1D-CNN-1sec-Dataloader

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1 Libraries

 $Import\ your\ libraries\ https://towards datascience.com/how-to-use-convolutional-neural-networks-for-time-series-classification-56b1b0a07a57$

```
[22]: import torch
      import os
      import math
      import numpy as np
      import pandas as pd
      from tqdm import tqdm
      import seaborn as sns
      from pylab import rcParams
      import matplotlib.pyplot as plt
      from matplotlib import rc
      from torch.utils.data import DataLoader, TensorDataset
      from sklearn.utils import resample
      from sklearn.model_selection import train_test_split
      from sklearn.metrics import confusion matrix, classification report
      from torch import nn, optim
      import torch.nn.functional as F
```

$2 ext{ NN = torch.load(MODEL_PATH)}$

3 Importing Data

Import the CSV file with Actions, Sum and Div as a Dataframe called df. Fill the empty values of Action with 0. Replace NaN values with 0. Delete first 100 rows.

```
[23]: #load in df
Player = 15
Game = 2
Quarter = 4
```

```
df_y = pd.read_csv('Player_15_Game2_Sprints_Q1234.csv')
      df_y = df_y[['Action','Quarter','timeLine']]
      df y = df y.iloc[::2]
      #Delete first 99 rows, so df starts at timeLine == 1.00
      df['wheelRotationalSpeedX_Diff'] = np.insert(np.diff(df.
       \rightarrowwheelRotationalSpeedX,n=1),0,0)
      df.head()
[23]:
         Unnamed: 0
                        frAcc frRoAcc frDispl frRoAng frSpeed timeLine \
      0
             358099 17.91200
                                2828.7
                                         3394.9
                                                   81.515 0.23278
                                                                      3581.0
      1
             358100
                      7.14760
                                2828.7
                                         3395.7
                                                   81.397 0.41190
                                                                      3581.0
      2
             358101 -0.89061
                                2828.8
                                         3396.5
                                                   82.233 0.48338
                                                                      3581.0
      3
             358102
                      4.17050
                                2828.8
                                         3397.3
                                                   74.342 0.47447
                                                                      3581.0
             358103
                      1.15710
                                2828.8
                                         3398.0
                                                   74.332 0.51618
                                                                      3581.0
         frameRotationalSpeedX frameRotationalSpeedY frameRotationalSpeedZ
      0
                        7.3500
                                               -8.9367
                                                                       80.033
      1
                        4.0600
                                               -8.1200
                                                                       80.010
      2
                      -17.5700
                                               -0.4200
                                                                       81.340
      3
                       -1.6940
                                              -10.5000
                                                                       72.576
      4
                       -2.0922
                                               -6.1600
                                                                        73.111
         wheelRotationalSpeedX wheelRotationalSpeedY wheelRotationalSpeedZ
      0
                       -32.737
                                               -39.114
                                                                        45.033
      1
                        -1.050
                                               -15.960
                                                                       38.570
      2
                        10.780
                                               -32.340
                                                                       45.640
      3
                                               -41.601
                                                                       51.163
                        16.485
      4
                        23.847
                                               -34.619
                                                                       54.281
         frRoSpeed Filt_WheelX Filt_FrameZ Action
                                                       Quarter
        -11.8030
                      67.674366
                                    8.849375
                                                  0.0
                                                  0.0
      1
           83.6110
                      65.140780
                                    8.214781
                                                             1
       -789.0700
                      62.446959
                                    7.721630
                                                  0.0
                                                             1
                                                  0.0
           -1.0099
                      59.592743
                                    7.380241
                                                             1
      3
      4
           94.2010
                      56.579696
                                    7.199759
                                                  0.0
                                                             1
         wheelRotationalSpeedX_Diff
      0
                              0.000
                             31.687
      1
      2
                             11.830
```

df = pd.read_csv('matrix_Player_' + str(Player) + '_game_' + str(Game) +__

```
3 5.705
4 7.362
```

