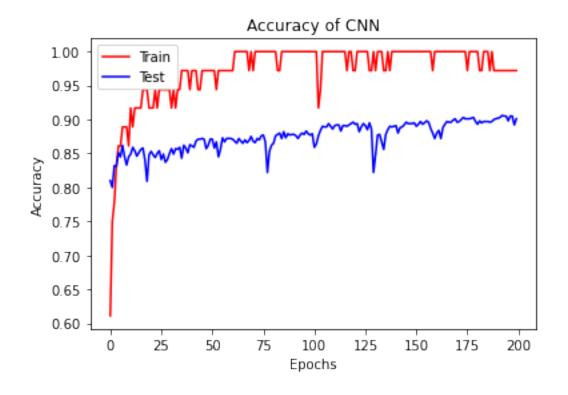
Prec = {'Epoch': epoch, 'Prec_test': round_tensor(test_prec)}

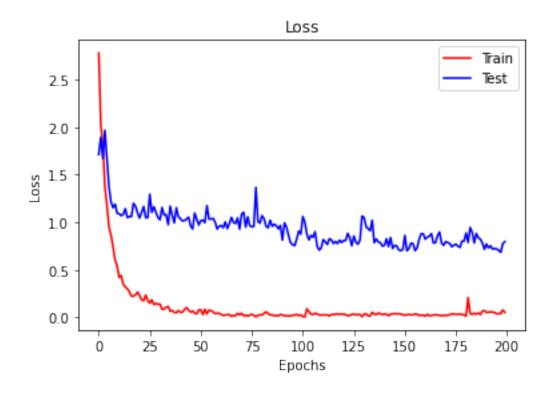
Results_acc = Results_acc.append(Acc, ignore_index=True)

Results_loss = Results_loss.append(Loss, ignore_index=True)

Results_recall = Results_recall.append(Recall, ignore_index=True)

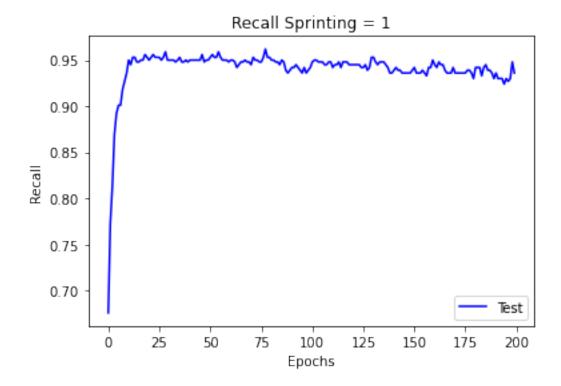
Results_prec = Results_prec.append(Prec, ignore_index=True)
```

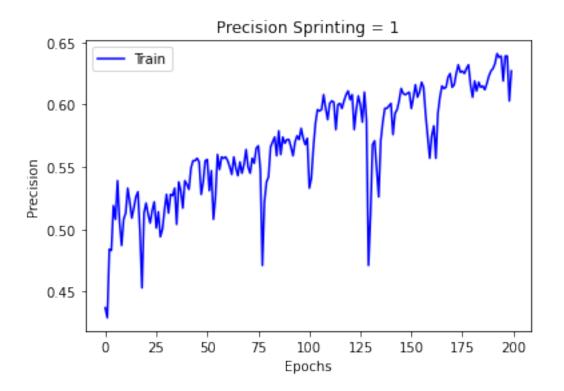




```
[14]: plt.plot(Results_recall.Epoch , Results_recall.Recall_test,'b')
   plt.legend(['Test'])
   plt.title('Recall Sprinting = 1')
   plt.ylabel('Recall')
   plt.xlabel('Epochs')
   plt.show()

plt.plot(Results_prec.Epoch,Results_prec.Prec_test,'b')
   plt.legend(['Train'])
   plt.title('Precision Sprinting = 1')
   plt.ylabel('Precision')
   plt.xlabel('Epochs')
   plt.show()
```





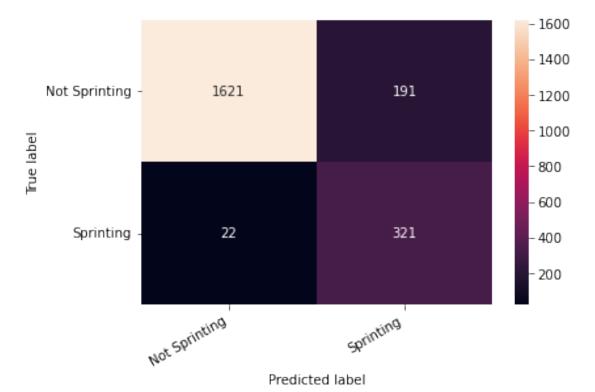
# 12 Validate/Tune Model

Validate results of the model (Precision/Recall). Tune the parameters of the model to achieve better results

```
[15]: classes = ['Not Sprinting', 'Sprinting']
    y_pred = RNN(X_test)
    y_pred = y_pred.ge(.5).view(-1).cpu()
    y_test = y_test.cpu()
    print(classification_report(y_test, y_pred, target_names=classes))
```

	precision	recall	f1-score	support
Not Sprinting	0.99	0.89	0.94	1812
Sprinting	0.63	0.94	0.75	343
accuracy			0.90	2155
macro avg	0.81	0.92	0.84	2155
weighted avg	0.93	0.90	0.91	2155

```
[16]: cm = confusion_matrix(y_test, y_pred)
    df_cm = pd.DataFrame(cm, index=classes, columns=classes)
    hmap = sns.heatmap(df_cm, annot=True, fmt="d")
    hmap.yaxis.set_ticklabels(hmap.yaxis.get_ticklabels(), rotation=0, ha='right')
    hmap.xaxis.set_ticklabels(hmap.xaxis.get_ticklabels(), rotation=30, ha='right')
    plt.ylabel('True label')
    plt.xlabel('Predicted label');
```



## 13 Export results

```
[17]: df_results = pd.DataFrame(y_pred)
df_results.to_csv('Predictions_15x2_Quartor'+str(Quarter)+'_Overlap.csv')
df_results
```

```
2150 False
2151 False
2152 False
2153 False
2154 False

[2155 rows x 1 columns]
```

# 14 Close Kernel

```
[]: %%javascript
Jupyter.notebook.session.delete();
```

<IPython.core.display.Javascript object>