4 Pre Preprocessing

```
[24]: #Convert Sprinting to 1
df.Action.replace({'Sprinting': 1},inplace=True)
```

5 Data Preparating

Split data into a train and test set

```
[25]: train = df[df.Quarter != Quarter]
    test = df[df.Quarter == Quarter]

y_train = df_y[df_y.Quarter != Quarter]
y_test = df_y[df_y.Quarter == Quarter]
y_test = y_test.iloc[:-1 , :]

def rounddown(x):
    return (int(math.ceil(x / 100.0)) * 100) - 100

X_train = train[['wheelRotationalSpeedX','frameRotationalSpeedZ','frAcc']]
X_train = X_train.iloc[0:rounddown(len(X_train))]

y_train = y_train[['Action']]

X_test = test[['wheelRotationalSpeedX','frameRotationalSpeedZ','frAcc']]
X_test = X_test.iloc[0:rounddown(len(X_test))]

y_test = y_test[['Action']]
```

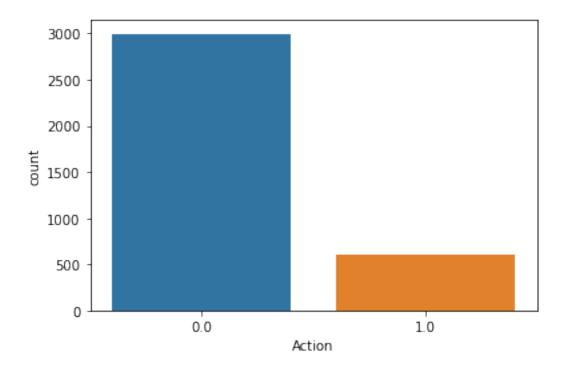
5.1 Slicing the train and test sets into windows of 1 sec (100 samples per window)

(3595, 3, 100)

/opt/jupyterhub/anaconda/lib/python3.9/site-packages/seaborn/_decorators.py:36: FutureWarning: Pass the following variable as a keyword arg: x. From version 0.12, the only valid positional argument will be `data`, and passing other arguments without an explicit keyword will result in an error or misinterpretation.

warnings.warn(

[28]: <AxesSubplot:xlabel='Action', ylabel='count'>



5.2 Balancing the data (Copy all positives and paste them after X_train)

```
[29]: X_train_Resample = pd.DataFrame()
    y_train_Resample = pd.DataFrame()

y_train = y_train.squeeze()
    y_train = y_train.to_numpy()

print(y_train)

for i in range(0,len(y_train)):
    if y_train[i] == 1:
        X_train_Resample = X_train_Resample.append(pd.DataFrame(X_train[i]))
        y_train_Resample = y_train_Resample.append(pd.DataFrame([1]))
```

[0. 0. 0. ... 0. 0. 0.]

```
for i in range(0,2):
    X_train_Resample = np.concatenate((X_train_Resample, X_train_Resample),
    axis=0)
    y_train_Resample = np.concatenate((y_train_Resample, y_train_Resample),
    axis=0)

print(y_train_Resample)

X_train_Resample = np.concatenate((X_train, X_train_Resample), axis=0)
    y_train_Resample = np.concatenate((y_train, y_train_Resample), axis=0)

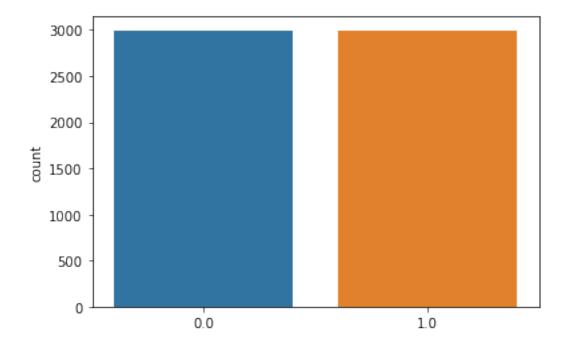
sns.countplot(y_train_Resample)
```

[1 1 1 ... 1 1 1]

/opt/jupyterhub/anaconda/lib/python3.9/site-packages/seaborn/_decorators.py:36: FutureWarning: Pass the following variable as a keyword arg: x. From version 0.12, the only valid positional argument will be `data`, and passing other arguments without an explicit keyword will result in an error or misinterpretation.

warnings.warn(

[30]: <AxesSubplot:ylabel='count'>



5.3 Convert the X_train, X_test, y_train, y_test to Tensors

```
[31]: X_train = torch.from_numpy(X_train_Resample).float()
y_train = torch.squeeze(torch.from_numpy(y_train_Resample).float())

X_test = torch.from_numpy(X_test).float()
y_test = torch.squeeze(torch.from_numpy(y_test.to_numpy()).float())

[32]: train_ds = TensorDataset(X_train, y_train)
train_dl = DataLoader(train_ds, batch_size=64, num_workers = 4, pin_memory = □
→True)
```

6 CNN def

Define the Convolutional Neural Network

```
[33]: class model(nn.Module):
          def __init__(self,n_features,kernel_size):
              super(model, self).__init__()
              #Use Padding to get good results
              self.conv1 = nn.Conv1d(n features, 36, kernel_size=kernel_size, stride_
       →= 1, padding='same') #3 input channels, 18 output channels
              self.conv2 = nn.Conv1d(36, 78, kernel_size=kernel_size, stride = 1,
       →padding='same') #18 input channels from previous Conv. layer, 36 out
              self.conv2_drop = nn.Dropout2d() #dropout
              self.fc1 = nn.Linear(78, 54) #Fully-connected classifier layer
              self.fc2 = nn.Linear(54, 19) #Fully-connected classifier layer
              self.fc3 = nn.Linear(19,1) #Fully-connected classifier layer
          def forward(self, x):
              x = F.relu(F.max_pool1d(self.conv1(x), 10)) #Use bigger Pool1d for model
              x = F.relu(F.max_pool1d(self.conv2_drop(self.conv2(x)), 10))
              #point A
              x = x.transpose(1, 2)
              #point B
              x = self.fc1(x)
              x = F.relu(x)
              x = F.dropout(x, training=self.training)
              x = self.fc2(x)
              return torch.sigmoid(self.fc3(x))
```

```
def post_forward(self, y):
    return torch.round(y)

CNN = model(X_train.shape[1],50)
```

7 Training options

```
[34]: criterion = nn.BCELoss()
optimizer = optim.Adam(CNN.parameters(), lr=0.001)
```

8 Training the NN on the GPU

```
[36]: device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")

X_test = X_test.to(device)
y_test = y_test.to(device)

CNN = CNN.to(device)
criterion = criterion.to(device)
```

9 Define functions for calculating Accuracy of model

```
[37]: def calculate_accuracy(y_true, y_pred):
    return (y_true == y_pred).sum().float() / len(y_true)
```

10 For loop through different epochs

```
[38]: def round_tensor(t, decimal_places=3):
    return round(t.item(), decimal_places)

Results_acc = pd.DataFrame(columns = ['Epoch', 'Acc_train', 'Acc_test'])
Results_loss = pd.DataFrame(columns = ['Epoch', 'Loss_train', 'Loss_test'])
Results_recall = pd.DataFrame(columns = ['Epoch', 'Recall_test'])
Results_prec = pd.DataFrame(columns = ['Epoch', 'Prec_test'])

for epoch in range(100):
    for x, y in train_dl:
```

```
x, y = x.to(device), y.to(device)
              optimizer.zero_grad()
              y_pred = CNN(x)
              y_pred = y_pred.squeeze()
              train_loss = criterion(y_pred, y)
              train loss.backward()
              optimizer.step()
          if epoch % 1 == 0:
              train_acc = calculate_accuracy(y, CNN.post_forward(y_pred))
              train_loss = criterion(y_pred,y)
              y_test_pred = CNN(X_test)
              y_test_pred = torch.squeeze(y_test_pred)
              test_loss = criterion(y_test_pred, y_test)
              test_acc = calculate_accuracy(y_test, CNN.post_forward(y_test_pred))
              Confusion = confusion_matrix(y_test.cpu(),y_test_pred.ge(.5).view(-1).
       →cpu())
              test recall = Confusion[1][1]/(Confusion[1][1] + Confusion[1][0])
              test_prec = Confusion[1][1]/(Confusion[0][1] + Confusion[1][1])
              Acc = {'Epoch': epoch, 'Acc_train': round_tensor(train_acc), 'Acc_test':
       → round_tensor(test_acc)}
              Loss = {'Epoch': epoch, 'Loss train': round tensor(train loss),
       →'Loss_test': round_tensor(test_loss)}
              Recall = {'Epoch': epoch, 'Recall test': round tensor(test recall)}
              Prec = {'Epoch': epoch, 'Prec_test': round_tensor(test_prec)}
              Results_acc = Results_acc.append(Acc, ignore_index=True)
              Results_loss = Results_loss.append(Loss, ignore_index=True)
              Results_recall = Results_recall.append(Recall, ignore_index=True)
              Results_prec = Results_prec.append(Prec, ignore_index=True)
[39]: plt.plot(Results_acc.Epoch,Results_acc.Acc_train,'r',Results_acc.
      →Epoch, Results acc. Acc test, 'b')
      plt.legend(['Train','Test'])
      plt.title('Accuracy of CNN')
      plt.ylabel('Accuracy')
      plt.xlabel('Epochs')
```

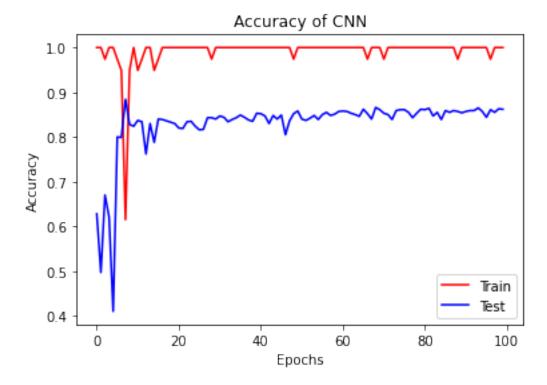
plt.plot(Results_loss.Epoch,Results_loss.Loss_train,'r',Results_loss.

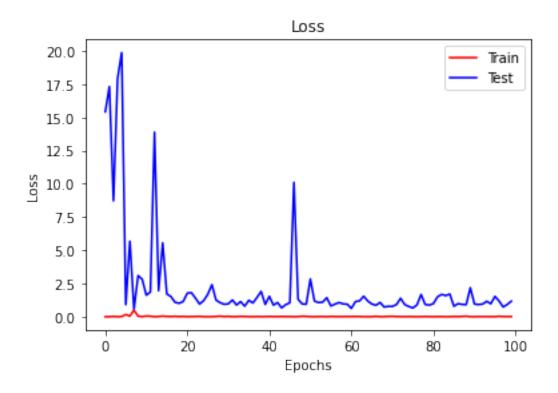
plt.show()

→Epoch,Results_loss.Loss_test,'b')

plt.legend(['Train','Test'])

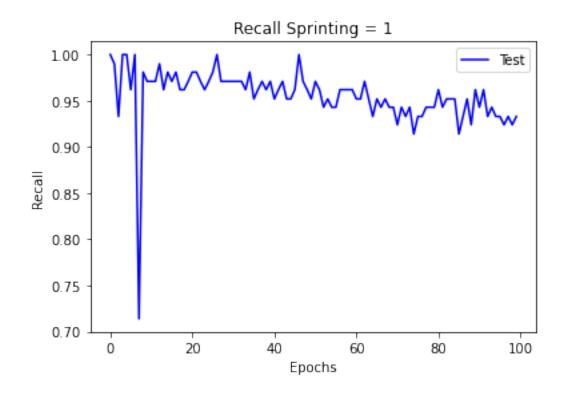
```
plt.title('Loss')
plt.ylabel('Loss')
plt.xlabel('Epochs')
plt.show()
```

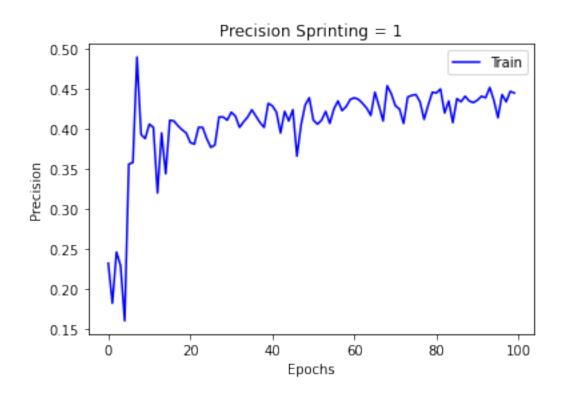




```
[40]: plt.plot(Results_recall.Epoch , Results_recall.Recall_test,'b')
    plt.legend(['Test'])
    plt.title('Recall Sprinting = 1')
    plt.ylabel('Recall')
    plt.xlabel('Epochs')
    plt.show()

plt.plot(Results_prec.Epoch,Results_prec.Prec_test,'b')
    plt.legend(['Train'])
    plt.title('Precision Sprinting = 1')
    plt.ylabel('Precision')
    plt.xlabel('Epochs')
    plt.show()
```





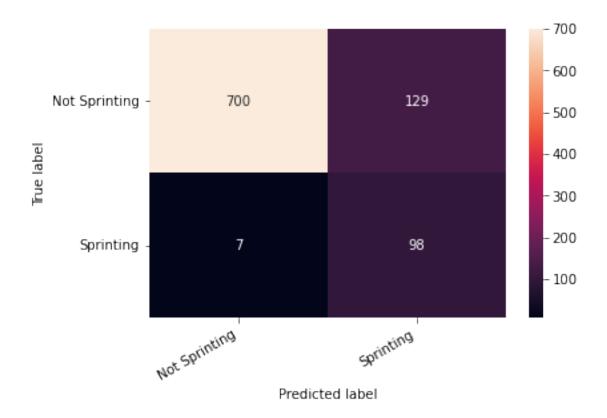
11 Validate/Tune Model

Validate results of the model (Precision/Recall). Tune the parameters of the model to achieve better results

```
[41]: classes = ['Not Sprinting', 'Sprinting']
y_pred = CNN(X_test)
y_pred = y_pred.ge(.5).view(-1).cpu()
y_test = y_test.cpu()
print(classification_report(y_test, y_pred, target_names=classes))
```

	precision	recall	f1-score	support
	_			
Not Sprinting	0.99	0.84	0.91	829
Sprinting	0.43	0.93	0.59	105
accuracy			0.85	934
macro avg	0.71	0.89	0.75	934
weighted avg	0.93	0.85	0.88	934

```
[42]: cm = confusion_matrix(y_test, y_pred)
    df_cm = pd.DataFrame(cm, index=classes, columns=classes)
    hmap = sns.heatmap(df_cm, annot=True, fmt="d")
    hmap.yaxis.set_ticklabels(hmap.yaxis.get_ticklabels(), rotation=0, ha='right')
    hmap.xaxis.set_ticklabels(hmap.xaxis.get_ticklabels(), rotation=30, ha='right')
    plt.ylabel('True label')
    plt.xlabel('Predicted label');
```



12 Closing Notebook

```
[]: \[ \%\'javascript \]
Jupyter.notebook.session.delete();
```

<IPython.core.display.Javascript object>